

circuits — mathematical models for the behavior of electrical systems
 components — elements that make up the circuit
 ideal circuit elements. (Thurs & Fri lectures)

practicing engineers try to use mature circuit models.
 (typically 20-100 years old).

1.4 voltage & current

energy is expended when positive & negative charges are separated

these are vectors.

$$v = \frac{dW}{dq} \quad \begin{array}{l} \text{energy (joules)} \\ \text{charge (coulombs)} \end{array}$$

voltage (volts) energy per unit charge created by the charge separation

$$i = \frac{dq}{dt} \quad \begin{array}{l} \text{charge (coulombs)} \\ \text{time (seconds)} \end{array}$$

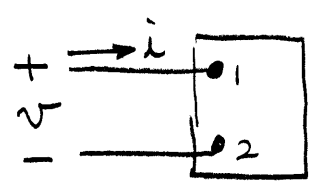
current (amperes)

$$e = 1.6022 \times 10^{-19} \text{ coulomb.}$$

components can be modeled strictly in terms of the voltage & current at the terminals

- usually don't need to know internal behavior
- use physics to develop circuit models.

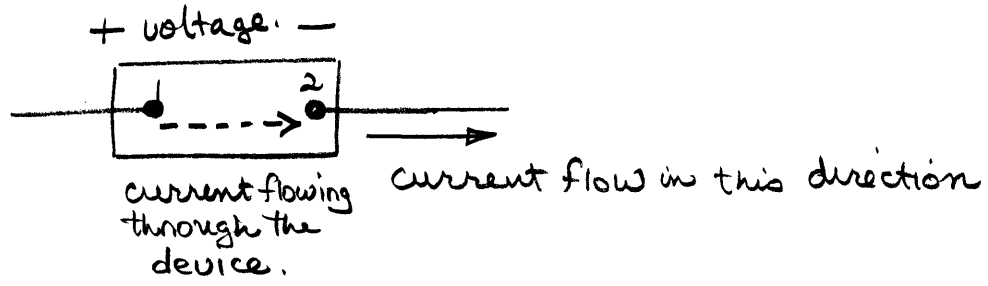
1.5 Basic circuit element



attributes

1. Has only two terminals
2. described mathematically in terms of voltage and/or current
3. cannot be subdivided into other elements

voltage polarity
current direction.

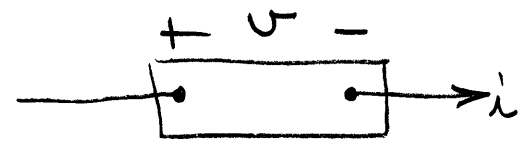


- if voltage > 0 there is a voltage drop across device
- if voltage < 0 there is a voltage rise across device.
- if $i > 0$ current flowing from 1 to 2
- if $i < 0$ current flowing from 2 to 1.

not a function of components.

assignment of polarities is entirely arbitrary but you can never change convention in a problem

passive sign convention



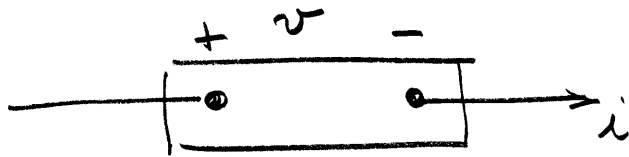
ideal - does not exist as a realizable circuit component
basic - cannot be further reduced or subdivided into other elements.

can better model "real" devices as connections of "ideal" devices.

1.6 Power and energy

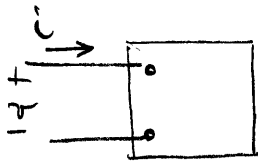
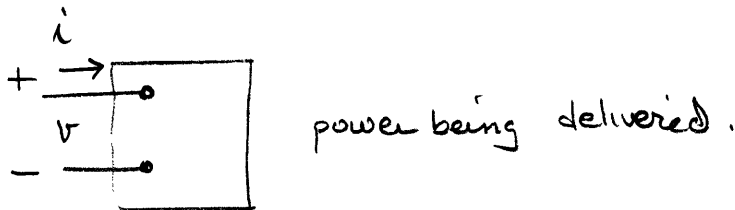
$$\begin{array}{l}
 \text{power (watts)} \\
 p = \frac{dw}{dt} = \frac{dw}{dq} \frac{dq}{dt} \\
 \begin{array}{l}
 \text{time} \\
 \text{(sec).} \\
 \text{voltage} \\
 \text{current}
 \end{array}
 \end{array}$$

energy (joules)

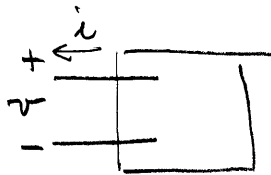


$p = vi > 0$ power is being delivered to circuit

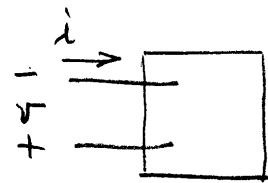
$p = vi < 0$ power is being extracted from circuit



$$\begin{aligned}
 p &= vi \\
 &= (+10)(+4) \\
 &= +40.
 \end{aligned}$$

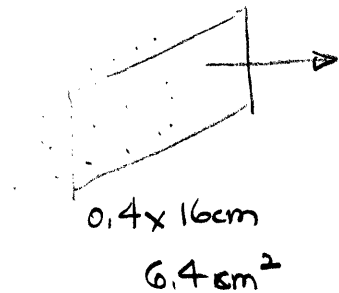


$$\begin{aligned}
 i &= +4 \\
 v &= -10 \\
 p &= -vi = -(-10)(4) \\
 &= +40
 \end{aligned}$$



Example problems:

1.7 A current of 1600 A exists in a rectangular (0.4 x 16 cm) copper bus bar. The current is due to free electrons moving through the bus bar at an average velocity of \bar{v} meters/sec. If the concentration of free electrons is 10^{29} electrons/m³ and if they are uniformly dispersed throughout the bus bar, then what is the average velocity of an electron.



$$\frac{q}{m^3} = 1.6022 \times 10^{-19} \frac{\text{coul.}}{\text{electron}} \cdot \frac{10^{29} \text{ electron}}{m^3}$$

$$\frac{q}{m^3} = 1.6022 \times 10^{10} \frac{\text{coul}}{m^3}$$

$$1.6022 \times 10^{10} \frac{\text{coul}}{m^3} \times \underbrace{(6.4 \times 10^{-4} m^2)}_{\text{assuming constant cross section}} = 10.25 \times 10^6 \frac{\text{coul}}{m}$$

$$i = 10.25 \times 10^6 \frac{\text{coul}}{m} \bar{v}$$

$$1600 = 10.25 \times 10^6 \bar{v}$$

$$\bar{v} = 156 \times 10^{-6} \frac{m}{sec.}$$

- 1.12 A 12-volt battery supplies 100 mA to a radio. How much energy does the battery supply in 4 hours.

$$p = vi = \frac{dW}{dt}$$

$$\frac{(12)(10^{-1})}{\text{units are watts}} = \frac{\Delta W}{14400 \text{ sec}}$$

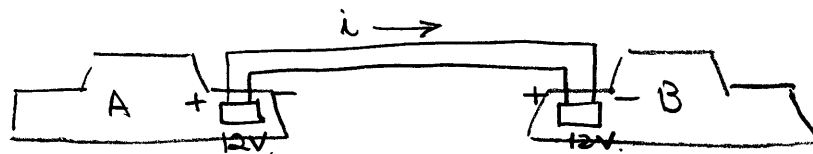
$$4 \text{ hrs} \times \frac{60 \text{ min}}{\text{hr}} \times \frac{60 \text{ sec}}{\text{min}}$$

$$\Delta W = 17280 \text{ joules}$$

- 1.20 When a car has a dead battery it can often be started by connecting the battery from another car across its terminals. The positive terminals are connected together as are the negative terminals. The connection is illustrated in Fig P1.20. Assume the current i in Fig P1.20 is measured and found to be -40 A .

(a) Which car has the dead battery?

(b) If this connection is maintained for 1.5 minutes, how much energy is transferred to the dead battery?



(a) $i = -40 \text{ A}$ so current is flowing from B to A.

A is dead.

$$vi = \frac{dW}{dt}$$

$$\text{or } W = \int_0^{1.5 \text{ min}} vi \, dt = \int_0^{90} (12)(40) \, dt = 43,200 \text{ joules}$$

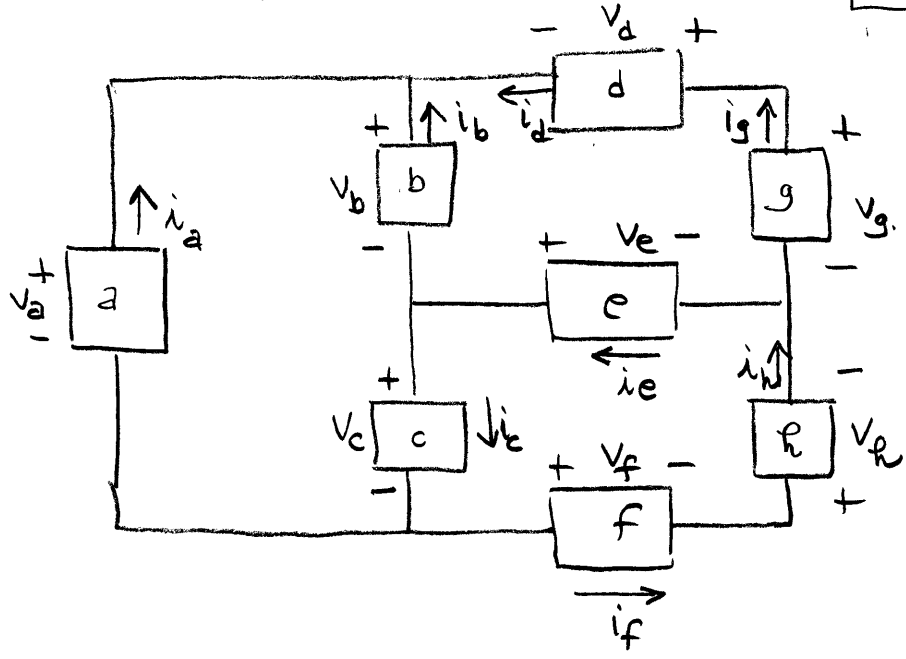
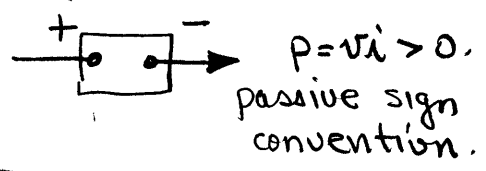
1.26 The numerical values of the voltages and currents in the interconnection seen in Fig. P1.26 are:

- $v_a = 990V, i_a = -22.5A$
- $v_b = 600V, i_b = -30A$
- $v_c = 300V, i_c = 60A$
- $v_d = 105V, i_d = 52.5A$
- $v_e = -120V, i_e = 30A$
- $v_f = 165V, i_f = 82.5A$
- $v_g = 585V, i_g = 52.5A$
- $v_h = -585V, i_h = 82.5A$

$-vi$	$-(990)(-22.5) = +22275$
$-vi$	$-(600)(-30) = +18000$
$+vi$	$+(300)(60) = +18000$
$+vi$	$+(105)(52.5) = +5512.5$
$-vi$	$-(-120)(30) = +3600$
$+vi$	$+(165)(82.5) = +13612.5$
$-vi$	$-(585)(52.5) = -30712.5$
$+vi$	$-(585)(82.5) = -48262.5$

Does the interconnection satisfy the power check?

