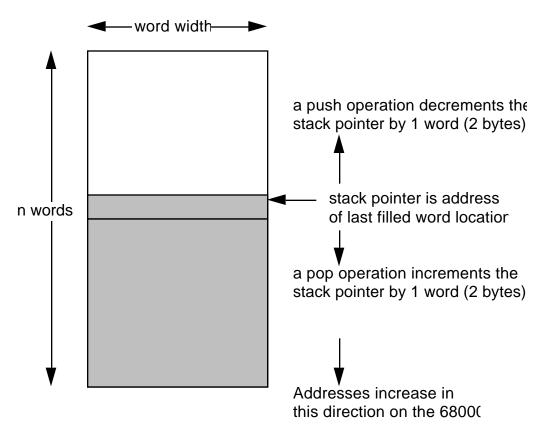
STACK

A stack is a first in, last out buffer usually implemented as a block of n consecutive bytes (it doesn't have to be bytes—it could be words or long words). In the example below, the stack is composed of words.



NOTES ABOUT 68000 STACKS

On the 68000 stack addresses begin in high memory (\$60000 for example) and are pushed toward low memory (\$50000 for example). Other machines might do this in the reverse order.

A stack can be implemented as bytes or longwords. The normal 68000 stack pointer is in A7 (Don't use this register for anything else!!!). If you want to use a special stack which is byte or long word in width you will need to use another register; A7 is only for word width stacks.

USES FOR STACKS

data storage This application is similar to an array, but is more useful for handling input/output information.
 program tracking & control The stack is usually used to pass variables to and from subroutines and for storage of

local variables.

ALLOCATING THE STACK IS THE PROGRAMMER'S RESPONSIBILITY!

This means that the programmer is responsible for reserving memory for stack operations and for properly initializing the value of the stack pointer at the top of the stack memory area.

For example, the following code will allocate memory for a stack of 200 words DS.W \$200 BOTTOM EQU *

To initialize the stack pointer, put the high memory address of the stack into A7 MOVE #BOTTOM,A7

To "push" something onto the stack, word the stack pointer must be decremented by one word and then <source> can be put on the stack. <source>,-(SP) MOVE To "pop" something off the stack, the information must be fetched from the stack, the stack pointer incremented new SPdata by 1 word, and the information put into <destination>. old SP-MOVE (SP)+,<destination>

The stack is usually put just ahead of the program in embedded microprocessor systems. This is not true for personal computers such as the Macintosh. They put the stack in very high memory (just under the heap) and put program information in low memory. For example, the program would begin just after the memory reserved for the stack in an embedded system.

	DS.W	\$200
BOTTOM	EQU	*
	<program< td=""><td>code begins here></td></program<>	code begins here>

A major problem with stacks is that the programmer makes them too small. The word size of a stack is a measure of the greatest number of data items that might be put into it.

stack overflow	attempt to push below the bottom end of the stack
stack underflow	attempt to pop an item from an empty stack

EXAMPLE: BACKWARD ECHO PROGRAM

This program will accept a character string terminated by a carriage return-line feed (CR-LF), place it into a stack buffer (temporary storage area), and output the string in reverse order to a computer terminal.

Functional specification (pseudocode)

initialize stack push CR onto stack; push LF onto stack

inloop if (TRMSTAT[0] 1) then goto inloop

get next char if (char = CR) goto outloop push char onto stack goto inloop ;wait for input from ;keyboard - this is polled i/o

