## STACK

A stack is a first in, last out buffer usually implemented as a block of n consecutive bytes (it doesn't have to be bytes-it could be words or long words). In the example below, the stack is composed of words.


On the 68000 stack addresses begin in high memory ( $\$ 60000$ for example) and are pushed toward low memory ( $\$ 50000$ for example). Other machines might do this in the reverse order.

A stack can be implemented as bytes or longwords. The normal 68000 stack pointer is in A7 (Don't use this register for anything else!!!). If you want to use a special stack which is byte or long word in width you will need to use another register; A7 is only for word width stacks.

## USES FOR STACKS

- data storage

This application is similar to an array, but is more useful for handling input/output information.

- program tracking \& control The stack is usually used to pass variables to and from subroutines and for storage of local variables.


## allocating the stack is the programmer's RESPONSIBILITY!

This means that the programmer is responsible for reserving memory for stack operations and for properly initializing the value of the stack pointer at the top of the stack memory area.

For example, the following code will allocate memory for a stack of 200 words DS.W $\$ 200$
BOTTOM EQU
To initialize the stack pointer, put the high memory address of the stack into A7 MOVE \#BOTTOM,A7

To "push" something onto the stack, the stack pointer must be decremented by one word and then <source> can be put on the stack.

MOVE <source>,-(SP)

To "pop" something off the stack, the information must be fetched from the stack, the stack pointer incremented by 1 word, and the information put into <destination>.

MOVE (SP)+,<destination>


The stack is usually put just ahead of the program in embedded microprocessor systems. This is not true for personal computers such as the Macintosh. They put the stack in very high memory (just under the heap) and put program information in low memory. For example, the program would begin just after the memory reserved for the stack in an embedded system.

|  | DS.W | $\$ 200$ |
| :--- | :--- | :--- |
| BOTTOM | EQU |  |
|  | <program code begins here> |  |

A major problem with stacks is that the programmer makes them too small. The word size of a stack is a measure of the greatest number of data items that might be put into it.
stack overflow attempt to push below the bottom end of the stack
stack underflow attempt to pop an item from an empty stack

## EXAMPLE: BACKWARD ECHO PROGRAM

This program will accept a character string terminated by a carriage return-line feed (CR-LF), place it into a stack buffer (temporary storage area), and output the string in reverse order to a computer terminal.

Functional specification (pseudocode)
initialize stack
push CR onto stack; push LF onto stack
inloop
if (TRMSTAT[0] $=1$ ) then goto inloop
get next char
if (char $=\mathrm{CR}$ ) goto outloop ;CR denotes end of input
push char onto stack
goto inloop
outloop
if (TRMSTAT[1] = 1) then goto outloop ;wait for busy display
pop char from stack
output char
if (SP less than initial SP) then goto outloop
;wait for input from ;keyboard - this is polled i/o
;ideal application for CharOut ;anything left in stack?

TRMSTAT and TRMDATA are special memory locations which are connected to the hardware of a computer terminal. Bit 0 of TRMSTAT whether a character has been input from the keyboard: 1 indicates a character has been input and can be found in TRMDATA, 0 indicates that nothing has been input since the last read of TRMDATA. Bit 1 of TRMSTAT indicates whether the terminal display is busy outputting the character last placed into TRMDATA. A 1 indicates that the terminal is still busy and is not ready for the next character to be output. TRMDATA is used for input and output of ASCII data. When read, TRMDATA indicates input from the keyboard whereas a write to TRMDATA will send the character to the display.


This is a stack for my data so I will use A6 NOT A7 for the stack pointer.


Note that the stack builds down in memory.

