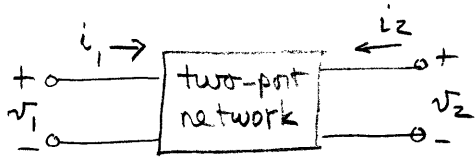
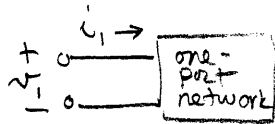


4.1 Basic Definitions



Consider writing the following voltage current relationships between voltage and current.

$$v_1 = z_{11} i_1 + z_{12} i_2$$

$$v_2 = z_{21} i_1 + z_{22} i_2$$

In matrix form

$$[V] = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} z_{11} & z_{12} \\ z_{21} & z_{22} \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \end{bmatrix} = [Z][I]$$

Note that each element in this matrix can be found by measuring the voltage v_i while port i is being driven by current i_i and all other currents are zero.

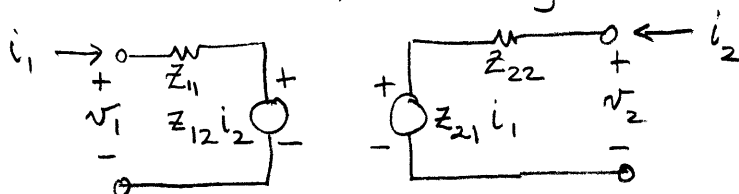
For example, let $i_2 = 0$, then the matrix equations reduce to

$$\begin{aligned} v_1 &= z_{11} i_1 \\ v_2 &= z_{21} i_1 \end{aligned} \quad \text{or} \quad \begin{aligned} z_{11} &= \frac{v_1}{i_1} \\ z_{21} &= \frac{v_2}{i_1} \end{aligned}$$

Similarly, if $i_1 = 0$

$$\begin{aligned} v_1 &= z_{12} i_2 \\ v_2 &= z_{22} i_2 \end{aligned} \quad \text{or} \quad \begin{aligned} z_{12} &= \frac{v_1}{i_2} \\ z_{22} &= \frac{v_2}{i_2} \end{aligned}$$

Z-parameters can be represented by the following equivalent circuit



Very commonly rf engineers use y-parameters instead of z-parameters,

Y parameters are defined by the following matrix equation

$$[I] = \begin{bmatrix} i_1 \\ i_2 \end{bmatrix} = \begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = [Y][V]$$

We can find the various y-parameters by shorting one of the outputs sequentially, i.e.

if $v_1 = 0$

$$i_1 = y_{12} v_2 \qquad y_{12} = \frac{i_1}{v_2}$$

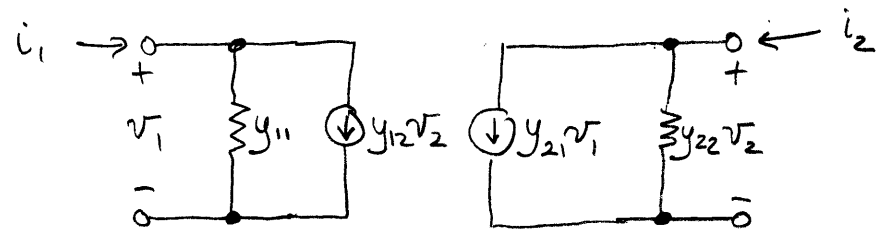
$$i_2 = y_{22} v_2 \qquad y_{22} = \frac{i_2}{v_2}$$

if $v_2 = 0$

$$i_1 = y_{11} v_1 \qquad y_{11} = \frac{i_1}{v_1}$$

$$i_2 = y_{21} v_1 \qquad y_{21} = \frac{i_2}{v_1}$$

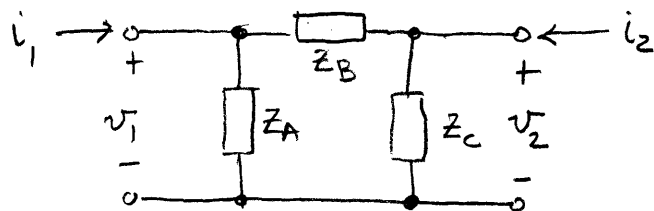
The y-parameters can be electrically modeled by the following equivalent circuit



NOTE: $[Z] = [Y]^{-1}$

Example: Z-parameters of Pi-network.

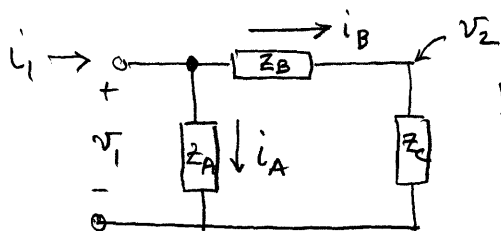
For the pi-network shown below with generic impedances Z_A , Z_B and Z_C find the impedance and admittance matrices.



to find Z_{ij} drive the input with i_1 and let the output open, i.e., $i_2 = 0$

$$\begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} Z_{11} & Z_{12} \\ Z_{21} & Z_{22} \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \end{bmatrix}$$

if $i_2 = 0$ $V_1 = Z_{11} i_1$ $\therefore Z_{11} = \frac{V_1}{i_1}$
 $V_2 = Z_{21} i_1$ $Z_{21} = \frac{V_2}{i_1}$



by inspection

$$V_2 = \frac{Z_C}{Z_B + Z_C} V_1$$

$$i_A = \frac{V_1}{Z_A}$$

$$i_B = \frac{V_1}{Z_B + Z_C}$$

$$Z_{11} = \frac{V_1}{i_1} = \frac{V_1}{\frac{V_1}{Z_A} + \frac{V_1}{Z_B + Z_C}} = \frac{(Z_B + Z_C)(Z_A)}{Z_A + Z_B + Z_C}$$

$$i_1 = i_A + i_B = \frac{V_1}{Z_A} + \frac{V_1}{Z_B + Z_C}$$

$$Z_{21} = \frac{V_2}{i_1} = \frac{\frac{Z_C}{Z_B + Z_C} V_1}{\frac{V_1}{Z_A} + \frac{V_1}{Z_B + Z_C}} = \frac{\frac{Z_C}{Z_B + Z_C}}{\frac{Z_B + Z_C + Z_A}{Z_A(Z_B + Z_C)}} = \frac{Z_A Z_C}{Z_B + Z_C + Z_A}$$

We get the remaining Z parameters by repeating the process for $i_1 = 0$.

if $i_1 = 0$ (input open)