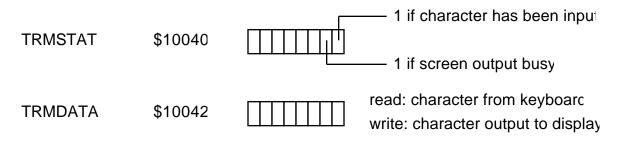
;CR denotes end of input

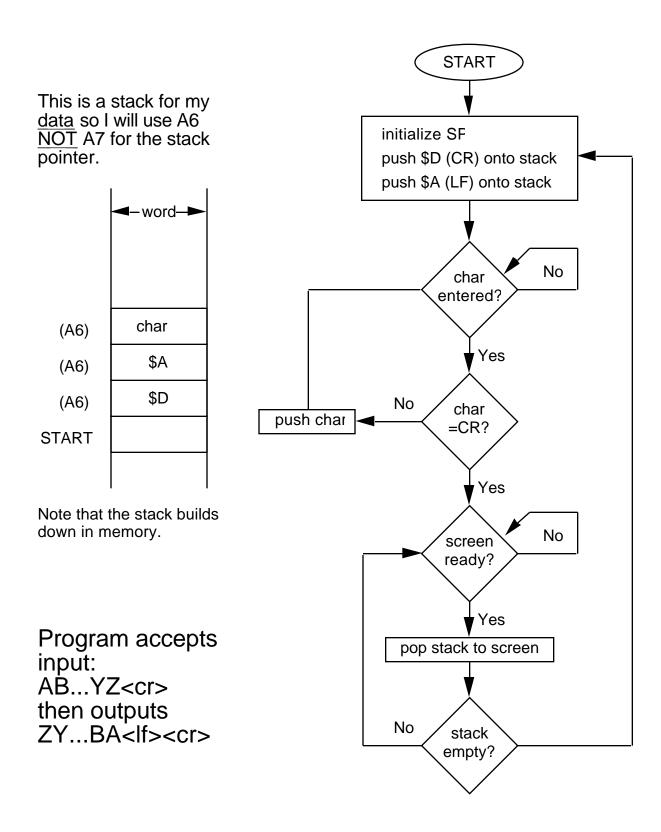
;anything left in stack?

outloop if (TRMSTAT[1] = 1) then goto outloop ;wait for busy display pop char from stack output char ;ideal application for CharOut

if (SP less than initial SP) then goto outloop

TRMSTAT and TRMDATA are special memory locations which are connected to the hardware of a computer terminal. Bit 0 of TRMSTAT whether a character has been input from the keyboard: 1 indicates a character has been input and can be found in TRMDATA, 0 indicates that nothing has been input since the last read of TRMDATA. Bit 1 of TRMSTAT indicates whether the terminal display is busy outputting the character last placed into TRMDATA. A 1 indicates that the terminal is still busy and is not ready for the next character to be output. TRMDATA is used for input and output of ASCII data. When read, TRMDATA indicates input from the keyboard whereas a write to TRMDATA will send the character to the display.





MC68000 CODE

	INCLUDE	io.s	;include io definitions
TRMSTAT	EQU	\$10040	;terminal status register
TRMDATA	EQU	\$10042	;terminal data register
	ORG	\$4000	;start program here
	DS.W	200	;save 200 words for a stack
START	EQU	*	;assign an address to START
	LEA	START,A6	;initialize SP to START address
	CLR.L	D0	
	MOVE	#\$D,-(A6)	;push CR onto stack
	MOVE	#\$A,-(A6)	;push LF onto stack
LOOP	EQU	*	
	BTST	#0,TRMSTAT	;character entered?
			;bit[0]=1 when character waiting
	BEQ	LOOP	;no input, keep waiting
	MOVE.B	TRMDATA,D0	;have input, get char entered
	CMP	#\$D,D0	;is char entered a CR?
	BEQ	OUT	;YES, goto to output routine
	MOVE	D0,-(A6)	;NO, push char onto stack
	BRA	LOOP	;and repeat input loop
OUT	EQU	*	
	MOVE	(A6)+,D0	;pop char from stack
	JSR	CharOut	;output character
	CMPA	START,A6	;is stack empty?
	BNE	OUT	;NO, keep outputting chars
	BRA	START	;YES, get new line
	END	START	
OUT	MOVE JSR CMPA BNE BRA	(A6)+,D0 CharOut START,A6 OUT START	;output character ;is stack empty? ;NO, keep outputting chars

NOTE: CMPA is a new instruction.