Program accepts input:
AB...YZ<cr> then outputs ZY...BA<lf><cr>


## MC68000 CODE

|  | INCLUDE | io.s | ;include io definitions |
| :---: | :---: | :---: | :---: |
| TRMSTAT | EQU | \$10040 | ;terminal status register |
| TRMDATA | EQU | \$10042 | ;terminal data register |
|  | ORG | \$4000 | ;start program here |
|  | DS.W | 200 | ;save 200 words for a stack |
| START | EQU | * | ;assign an address to START |
|  | LEA | START,A6 | ;initialize SP to START address |
|  | CLR.L | D0 |  |
|  | MOVE | \#\$D,-(A6) | ;push CR onto stack |
|  | MOVE | \#\$A,-(A6) | ;push LF onto stack |
| LOOP | EQU | * |  |
|  | BTST | \#0,TRMSTAT | ;character entered? |
|  |  |  | ;bit[0]=1 when character waiting |
|  | BEQ | LOOP | ;no input, keep waiting |
|  | MOVE.B | TRMDATA,D0 | ;have input, get char entered |
|  | CMP | \#\$D, D0 | ;is char entered a CR? |
|  | BEQ | OUT | ;YES, goto to output routine |
|  | MOVE | D0,-(A6) | ;NO, push char onto stack |
|  | BRA | LOOP | ;and repeat input loop |
| OUT | EQU | * |  |
|  | MOVE | (A6)+, D0 | ;pop char from stack |
|  | JSR | CharOut | ;output character |
|  | CMPA | START,A6 | ;is stack empty? |
|  | BNE | OUT | ;NO, keep outputting chars |
|  | BRA | START | ;YES, get new line |
|  | END | START |  |

NOTE: CMPA is a new instruction.

## EXAMPLE: RPN CALCULATOR (problem 6.3)

This program implements a reverse Polisn (RPN) calculator using a stack.
Examples of input:
11* equals 1 AND 1
10+ equals 1 OR 0
The operands ' 0 ' and ' 1 ' have ASCII values $\$ 30$ and $\$ 31$ respectively. Convert ASCII to binary by subtracting ' 0 ', i.e. ASCII $\$ 30$ from the ASCII value. Reverse the process for input.

The program uses:
MULTIPLICAND 8 -bit number to be multiplied

Functional specification (pseudocode)


# MC68000 assembly code for RPN calculator program: 

|  | ORG | \$5000 |  |
| :---: | :---: | :---: | :---: |
| BUFSIZ | EQU | 80 | ;input buffer size |
| OPSTK | DS.B | 20 | ;size of operations stack |
| INPUTBUF | DS.B | BUFSIZ |  |
| START | LEA | INPUTBUF,A0 | ;load address of input buffer into A0 |
|  | MOVE.W | \#BUFSIZ,D0 | ;set D0 to size of input buffer |
| ; $(\mathrm{AO})=$ address of input, (D0.W) = max number of characters to read |  |  |  |
|  | JSR | STRIN | ;get input |
|  | JSR | STROUT | ;echo input |
|  | SUBQ | \#2,D0 | ;adjust character count for DB instruction |
|  | LEA | INPUTBUF,A1 | ;set A1 to top of stack |
| SCANNEXT | CMPI.B | \#'0',(A0) | ;input='0'? |
|  | BLT.S | EVALUATE | ;if input<0 then input is operator |
|  | MOVE.B | (A0)+,-(A1) | ;push input onto stack |
|  | SUBI.B | \#'0',(A1) | ;convert stack entry to binary |
|  | BRA.S | CHKCNT | ;test for more input |
| EVALUATE | MOVE.B | (A1)+, D2 | ;pop the operand stack |
|  | MOVE.B | (A1)+, D1 | ; |
|  | CMPI.B | \#'*',(A0)+ | ;is operand an '*'? |
|  | BEQ | ANDOP | ;Yes it is - goto AND operand |
|  | OR.B | D1,D2 | ;otherwise OR arguements |
|  | BRA.S | PUSHOP |  |
| ANDOP | AND.B | D1,D2 | ;AND arguements |
| PUSHOP | MOVE.B | D2,-(A1) | ;push result onto stack |
| CHKCNT | DBF | D0,SCANNEXT |  |
| PUTANS | ADDI.B | \#'0',(A1) | ;convert stack to ASCII |
|  | MOVEA.L | A1,A0 | ;set up pointer to output, i.e. A0 |
|  | MOVE.W | \#1,D0 | ;set up \# of characters to output, i.e. DO.W |
|  | JSR | STROUT |  |
|  | JSR | NEWLINE |  |

## PC RELATIVE ADDRESSING MODES

Bcc
DBcc

Both of these branches use relative addressing allowing a program to work anywhere in memory independent of absolute addresses.
program counter with displacement $\mathrm{d}(\mathrm{PC}) \quad \mathrm{d}$ is a 16 -bit 2 's complement displacement ( -32 K to + 32 K bytes) which is sign extended
program counter with index and displacement
d(PC, Ri.W)
d(PC, Ri.L)

Ri can be wither an address or data register. The register is sign extended if <size> is .W. Note that the displacement is -128 to +127 bytes.