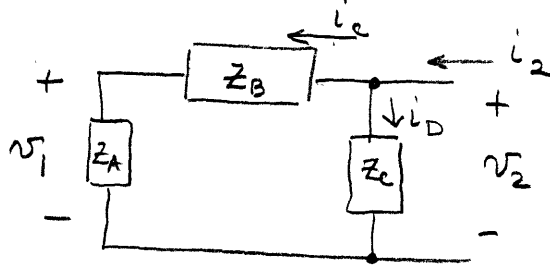
$$v_1 = z_{12} i_2 \quad \text{or}$$

$$z_{12} = \frac{v_1}{i_2}$$

$$v_2 = z_{22} i_2$$

$$z_{22} = \frac{v_2}{i_2}$$

For the given circuit



by inspection

$$v_1 = \frac{z_A}{z_A + z_B} v_2$$

$$i_C = \frac{v_2}{z_A + z_B}$$

$$i_D = \frac{v_2}{z_C}$$

$$i_2 = i_C + i_D$$

using these results in the above formulas gives

$$z_{12} = \frac{v_1}{i_2} = \frac{\frac{z_A}{z_A + z_B} v_2}{\frac{v_2}{z_A + z_B} + \frac{v_2}{z_C}} = \frac{\frac{z_A}{z_A + z_B}}{\frac{z_C + z_A + z_B}{(z_A + z_B) z_C}}$$

$$z_{12} = \frac{z_C z_A}{z_A + z_B + z_C}$$

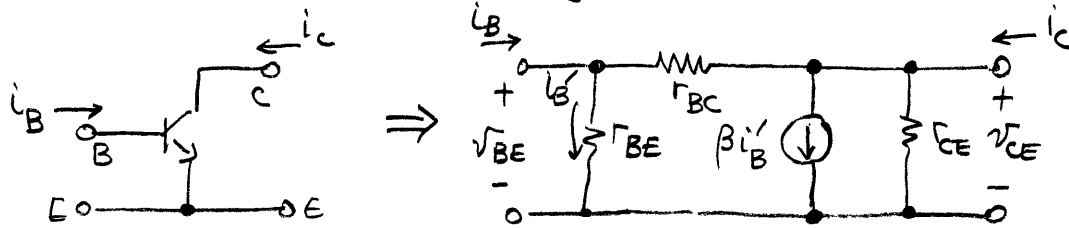
$$z_{22} = \frac{v_2}{i_2} = \frac{v_2}{\frac{v_2}{z_A + z_B} + \frac{v_2}{z_C}} = \frac{1}{\frac{1}{z_A + z_B} + \frac{1}{z_C}} = \frac{z_C (z_A + z_B)}{z_A + z_B + z_C}$$

$$z = \begin{bmatrix} \frac{z_A (z_B + z_C)}{z_A + z_B + z_C} & \frac{z_A z_C}{z_A + z_B + z_C} \\ \frac{z_A z_C}{z_A + z_B + z_C} & \frac{z_C (z_A + z_B)}{z_A + z_B + z_C} \end{bmatrix}$$

You can find the Y parameters the same way.

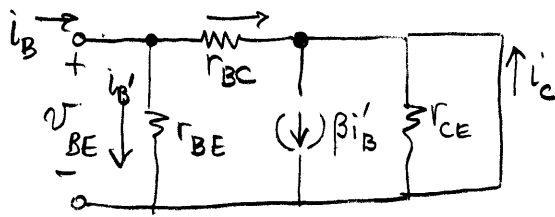
Example 4.2

Describe the common-emitter BJT transistor in terms of its h (hybrid) parameters for the low-frequency, small signal model shown below.



$$\begin{bmatrix} v_1 \\ i_2 \end{bmatrix} = \begin{bmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{bmatrix} \begin{bmatrix} i_1 \\ v_2 \end{bmatrix}$$

① to evaluate h_{11} short the output, i.e. $v_2 = v_{CE} = 0$



$$i_{R_{BE}} = \frac{v_{BE}}{r_{BE}}$$

$$i_{R_{BC}} = \frac{v_{BE}}{r_{BC}} \quad (\text{since } v_{CE} = 0)$$

$$i_B = \frac{v_{BE}}{r_{BE}} + \frac{v_{BE}}{r_{BC}} = v_{BE} \frac{r_{BE} + r_{BC}}{r_{BE} r_{BC}}$$

$$i_C = -i_{R_{BC}} + \beta i'_B = -\frac{v_{BE}}{r_{BC}} + \beta \frac{v_{BE}}{r_{BE}}$$

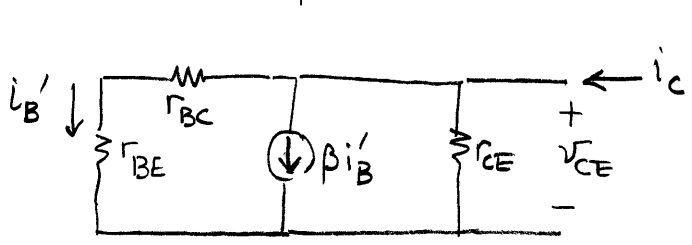
from matrix if $v_2 = 0$

$$v_1 = h_{11} i_1 \Rightarrow h_{11} = \frac{v_1}{i_1} = \frac{v_{BE}}{i_B}$$

$$i_2 = h_{21} i_1 \Rightarrow h_{21} = \frac{i_2}{i_1} = \frac{i_C}{i_B}$$

$$h_{11} = \frac{v_{BE}}{i_B} = \frac{v_{BE}}{v_{BE} \left(\frac{r_{BE} + r_{BC}}{r_{BE} r_{BC}} \right)} = \frac{r_{BE} r_{BC}}{r_{BE} + r_{BC}}$$

$$h_{21} = \frac{i_C}{i_B} = \frac{v_{BE} \left(\frac{-r_{BE} + \beta r_{BC}}{r_{BC} r_{BE}} \right)}{v_{BE} \left(\frac{r_{BE} + r_{BC}}{r_{BE} r_{BC}} \right)} = \frac{-r_{BE} + \beta r_{BC}}{r_{BE} + r_{BC}} = \frac{\beta r_{BC} - r_{BE}}{r_{BE} + r_{BC}}$$



$$i'_B = \frac{v_{CE}}{r_{BC} + r_{BE}}$$

$$i_{R_{CE}} = \frac{v_{CE}}{r_{CE}}$$

$$\beta i'_B = \beta \frac{v_{CE}}{r_{BC} + r_{BE}}$$

$$i_c = \frac{v_{CE}}{r_{BC} + r_{BE}} + \beta \frac{v_{CE}}{r_{BC} + r_{BE}} + \frac{v_{CE}}{r_{CE}}$$

$$v_{BE} = \frac{r_{BE}}{r_{BE} + r_{BC}} v_{CE}$$

from matrix if $i_1 = i_B = 0$

$$v_1 = h_{12} v_2 \quad h_{12} = \frac{v_1}{v_2}$$

$$i_2 = h_{22} v_2 \quad h_{22} = \frac{i_2}{v_2}$$

$$h_{12} = \frac{v_1}{v_2} = \frac{\frac{r_{BE}}{r_{BE} + r_{BC}} v_{CE}}{v_{CE}} = \frac{r_{BE}}{r_{BE} + r_{BC}}$$

