

EECS 391: Introduction to AI

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Announcements

- HW1 will be posted online and on blackboard, due Jan 26
- PA1 will be posted, due Feb 7
- Reading assignment: Chapter 3 of textbook

Today

- What is AI?
- A brief history of AI
- Applications of AI today
- AI in the near future
- Intelligent Agents

What is AI?

- What is “intelligence”?
 - A human-centric view: “Can machines think?”
 - Intelligence is *not* some mystical special quality humans alone are endowed with
 - We don’t know exactly, but it is the result of a computational process
- Modern AI is about the *process* of intelligence, decoupled from the entity performing it

~~What is intelligence?~~

- What does intelligence *allow you to do?*
- Try to characterize intelligence “operationally”
 - I give you a sealed box and some rules for input/output. I claim, “This is an intelligent box.”
 - How do you try to prove/disprove my claim?

What does intelligence do?

- Enables *Behavior*
 - That allows *flexible, rational problem solving*
 - That allows *learning*

Intelligence is a capability that enables flexible, adaptive, rational problem solving behavior.

What is AI?

- Intelligent behavior
- Embodied in an *artifact*
 - Something made by humans
 - Usually we take this to mean a digital computer
- Term “artificial intelligence”
created by John McCarthy in 1956



Human Intelligence and modern AI

- Human intelligence can be used to identify a set of problems that could be a part of an intelligent system's repertoire of problems
- Several parts of AI are involved in simulating human intelligence

A Closer Look

- Person A tells person B, “Please pick up the pencil on the desk.” Person B does this.
 - What just happened?

A Closer Look (2)

- Person B hears a sequence of sounds, which have to be converted to *words* (**speech recognition**)
- The *sentence structure* must be recovered in order to know what needs to be done to whom (**natural language processing**)

A Closer Look (3)

- Person B must then *look around to identify* (a) the current state of the environment (desk, etc) and (b) the correct “pencil” (**computer vision and classification**)
- The facts about the pencil and its environment are *converted into a representation* that can be reasoned with (**knowledge representation and reasoning**)

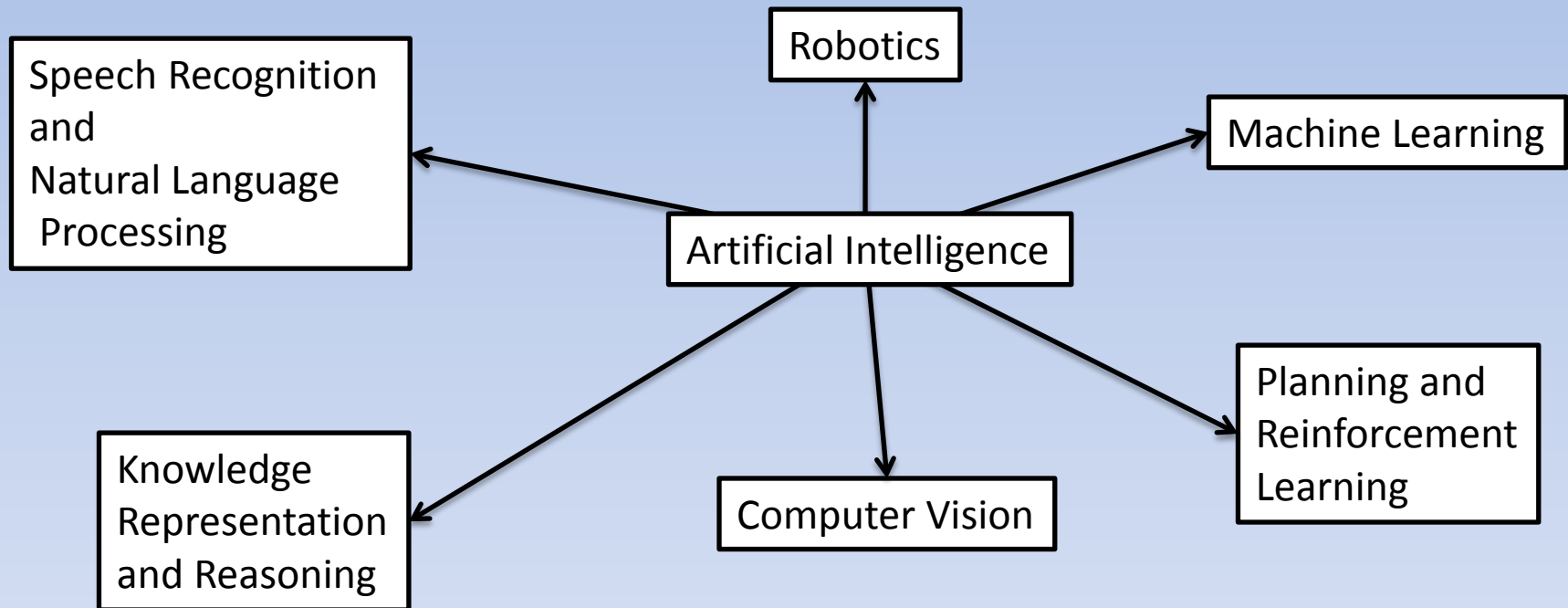
A Closer Look (4)