Consider the instruction
MOVE.W \$500(PC),D4
This is a two word instruction. Assume that $(P C)=\$ 1000$ at start of instruction.

1. fetch first instruction word
2. increment $\mathrm{PC}, \mathrm{PC}=\mathrm{PC}+2$
3. decode instruction
4. then add $\$ 500$ to $\$ 1502$
5. (PC) $=\$ 1004$ at end of instruction

PEA implements call by reference parameter passing
PEA <ea> pushes an address onto stack
Equivalent to the instruction
MOVE.L <ea>,-(SP)

CMPM compare memory
CMPM.<size> (Ay)+,(Ax)+
Both source and destination MUST be in post increment mode.
RTR return and restore instruction
Word is popped from the stack and the least significant byte (LSB) of this word is put into the CCR. Long word is popped from the stack and placed into the PC.

Should execute
MOVE.W CCR,-(SP)
at beginning of program
Problem: How to save registers (subroutine needs to use registers also)
Solution: Push all registers onto stack after JSR Pop all registers off stack before RTS
MOVEM.<size> <register list>,<ea>
MOVEM.<size> <ea>,<register list>
Push registers onto stack.
MOVEM.<size> <register list>,-(SP)
Pop registers off stack.
MOVEM.<size> (SP)+,<register list>
Register list (no commas)
D0,D2,D3,D4,A0,A1,A6
is equivalent to
D0/D2-D4/A0-A1/A6
where you use the '/' instead of a comman to seperate registers and '-' indicates a range of registers, i.e. D2-D4 indicates all data registers from D2 to D4.
<size> = .W or .L
When <size>=.W all registers are sign extended first.

## SUBROUTINES

General format of calling and returning from a subroutine


Problem: How do we know where to return to when the subroutine is completed? Solution: store the address of the next instruction after the call (as well as the current value of the registers and any local variables) on a stack

PROGRAMMER IS RESPONSIBLE FOR SETTING THE STACK POINTER AND ALLOCATING MEMORY FOR THE STACK. THIS IS NORMALLY A7.

Examples of calling a subroutine:
BSR <label> where label MUST be a label with no more than a 16 -bit signed offset, i.e. within $\pm 64 \mathrm{~K}$ of the BSR instruction JSR <ea> where <ea> must be a memory addressing mode, i.e. <ea> cannot be a data or address register. This is the most common form of calling a subroutine.

Both forms put the address of the next instruction on the 68000 stack into A7, i.e. they push the long word address of the next instruction after the call onto the stack.

Examples of returning from a subroutine:
RTS pops a long word, an address, off the stack (in A7) and and loads the PC with that address.

WARNING If the stack pointer is not pointing to the correct return address you will not return to the next instruction after the subroutine call.

## WHY USE A SUBROUTINE

- If you use the same code at different points in your program, the use of a subroutine will result in a savings of program memory.
- Use of subroutines results in modular program design which is easier to comprehend, debug, etc.


## ISSUES IN WRITING SUBROUTINES

| linkage | this is the address at which the program resumes <br> after executing the subroutine |
| :--- | :--- |
| argument transmission | how do you supply the subroutine with values for its <br> arguments <br> subroutines should always be written as pure <br> procedures with no self-modifying code |
| coding | lat |

## Linkage:

Both of the following instructions
JSR SUB ;jumps to a subroutine anywhere in memory
BSR SUB ;jumps to a subroutine within a limited addressing range are equivalent to the instruction sequence

MOVE.L address of next instruction,-(SP)
JMP SUB
which pushes the return address onto the stack and jumps to the subroutine code. SP is a mnemonic for the stack pointer and means the same as A7 on the 68000.

The following instruction
RTS ;return from subroutine
is equivalent to the instruction
JMP (SP)+ ;does not affect condition codes of SR
which jumps to the next instruction after the JSR (assuming the SP is correctly placed) and pops the return address off the stack.