$$h_{22} = \frac{i_2}{v_2} = \frac{(1 + \beta) \frac{v_{CE}}{r_{BC} + r_{BE}} + \frac{v_{CE}}{r_{CE}}}{v_{CE}} = \frac{(1 + \beta)}{r_{BC} + r_{BE}} + \frac{1}{r_{CE}}$$

$$h_{22} = \frac{(1 + \beta) r_{CE} + r_{BC} + r_{BE}}{r_{CE} (r_{BC} + r_{BE})}$$

$$[h] = \begin{bmatrix} \frac{r_{BE} r_{BC}}{r_{BE} + r_{BC}} & \frac{r_{BE}}{r_{BE} + r_{BC}} \\ \frac{\beta r_{BC} - r_{BE}}{r_{BE} + r_{BC}} & \frac{(\beta + 1)}{r_{BC} + r_{BE}} + \frac{1}{r_{CE}} \end{bmatrix} \approx \begin{bmatrix} r_{BE} & 0 \\ \beta & \frac{1}{r_{CE}} + \frac{\beta}{r_{BC}} \end{bmatrix}$$

for real transistors $\beta \gg 1$, $r_{BC} \gg r_{BE}$

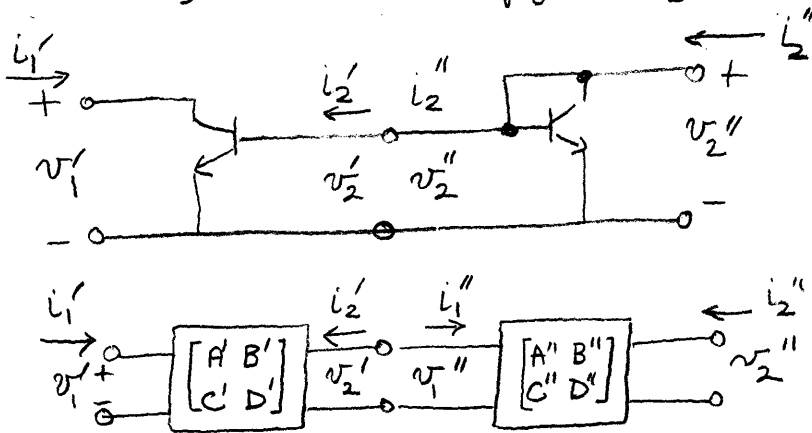
The hybrid network representation is a very popular way to characterize the BJT, and h-parameter coefficients are reported in many data sheets.

Define the chain or ABCD parameters as



$$\begin{bmatrix} v_1 \\ i_1 \end{bmatrix} = \begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{bmatrix} v_2 \\ -i_2 \end{bmatrix}$$

Cascading networks analyzed using ABCD matrices



For the first network

$$\begin{bmatrix} v_1' \\ i_1' \end{bmatrix} = \begin{bmatrix} A' & B' \\ C' & D' \end{bmatrix} \begin{bmatrix} v_2' \\ -i_2' \end{bmatrix}$$

For the second network

$$\begin{bmatrix} v_1'' \\ i_1'' \end{bmatrix} = \begin{bmatrix} A'' & B'' \\ C'' & D'' \end{bmatrix} \begin{bmatrix} v_2'' \\ -i_2'' \end{bmatrix}$$

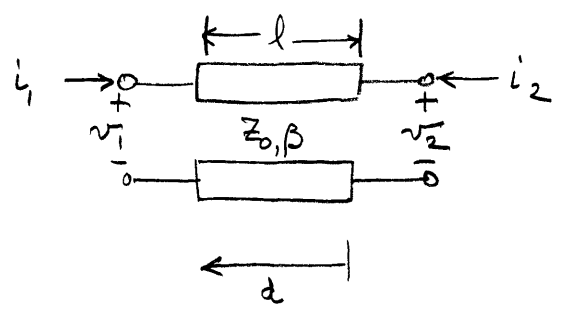
The key thing about cascading networks is that $i_1'' = -i_2'$
and $v_1'' = v_2'$

Then

$$\begin{bmatrix} v_1' \\ i_1' \end{bmatrix} = \begin{bmatrix} A' & B' \\ C' & D' \end{bmatrix} \begin{bmatrix} v_2' \\ -i_2' \end{bmatrix} = \begin{bmatrix} A' & B' \\ C' & D' \end{bmatrix} \begin{bmatrix} v_1'' \\ i_1'' \end{bmatrix}$$

$$\begin{bmatrix} v_1' \\ i_1' \end{bmatrix} = \begin{bmatrix} A' & B' \\ C' & D' \end{bmatrix} \begin{bmatrix} A'' & B'' \\ C'' & D'' \end{bmatrix} \begin{bmatrix} v_1'' \\ i_1'' \end{bmatrix}$$

Example 4-6 ABCD-matrix coefficient representation of a transmission line section.



$$\begin{bmatrix} v_1 \\ i_1 \end{bmatrix} = \begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{bmatrix} v_2 \\ -i_2 \end{bmatrix}$$

If we short port 2, i.e. $v_2 = 0$ (a shorted line)

$$v_1 = -B i_2 \quad B = -\frac{v_1}{i_2}$$

$$i_1 = -D i_2 \quad D = -\frac{i_1}{i_2}$$

If we open port 2, i.e., $i_2 = 0$ (an open line)

$$v_1 = A v_2 \quad A = \frac{v_1}{v_2}$$

$$i_1 = C v_2 \quad C = \frac{i_1}{v_2}$$

For an open-line $V(d) = 2V^+ \cos(\beta d)$

$I(d) = \frac{2jV^+}{Z_0} \sin(\beta d)$ current defined as towards load

For a short line $V(d) = 2jV^+ \sin(\beta d)$

$I(d) = \frac{2V^+}{Z_0} \cos(\beta d)$ current defined as towards load.