EXAMPLE: RPN CALCULATOR (problem 6.3)

This program implements a reverse Polisn (RPN) calculator using a stack.

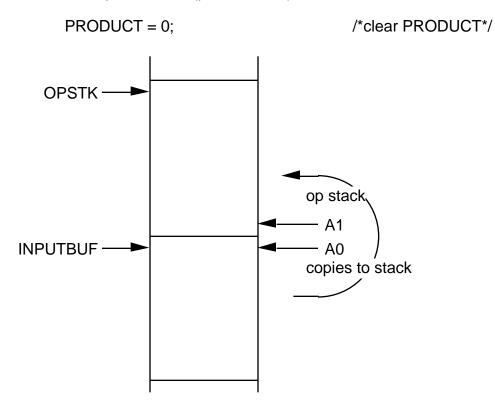
Examples of input: 11* equals 1 AND 1 10+ equals 1 OR 0

The operands '0' and '1' have ASCII values \$30 and \$31 respectively. Convert ASCII to binary by subtracting '0', i.e. ASCII \$30 from the ASCII value. Reverse the process for input.

The program uses: MULTIPLICAND 8

8-bit number to be multiplied

Functional specification (pseudocode)



MC68000 assembly code for RPN calculator program:

	ORG	\$5000	
BUFSIZ	EQU	80	;input buffer size
OPSTK	DS.B	20	;size of operations stack
INPUTBUF	DS.B	BUFSIZ	
START	LEA	INPUTBUF,A0	;load address of input buffer into
			A0
	MOVE.W	#BUFSIZ,D0	;set D0 to size of input buffer
; (A0) = addr	ess of input, ((D0.W) = max numbe	er of characters to read
; on input (D	0.W) is # of cl	naracters to input	
	JSR	STRIN	;get input
	JSR	STROUT	;echo input
	SUBQ	#2,D0	;adjust character count for DB
			instruction
	LEA	INPUTBUF,A1	;set A1 to top of stack
SCANNEXT	CMPI.B	#'0',(A0)	;input='0'?
	BLT.S	EVALUATE	;if input<0 then input is operator
	MOVE.B	(A0)+,-(A1)	;push input onto stack
	SUBI.B	#'0',(A1)	;convert stack entry to binary
	BRA.S	CHKCNT	;test for more input
EVALUATE	MOVE.B	(A1)+,D2	;pop the operand stack
	MOVE.B	(A1)+,D1	;
	CMPI.B	#'*',(A0)+	;is operand an '*'?
	BEQ	ANDOP	;Yes it is - goto AND operand
	OR.B	D1,D2	;otherwise OR arguements
	BRA.S	PUSHOP	
ANDOP	AND.B	D1,D2	;AND arguements
PUSHOP	MOVE.B	D2,-(A1)	;push result onto stack
CHKCNT	DBF	D0,SCANNEXT	
PUTANS	ADDI.B	#'0',(A1)	;convert stack to ASCII
	MOVEA.L	A1,A0	;set up pointer to output, i.e. A0
	MOVE.W	#1,D0	;set up # of characters to output,
			i.e. D0.W
	JSR	STROUT	
	JSR	NEWLINE	

PC RELATIVE ADDRESSING MODES

BccBoth of these branches use relativeDBccaddressing allowing a program to work
anywhere in memory independent of
absolute addresses.

program counter with displacement

d(PC) d is a 16-bit 2's complement displacement (-32K to + 32K bytes) which is sign extended

program counter with index and displacement

d(PC, Ri.W)Ri can be wither an address or datad(PC, Ri.L)register. The register is sign extended if
<size> is .W. Note that the displacement
is -128 to +127 bytes.