## EXAMPLE:

RTS
ORG $\quad \$ 100$
JSR
<next instruction>
SAM <subroutine code> ;keep for comparison
<rest of program>
;beginning of CODE section ;jump to subroutine SAM
\$1000
SAM

Example of the above subroutine call sequence:
NOTE: There is NO saving of any register contents, the SR, or any local variables.

| just before executing the instruction JSR SAM | just after executing the instruction JSR SAM | just after execution of the instruction RTS |
| :---: | :---: | :---: |
| $\begin{array}{ll} \text { SP: } & \$ 6416 \\ \text { PC: } & \$ 1000 \end{array}$ | $\begin{array}{ll} \text { SP: } & \$ 6412 \\ \text { PC: } & \$ 1064 \end{array}$ | $\begin{array}{ll} \text { SP: } & \$ 6416 \\ \text { PC: } & \$ 1004 \end{array}$ |
| STACK: $\begin{array}{r} \$ 6412 \\ \$ 6414 \\ S P \rightarrow \$ 6416 \end{array}$ | STACK: $\begin{array}{r\|r\|} \hline S P \rightarrow \$ 6412 & \$ 0000 \\ \$ 6414 & 1004 * \\ \hline \$ 6416 & \\ \hline \end{array}$ <br> *long word return addres | STACK: $\begin{array}{r} \$ 6412 \\ \$ 6414 \\ \mathrm{SP} \rightarrow \$ 6416 \end{array}$ |
| PROGRAM: | PROGRAM: <br> * 4 byte instruction | PROGRAM: $\begin{array}{r\|c\|} \hline \$ 1000 & \\ \$ 1002 & \\ \hline & \text { next } \\ \hline \text { instruction } \\ \end{array}$ |
| SUBROUTINE: <br> SAM <br> begins $\rightarrow$ 1064 <br> here $\begin{array}{r}\$ 1066 \\ \\ \$ 1068\end{array}$ | SUBROUTINE: | SUBROUTINE: $\begin{aligned} & \$ 1064 \\ & \$ 1066 \\ & \$ 1068 \end{aligned}$ |

- using registers
- using registers
- in-line coding
- using the stack
data registers-call by value (uses actual data values)
put arguments in data registers before JSR
address registers-call by reference (uses actual data values)
put the addresses of the arguments in address registers before JSR
- put arguments immediately after JSR, address of arguments passed via return address on stack
- put addresses of arguments immediately after JSR, address of arguments passed via return address on stack
- arguments listed in a table or array, pase base address of table to subroutine via an address register
(this is the preferred method)
Optionally use LINK and UNLK instruction to create and destroy temporary storage on stack.

The MOVEM instruction
This instruction saves or restores multiple registers. If you have a small assembly language program this instruction allows you to save to values of registers NOT used to pass parameters.

MOVEM has two forms:
MOVEM register_list,<ea>
MOVEM <ea>,register_list

Example:
SUBRTN EQU *
MOVEM D0-D7/A0-A6,SAVEBLOCK
-••
MOVEM SAVEBLOCK,D0-D7/A0-A6
RTS
where SAVEBLOCK is local memory. This is bad practice in general since SAVEBLOCK could be overwritten.

Example:
SUBRTN EQU *
MOVEM D0-D7/A0-A6,-(SP)
MOVEM (SP)+,D0-D7/A0-A6
RTS
This is the most common method of using the MOVEM instruction to save registers on the stack and restore them when the subroutine is done. This is especially useful for re-entrant and/or recursive subroutines. A recursive procedure is one that may call or use itself. A re-entrant procedure is one that is usable by interrupt and non-interrupt driven programs without loss of data.

The MOVEM instruction always transfers contents to and from memory in a predetermined sequence, regardless of the order in which they are listed in the instruction.
address register indirect with pre-decrement
transferred in order A7 $\rightarrow \mathrm{A} 0, \mathrm{D} 7 \rightarrow \mathrm{D} 0$
for all control modes and address register indirect with post-increment transferred in order D0 $\rightarrow$ D7, A0 $\rightarrow$ A7

This allows you to easily build stacks and lists.

## POWR subroutine

This subroutine accepts two input parameters, a base and an exponent, and calculates the function base exponent.