① Check for sign conventions!



summing $+ 81000$ ← $P_{absorbed}$
 $- 78975$ ← $P_{delivered}$

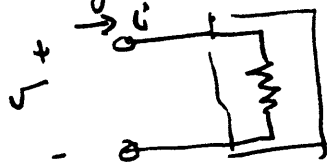
$P_{abs} \neq P_{del.}$

EEAP 243 - 1/20/93

The concepts of voltage and current are based on the physics of charges in electric fields. Voltage is associated with work on charges or work that can be produced by charge motion. Take the ~~the~~ human body

If we are subjected to a few hundred volts, under ~~some~~ ^{some} circumstances this may produce a non-lethal shock because it is the flow of current through the body that causes the damage. and if the work necessary to cause the actual flow exceeds this voltage - for reasons of skin resistance to flow or the path through the body to the source involves insulating material, such as ~~rubber~~ dry-rubber soled shoes, we may be made aware of our foolishness by a minor shock. The work required to push a lethal flow of charges exceeds the work available!

Clearly, in analogy to water flow in a pipe, the narrower the pipe, the more work will be required to push the same flow of water - we require more voltage to push a given number of charges through a resistive material per second. This resistor impedes current flow. The relationship between work (voltage) and charge flow (current) is called Ohm's law.

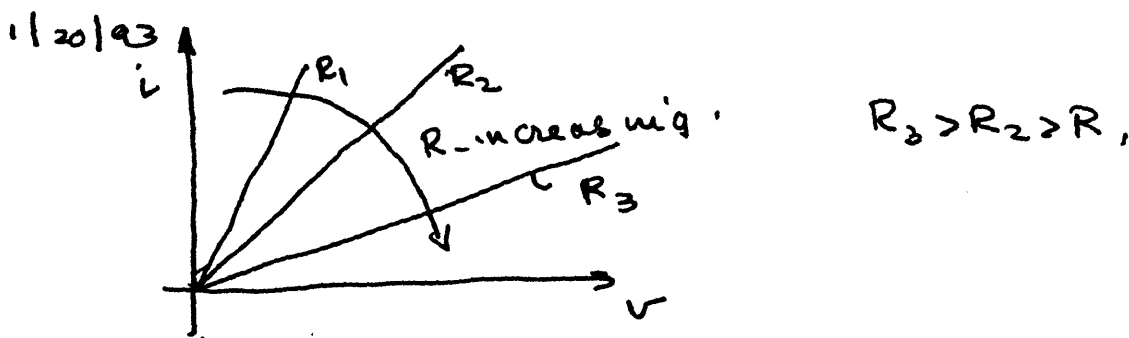


$$V/i = R$$

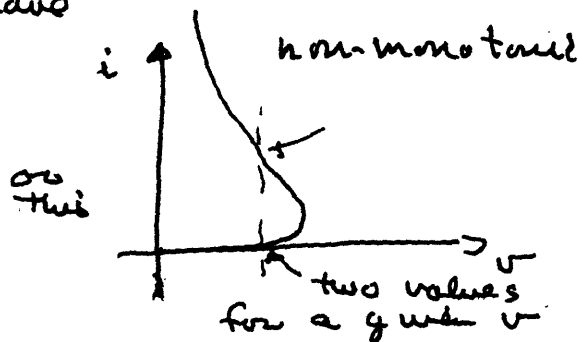
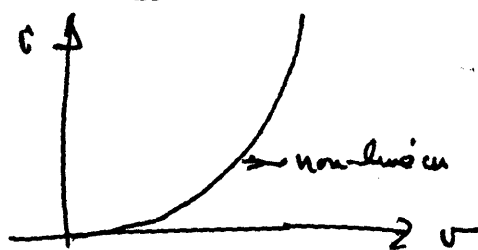
note ^{defined} direction of current flow and voltage signs!

This is ~~the~~ convention.

Notice the linear relationship between the two variables V, i .



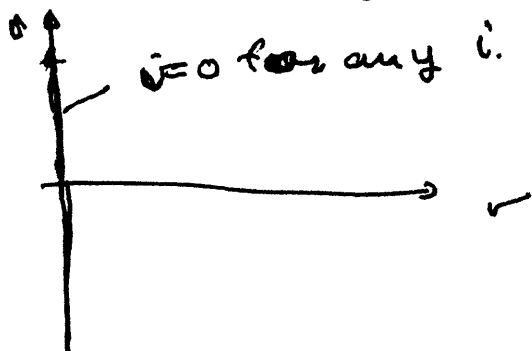
between voltage and current
 This need linear behavior isn't a necessity for a device. We could have



These are i, v characteristics for real physical devices - BUT NOT A RESISTOR. which is defined by ohm's law, $v = iR$. An open circuit is an infinite resistance

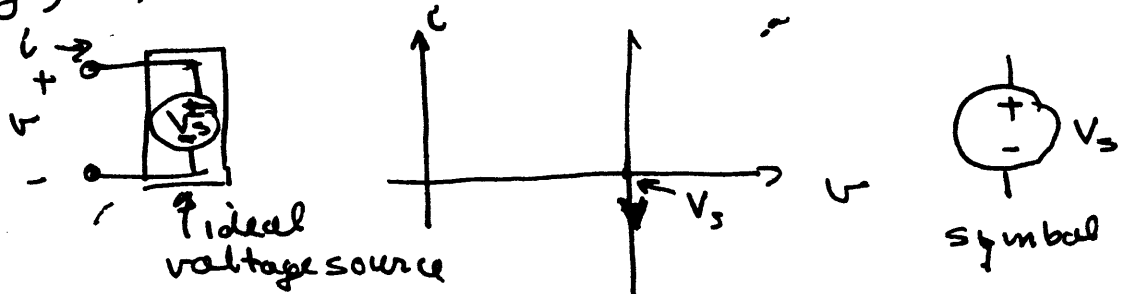


A short circuit is a zero-valued resistor



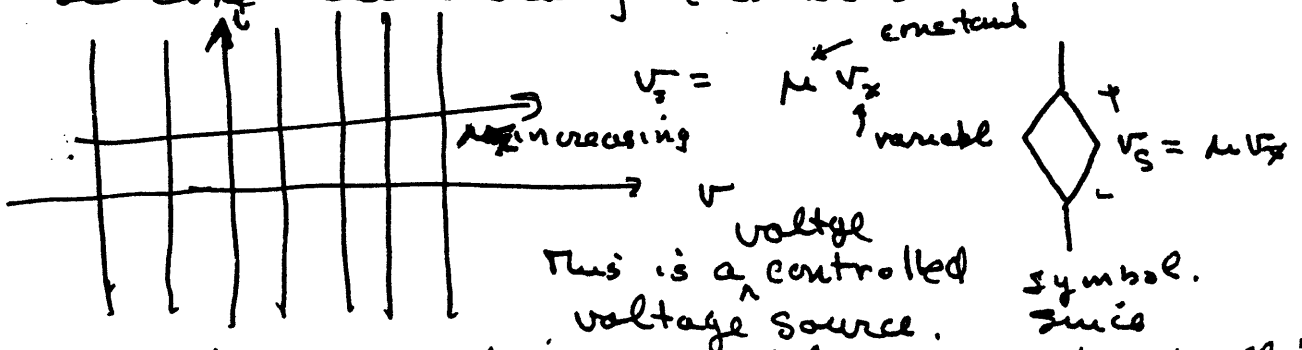
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We have been talking about voltages and currents. We also know that batteries produce voltages - i.e. they are voltage sources. They too, have terminal characteristics



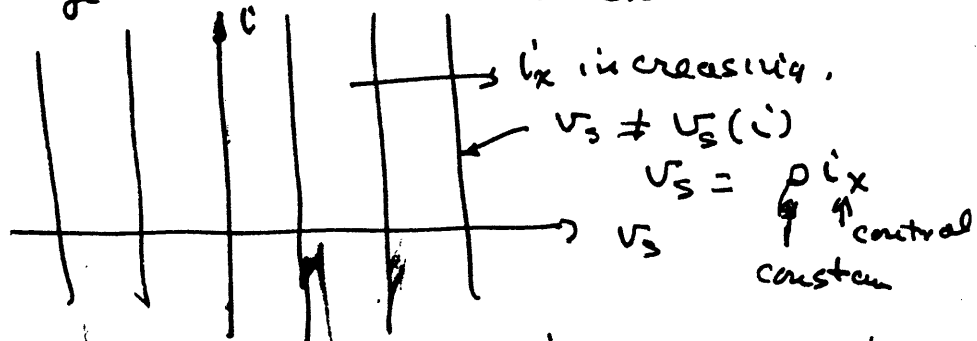
In some sense the voltage source is a displaced (in v) short circuit.

You can imagine that a voltage source is made to vary, perhaps as easily as turning a knob mechanically. This could be done electronically (as we shall see later)



This is a controlled voltage source.

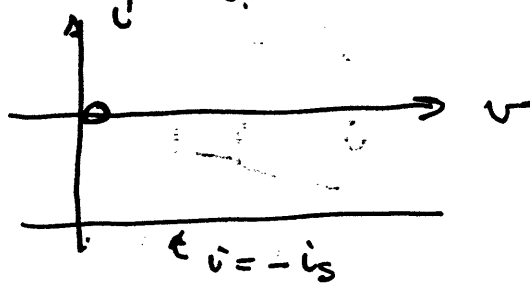
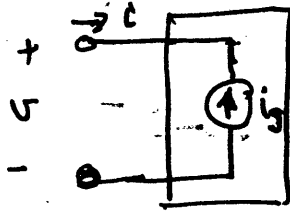
currents are also possible means of controlling voltage sources - current controlled voltage source



BE AWARE THAT i_x IS NOT the current flowing in v_s !!! We shall ~~see~~ examine

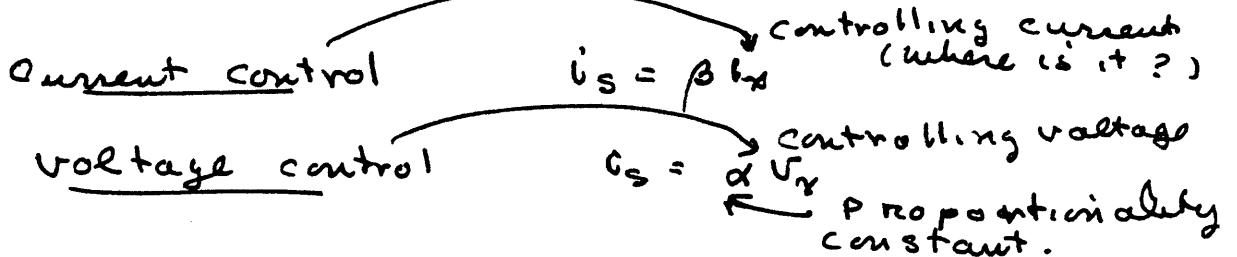
these two strange, but interesting beasts later in the course

Just as we have sources of voltage, we can have sources of current. This means that whatever the resistance placed in its path, the same current will flow.



This appears to be a displaced (along current axis) infinite resistor. Note: Because of the definitions (i, v, i_s) we wind up with $i = -i_s$. Since they are in opposite directions - physically the current flows out of the + terminal in spite of our definition of positive current flow in. This is characteristic of sources - (see how current ^{definition} went into the voltage source while we should expect current to flow out of the (+) terminal).