Consider the instruction MOVE.W \$500(PC),D4 This is a two word instruction. Assume that (PC) = \$1000 at start of instruction. 1. fetch first instruction word

- 2. increment PC, PC=PC+2
- 3. decode instruction
- 4. then add \$500 to \$1502
- 5. (PC)=\$1004 at end of instruction
- PEA implements call by reference parameter passing

PEA <ea> pushes an address onto stack Equivalent to the instruction MOVE.L <ea>,-(SP) CMPM compare memory

CMPM.<size> (Ay)+,(Ax)+ Both source and destination MUST be in post increment mode.

RTR return and restore instruction Word is popped from the stack and the least significant byte (LSB) of this word is put into the CCR. Long word is popped from the stack and placed into the PC.

Should execute MOVE.W CCR,-(SP) at beginning of program

Problem: How to save registers (subroutine needs to use registers also)

Solution: Push all registers onto stack after JSR Pop all registers off stack before RTS

MOVEM.<size> <register list>,<ea>

MOVEM.<size> <ea>,<register list>

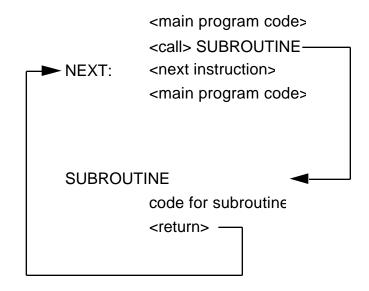
Push registers onto stack. MOVEM.<size> <register list>,-(SP) Pop registers off stack. MOVEM.<size> (SP)+,<register list>

Register list (no commas) D0,D2,D3,D4,A0,A1,A6 is equivalent to D0/D2-D4/A0-A1/A6 where you use the '/' instead of a comman to seperate registers and '-' indicates a range of registers, i.e. D2-D4 indicates all data registers from D2 to D4.

<size> = .W or .L When <size>=.W all registers are sign extended first.

SUBROUTINES

General format of calling and returning from a subroutine



Problem: How do we know where to return to when the subroutine is completed? Solution: store the address of the next instruction after the call (as well as the current value of the registers and any local variables) on a stack

PROGRAMMER IS RESPONSIBLE FOR SETTING THE STACK POINTER AND ALLOCATING MEMORY FOR THE STACK. THIS IS NORMALLY A7.

Examples of calling a subroutine:

BSR	<label></label>	where label MUST be a label with no more than a 16-bit
		signed offset, i.e. within ± 64 K of the BSR instruction
JSR	<ea></ea>	where <ea> must be a memory addressing mode, i.e. <ea> cannot be a data or address register. This is the most common form of calling a subroutine.</ea></ea>

Both forms put the address of the next instruction on the 68000 stack into A7, i.e. they push the long word address of the next instruction after the call onto the stack.

Examples of returning from a subroutine:

RTS	pops a long word, an address, off the stack (in A7) and and
	loads the PC with that address.

<u>WARNING</u> If the stack pointer is not pointing to the correct return address you will not return to the next instruction after the subroutine call.

WHY USE A SUBROUTINE

- If you use the same code at different points in your program, the use of a subroutine will result in a savings of program memory.
- Use of subroutines results in modular program design which is easier to comprehend, debug, etc.

ISSUES IN WRITING SUBROUTINES

linkage	this is the address at which the program resumes after executing the subroutine
argument transmission	how do you supply the subroutine with values for its
coding	arguments subroutines should always be written as pure procedures with no self-modifying code

Linkage:

Both of the following instructions

JSR SUB ;jumps to a subroutine anywhere in memory BSR SUB ;jumps to a subroutine within a limited addressing range are equivalent to the instruction sequence

MOVE.L address of next instruction,-(SP)

JMP SUB

which pushes the return address onto the stack and jumps to the subroutine code. SP is a mnemonic for the stack pointer and means the same as A7 on the 68000.

The following instruction

RTS ;return from subroutine

is equivalent to the instruction JMP (SP)+

(SP)+ ;does <u>not</u> affect condition codes of SR

which jumps to the next instruction after the JSR (assuming the SP is correctly placed) and pops the return address off the stack.