- Given the current state of the environment and the “goal” (i.e. the pencil should be picked up), person B then *moves their hand to achieve the goal* (**planning** and **reinforcement learning**)
- The next time such a request (or a similar one) is made, we may expect person B to respond more quickly, having *learned to do this task* (**machine learning**)

A Closer Look (5)

- Finally, if we want to *build a physical system* to emulate this behavior, we also need **robotics**

AI subfields



A brief history of AI

- Stage 1---Euphoria (1950-1965)
 - Computational models of the neuron proposed
 - Simple problem-solving demonstrated (checkers playing program, Logic Theorist)
- Stage 2---Reality (1965-1975)
 - Strong limits discovered on what problems could be solved with simple models
 - Ideas did not generalize to significantly different problems or scale to realistic problems

A brief history of AI (2)

- Stage 3---Resurgence (1975-1990s)
 - By combining human expertise with AI principles, rule-based systems started to solve complex problems
 - Neural networks made a comeback, with better understanding of underlying theory

A brief history of AI (3)

- Stage 4---Steady Progress (1990s-Now)
 - AI has matured
 - Concepts are mathematically grounded, ideas are scientifically evaluated
 - Very interdisciplinary
 - Uses tools from logic, probability and statistics, operations research along with computer science
 - AI technologies are used in numerous industries, from vacuum cleaners to Mars rovers
 - Many significant challenges remain, but progress is being made

“If you invent a breakthrough in artificial intelligence, so machines can learn, that is worth 10 Microsofts.”

Bill Gates, at a speech in MIT in 2004

Poster by

AAAI

Association for the Advancement of Artificial Intelligence

AI Magazine

Poster development supported in part by



Optimizing Paths & Flows

Planning

AI & Creative Expression

Plan Recognition

AI in Art

AI in Music

Humanoid Robots

Intelligent Tutoring

Autonomous Vehicles & Safety

Robot Guides & Assistants

Augmenting Cognition

Ubiquitous Computing

Social Computing

Gesture Recognition

Multimodal Interfaces

Mixed-Initiative Collaboration

Autonomous Space Exploration

AI and Preferences, Media & Entertainment

Descartes
Aristotle

Robots For Education

Robotic Surgery

Home Robotics

Leibniz
Lovelace

HOW CAN WE TELL IF WE'RE BEING CONTROLLED BY A MACHINE?

Diagnosis
Drug Design

Scientific Discovery

Security & Privacy

Turing

Vehicle Navigation

See the AI timeline and more at www.aaai.org/AILandscape

The AI Landscape

David Leake, Indiana University, Poster Development Committee Chair
Poster Design: Giacomo Marchesi, www.GiacomoMarchesi.com

AI HISTORY TOUR

HOW CAN WE BRING ROBOTS TO LIFE? CAN WE MAKE THEM THINK?

CAN WE BRING PEOPLE TO LIFE?

Eco-computing

HOW CAN WE SOLVE PROBLEMS THAT ARE TOO COMPLEX FOR US?