We also have the possibility of controlled current sources - (we need to exhaust all cases)



Chapter 2 Circuit Elements

basic circuit elements

voltage sources

current sources

resistors

inductors See section 7.1

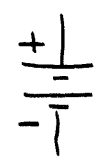
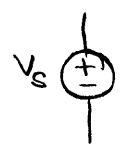
capacitors See section 7.2

switches (not in text) see problem 2.25

diodes (not in text) See Carlson p. 250-251

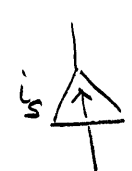
op-amps (not basic) See section 6.1

ideal independent voltage source.



maintains voltage across its terminals regardless of current

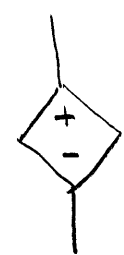
ideal independent current source.



older style.

maintains the current through its terminals regardless of voltage.

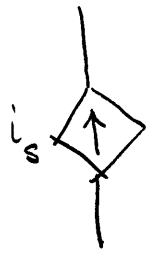
ideal dependent (controlled) voltage source.



$$v_s = \mu v_x \quad \text{or} \quad v_s = \rho i_x$$

can be controlled by a current or a voltage

ideal dependent (controlled) current source



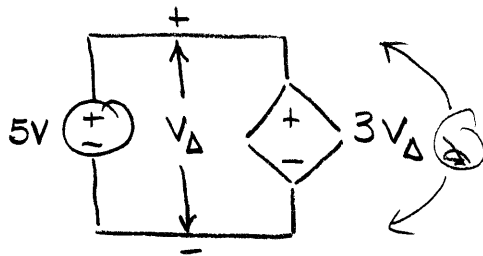
$$i_s = \alpha v_x$$

$$i_s = \beta i_x$$

can be controlled by a voltage or a current

Example 2.2.

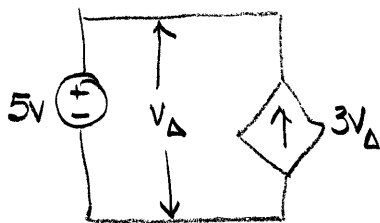
(a)



invalid

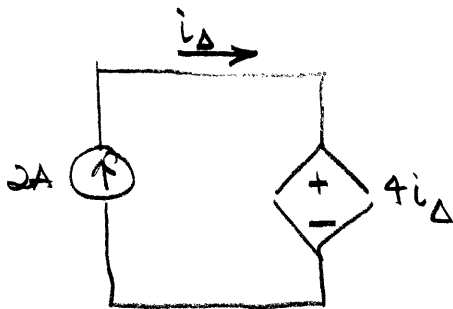
this voltage can't be both 5V and 15V.

(b)



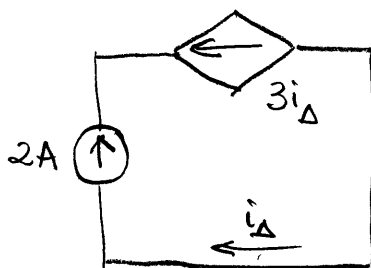
OK.

(c)



OK.

(d)



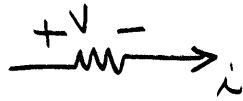
invalid.

2.2 Electrical resistance (Ohm's Law)



circuit symbol

resistance in Ohms (Ω)



$$v = iR$$

Ohm's Law

voltage drop.

$$\propto i = \frac{v}{R}$$

properties of resistance

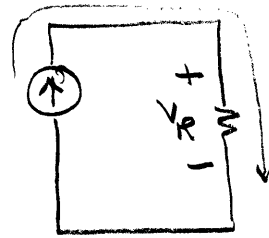
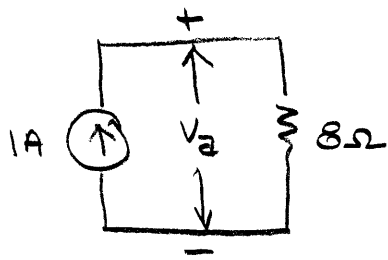
1. linear, time-invariant (constant)
independent of voltage, current or time
2. bilateral
if polarity of v reverses, current reverses
3. lumped
independent of spatial dimensions

A positive resistor always absorbs power from the circuit
since $P > 0$

$$\begin{aligned}
 \text{power } P &= v i > 0 \\
 &= (iR) i = i^2 R \\
 &= v \left(\frac{v}{R} \right) = \frac{v^2}{R}
 \end{aligned}$$

conductance $G = \frac{1}{R}$ Siemens

Example 2.3 (a)

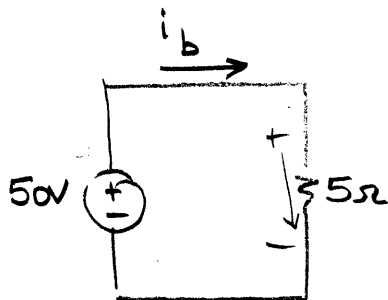


Signs due to current

$$v_a = v_R = iR = (1)(8) = 8V.$$

$$P_{8\Omega} = v i = (8V)(1A) = 8W.$$

(b)



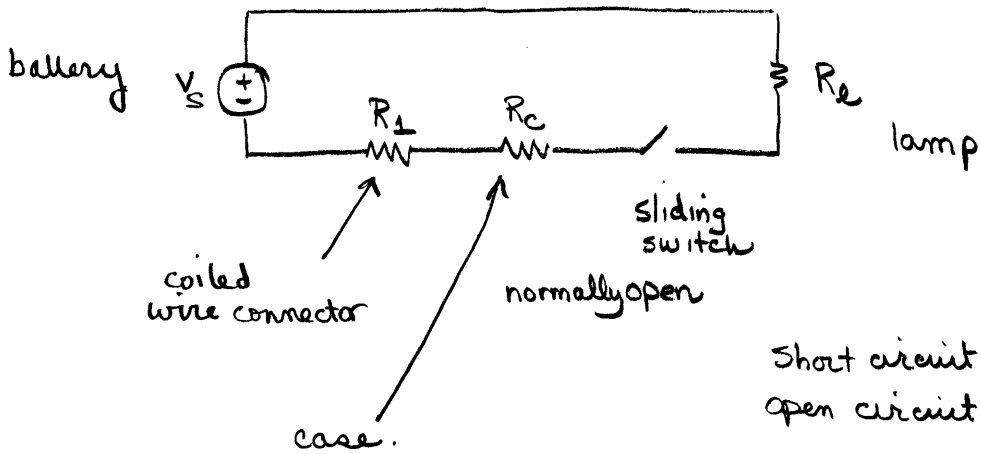
$$v_{5\Omega} = i_b R.$$

$$50 = i_b 5$$

$$i_b = 10A.$$

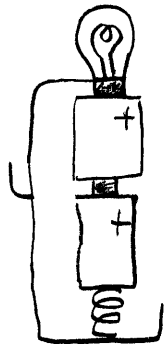
$$P_{5\Omega} = v i = (50V)(10A) = 500W.$$

2.3 Simple Circuits

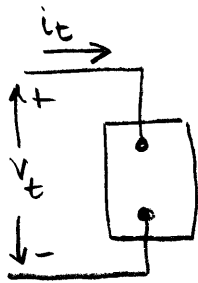


short circuit $R = 0$
 open circuit $R = \infty$

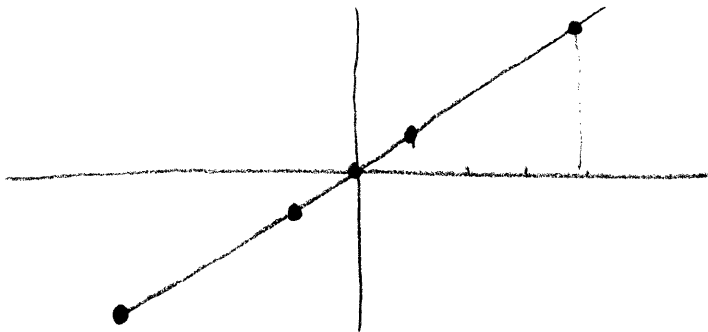
physically



Example 2.5.



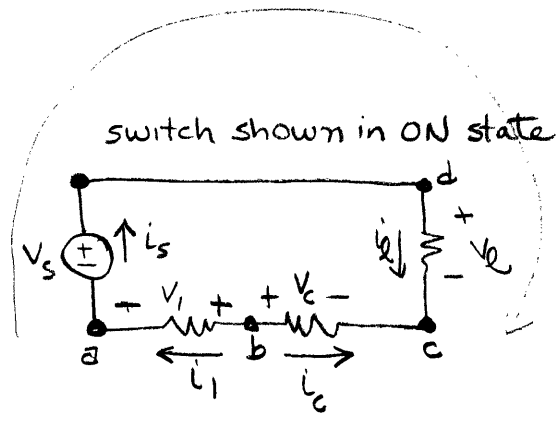
v_t	i_t
-40	-10
-20	-5
0	0
20	5
40	10



Note $V = k i$
 where k must be a constant resistance.

2.4 Kurehoff's Law's

battery example



V_s known

$i_s, i_e, V_e, V_l, i_l, V_c, i_c$ are unknown

$$\left. \begin{aligned} V_l &= i_l R_l \\ V_c &= i_c R_c \\ V_e &= i_e R_e \end{aligned} \right\}$$

3 equations in 6 unknowns
 R 's are known.

want to solve for these

Kurehoff's voltage laws & current law have additional constraints that let us solve for the remaining unknowns.

node \triangleq point at which two or more circuit elements join
 a, b, c, d are nodes in above diagram

KCL: The algebraic sum of the currents at any node is zero.

You can choose + to be into the node or - to be into the node but you MUST be consistent at each node.

applying to battery circuit: positive sign leaving

$$\left. \begin{aligned} a: \quad i_s - i_l &= 0 \\ b: \quad i_l + i_c &= 0 \\ c: \quad -i_c - i_e &= 0 \\ d: \quad -i_s + i_e &= 0 \end{aligned} \right\} \begin{aligned} &4 \text{ more equations} \\ &\text{only 3 of which are independent} \\ &\text{need one more equation} \end{aligned}$$

KVL: The algebraic sum of all the voltages around any closed path in a circuit is zero
must choose a direction clockwise in this case

$$-V_s + V_e - V_c + V_l = 0$$

7 equations in 7 unknowns is a mess to solve.

observations

1. use Ohm's Law to eliminate variables
reduces number of equations
2. you only need one current if only
two components connect at a node

I. lab reports

1. Statement of lab goals (short)
2. Response to questions posed
3. Graphics where appropriate - data analyses.
4. Special observations -
 - Comments on lab reasonableness
 - Suggestive.

II. Lockers = names on labels

- not responsible for losses
- locks to be removed at end of semester

III. Horowitz & Hill is NOT required.

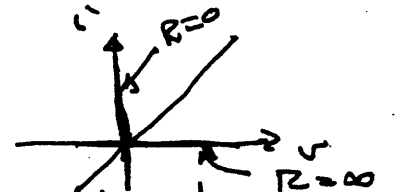
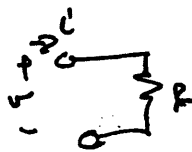
4 copies on 2 hour reserve at Sears.