EXAMPLE:

	ORG	\$1000	;beginning of CODE section
	JSR	SAM	;jump to subroutine SAM
	<next instructi<="" th=""><th>on></th><th></th></next>	on>	
	<rest of="" progra<="" th=""><th>am></th><th></th></rest>	am>	
SAM	<subroutine co<br="">RTS</subroutine>	ode>	;keep for comparison

Example of the above subroutine call sequence: NOTE: There is NO saving of any register contents, the SR, or any local variables.

just before executing the instruction JSR SAM	just after executing the instruction JSR SAM	just after execution of the instruction RTS
SP: \$6416 PC: \$1000	SP: \$6412 PC: \$1064	SP: \$6416 PC: \$1004
STACK: \$6412 \$6414 SP \$6416	STACK: SP \$6412 <u>\$ 0000</u> \$6414 1004 * \$6416 * long word return address	STACK: \$6412 \$6414 SP \$6416
PROGRAM: PC \$1000 JSR \$1002 SAM* \$1004 next instruction	PROGRAM: \$1000 JSR \$1002 SAM* \$1004 * 4 byte instruction	PROGRAM: \$1000 \$1002 PC \$1004 next instruction
SUBROUTINE: SAM begins \$1064 here \$1066 \$1068	SUBROUTINE: PC \$1064 \$1066 \$1068	SUBROUTINE: \$1064 \$1066 \$1068

HOW TO PASS PARAMETERS TO SUBROUTINES

- using registers
 data registers—call by value (uses actual data values) put arguments in data registers before JSR
 using registers
 address registers—call by reference
- using registers address registers—call by reference (uses actual data values) put the addresses of the arguments in address registers before JSR

•

- in-line codingput arguments immediately after JSR, address of arguments passed via return address on stack
 - put addresses of arguments immediately after JSR, address of arguments passed via return address on stack
 - arguments listed in a table or array, pase base address of table to subroutine via an address register
- using the stack (this is the preferred method) Optionally use LINK and UNLK instruction to create and destroy temporary storage on stack.

The MOVEM instruction

This instruction saves or restores multiple registers. If you have a small assembly language program this instruction allows you to save to values of registers NOT used to pass parameters.

MOVEM has two forms:

MOVEM	register_list, <ea></ea>
MOVEM	<ea>,register_list</ea>

Example:

SUBRTN	EOU	*
~	MOVEM	D0-D7/A0-A6,SAVEBLOCK
	• • •	
	MOVEM RTS	SAVEBLOCK, D0-D7/A0-A6

where SAVEBLOCK is local memory. This is bad practice in general since SAVEBLOCK could be overwritten.

Example:

SUBRTN EQU * MOVEM D0-D7/A0-A6,-(SP) ••• MOVEM (SP)+,D0-D7/A0-A6 RTS

This is the most common method of using the MOVEM instruction to save registers on the stack and restore them when the subroutine is done. This is especially useful for re-entrant and/or recursive subroutines. A recursive procedure is one that may call or use itself. A re-entrant procedure is one that is usable by interrupt and non-interrupt driven programs without loss of data.

The MOVEM instruction always transfers contents to and from memory in a predetermined sequence, regardless of the order in which they are listed in the instruction.

address register indirect with pre-decrement

transferred in order A7 A0,D7 D0

for all control modes and address register indirect with post-increment transferred in order D0 D7,A0 A7

This allows you to easily build stacks and lists.

POWR subroutine

This subroutine accepts two input parameters, a base and an exponent, and calculates the function base^{exponent}.

Functional specification (pseudocode)

POWR (base, exponent)

D1=base D2=exponent

initialize D3 to 1 exponent=exponent-1 while exponent 0 D3=base*D3 ;input arguments ;exponent must be an integer

;

;compute using continued ;product of base

end POWR.