Functional specification (pseudocode)
POWR (base, exponent)

D1=base
D2=exponent
initialize D3 to 1 exponent=exponent-1 while exponent $\geq 0$ D3=base*D3
end POWR.
;input arguments
;exponent must be an integer
;
;compute using continued ;product of base

Basic documentation of POWR (see p. 3 of lab manual)
Subroutine documentation:
name:
function:
input/output:
registers destructively addressed:
memory requirements:
subroutines called:
length of subroutine (bytes):

## POWR

computers base exponent where exponent is an interger using continued product input:
D1=base, D2=exponent
output:
D3=result
D2,D3
none
none 40

POWR (parameter passing using data registers)
;Program to compute the power of a number using subroutine. ;Power MUST be an integer. A and B are signed numbers. ;Parameter passing via data registers.

| MOVE | A,D1 | ;put base into D1 |
| :--- | :--- | :--- |
| MOVE | B,D2 | ;put exponent into D2 |
| JSR | POWR | ;call subroutine POWR |
| LEA | C,A5 | ;put address of where to put answer |
|  |  | into A5 |
| MOVE | D3,(A5) | ;save answer |


| DATA | EQU | $*$ |
| :--- | :--- | :--- |
| A | DC.W | 4 |
| B | DC.W | 2 |
| C | DS.W | 1 |


| POWR | MOVE.L | \#1,D3 | ;put starting 1 into D3 |
| :--- | :--- | :--- | :--- |
| LOOP | EQU | $*$ |  |
|  | SUBQ | \#1,D2 | ;decrement power |
|  | BMI | EXIT | ;if D2<0 then quit subroutine |
|  | MULS | D1,D3 | ;multiply out |
|  | BRA | LOOP | ;and repeat as necessary |
| EXIT | EQU | $*$ |  |
|  | RTS |  |  |



POWR (parameter passing using address registers)
;Program to compute the power of a number using subroutine.
;Power MUST be an integer. A and B are signed numbers.
;Parameter passing via address registers.

| LEA | A,A1 | ;put address of base into A1 |
| :--- | :--- | :--- |
| LEA | B,A2 | ;put address of exponent into A2 |
| JSR | POWR | ;call subroutine POWR |
| LEA | C,A5 | ;put address of where to put answer |
|  |  | into A5 |
| MOVE | D3,(A5) | ;save answer |


| DATA | EQU | $*$ |
| :--- | :--- | :--- |
| A | DC.W | 4 |
| B | DC.W | 2 |
| C | DS.W | 1 |


| POWR | EQU | * |  |
| :--- | :--- | :--- | :--- |
| * only difference is that following instructions are | address register indirect |  |  |
|  | MOVE | (A1),D1 | ;get base |
|  | MOVE | (A2),D2 | ;get exponent |
|  | MOVE.L | \#1,D3 | ;put starting 1 into D3 |
| LOOP | EQU | * |  |
|  | SUBQ | \#1,D2 | ;decrement power |
|  | BMI | EXIT | ;if D2<0 then quit subroutine |
|  | MULS | D1,D3 | ;multiply out |
|  | BRA | LOOP | ;and repeat as necessary |
| EXIT | EQU | $*$ |  |
|  | RTS |  |  |

POWR (parameter passing using inline coding of data)
;Program to compute the power of a number using subroutine. ;Power MUST be an integer. A and B are signed numbers. ;Parameter passing via inline coding of data.

| * no longer load parameters into registers BEFORE subroutine call |  |  |  |
| :---: | :---: | :---: | :---: |
|  | JSR | POWR | ;call subroutine POWR |
| * parameters are inline AFTER subroutine call |  |  |  |
| DATA | EQU |  |  |
| A | DC.W | 4 | ;base |
| $B$ | DC.W | 2 | ; exponent |
| C | DS.W | 1 | ;result |

* the rest of the program would go here

| POWR | EQU | * |  |
| :---: | :---: | :---: | :---: |
|  | MOVE.L | (SP),A5 | ;put return address into A5 <br> ;get $A$, increment $A 5$ to point to $B$ ;get $B$, increment $A 5$ to point to where to put result <br> ;put starting 1 into D3 |
|  | MOVE | (A5)+, D1 |  |
|  | MOVE | (A5)+,D2 |  |
|  | MOVE.L | \#1,D3 |  |
| LOOP | EQU | * |  |
|  | SUBQ | \#1,D2 | ;decrement power <br> ;if D2-1<0 then quit subroutine <br> ;multiply out ;and repeat as necessary |
|  | BMI | EXIT |  |
|  | MULS | D1,D3 |  |
|  | BRA | LOOP |  |
| EXIT | EQU | * |  |
|  | MOVE | D3,(A5)+ | $;(C)=\text { answer }$ <br> ;(A5)=return address <br> ;put correct return address on stack |
|  | MOVE.L RTS | A5,(SP) |  |


| Behavior of the stack | How program memory is arranged |
| :--- | :--- | :--- | :--- | :--- |

POWR (parameter passing using inline coding of addresses)
;Program to compute the power of a number using subroutine. ;Power MUST be an integer. A and B are signed numbers. ;Parameter passing via inline coding of addresses.