IV. Judd Gardner lectures M-Th 1430-1700.

CIRCUIT ELEMENTS

Resistor

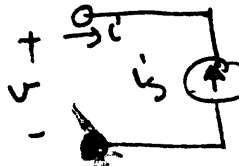
$V = iR$
Ohm's law



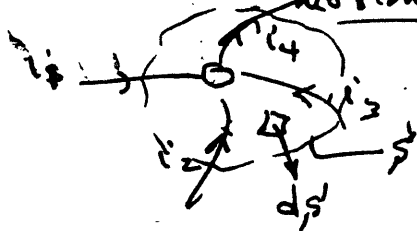
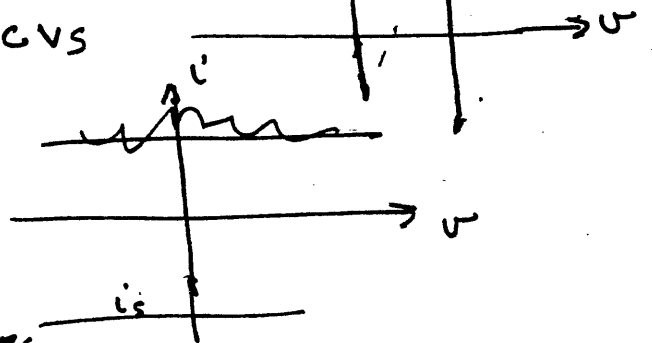
Voltage source

also DCVS, CCVS

Current Source



$i = -i_s$
explain by
two forms of charges



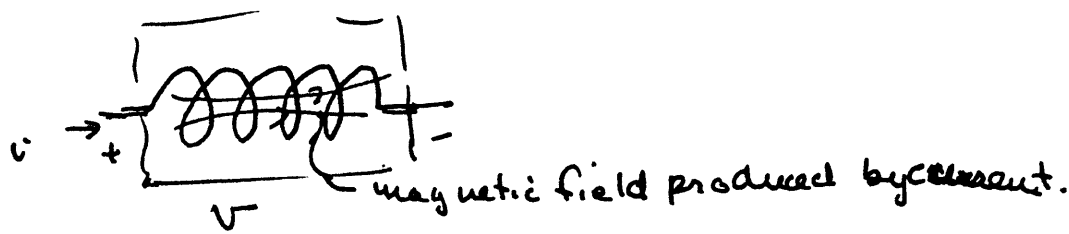
$$\oint_S \mathbf{J} \cdot d\mathbf{s}' = 0 = -i_1 - i_2 + i_4 - i_3 = 0$$

↑
outward

KCL

NEW ELEMENTS - Chapter 7 pps 227-240 of text.

① The inductor



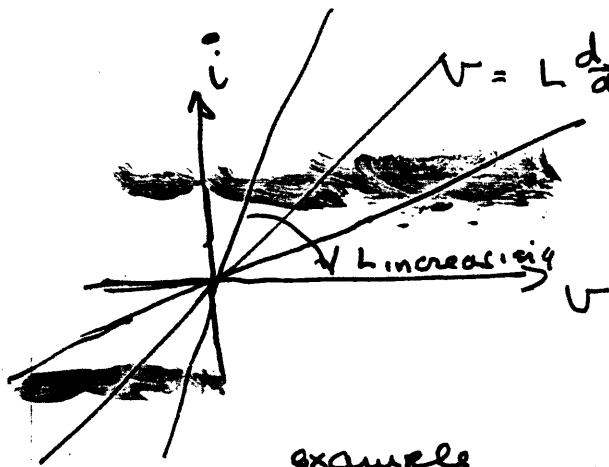
The terminal relationship is based upon Maxwell's equation

$$\oint \underline{E} \cdot d\underline{l} = -\frac{d}{dt} \oint \underline{B} \cdot d\underline{s}$$

$$\downarrow$$

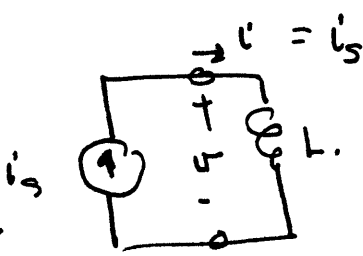
$$-v = -\frac{di}{dt} \oint \underline{k}_L \cdot d\underline{s}$$

$B \sim i$ unless
 $B = \frac{\mu_0}{4\pi} \frac{N^2}{l} i$
 geometric factor

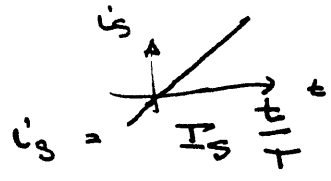


$v = L \frac{di}{dt} + i \frac{dL}{dt}$ \leftarrow this is inductance, L (henrie)
~~we cannot plot (i, v) except for specific cases. we can plot i, v~~
 geometry, not current, nor time varying.

example



constant
 $i_s = I_s \neq I_s(t)$
 $v = 0$

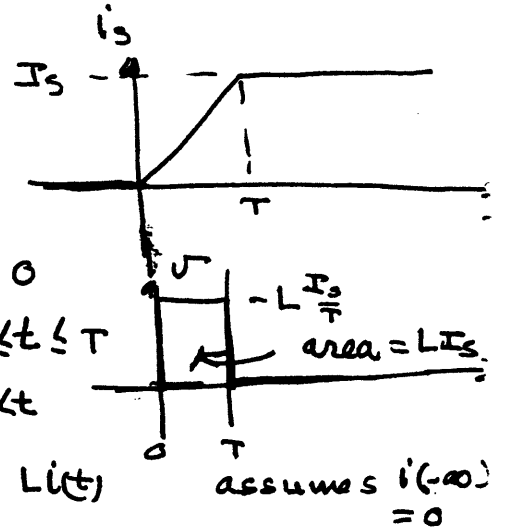


$$\frac{di}{dt} = \frac{di_s}{dt} = \frac{d(I_s/\tau)}{dt} = \frac{I_s}{\tau}$$

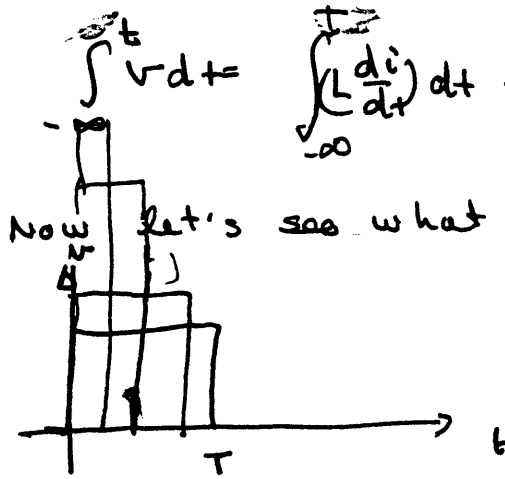
hence $v = \frac{L I_s}{\tau}$

11/22/93

$$i_s = \begin{cases} 0 & t < 0 \\ I_s \frac{t}{T} & 0 \leq t \leq T \\ I_s & T < t \end{cases}$$



$$V = L \frac{di}{dt} = L \frac{di}{dt} = \begin{cases} 0 & t < 0 \\ L \frac{I_s}{T} & 0 \leq t \leq T \\ 0 & t > T \end{cases}$$



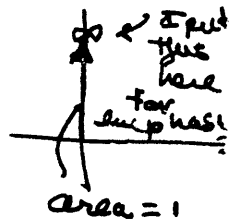
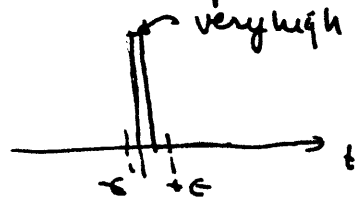
Now let's see what happens as T gets smaller.

even as $T \rightarrow 0$ the area must be LI_s , so the height must go to ∞ that is, infinite volts for an infinitesimal time

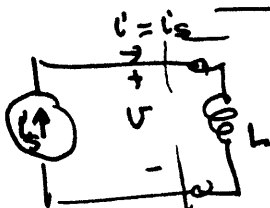
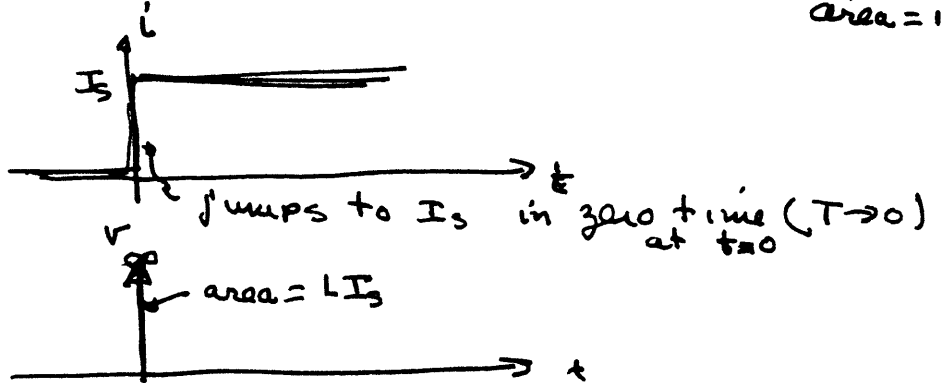
but the area is constant (LI_s). The function which has zero width and finite unit area (infinite height) is called an impulse $\delta(t)$

$$\int_{t=-\epsilon}^{t=+\epsilon} \delta(t) dt = 1$$

as $\epsilon \rightarrow 0$



So if



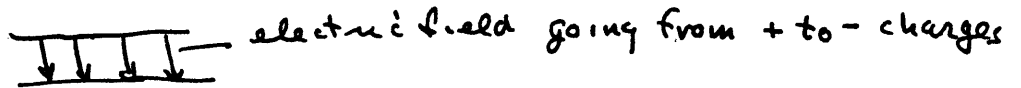
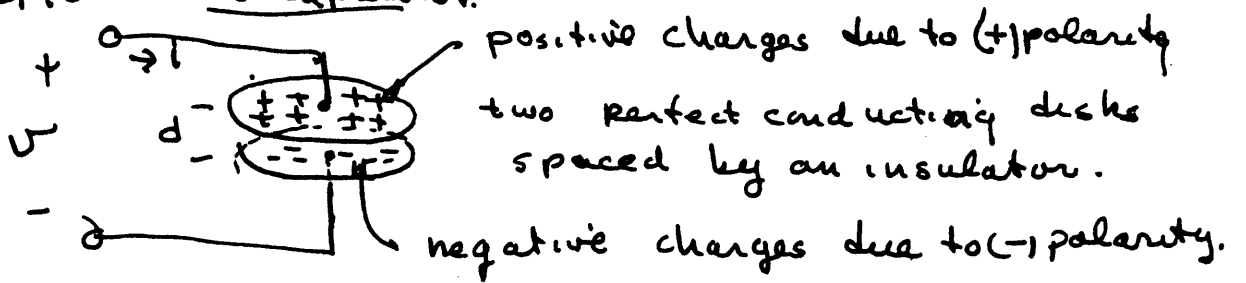
let $i_s = I_s \cos \omega t$ for all time

$$V = L \frac{di_s}{dt} = -\omega L I_s \sin \omega t$$

while i_s current varies as a cosine, v voltage varies as a sine

1/22/93

The capacitor.



Maxwell's continuity equation

$$\oint \mathbf{J} \cdot d\mathbf{S} + \frac{d}{dt} \int \epsilon \mathbf{E} \cdot d\mathbf{V} = 0$$

Total Charges on a surface are proportional to the voltage.