HOW CAN WE MAKE MACHINES UNDERSTAND US?

Applications (1)

- Speech Recognition
 - “Please describe your problem in a few words”
- Board Games
 - Chess (Deep Blue beat Kasparov in 1997)
 - Checkers (“Checkers is Solved”, Schaeffer et al, Science 2007)

Applications (2)

- Web search
- Recommender systems (Netflix prize)
- Medical diagnosis systems
- “Smart” user interfaces
- HSTS planner used by Hubble Space Telescope
- Chatbots (Loebner prize)

Applications (3)

- Robotics

(<http://www.youtube.com/watch?v=a9r4bvChWFc>,
<http://video.google.com/videoplay?docid=-3227236507141963827&hl=en>)

Applications of AI Today (4)

- <http://video.google.com/videoplay?docid=-8274817955695344576&hl=en>
- <http://www.youtube.com/watch?v=IUUI63ERek0>
- urbanchallenge.case.edu

In the near future...

- Computer processing power is growing rapidly
- In a decade or two, we will have computers that are roughly hardware equivalent to the human brain

In the near future...

- Autonomous vehicles
- Artificial characters in video games/ online worlds

- But still some time away from a flexible, integrated intelligent system

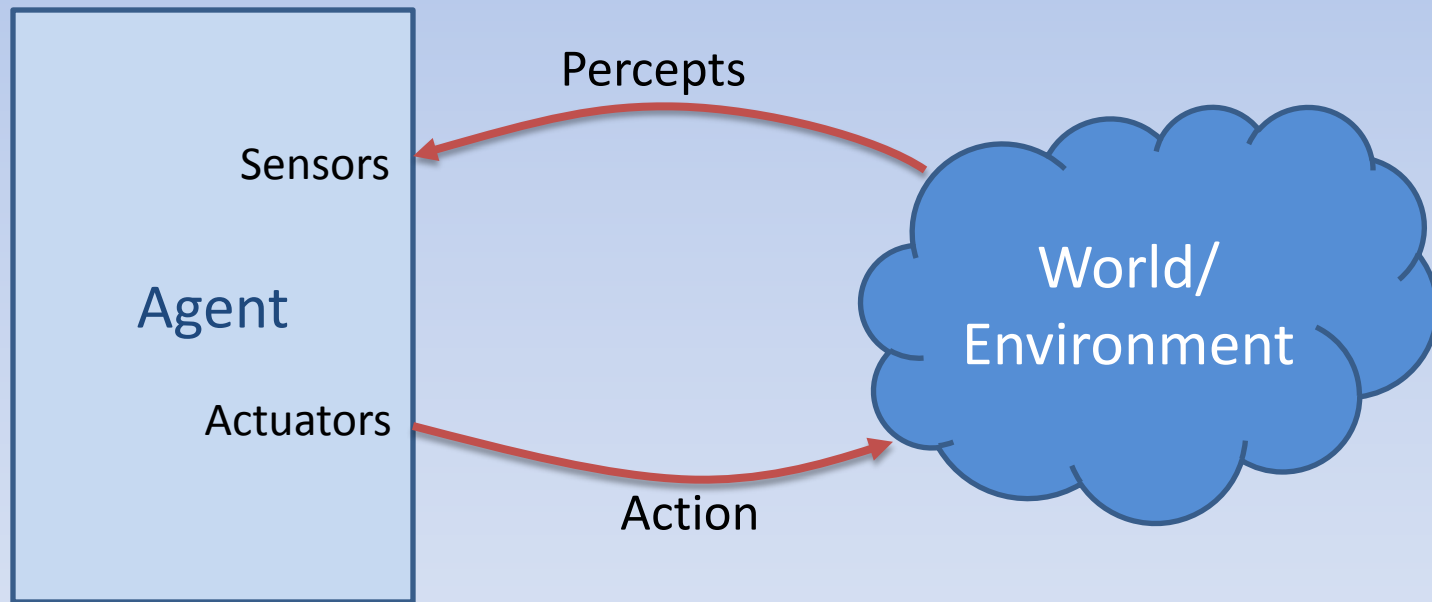
Summary

- We learned about:
 - What AI is about and its subfields
 - A brief history of the field
 - Some current applications of AI

Intelligent Agents (Chapter 2)

Basic Agent Architecture

- Something that interacts with the world



“Agent Function” A : Percept Sequences \rightarrow Actions

Examples

- Chess-playing agent
 - Sensors?
 - Actuators?