Using these results for a transmission line:

$$A = \left. \frac{v_1}{v_2} \right|_{i_2=0} = \frac{2V^+ \cos(\beta l) \Big|_{d=l}}{2V^+ \cos(\beta \cdot 0) \Big|_{d=0}} = \cos \beta l$$

$$B = -\left. \frac{v_1}{i_2} \right|_{v_2=0} = -\frac{2jV^+ \sin(\beta l) \Big|_{d=l}}{\frac{2V^+}{Z_0} \cos(\beta \cdot 0) \Big|_{d=0}} = -jZ_0 \sin(\beta l)$$

$$C = \left. \frac{I_1}{V_2} \right|_{I_2=0} = \frac{2j \frac{V^+}{Z_0} \sin(\beta l)}{2V^+ \cos(\beta \cdot 0)} = jY_0 \sin(\beta l)$$

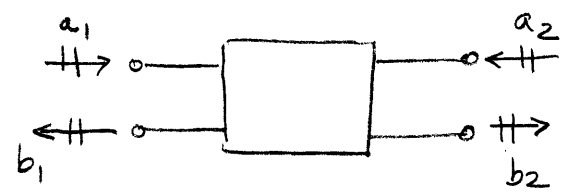
$$D = - \left. \frac{I_1}{I_2} \right|_{V_2=0} = - \frac{2 \frac{V^+}{Z_0} \cos(\beta l)}{2 \frac{V^+}{Z_0} \cos(\beta \cdot 0)} = - \cos(\beta l)$$

∴ For a transmission line

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} \cos \beta l & jZ_0 \sin \beta l \\ jY_0 \sin \beta l & - \cos \beta l \end{bmatrix}$$

4.4 Scattering parameters

Almost all microwave engineers use S-parameters (scattering parameters) at microwave frequencies because it is very difficult to achieve a true open or short at r.f./microwave frequencies. Furthermore, you do not want to introduce large reflection coefficients which can lead to oscillations and/or destroy a semiconductor device.



define a NORMALIZED incident power wave

$$a_1 = \frac{1}{2\sqrt{Z_0}} (V_1 + Z_0 I_1) \quad \text{where } I_1, V_1 \text{ are at the input}$$

$$a_2 = \frac{1}{2\sqrt{Z_0}} (V_2 + Z_0 I_2) \quad \text{where } I_2, V_2 \text{ are at the output}$$

and a reflected normalized power

$$b_1 = \frac{1}{2\sqrt{Z_0}} (V_1 - Z_0 I_1)$$

$$b_2 = \frac{1}{2\sqrt{Z_0}} (V_2 - Z_0 I_2)$$

If we solve these equations for V and I we get

$$V_1 = \sqrt{Z_0} (a_1 + b_1) \quad (1)$$

$$V_2 = \sqrt{Z_0} (a_2 + b_2) \quad (2)$$

$$I_1 = \frac{1}{\sqrt{Z_0}} (a_1 - b_1) \quad (3)$$

$$I_2 = \frac{1}{\sqrt{Z_0}} (a_2 - b_2) \quad (4)$$

These look like strange definitions but consider these in terms of traveling waves and power

If you simply examine (1) & (3) a_1 is simply the forward traveling wave and b_1 is the backward traveling wave.

$$a_1 = \frac{V_1^+}{\sqrt{Z_0}} = \sqrt{Z_0} I_1^+$$

$$b_1 = \frac{V_1^-}{\sqrt{Z_0}} = -\sqrt{Z_0} I_1^-$$

Note that $V^+ = I_1^* Z_0$ and $V_1^- = -Z_0 I_1^-$

$$a_2 = \frac{V_2^+}{\sqrt{Z_0}} = \sqrt{Z_0} I_2^+$$

$$b_2 = \frac{V_2^-}{\sqrt{Z_0}} = -\sqrt{Z_0} I_2^-$$

The S-parameters are closely related to power.

$$\begin{bmatrix} b_1 \\ b_2 \end{bmatrix} = \begin{bmatrix} S_{11} & S_{12} \\ S_{21} & S_{22} \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} \begin{array}{l} \leftarrow \text{incident \& reflected at port \#1} \\ \leftarrow \text{incident \& reflected at port \#2} \end{array}$$

$$S_{11} = \left. \frac{b_1}{a_1} \right|_{a_2=0} = \frac{\text{reflected power wave at port \#1}}{\text{incident power wave at port \#1}} \left| \begin{array}{l} \text{no input power} \\ \text{at port \#2} \end{array} \right.$$

$$S_{12} = \left. \frac{b_1}{a_2} \right|_{a_1=0} = \frac{\text{transmitted power wave at port \#1}}{\text{incident power wave at port \#2}} \left| \begin{array}{l} \text{no input power} \\ \text{at port \#1} \end{array} \right.$$

$$S_{21} = \left. \frac{b_2}{a_1} \right|_{a_2=0} = \frac{\text{transmitted power wave at port \#2}}{\text{incident power wave at port \#1}} \left| \begin{array}{l} \text{no input power} \\ \text{at port \#2} \end{array} \right.$$

$$S_{22} = \left. \frac{b_2}{a_2} \right|_{a_1=0} = \frac{\text{reflected power wave at port \#2}}{\text{incident power wave at port \#1}} \left| \begin{array}{l} \text{no input power} \\ \text{at port \#1} \end{array} \right.$$

these conditions
are true when input (a_1)
or output (a_2) are
matched to port impedance.

Recall that $P_{AV} = \frac{1}{2} \operatorname{Re} \{V I^*\}$

At the input port

$$P_1 = \frac{1}{2} \operatorname{Re} \{V_1 I_1^*\} = \frac{1}{2} \operatorname{Re} \left\{ V^+ (1 + \Gamma_{in}) \frac{V^+}{Z_0} (1 - \Gamma_{in}) \right\}$$

$$P_1 = \frac{1}{2} \frac{|V^+|^2}{Z_0} (1 - |\Gamma_{in}|^2) = P_1^+ + P_1^-$$

using our definitions that

$$V_1 = \sqrt{Z_0} (a_1 + b_1)$$

$$I_1 = \frac{1}{\sqrt{Z_0}} (a_1 - b_1)$$

we can also compute the power at port #1 as

$$P_1 = \frac{1}{2} \operatorname{Re} \{V_1 I_1^*\} = \frac{1}{2} \operatorname{Re} \left\{ \sqrt{Z_0} (a_1 + b_1) \frac{1}{\sqrt{Z_0}} (a_1^* - b_1^*) \right\}$$

$$P_1 = \frac{1}{2} \operatorname{Re} \{ |a_1|^2 - |b_1|^2 \} = \frac{1}{2} \{ |a_1|^2 - |b_1|^2 \} = \frac{1}{2} |a_1|^2 \left\{ 1 - \frac{|b_1|^2}{|a_1|^2} \right\}$$

but $a_1 = \frac{V_1^+}{\sqrt{Z_0}}$ so we can re-write this equation as

$$P_1 = \frac{1}{2} \frac{|V_1^+|^2}{Z_0} \left\{ 1 - \frac{|b_1|^2}{|a_1|^2} \right\} = \frac{1}{2} \frac{|V_1^+|^2}{Z_0} \left\{ 1 - |S_{11}|^2 \right\}$$

Comparing these two expressions for P_1 we quickly see that

$$\Gamma_{in} = \frac{V_1^-}{V_1^+} = \left. \frac{b_1}{a_1} \right|_{a_2=0} = S_{11}$$