$q = CV$ the constant of proportionality

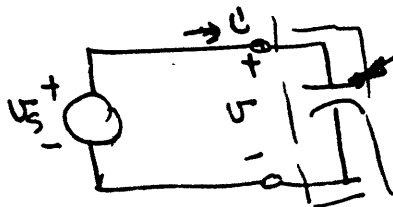
is the capacitance. But we know $i = \frac{dq}{dt}$

So $i = \frac{d(q)}{dt} = \epsilon \frac{dV}{dt} + V \frac{d\epsilon}{dt}$ by chain rule.

if the capacitance is not time varying (fixed geometry) then

ended here $i = C \frac{dV}{dt}$
here $\approx 1/22$

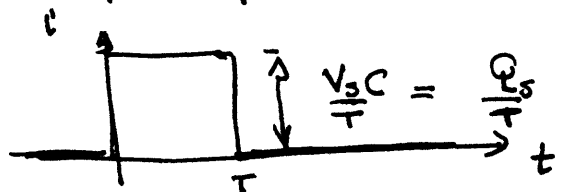
which works for this course



Symbol for capacitor

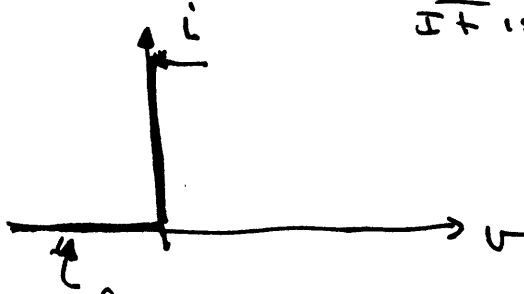
units are farads

$$V = V_s(t) = \begin{cases} 0 & t < 0 \\ V_s \frac{t}{T} & 0 \leq t \leq T \\ V_s & t > T \end{cases}$$



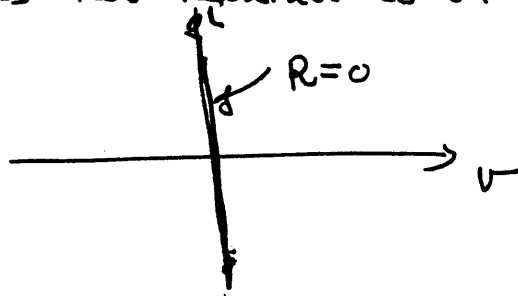
remember dimensions $i = \text{charge} / \text{time}$ [Coulombs/sec]

1/22/93 Another new element - a diode (ideal for now).
 This is our first non-linear element.
 It is defined by the $v-i$ characteristic



$$i = 0 \quad \text{for } v < 0 ;$$

i can be anything for $v = 0$, note that it won't allow v to be non-zero. What does this remind us of?



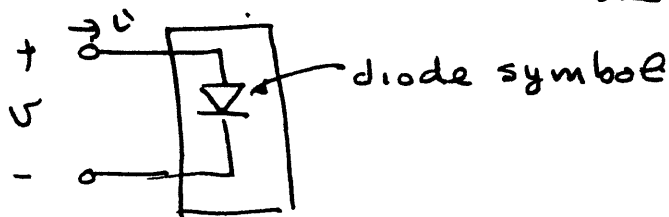
so for any attempt to get $v > 0$ it becomes a short circuit! in a sense, the diode is a voltage controlled resistor

$$R = \infty$$

$$v < 0$$

$$R = 0$$

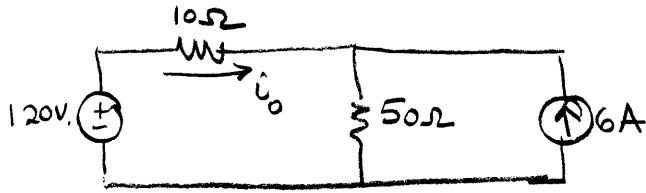
$v = 0$. Again, it won't let v be non-zero positive like a switch



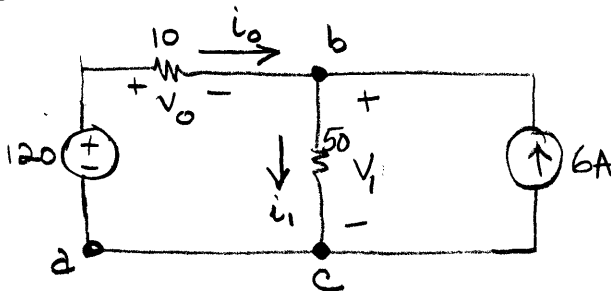
Example 2.8

(a) Use Kirchoff's laws and Ohm's Law to find i_0 in the circuit shown in Fig. 2.20.

(b) Test the solution by verifying that the total power generated equals the total power dissipated



redraw



in PSpice you number the reference node (usually ground) as zero. All others are positive numbers

How many unknowns: i_0, i_1

$V_0 \& V_1$ are known thru Ohm's Law

need two equations in two unknowns

KCL at either c or b: at b using + in

$$\sum i = 0 \quad i_0 - i_1 + 6 = 0$$

need second equation

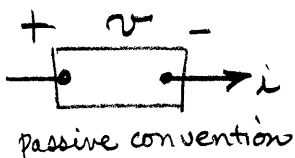
KVL around a-c-b

$$\sum V = 0 \quad -120 + V_0 + V_1 = 0$$

$$-120 + i_0 \cdot 10 + 50i_1 = 0$$

$$\left. \begin{aligned} i_0 - i_1 &= -6 \\ 10i_0 + 50i_1 &= +120 \end{aligned} \right\} \text{2 equations in two unknowns}$$

$$i_0 = -3A \quad i_1 = 3A$$



$$P_{120V} = -vi = (120V)(-3) = +360W$$

power absorbed.

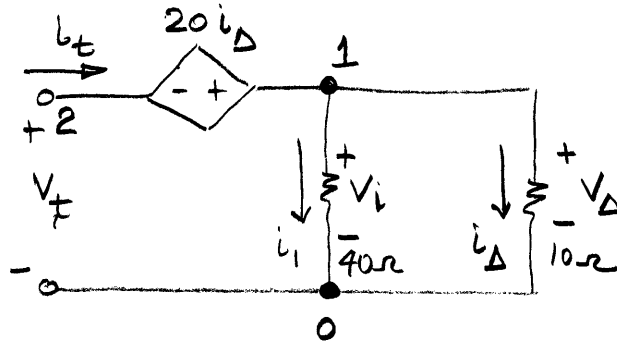
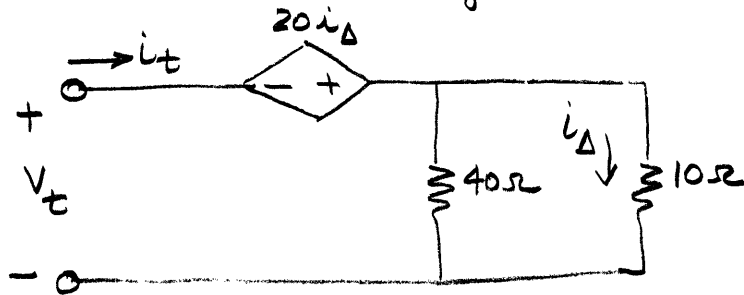
↑
opposite to correct passive convention

$$V_1 = 50i_1 = 150V$$

$$P_{6A} = -(v)(i) = -(150)(6) = -900W$$

calculate others the same way.

In section 2.2 we mentioned that a negative resistance can appear in the circuit model of a device. With this thought in mind, verify that the circuit inside the dashed box can be modeled with a negative resistance.



at node 1:

+ going in use KCL $+i_t - i_1 - i_\Delta = 0$ (1)

using KVL around (clockwise) outside loop.

$$-V_t - 20i_\Delta + V_\Delta = 0. \quad (2)$$

Solve (2) for V_t
and using
Ohm's Law

$$V_t = -20i_\Delta + V_\Delta = -20i_\Delta + 10i_\Delta = -10i_\Delta$$

now, using (1)

$$i_t = i_1 + i_\Delta \quad (3)$$

$$V_1 = V_\Delta$$

using Ohm's Law $i_1 \cdot 40 = i_\Delta \cdot 10$

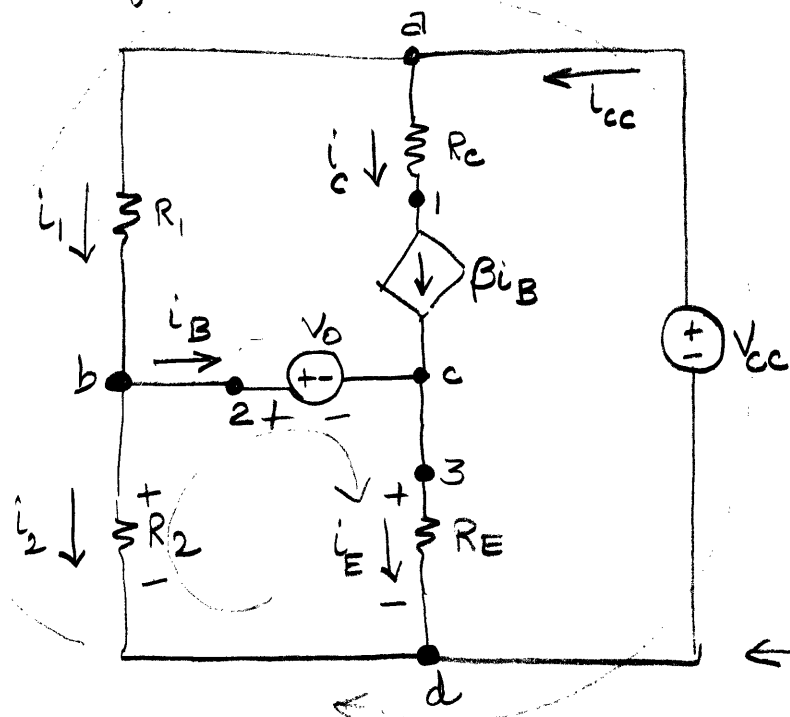
← this point is not made clearly enough in textbook V_1 and V_Δ in parallel

Now use this for i_1 in (3) $i_t = i_1 + i_\Delta = i_\Delta \left(\frac{10}{40}\right) + i_\Delta = 1.25i_\Delta$

at terminals

$$R_t = \frac{V_t}{i_t} = \frac{-10i_\Delta}{1.25i_\Delta} = -8\Omega$$

2.5 Analysis of a circuit containing a dependent source



- These are consequences of Kirchhoff's Laws.
- ① currents thru things in series are the same
 - ② voltages across things in parallel are the same.