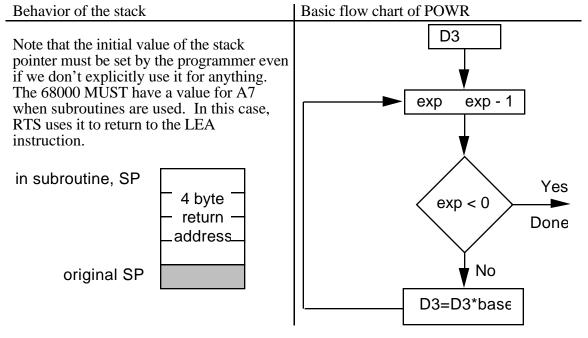
Basic documentation of POWR (see p.3 of lab manual)

Subroutine documentation:	
name:	POWR
function:	computers base ^{exponent} where exponent is an interger using continued product
input/output:	input: D1=base, D2=exponent output: D3=result
registers destructively addressed: memory requirements: subroutines called: length of subroutine (bytes):	D2,D3 none none 40

POWR (parameter passing using data registers)

;Program to compute the power of a number using subroutine. ;Power MUST be an integer. A and B are signed numbers. ;Parameter passing via <u>data</u> registers.

	MOVE MOVE JSR LEA	A,D1 B,D2 POWR C,A5	;put base into D1 ;put exponent into D2 ;call subroutine POWR ;put address of where to put answer into A5
	MOVE	D3,(A5)	;save answer
DATA A B C	EQU DC.W DC.W DS.W	* 4 2 1	
POWR LOOP	MOVE.L EQU	#1,D3 *	;put starting 1 into D3
EXIT	EQU SUBQ BMI MULS BRA EQU RTS	#1,D2 EXIT D1,D3 LOOP *	;decrement power ;if D2<0 then quit subroutine ;multiply out ;and repeat as necessary



POWR (parameter passing using address registers)

;Program to compute the power of a number using subroutine.

;Power MUST be an integer. A and B are signed numbers. ;Parameter passing via <u>address</u> registers.

	<i>LEA LEA</i> JSR LEA	A,A1 B,A2 POWR C,A5	<i>;put address of base into A1</i> <i>;put address of exponent into A2</i> ;call subroutine POWR ;put address of where to put answer into A5
	MOVE	D3,(A5)	;save answer
DATA	EQU	*	
А	DČ.W	4	
В	DC.W	2	
С	DS.W	1	
POWR	EQU	*	
* only differen	ice is that follow	ving instructions are ad	ldress register indirect
	MOVE	(Å1),D1	;get base
	MOVE	(A2),D2	;get exponent
	MOVE.L	#1,D3	;put starting 1 into D3
LOOP	EQU	*	
	SUBQ	#1,D2	;decrement power
	BMI	EXIT	;if D2<0 then quit subroutine
	MULS	D1,D3	;multiply out
	BRA	LOOP	;and repeat as necessary
EXIT	BRA EQU RTS	LOOP *	;and repeat as necessary

POWR (parameter passing using inline coding of data)

;Program to compute the power of a number using subroutine. ;Power MUST be an integer. A and B are signed numbers. ;Parameter passing via inline coding of data.

* no longer load parameters into registers BEFORE subroutine call JSR POWR ;call subroutine POWR * parameters are inline AFTER subroutine call

* paramet	ers are iniine Af	'IEK subroutii	пе сан
DATA	EQU	*	
A	DC.W	4	;base
В	DC.W	2	;exponent
С	DS.W	1	;result

* the rest of the program would go here

POWR	EQU MOVE.L MOVE MOVE	* (SP),A5 (A5)+,D1 (A5)+,D2	;put return address into A5 ;get A, increment A5 to point to B ;get B, increment A5 to point to where to put result
LOOP	MOVE.L EQU	#1,D3 *	;put starting 1 into D3
LOOP	EQU SUBQ BMI MULS BRA	#1,D2 EXIT D1,D3 LOOP	;decrement power ;if D2-1<0 then quit subroutine ;multiply out ;and repeat as necessary
EXIT	EQU MOVE	* D3,(A5)+	;(C)=answer, ;(A5)=return address
	<i>MOVE.L</i> RTS	A5,(SP)	;put correct return address on stack

Behavior of the stack		How program memory is arr	anged	
in subroutine, SP original SP	4 byte return – address	A5 will start here in subroutine	\$1064 \$1066 \$1068 \$106A \$106C	JSR instruction A B
Return address on stac A, NOT the next progra which would be severa beyond this.	am instruction	subroutine should return	\$106E here	C

POWR (parameter passing using inline coding of addresses)

;Program to compute the power of a number using subroutine. ;Power MUST be an integer. A and B are signed numbers. ;Parameter passing via inline coding of addresses.