- Autonomous vehicle agent
 - Sensors?
 - Actuators?

Performance Measures

- Agents are usually “goal-based”, i.e. they are designed to achieve certain things in the world
 - Chess-playing agent?
 - Autonomous vehicle agent?
- These are often encoded using a “performance measure”
 - A function that maps a (percept, action) sequence to a real number
 - Externally imposed

Rational Agents

- A **rational agent** is one whose agent function always acts to maximize its performance measure, given its percept sequence until the current moment

Example

- Suppose the chess-playing agent is given the performance measure: every time it makes a move, it gets -1 point
 - What will a rational agent do?
- Suppose the autonomous vehicle agent is given the measure: $+1$ point every second without a collision
 - What might a rational agent do?

Information Gathering

- Agents may be used in unknown environments that we didn't anticipate when designing them
- In this case, it's a good idea to design the performance measure to reward the agent for collecting information about its environment along with achieving the goal

“PEAS” description

- To design the (rational) agent program we need four things:
 - The **P**erformance measure
 - A description of the **E**nvironment
 - A description of what **A**ctions the agent has
 - A description of what **S**ensors the agent has

Examples

- Chess-playing agent PEAS?
- Autonomous vehicle agent PEAS?

Types of Environments

Type	Definition
Fully observable (vs. <i>Partially Observable</i>)	Agent's sensors present complete, accurate picture of the world
Deterministic (vs. <i>Stochastic</i>)	The next state of the world is completely determined by current state and agent's action
Episodic (vs. <i>Sequential</i>)	Agent's current action does not affect future actions
Static (vs. <i>Dynamic</i>)	The world does not change until the agent takes an action
Discrete (vs. <i>Continuous</i>)	States, percepts and actions are discrete
Single Agent (vs. <i>Multiagent</i>)	The world has only one agent in it

Example

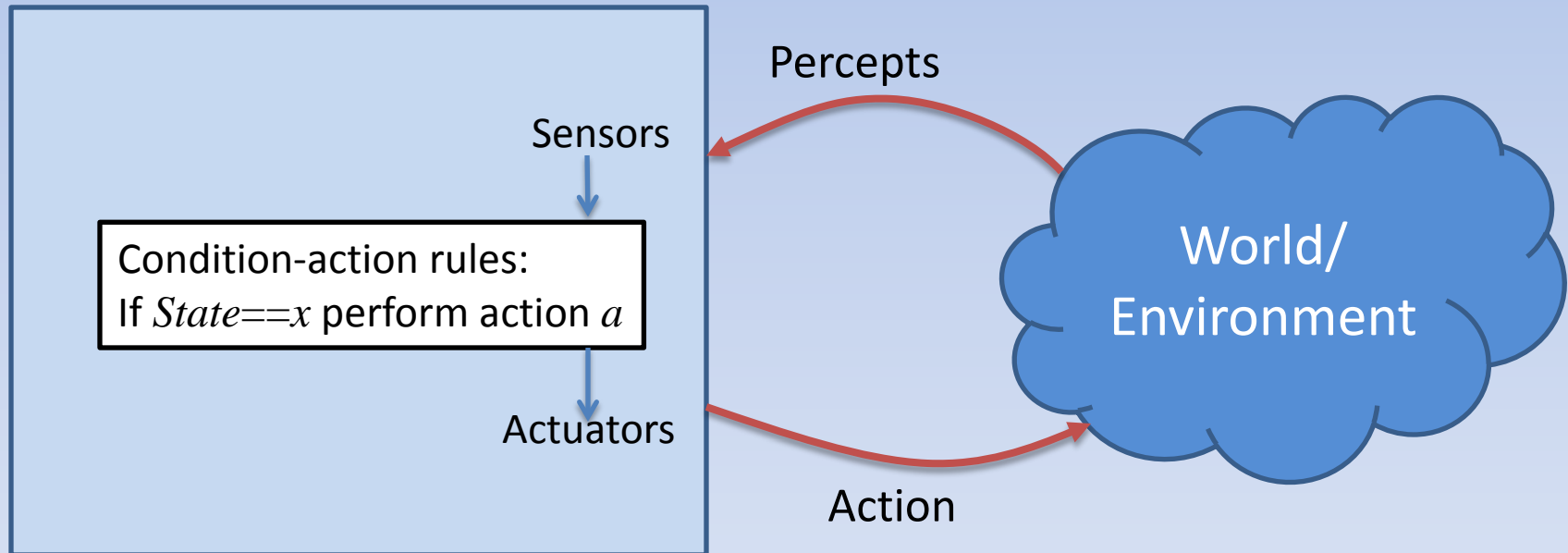
- Environment of chess-playing agent?
- Environment of autonomous vehicle agent?