← this would be node ϕ in PSpice

all resistors V_{cc} , V_0 and β are known.

use currents as your unknowns: 6 unknowns

KCL @ a,b,c use out as positive

$$\begin{aligned} a: & \quad +i_1 + i_c - i_{cc} = 0 \quad (1) \\ b: & \quad -i_1 + i_2 + i_B = 0 \quad (2) \\ c: & \quad -i_B - i_c + i_E = 0 \quad (3) \end{aligned}$$

3 equations in 6 unknowns.

controlled sources always produce constraints

$$i_c = \beta i_B \quad (4)$$

Now use KVL to get two more equations

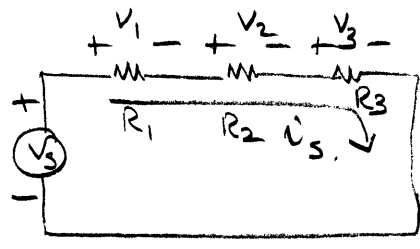
DO NOT DO KVL across a current source!

$$bcdb: \quad -i_2 R_2 + V_0 + i_E R_E = 0$$

$$badb: \quad -i_2 R_2 - i_1 R_1 + V_{cc} = 0$$

$$\text{Solve: } i_B = \frac{\frac{V_{cc} R_2}{R_1 + R_2} - V_0}{\frac{R_1 R_2}{R_1 + R_2} + (1 + \beta) R_E}$$

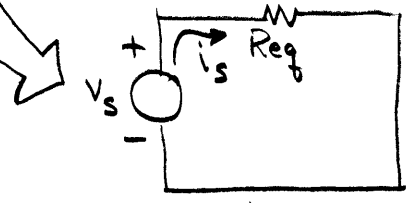
3.1 Resistors in Series



know currents will be the same
 voltage is known by Ohm's Law.

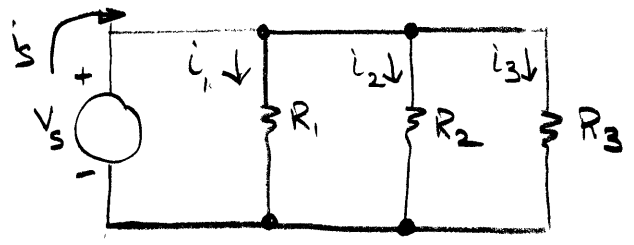
$$\text{KVL} \quad -V_s + i_s R_1 + i_s R_2 + i_s R_3 = 0.$$

$$V_s = i_s (R_1 + R_2 + R_3) = i_s R_{eq}$$



$$R_{eq} = \sum_{i=1}^n R_i$$

3.2 Resistors in parallel



know voltages across R_1, R_2, R_3 will be the same
 from ohm's law

$$V_s = V_1 = V_2 = V_3$$

$$V_s = i_1 R_1 = i_2 R_2 = i_3 R_3$$

$$i_1 = \frac{V_s}{R_1} \quad i_2 = \frac{V_s}{R_2} \quad i_3 = \frac{V_s}{R_3}$$

using KCL (+out)

$$-i_s + i_1 + i_2 + i_3 = 0$$

$$i_s = \frac{V_s}{R_1} + \frac{V_s}{R_2} + \frac{V_s}{R_3} =$$

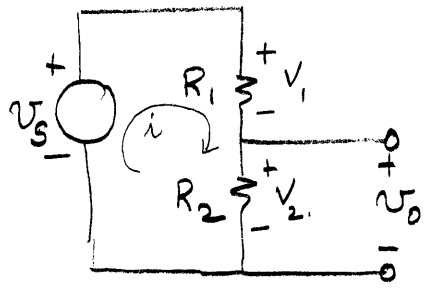
$$V_s \left(\frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} \right)$$

$$\frac{1}{R_{eq}} = \frac{i_s}{V_s} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3}$$

Very important special case, 2 resistors in parallel

$$R_{eq} = \frac{R_1 R_2}{R_1 + R_2}.$$

3.3 Voltage Divider Circuit



assume clockwise current i

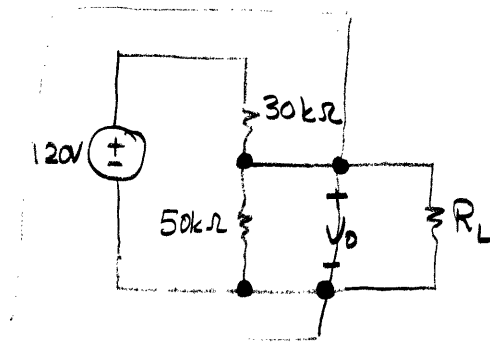
$$-v_s + v_1 + v_2 = 0$$

$$-v_s + iR_1 + iR_2 = 0$$

$$i = \frac{v_s}{R_1 + R_2}$$

$$v_o = v_2 = iR_2 = \frac{R_2}{R_1 + R_2} v_s \quad \blacksquare$$

Drill Exercise 3.2

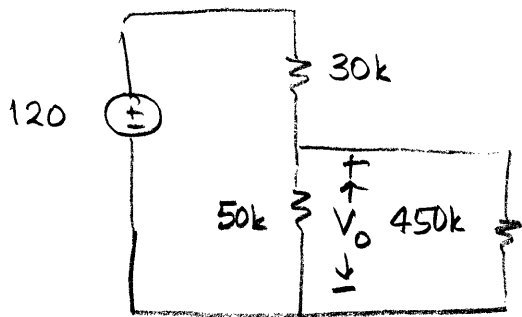


(a) Find the no-load value of v_o in the circuit shown.

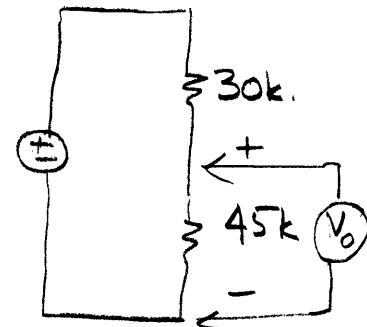
By inspection it's a voltage divider

$$v_o = \frac{50k}{30k + 50k} 120 = \frac{5}{8}(120) = 75V.$$

(b) Find v_o when R_L is $450k\Omega$.



⇒



$$R = \frac{50 \cdot 450}{50 + 450} = 45$$

Now use voltage divider

$$v_o = \frac{45k}{45k + 30k} (120) = 72 \text{ Volts lower.}$$

Chapter 4

Reading

4.1, 4.2 (Intro only), 4.5 (4.6, 4.7?)
 4.8 4.9, 4.10, 4.11
 Thevenin & Norton
 4.13 superposition

4.1 terminology

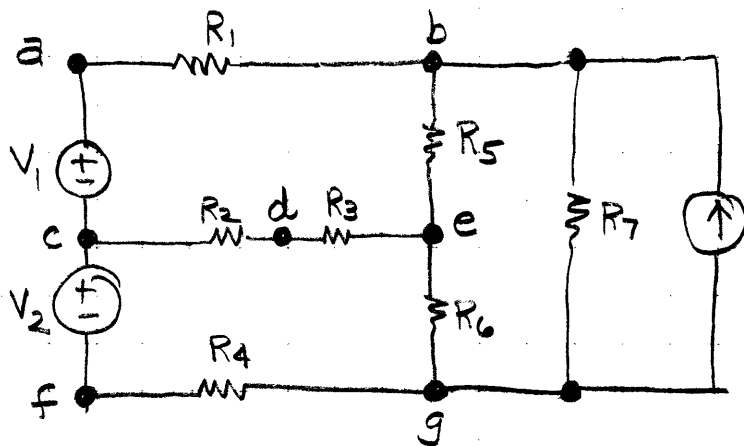
nodes - point where 2 or more circuit elements join

path - formed when a set of adjoining basic circuit elements is traced, in order, without passing through a connecting node more than once.

branch - path that connects two nodes

mesh - special type of loop that doesn't contain any other loops within it.

closed path (loop) - start at a selected node, trace a set of connected basic circuit elements and return to the original starting node without passing through any intermediate node more than once.



seven nodes: a, b, c, d, e, f, g.

ten branches: $V_1, R_1, R_2, R_3, V_2, R_4, R_5, R_6, R_7, I$

four meshes: $V_1 - R_1 - R_5 - R_3 - R_2$, $V_2 - R_2 - R_3 - R_6 - R_4$
 $R_5 - R_6 - R_7$, $R_7 - I$

also several loops that are not meshes $V_1 - R_1 - R_5 - R_6 - R_4 - V_2$, etc.

essential nodes \rightarrow connect three or more elements
i.e. c and b

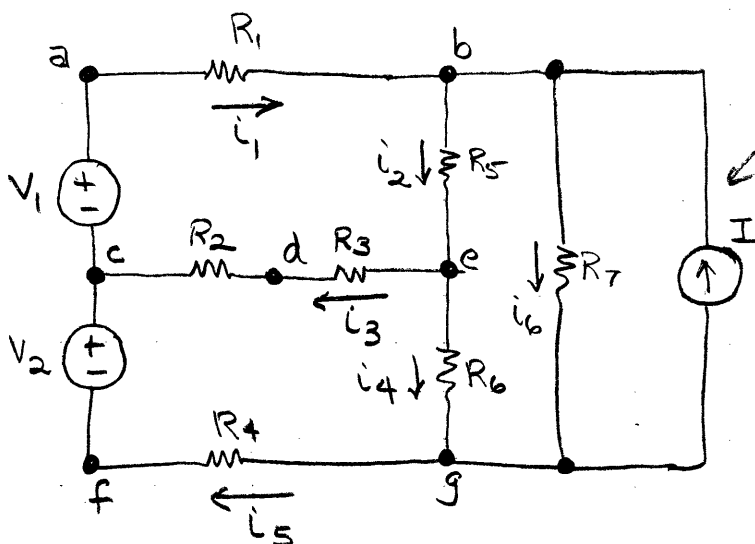
essential branches \rightarrow connect essential nodes without passing through essential nodes.
i.e. $v_1 - R_1$

simultaneous equations # of nodes = n
of branches = b
KCL to $n-1$ junctions to get $n-1$ equations

KVL to $b-(n-1)$ meshes to get $b-(n-1)$ independent eqns.

illustration of the systematic approach.

Fig. 4.4.



4,7 more about current sources!

four essential nodes
b, c, e, g

six essential branches

$V_1 - R_1$
 $R_2 - R_3$
 $V_2 - R_4$

R_5
 R_6
 $R_7 (I)$

unknowns - correspond to branches.

apply KCL at nodes b, c, e 3 essential nodes.

+ out @ b $-i_1 + i_2 + i_6 - I = 0$

+ out @ c $i_1 - i_3 - i_5 = 0$

can only do $n-1$

+ out @ e $i_3 + i_4 - i_2 = 0$

now derive loop equations using KVL need 3 can't use $R_7 - I$.

abec $R_1 i_1 + R_5 i_2 + i_3 (R_2 + R_3) - v_1 = 0$

cegf $-i_3 (R_2 + R_3) + i_4 R_6 + R_4 i_5 - v_2 = 0$

bg $-i_2 R_5 + i_6 R_7 - i_4 R_6 = 0$

re-arrange in form of matrix

$$\begin{array}{rcccccc}
 -i_1 & i_2 & - & - & - & i_6 = I \\
 i_1 & & -i_3 & & -i_5 & = 0 \\
 & -i_2 & +i_3 & i_4 & & = 0 \\
 R_1 i_1 & R_5 i_2 & (R_2 + R_3) i_3 & & & = v_1 \\
 & & -(R_2 + R_3) i_3 & R_6 i_4 & R_4 i_5 & = v_2 \\
 & R_5 i_2 & & -R_6 i_4 & & R_7 i_6 = 0.
 \end{array}$$

6 equations in 6 unknowns.