This allows us to write the SWR at port #1 as

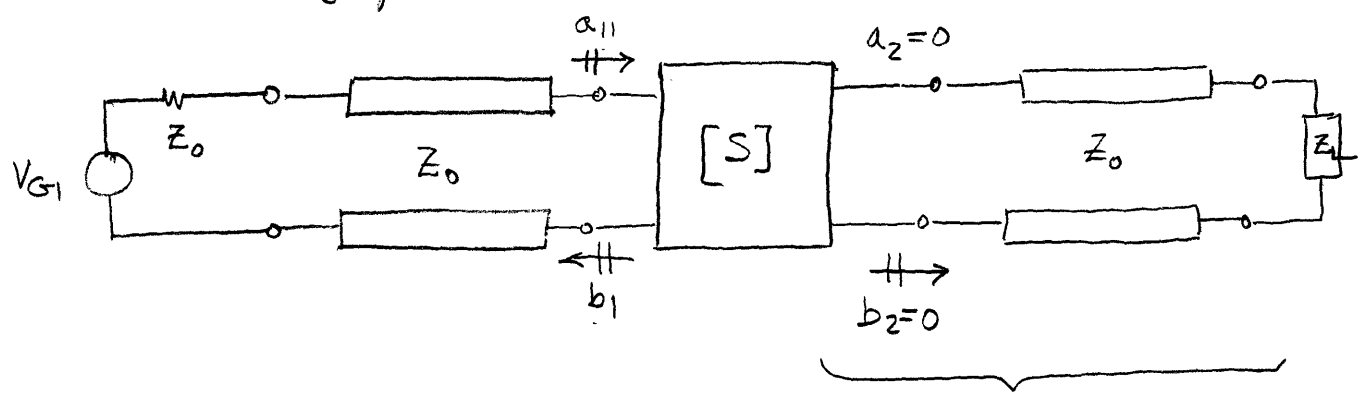
$$S = \frac{1 + |S_{11}|}{1 - |S_{11}|}$$

Note also that $\frac{1}{2} |a_1|^2 = \frac{1}{2} \frac{|V_1^+|^2}{Z_0} = P_{\text{incident}}$

You can do the same analysis at the output to get at port #2

$$P_2 = \frac{1}{2} \{ |a_2|^2 - |b_2|^2 \} = \frac{|a_2|^2}{2} (1 - |\Gamma_{out}|^2)$$

4.4.2. Meaning of s-parameters



the output Z_L is matched to Z_0 so that no V_2^+ is created at the output.

under the about output matched conditions $a_2 = 0$.

Since $S_{11} = \Gamma_{in} = \frac{Z_{in} - Z_0}{Z_{in} + Z_0}$ since $S_{11} = \left. \frac{b_1}{a_1} \right|_{b_2=0}$

we have just developed a method for measuring S_{11}

also since $a_2 = 0$

$$S_{21} = \left. \frac{b_2}{a_1} \right|_{b_2=0} = \frac{\frac{V_2^-}{\sqrt{Z_0}}}{\frac{1}{2\sqrt{Z_0}} (V_1 + Z_0 I_1)} \Big|_{I_2^+ = V_2^+ = 0}$$

Note that V_2^+, I_2^+ are going into the output just like a two-port

substituting $V_1 = V_{G1} - Z_0 I_1$

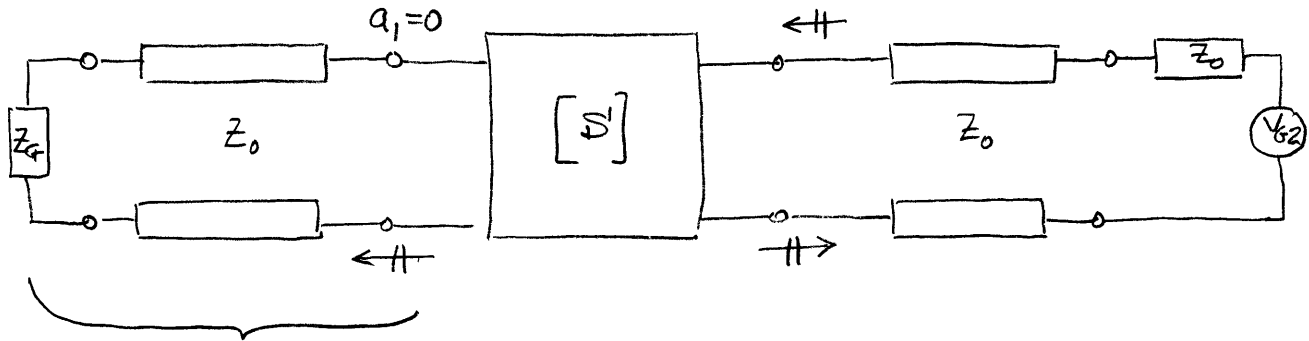
$$S_{21} = \frac{2V_2'}{V_{G1} - Z_0 I_1 + Z_0 I_1} = \frac{2V_2'}{V_{G1}} = \frac{2V_2}{V_{G1}}$$

This is the forward voltage gain G of the network

$$G_0 = |S_{21}|^2 = \left| \frac{V_2}{V_{G1/2}} \right|^2$$

is the forward power gain

You can measure S_{22} and S_{12} by matching at port #1 and using a generator at port #2.



line is matched to the impedance Z_0 to make sure no V_1^- is created at the load

The results at the output are identical to the input

$$S_{22} = \Gamma_{out} = \frac{Z_{out} - Z_0}{Z_{out} + Z_0} \quad \text{since } S_{22} = \left. \frac{b_2}{a_2} \right|_{a_1=0}$$

Since $a_1 = 0$

$$S_{12} = \left. \frac{b_1}{a_2} \right|_{a_1=0} = \frac{\frac{V_1^-}{\sqrt{Z_0}}}{\frac{1}{2\sqrt{Z_0}} (V_2 + Z_0 I_2)} \Bigg|_{I_1^+ = V_1^+ = 0}$$

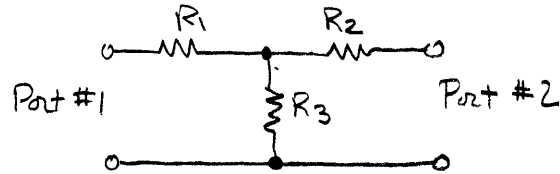
Note again that I_1^+, V_1^+ are going into the input just like a two-port

canceling terms and substituting $V_2 = V_{G2} - Z_0 I_2$.

$$S_{12} = \frac{2V_1^-}{V_{G2} - Z_0 I_2 + Z_0 I_2} = \frac{2V_1^-}{V_{G1}} = \frac{2V_1}{V_{G1}}$$

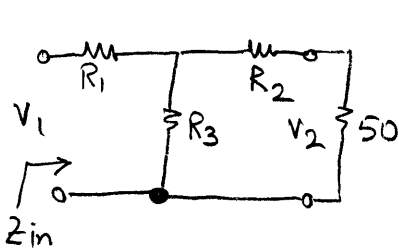
This is the reverse voltage gain.