JSR POWR ;call subroutine POWR

* addresses of parameters are put inline AFTER subroutine call
$D C . L \quad A, B, C \quad$;address of $A, B$ and $C$ are inline
* the rest of the program would go here

| DATA | EQU | $*$ |  |
| :--- | :--- | :--- | :--- |
| A | DC.W | 4 | ;base |
| B | DC.W | 2 | ;exponent |
| C | DS.W | 1 | ;result |


| POWR | EQU | * |  |
| :---: | :---: | :---: | :---: |
|  | MOVE.L | (SP),A5 | ;put return address into A5 |
|  | MOVE | (A5)+,A1 | ;get address of $A$, increment $A 5$ so (A5) =address of $B$ |
|  | MOVE | (A5)+,A2 | ; get address of $B$, increment $A 5$ so (A5) $=$ address of $C$ |
|  | MOVE | (A1), D1 | ;put A into D1 |
|  | MOVE | (A2), D2 | ;put B into D2 |
| LOOP | MOVE.L | $\underset{*}{\# 1, D 3}$ | ;put starting 1 into D3 |
|  | EQU |  |  |
|  | SUBQ | \#1,D2 | ;decrement power |
|  | BMI | EXIT | ;if D2<0 then quit subroutine |
|  | MULS | D1,D3 | ;multiply out |
|  | BRA | LOOP | ;and repeat as necessary |
| EXIT | EQU | * |  |
|  | MOVE.L | (A5)+,A3 | ;increment A5 to point to correct return address, put address of $C$ into A3 |
|  | MOVE | D3,(A3) | ;put answer into C |
|  | MOVE.L | A5,(SP) | ;restore correct return address onto stack |
|  | RTS |  |  |


| Behavior of the stack | How program memory is arranged |  |
| :---: | :---: | :---: |
| in subroutine, $\mathrm{SP} \rightarrow$ |  $\$ 1064$ <br> A5 will start $\$ 1066$ <br> here in subroutine $\rightarrow$ $\$ 1068$ <br>  $\$ 106 \mathrm{~A}$ |  |
| - 4 byte |  | JSR |
| - return - |  | instruction |
|  |  |  |
| original $\mathrm{SP} \rightarrow$ |  | A |
| Return address on stack is address of A, NOT the next program instruction which would be several bytes beyond this. | \$106E |  |
|  | \$1070 |  |
|  | \$1072 |  |
|  | \$1074 | C |
|  | subroutine should return here $\rightarrow$ |  |

POWR (parameter passing using the address of a parameter array in an address register)
;Program to compute the power of a number using subroutine.
;Power MUST be an integer. A and B are signed numbers.
;Parameter passing via the address of a parameter array in an address register.

$$
\begin{array}{lll}
\text { LEA } & \text { ARG,A5 } & \text {;put address of argument array in A5 } \\
\text { JSR } & \text { POWR } & \text {;call subroutine POWR }
\end{array}
$$

* the rest of the program would go here

| ARG | EQU | $*$ |  |
| :--- | :--- | :--- | :--- |
| A | DC.W | 4 | ;base |
| B | DC.W | 2 | ;exponent |
| C | DS.W | 1 | ;result |
|  |  |  |  |
|  |  |  |  |
| POWR | EQU | $*$ | (A5),D1 |

* table means use address register indirect with displacement and/or offset

|  | MOVE.L | \#1,D3 | ;put starting 1 into D3 |
| :--- | :--- | :--- | :--- |
| LOOP | EQU | * |  |
|  | SUBQ | \#1,D2 | ;decrement power |
|  | BMI | EXIT | ;if D2-1<0 then quit subroutine |
|  | MULS | D1,D3 | ;multiply out |
|  | BRA | LOOP | ;and repeat as necessary |
| EXIT | EQU | $*$ |  |
|  | $M O V E$ | D3,4(A5) | ;put answer from D3 into $C$ |
|  | RTS |  |  |

How program memory is arranged:


POWR (parameter passing by placing parameters on stack)
;Program to compute the power of a number using subroutine. ;Power MUST be an integer. A and B are signed numbers. ;Parameter are passed on the stack.