·	JSR <i>parameters are</i> DC.L e program wou	POWR <i>e put inline AFTER subr</i> <i>A, B, C</i> Ild go here	;call subroutine POWR routine call ;address of A,B and C are inline
DATA A B C	EQU DC.W DC.W DS.W	* 4 2 1	;base ;exponent ;result
POWR	EQU MOVE.L MOVE MOVE MOVE MOVE	* (SP),A5 (A5)+,A1 (A5)+,A2 (A1),D1 (A2),D2	;put return address into A5 ;get address of A, increment A5 so (A5)=address of B ;get address of B, increment A5 so (A5)=address of C ;put A into D1 ;put B into D2
LOOP	MOVE.L EQU SUBQ BMI MULS BRA	#1,D3 * #1,D2 EXIT D1,D3 LOOP	;put starting 1 into D3 ;decrement power ;if D2<0 then quit subroutine ;multiply out ;and repeat as necessary
EXIT	EQU MOVE.L MOVE MOVE.L RTS	* (A5)+,A3 D3,(A3) A5,(SP)	;increment A5 to point to correct return address, put address of C into A3 ;put answer into C ;restore correct return address onto stack

Behavior of the stack	How program memory is an	ranged	
in subroutine, SP 4 byte return – address original SP Return address on stack is address of A, NOT the next program instruction which would be several bytes beyond this.		\$1064 \$1066 \$1068 \$106A \$106C \$106E \$1070 \$1072 \$1074 here	JSR instruction — A— — B— — C—

POWR (parameter passing using the address of a parameter array in an address register)

;Program to compute the power of a number using subroutine. ;Power MUST be an integer. A and B are signed numbers. ;Parameter passing via the address of a parameter array in an address register.

* the rest of th	<i>LEA</i> JSR ne program wou	<i>ARG,A5</i> POWR Ild go here	;put address of argument array in A5 ;call subroutine POWR
ARG A	EQU DC.W	* 4	;base
B C	DC.W DS.W	2 1	;exponent ;result
POWR * table means	EQU MOVE MOVE use address reg	* (A5),D1 2(A5),D2 gister indirect with displ	;put A into D1 ;put B into D2 lacement and/or offset
LOOP	MOVE.L EQU SUBQ BMI MULS	#1,D3 * #1,D2 EXIT D1,D3	;put starting 1 into D3 ;decrement power ;if D2-1<0 then quit subroutine ;multiply out
EXIT	BRA EQU MOVE RTS	$LOOP \\ * \\ D3,4(A5)$;and repeat as necessary ;put answer from D3 into C

How program memory is arranged:

	\$1068	
ARG and A5 point here	\$106A	٨
	\$106C	—_A
2(A5) points here	\$106E	
	\$1070	B
4(A5) points here	\$1072	0
	\$1074	

POWR

(parameter passing by placing parameters on stack)

;Program to compute the power of a number using subroutine. ;Power MUST be an integer. A and B are signed numbers. ;Parameter are passed on the stack.