Types of Agents

- Simple Reflex Agents
- Model-based Reflex Agents
- Goal-based Agents
- Utility-based Agents

Simple Reflex Agents

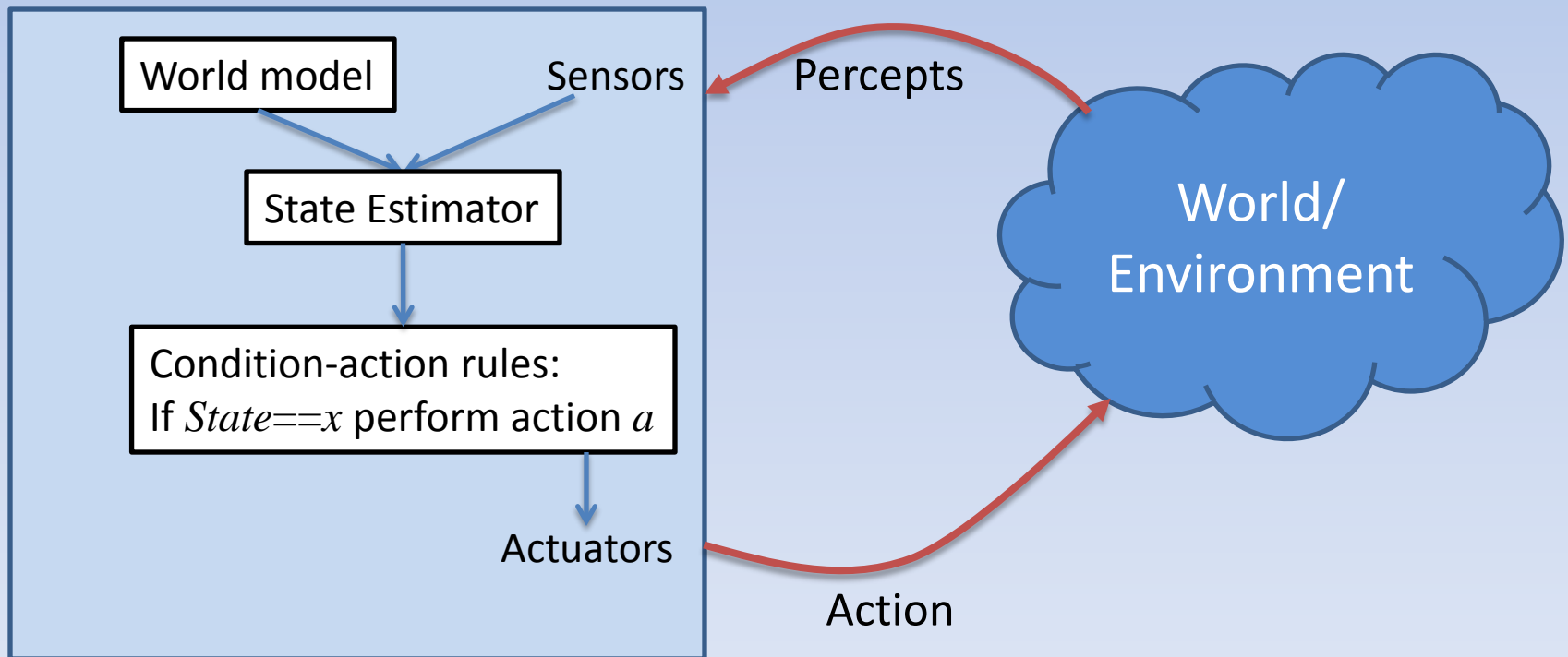
- Agent function maps current state directly to action