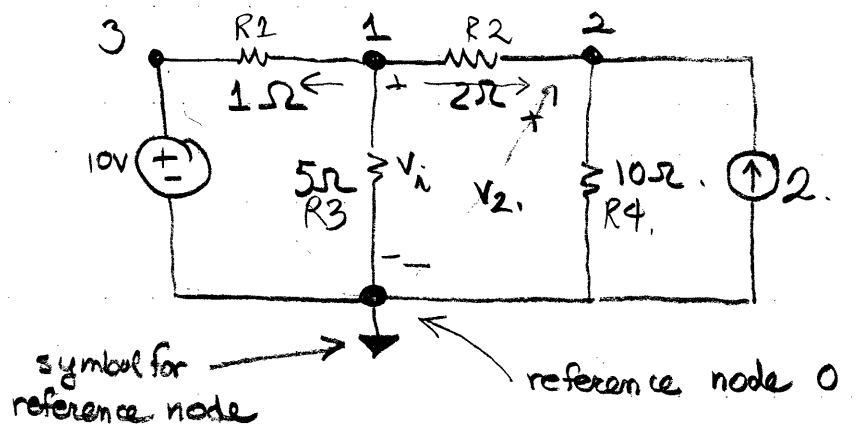
new methods allow us to use fewer equations:
 specifically $n-1$ equations by using new variables

node-voltage $n-1$ equations

mesh-current $b-(n-1)$ equations.

How computer analysis works

4.2 Node-voltage method. (refers to KCL at each node).



1. draw a planar circuit with no branches crossing
2. label reference mode as zero
3. label all other modes
 all [^]voltages are with respect to this reference mode.
 nod
4. apply KCL at every essential node.

at node 1
+ out

$$\frac{V_1 - 10}{1} + \frac{V_1}{5} + \frac{V_1 - V_2}{2} = 0$$

$V_1 < V_2$

at node 2
+ out

$$\frac{V_2 - V_1}{2} + \frac{V_2}{10} - 2 = 0$$

$$10V_1 - 100 + 2V_1 + 5V_1 - 5V_2 = 0.$$

$$5V_2 - 5V_1 + V_2 - 20 = 0.$$

$$17V_1 - 5V_2 = 100$$

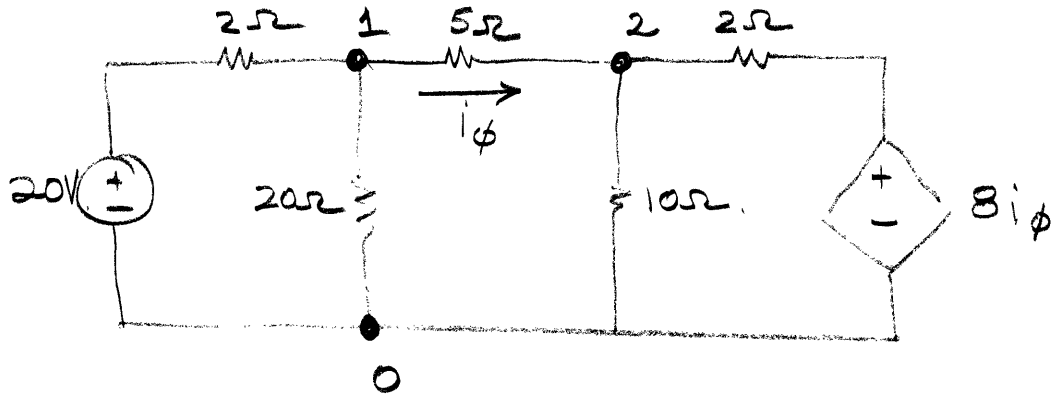
$$-5V_1 + 6V_2 = 20$$

according to book: $V_1 = \frac{100}{11} = 9.09V$

$$V_2 = \frac{120}{11} = 10.91V.$$

Node voltage and dependent sources:

how to add dependent sources to node-voltage analysis



at 1:
+ out

$$\frac{v_1 - 20}{2} + \frac{v_1}{20} + \frac{v_1 - v_2}{5} = 0.$$

at 2:
+ out

$$\frac{v_2 - v_1}{5} + \frac{v_2}{10} + \frac{v_2 - 8i_\phi}{2} = 0.$$

opposite

2 eqms in 3 unknowns v_1, v_2, i_ϕ

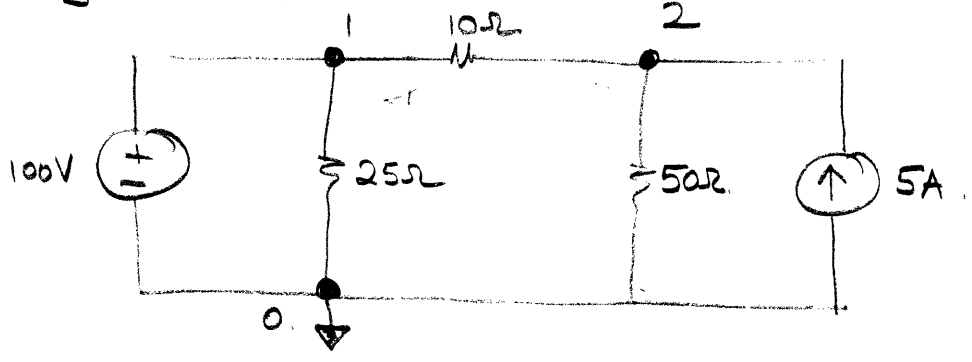
need source equation to finish

$$i_\phi = \frac{v_1 - v_2}{5}$$

add a constraint equation.

special problems: voltage sources...

only a voltage source in branch between 0 and 1.



problem: what is current from voltage source.
 solution: write as difference of voltages.
 look at node 2: + out.

$$\frac{v_2 - v_1}{10} + \frac{v_2}{50} - 5 = 0.$$

assume $v_2 > v_1$
 then use passive current convention which is + ←

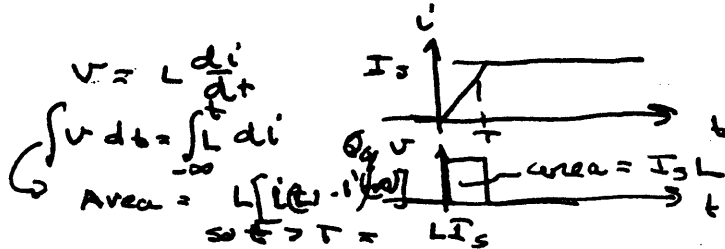
then looking at circuit shows $v_1 = 100V$ so no problem.

⇒ voltage sources reduce # of equations

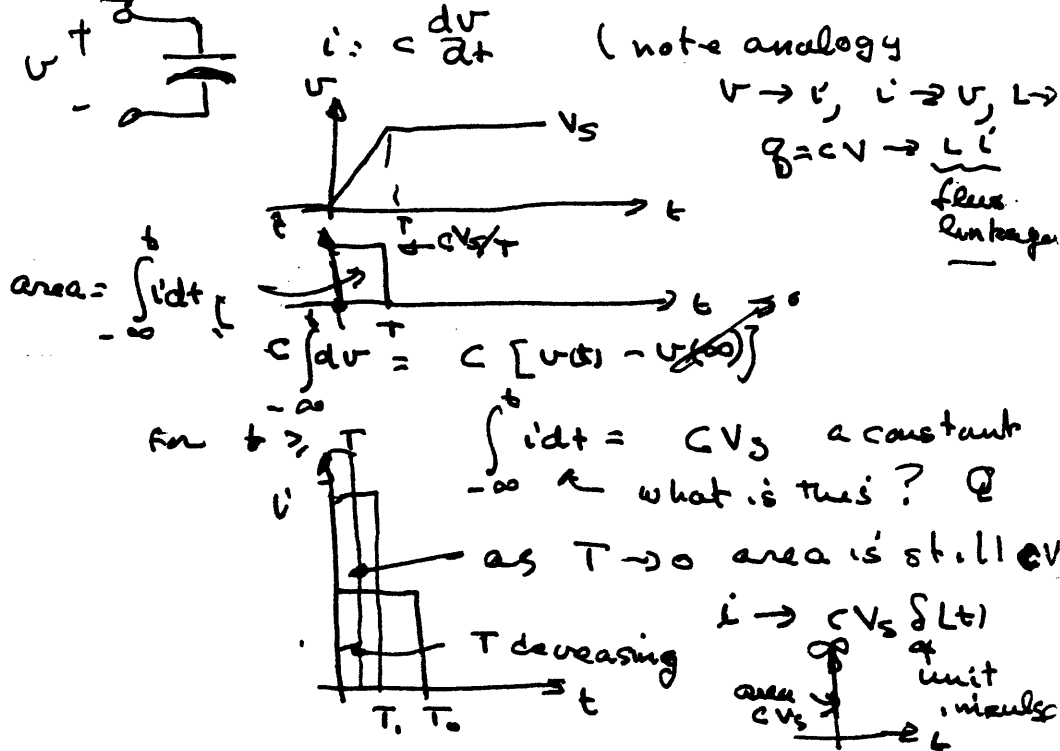
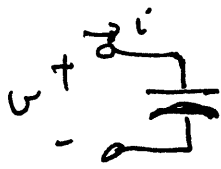
LAB ANNOUNCEMENTS

1. KITS SHOULD BE COMPLETED & TESTED BY FEB 3,
2. LAB 1 DO 2/5
3. DO NOT DIG INTO THE EQUIPMENT - NOR MOVE IT!

INDUCTOR



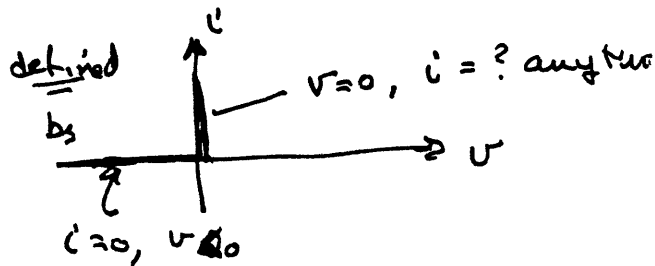
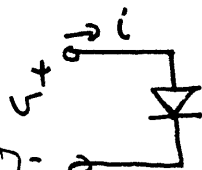
CAPACITOR



New Element
IDEAL DIODE

NON-LINEAR ELEMENT

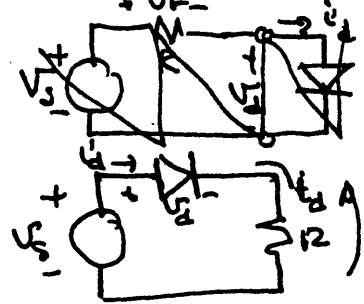
It is like a voltage controlled switch.