MOVE.W	A, -(SP)	;push A onto stack
MOVE.W	B, -(SP)	push B onto stack
JSR	POWR	;call subroutine POWR
MOVE.W	(SP)+,C	;pop answer from stack resetting SP
		to original value

* the rest of the program would go here

ARG A B C	EQU DC.W DC.W DS.W	* 4 2 1	;base ;exponent ;result
POWR	EQU MOVE.W MOVE.W	* 6(SP),D1 4(SP),D2	;put A into D1 ;put B into D2
LOOP	MOVE.L EQU SUBQ BMI	#1,D3 * #1,D2 EXIT	;put starting 1 into D3 ;decrement power ;if D2-1<0 then quit subroutine
EXIT	MULS BRA EQU MOVE.W	D1,D3 LOOP * D3,6(SP)	;multiply out ;and repeat as necessary ;put answer on stack on top of A
	MOVE.L ADDQ.L RTS	(SP),2(SP) #2,SP	;move return address two bytes up in stack ;increment SP by 2 bytes

How the stack is manipulated by this program:

The stack just after JSR has been executed	final SP	\$1064 \$1066	
	SP after	\$1066 \$1068	return address
	putting parameters	\$1068 \$106A	B
	on stack	\$106C	A
	original SP	\$106E	
		\$1070	
		\$1064	
RTS is executed. Notice	return address & SP	\$1064 \$1066	
RTS is executed. Notice how the stack had to be corrected by two bytes to	return address & SP moved two bytes	· -	return
RTS is executed. Notice how the stack had to be corrected by two bytes to account for the fact that two parameters were passed to		\$1066	return address
RTS is executed. Notice how the stack had to be corrected by two bytes to account for the fact that two parameters were passed to POWR but only one		\$1066 \$1068	
The stack just before the RTS is executed. Notice how the stack had to be corrected by two bytes to account for the fact that two parameters were passed to POWR but only one parameter was returned	moved two bytes	\$1066 \$1068 \$106A	address

Recursive subroutine

This subroutine accepts one input and computes the factorial of that number using recursive procedure calls on the stack.

Functional specification (pseudocode)

FACTOR(input) factorial=input push factorial on stack

factorial=factorial-1 if number 1 call FACTOR else {end FACTOR} temp=pop stack factorial=factorial*temp end FACTOR. ;number input ;save the current number on ;stack ;decrement the number ;continue putting on stack? ;this ends up with factorial=1 ;pop number from stack ;compute factorial

Basic documentation of FACTOR (see p.3 of lab manual)

Subroutine documentation:	FACTOR
name:	computes the factorial of a given number
function:	input: D0.W
input/output:	output: D0.W
registers destructively addressed:	D0
memory requirements:	none
subroutines called:	none
length of subroutine (bytes):	40 (estimated)

FACTOR (parameter passing using data register D0)

;Program to compute the factorial of a number using subroutine. ;Parameter passing via <u>data</u> registers.

DATA PROGRAM	EQU EQU ORG	\$6000 \$4000 DATA	;data segment ;program segment
NUMB F_NUMB	DS.W DS.W	1 1 PROGRAM	;number to be factorialized ;factorial of number
MAIN	ORG MOVE.W JSR MOVE.W	NUMB,D0 FACTOR D0,F_NUMB	;get number ;goto factorial routine ;store result

* subroutine FACTOR (parameter passing using data register D0)

* Computes the factorial of a number.

*	Initial conditions:	D0.W=number to compute factorial of.
*		0 <d0.w<9< td=""></d0.w<9<>
*	Final conditions:	D0.W=factorial of input number

	egister usage: ample case: Input	D0.W destructively used D0.W=5 Output D0.W=120	
FACTOF	R MOVE.W SUBQ.W BNE.S MOVE.W RTS	D0,-(SP) #1,D0 F_CONT (SP)+,D0	;push input number onto stack ;decrement number ;reached 1 yet? ;yes, factorial=1 ;return
F_CONT	JSR MULU	FACTOR (SP)+,D0	;no, call FACTOR ;multiply only after stack contains all numbers
RETURN	N RTS		

Stack usage by subroutine FACTOR

	word
after last call, SP	1
	4 byte
	return address
	2
	4 byte
	return address
	3
	4 byte
	return address
	4
	4 byte
	return address
	5
	4 byte
	return address
original SP	

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