Would this work for the chess agent? For the vehicle agent?

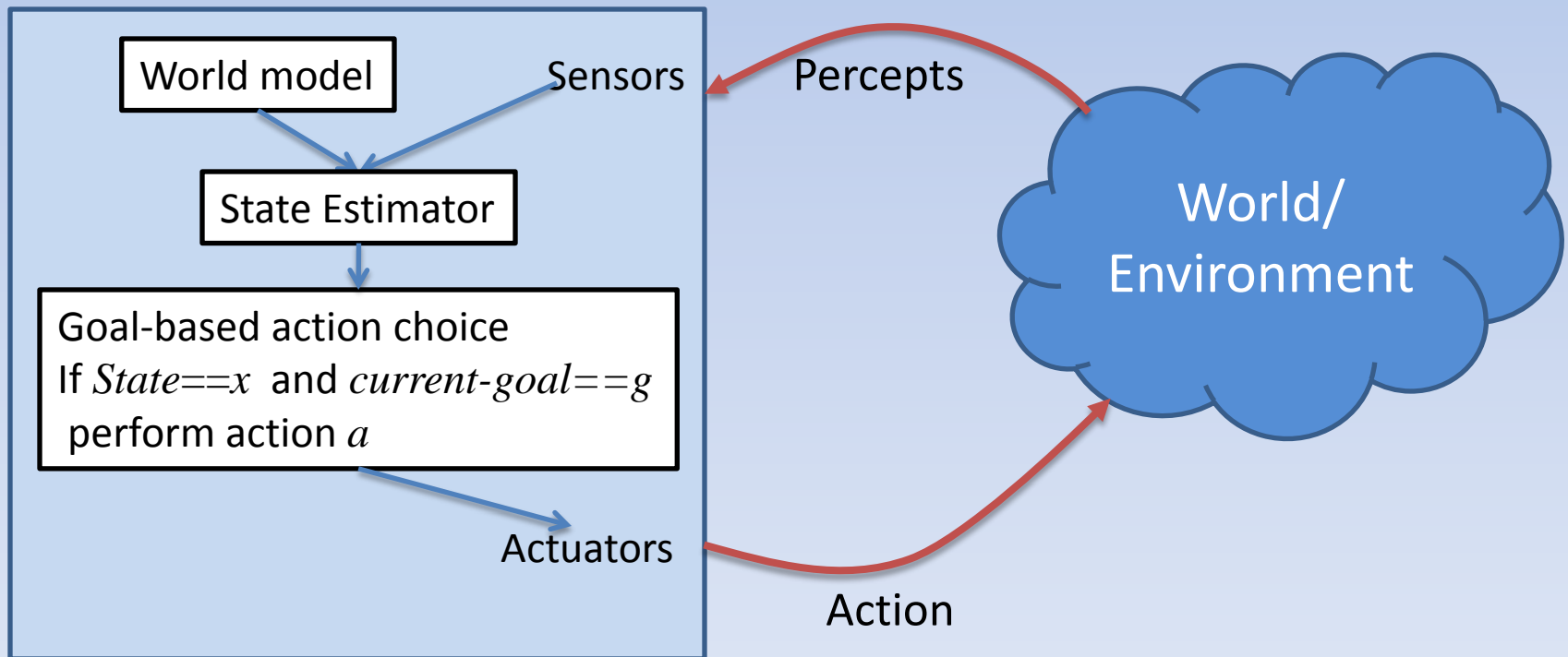
Model-based Reflex Agent

- Maps current percept and “*world model*” to action



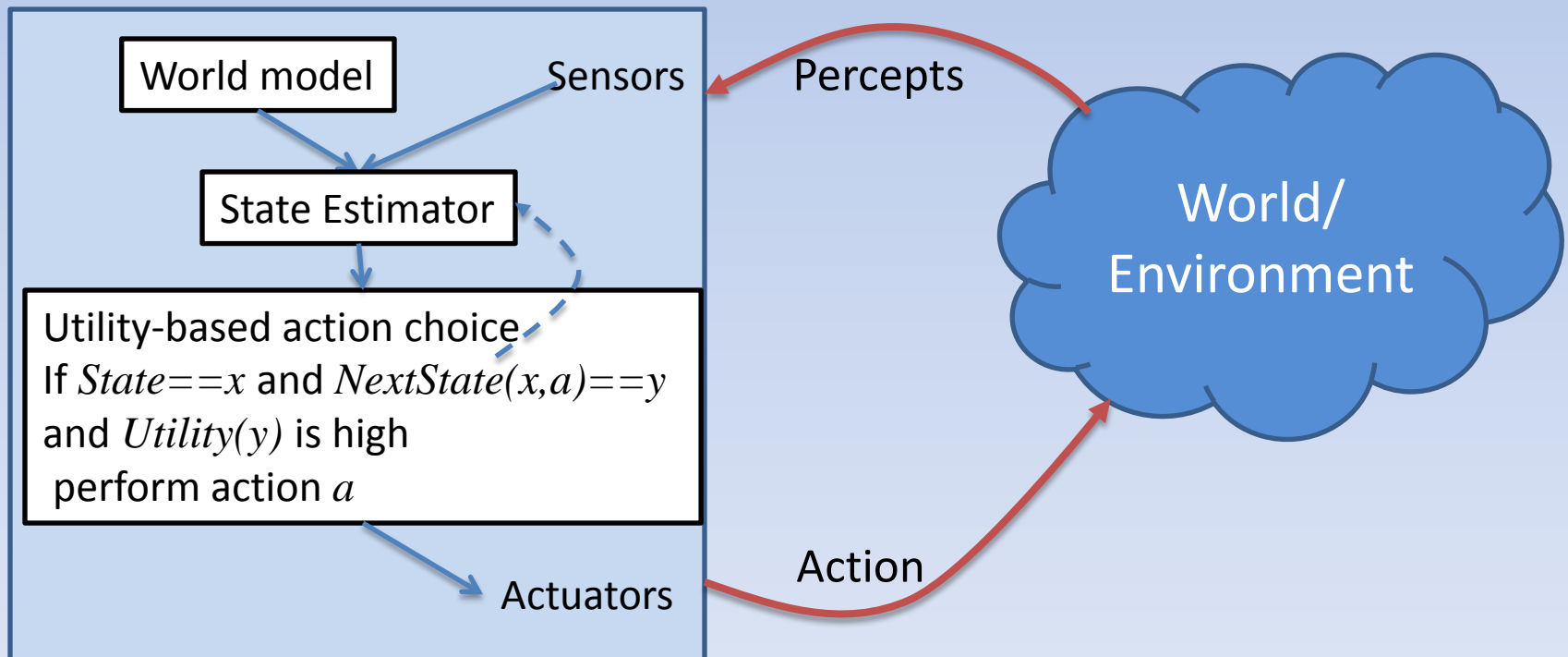
Goal-based Agent

- Maps current percept and knowledge of current goal to action



Utility-based Agent

- Instead of binary goal, an agent could have a fine-grained notion of how useful certain states are