| MOVE.W | A,-(SP) | ;push A onto stack |
| :--- | :--- | :--- |
| MOVE.W | B,-(SP) | ;push B onto stack |
| JSR | POWR | ;call subroutine POWR |
| MOVE.W | $(S P)+, C$ | ;pop answer from stack resetting SP |
|  |  | to original value |

* the rest of the program would go here

| ARG | EQU | $*$ |  |
| :--- | :--- | :--- | :--- |
| A | DC.W | 4 | ;base |
| B | DC.W | 2 | ;exponent |
| C | DS.W | 1 | ;result |
|  |  |  |  |
| POWR | EQU | $*$ |  |
|  | $M O V E . W$ | $6(S P), D 1$ | ;put A into D1 |
|  | $M O V E . W$ | $4(S P), D 2$ | ;put B into D2 |
|  |  |  |  |
|  | MOVE.L | \#1,D3 | ;put starting 1 into D3 |
| LOOP | EQU | $*$ |  |
|  | SUBQ | \#1,D2 | ;decrement power |
|  | BMI | EXIT | ;if D2-1<0 then quit subroutine |
|  | MULS | D1,D3 | ;multiply out |
|  | BRA | LOOP | ;and repeat as necessary |
| EXIT | EQU | $*$ | ;put answer on stack on top of $A$ |
|  | $M O V E . W$ | $D 3,6(S P)$ | ;move return address two bytes up in |
|  | $M O V E . L$ | $(S P), 2(S P)$ | stack |
|  |  |  | ;increment $S P$ by 2 bytes |

How the stack is manipulated by this program:

| The stack just after JSR has been executed | \$1064 |  |
| :---: | :---: | :---: |
|  | final SP \$1066 | return |
|  | SP after \$1068 | address |
|  | putting parameters $\rightarrow$ \$106A | B |
|  | on stack \$1060 | A |
|  | original SP $\rightarrow$ \$106E |  |
|  | \$1070 |  |
| The stack just before the RTS is executed. Notice how the stack had to be corrected by two bytes to account for the fact that two parameters were passed to POWR but only one parameter was returned | return address \& SP  <br> moved two bytes $\$ 1064$ <br> $\$ 1066$ <br> $\$ 1068$ <br> $\$ 106 A$ |  |
|  |  |  |
|  |  |  |
|  |  | return |
|  |  | address |
|  | SP after RTS $\rightarrow \$ 106 \mathrm{C}$ original SP $\rightarrow$ \$106E | C |
|  |  |  |
|  | \$1070 |  |

Recursive subroutine
This subroutine accepts one input and computes the factorial of that number using recursive procedure calls on the stack.

Functional specification (pseudocode)
FACTOR(input)
factorial=input push factorial on stack
factorial=factorial-1
if number $=1$ call FACTOR
else \{end FACTOR \}
temp=pop stack
factorial=factorial*temp end FACTOR.
;number input ;save the current number on ;stack
;decrement the number ;continue putting on stack? ;this ends up with factorial=1 ;pop number from stack ;compute factorial

Basic documentation of FACTOR (see p. 3 of lab manual)
Subroutine documentation:
name:
function:
input/output:
registers destructively addressed:
memory requirements:
subroutines called:
length of subroutine (bytes):

FACTOR
computes the factorial of a given number input: D0.W
output: D0.W
D0
none
none
40 (estimated)

FACTOR (parameter passing using data register D0)
;Program to compute the factorial of a number using subroutine.
;Parameter passing via data registers.


| * | Register usage: | D0.W destructively used |
| :--- | :--- | :--- |
| * | Sample case: Input | D0.W=5 |
| * |  |  |
|  |  | Output D0.W=120 |


| FACTOR | MOVE.W | D0,--(SP) | ;push input number onto stack |
| :--- | :--- | :--- | :---: |
|  | SUBQ.W | \#1,D0 | ;decrement number |
|  | BNE.S | F_CONT | ;reached 1 yet? |
|  | MOVE.W | (SP)+,D0 | ;yes, factorial=1 |
|  | RTS |  | ;return |
| F_CONT | JSR | FACTOR | ;no, call FACTOR |
|  | MULU | (SP)+,D0 | ;multiply only after stack contains all <br>  <br> RETURN |
|  | RTS |  | numbers |

Stack usage by subroutine FACTOR