Example 4-7 Find the s-parameters and the resistive elements for the 3dB attenuator network shown below assuming that the network is placed in a transmission line section with a characteristic line impedance of $Z_0 = 50\Omega$



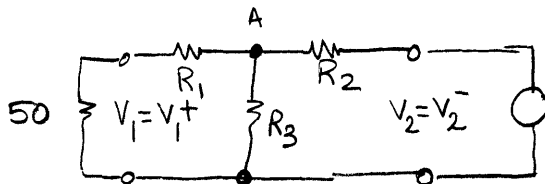
The attenuator must be matched to the line impedance Z_0

For a terminated output ($Z = 50\Omega$) we have



$$Z_{in} = R_1 + \frac{R_3(R_2 + 50)}{R_3 + R_2 + 50} = 50$$

For the terminated input ($Z = 50\Omega$) we have the same circuit



if matched
no reflection

For the voltage relationship we have the output voltage given by

$$V_2 = \frac{R_3 \parallel (R_2 + 50)}{R_3 \parallel (R_2 + 50) + R_2} \cdot \frac{50}{R_1 + 50} V_1$$

voltage at A

voltage at 50Ω
input termination

For 3 db attenuation (no input power at port #2)

$$S_{21} = \frac{V_2}{V_1} \Big|_{I_2^+ = V_2^+ = 0} = \frac{1}{\sqrt{2}} = \frac{2V_2}{V_{G1}}$$

This is where we bring in the s-parameters.

This gives two equations.

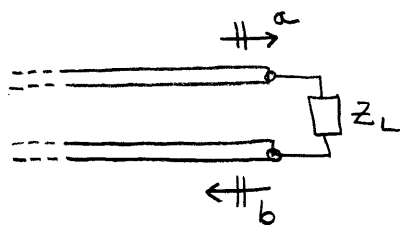
Since we want the network to be symmetric $R_1 = R_2$,
leaving two equations in two unknowns.

These can be solved to give

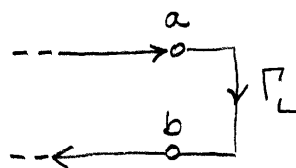
$$R_1 = R_2 = \frac{\sqrt{2}-1}{\sqrt{2}+1} Z_0 = 8.58 \Omega$$

$$R_3 = 2\sqrt{2} Z_0 = 141.4 \Omega.$$

4.4.5. Signal Flow Chart Modeling



conventional transmission line representation



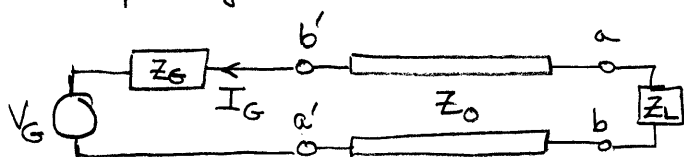
equivalent signal flow representation

$\begin{matrix} a \\ \circ \end{matrix} \xrightarrow{\quad}$
 source node a which launches a wave

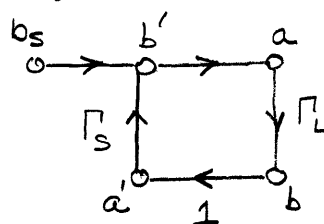
$\xrightarrow{\quad} \begin{matrix} b \\ \circ \end{matrix}$
 sink node b which receives a wave

$\begin{matrix} a & \Gamma & b \\ \circ & \xrightarrow{\quad} & \circ \end{matrix}$
 branch which connects source and sink $b = \Gamma a$

Simple system



signal generator



Note: Don't interpret variables as static voltages but waves propagating either $L \rightarrow R$ or $R \rightarrow L$

equivalent signal flow chart

by inspection

$$b' = b_s + a' \Gamma_s$$

$$\text{giving the source as } b_s = b' - a' \Gamma_s'$$

We can compare this with the wave based equivalent representation.

$$\underbrace{V_s^+ + V_s^-}_{\text{at input of line}} = \underbrace{V_G}_{\text{generator}} + \underbrace{Z_G \left[\frac{V_s^+}{Z_0} - \frac{V_s^-}{Z_0} \right]}_{\text{voltage drop across } Z_G}$$

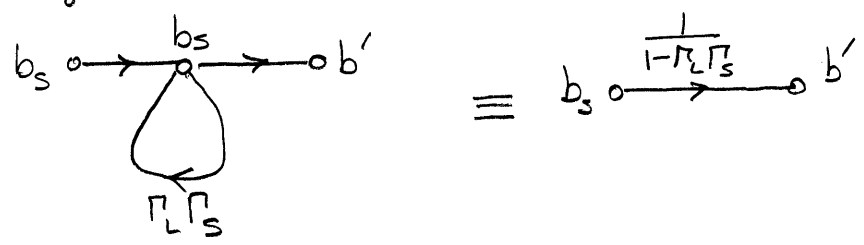
Note that $a' = \Gamma_L b'$

so that $b' = b_s + a' \Gamma_s = b_s + \Gamma_L \Gamma_s b'$

$$\therefore b'(1 - \Gamma_L \Gamma_s) = b_s$$

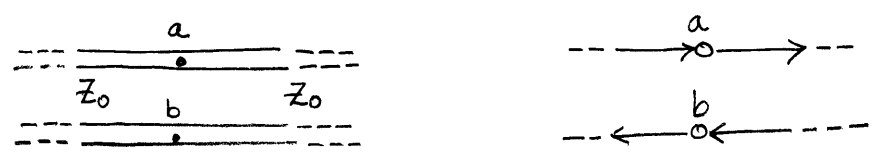
$$b' = \frac{b_s}{1 - \Gamma_L \Gamma_s}$$