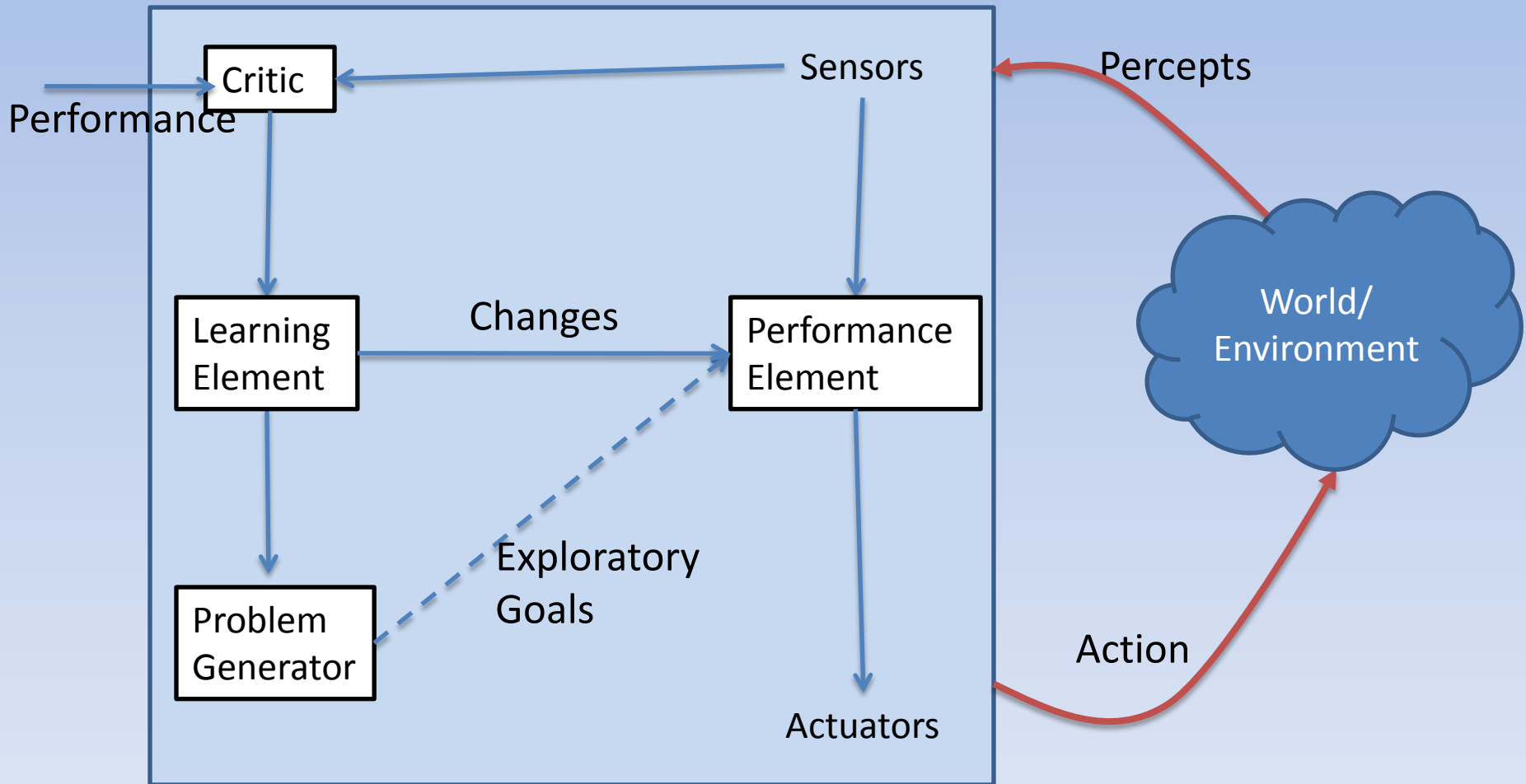
Learning Agents

- Who writes all these rules?
 - Or designs the agent function?
 - Could be quite complex!
- Could we have the agent *learn* the agent function on its own?
 - Would also help in unknown environments...

General Architecture

- Before, we had fixed rules (or functions)
 - We'll call this the “performance element”
- Now we need to add something that generates those functions, based on its (partial) knowledge of the environment and any feedback it receives
 - We'll call this the learning element

General Architecture



Summary

- We learned about:
 - Agent architecture
 - PEAS descriptions
 - Types of environments
 - Types of Agents