In signal flowchart terms this can be reduced to a single branch



Basic signal flowchart elements

node assignment



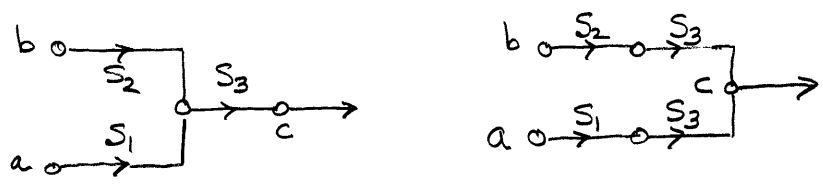
branch



series connection



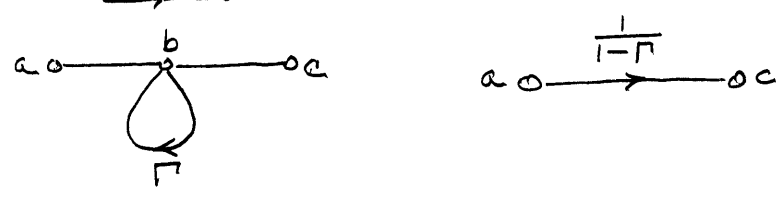
splitting of branches



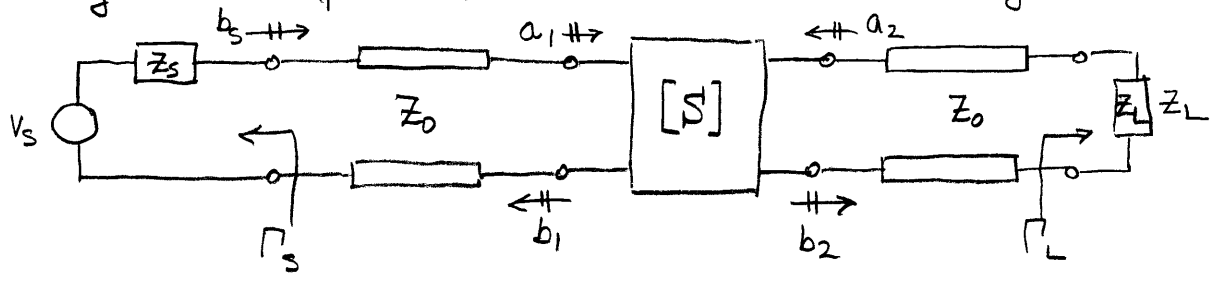
parallel connection



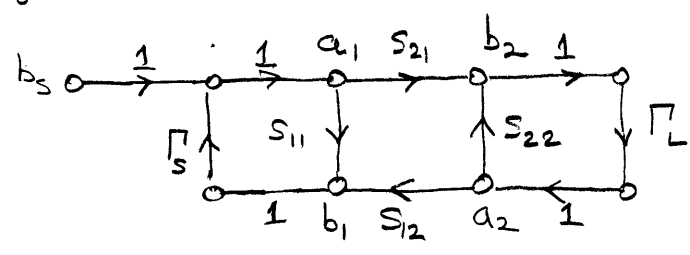
self-loop



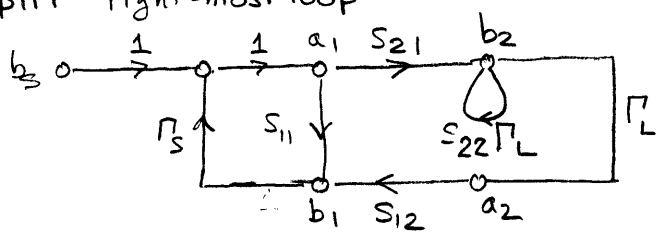
Example 4-8 For the network shown below find the ratio of a_1/b_s . Assume unity for the multiplication factor of the transmission line segments.



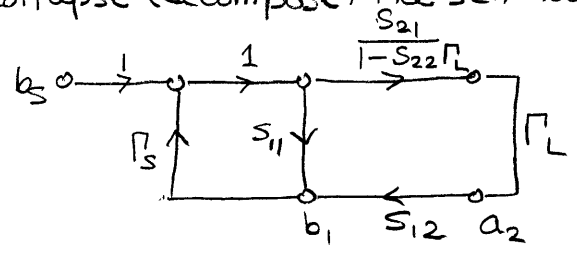
Initial signal flow chart



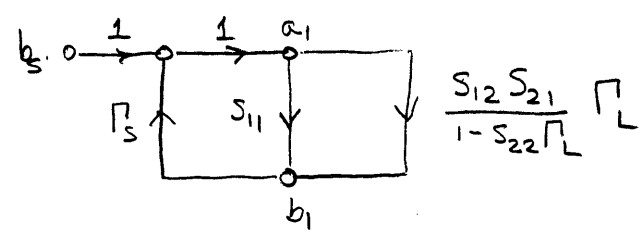
step 1: split right-most loop



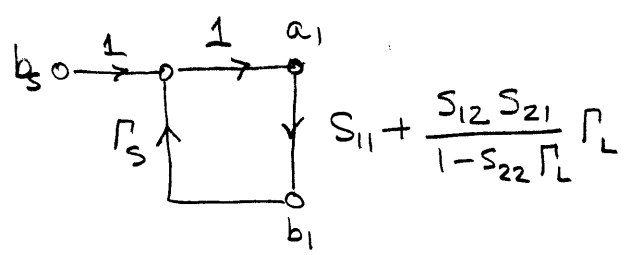
step 2: collapse (decompose) the self-loop between b_2 and a_2



step 3:

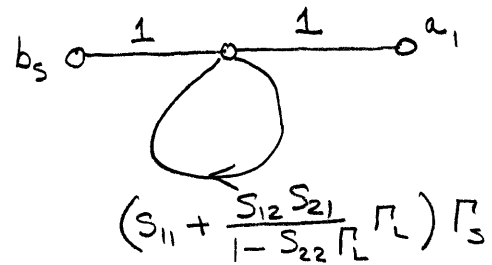


then combine series elements

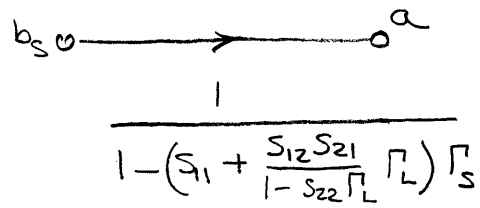


and parallel elements

step 4: split loop into a self-loop



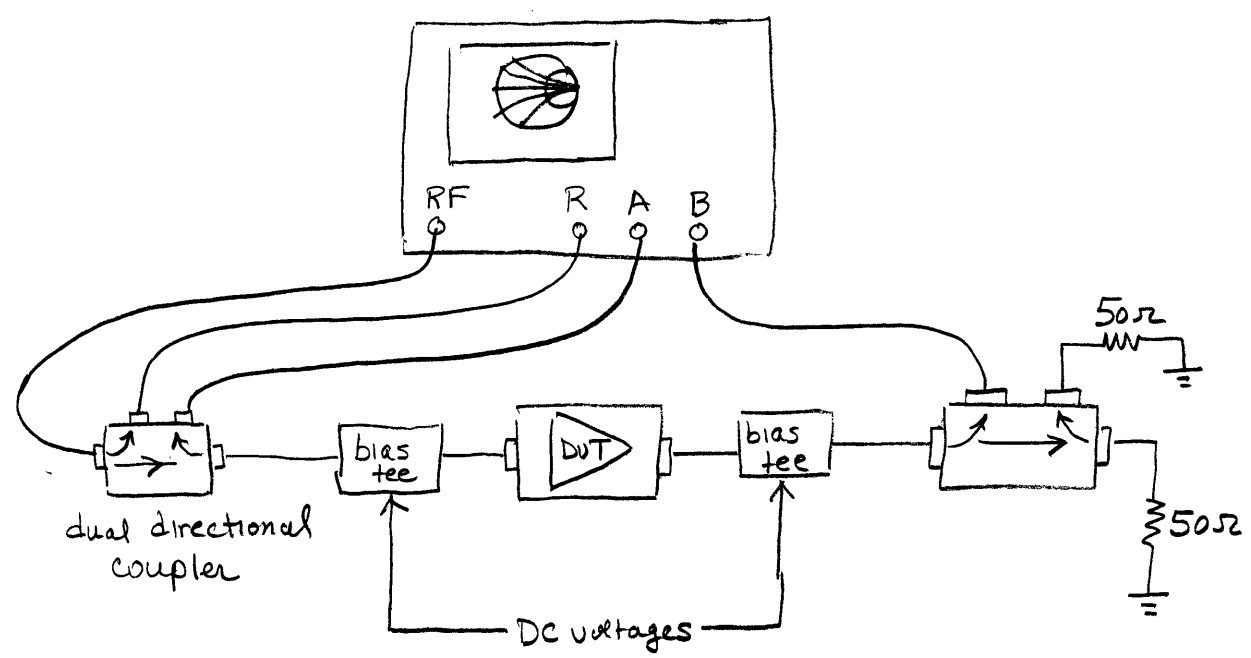
step 5: decompose the self-loop



$$a_1 = \frac{1}{1 - \left(s_{11} + \frac{s_{12}s_{21}}{1-s_{22}\Gamma_L} \right) \Gamma_S} \cdot b_s$$

$$\frac{a_1}{b_s} = \frac{1 - s_{22}\Gamma_L}{1 - (s_{11}\Gamma_S + s_{22}\Gamma_L + s_{12}s_{21}\Gamma_S) + s_{11}s_{22}\Gamma_S\Gamma_L}$$

4.4.7. Practical Measurement of S-parameters.

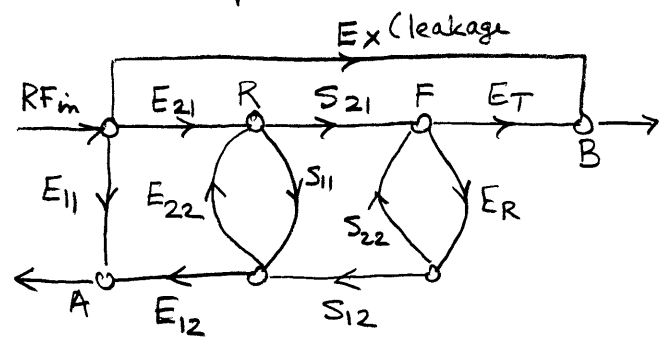
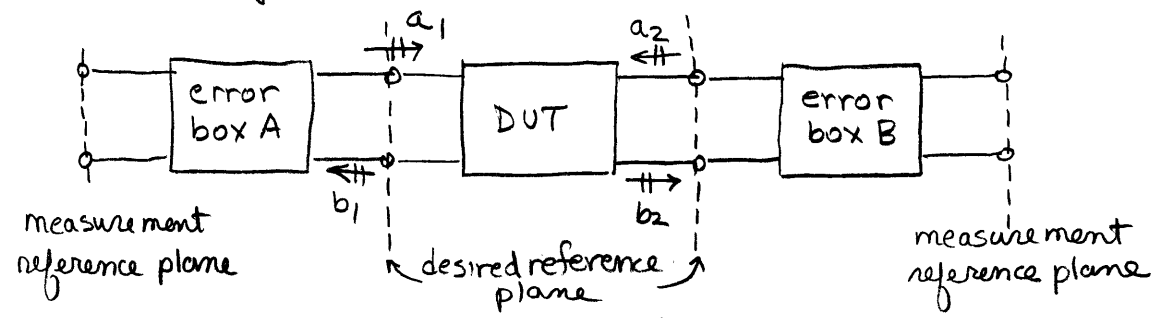


Basic concept is relatively simple. The ratio A/R gives S_{11} ; S_{21} comes from B/R .

You can measure S_{12} and S_{22} by reversing the DUT.

Real system is much more complex because of cable lengths, impedances, non-ideal external components, etc.

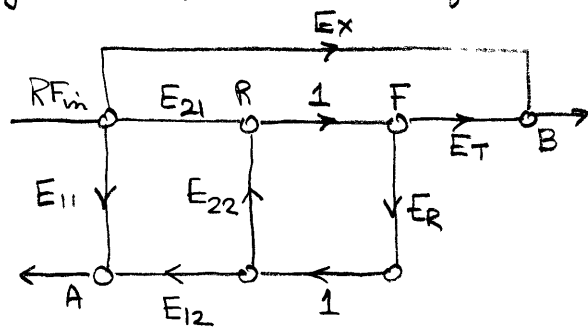
Practical system for measurement



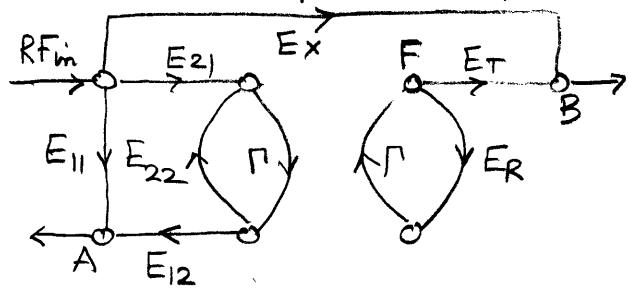
A lot of research involves using a computer and three known loads (open, short, and matched) to estimate $E_{11}, E_{12}, E_{22}, E_x, E_R$ and E_T .

Another popular method is the Through-Reflect-Line (TRL) method.

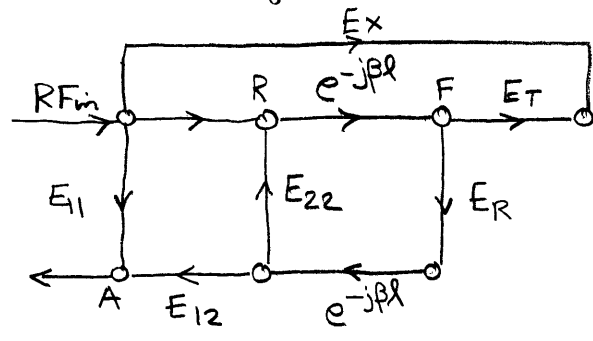
Through: directly connect ports 1 and 2 of the DUT
(a through short, not an end short)



Reflect: use a load with high reflectivity and the same reflection coefficient for both input and output ports of the DUT.



Through: Connect ports 1 and 2 by a transmission line matched to the impedance of the error boxes.
(matched short)



See: G.F. Engen & C.A. Hoer, "Thru-Reflect-Line: An Improved Technique for Calibrating the Dual Six-Port Automatic Network Analyzer," IEEE Trans. Microwave Theory and Techniques, Vol. MTT-27, pp. 987-998, 1979.