flow

NOTE arrow points in direction of possible current flow

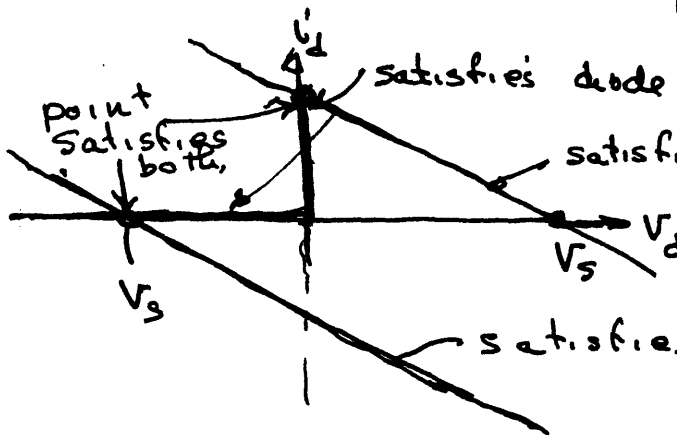
let's examine this circuit



KVL $\Rightarrow +V_s - i_D R - V_D = 0$
 $\sum \text{voltage rises} = 0$

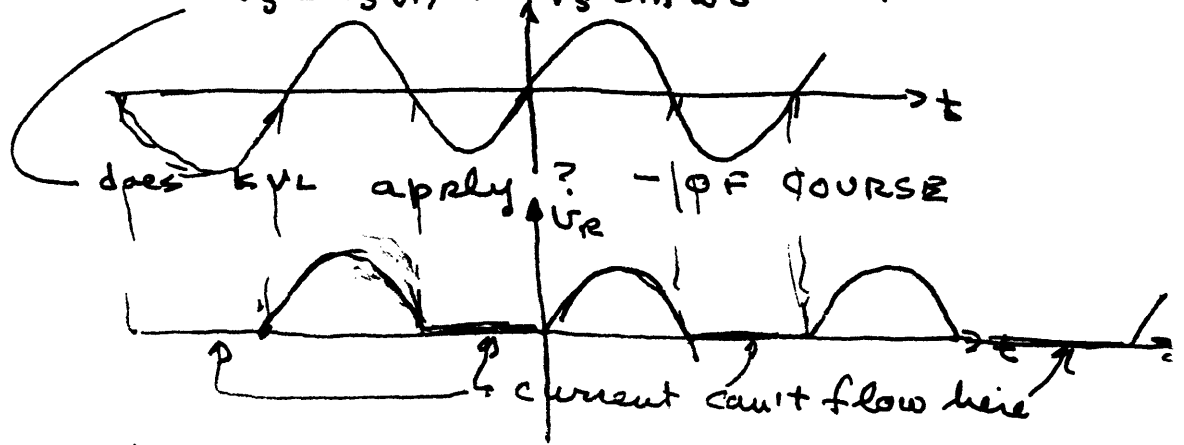
$V_R = i_D R$

$V_D = V_s - i_D R$
 if $V_s > 0$ then current can flow
 $0 = V_s - i_D R, V_R = V_s$
 if $V_s < 0$ no current can flow
 $V_D = V_s$ ($V_s < 0$)
 and $V_R = 0$



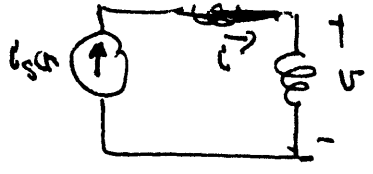
which doesn't necessarily satisfy diode

what if $V_s = V_s(t) = V_s \sin \omega t$?



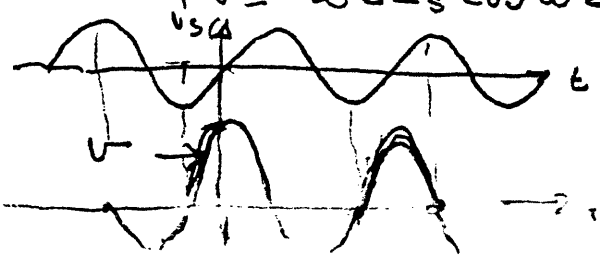
does KVL apply? - | PF COURSE

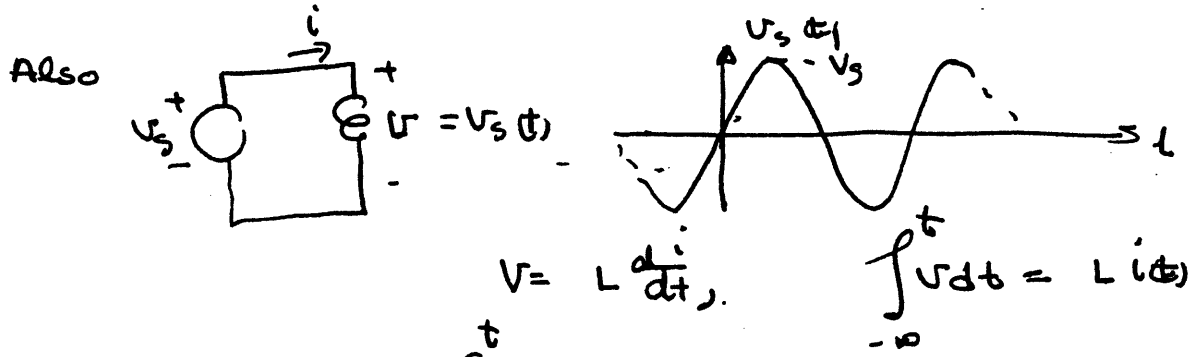
Now that we've introduced a time-varying source let's examine the case for a current source $i_s(t) = I_s \sin \omega t$ and an inductor, L.



$V = L \frac{di}{dt} = L \frac{di_s}{dt}$

$V = \omega L I_s \cos \omega t$





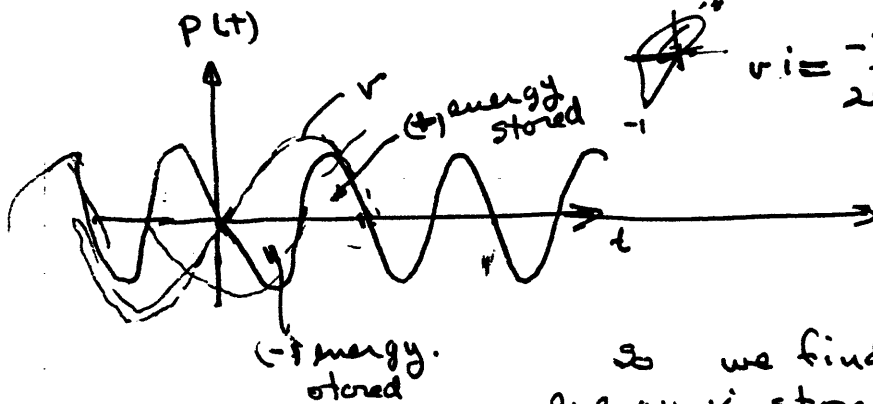
$$\frac{1}{L} V_s \int \sin \omega t dt = i(t)$$

$$-\frac{V_s}{\omega L} \cos \omega t = i(t)$$

check it $L \frac{d}{dt} \left(-\frac{V_s}{\omega L} \cos \omega t \right) = V_s \sin \omega t$ (OK)

power = $p(t) = v i = V_s \sin \omega t \times \left(-\frac{V_s}{\omega L} \cos \omega t \right)$
 into inductor

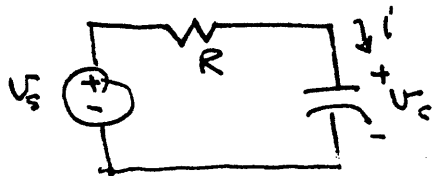
$$\sin A \cos B = \frac{1}{2} [\sin(A-B) + \sin(A+B)]$$



$$v i = -\frac{V_s^2}{2\omega L} [\sin 2\omega t]$$

so we find that alternately energy is stored then returned to the source

source power input = $-V_s i$ (sign convention)



KVL $v_s - iR - v_c = 0$

and $i = C \frac{dv_c}{dt}$ so we

arrive at a single equation for v_c in terms of v_s , C , and R

$$v_s - RC \frac{dv_c}{dt} - v_c = 0 \quad \leftarrow v_c \text{ is the unknown}$$

$$RC \frac{dv_c}{dt} + v_c = v_s \quad \leftarrow \text{source}$$

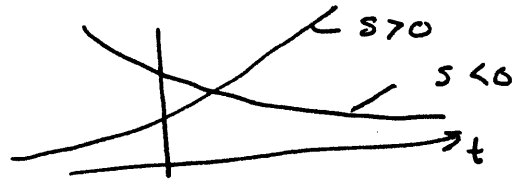
called a linear differential equation with constant coefficients

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(4)

How to solve? Let's use a source that

is $V_s(t) = V_s e^{st}$



note that if we guess that $V_c = V_c e^{st}$ as well then substitute unknown constant (not function of t)

$$RCsV_c e^{st} + V_c e^{st} = V_s e^{st}$$

Notice e^{st} factor throughout.

An exponential is returned when a derivative (or integral) is taken and this is very important

$$\frac{d}{dt}(e^{st}) = s e^{st}$$

same time dependence.

$$[RCsV_c + V_c - V_s] e^{st} = 0$$

this must be zero

if this is non-zero then

$$V_c = \left[\frac{V_s}{1+RCs} \right]$$

creates a good solution - check by substitution

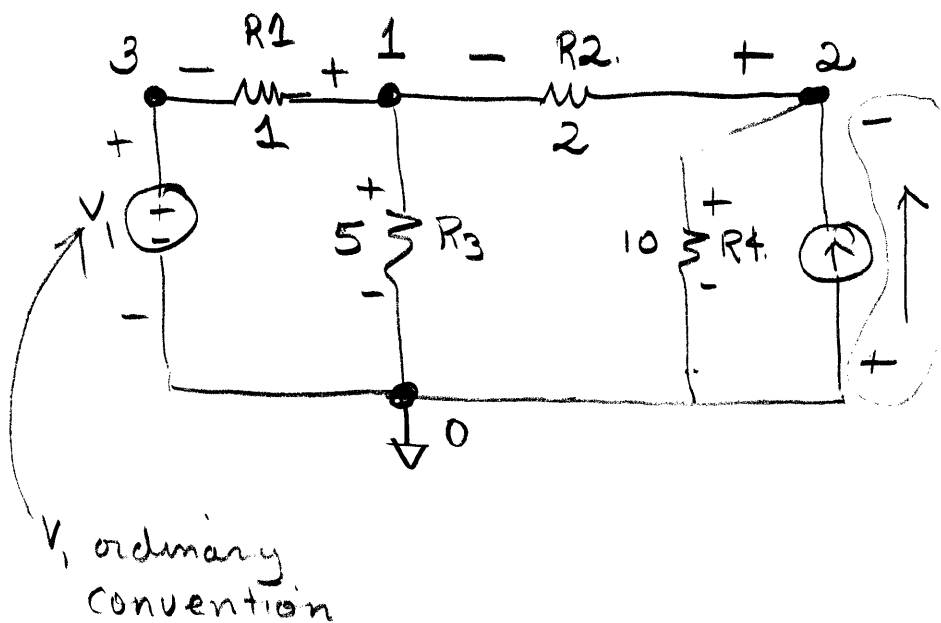
$$RCs \left[\frac{V_s}{1+RCs} \right] e^{st} + \frac{V_s}{1+RCs} e^{st} = V_s e^{st} !!$$

OK.

```

Problem 4.2
V1 3 0 DC 10
I1 0 2 DC 2
R1 1 3 1
R2 2 1 2
R3 1 0 5
R4 2 0 10
.PROBE
.END

```



calculated

$$V(1) = +9.0909$$

$$V(2) = +10.9090$$

$$V(3) = +10.0000$$

$$V1 \text{ current} = -9.091E-01$$

**** 01/27/93 17:54:08 ***** Evaluation PSpice (Jan 1992) *****

Problem 4.2

**** CIRCUIT DESCRIPTION

```
U1 3 0 DC 10
I1 0 2 DC 2
R1 1 3 1
R2 2 1 2
R3 1 0 5
R4 2 0 10
.PROBE
.END
```

**** 01/27/93 17:54:08 ***** Evaluation PSpice (Jan 1992) *****

Problem 4.2

**** SMALL SIGNAL BIAS SOLUTION TEMPERATURE = 27.000 DEG C

NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE

(1) 9.0909 (2) 10.9090 (3) 10.0000

VOLTAGE SOURCE CURRENTS
NAME CURRENT

U1 -9.091E-01

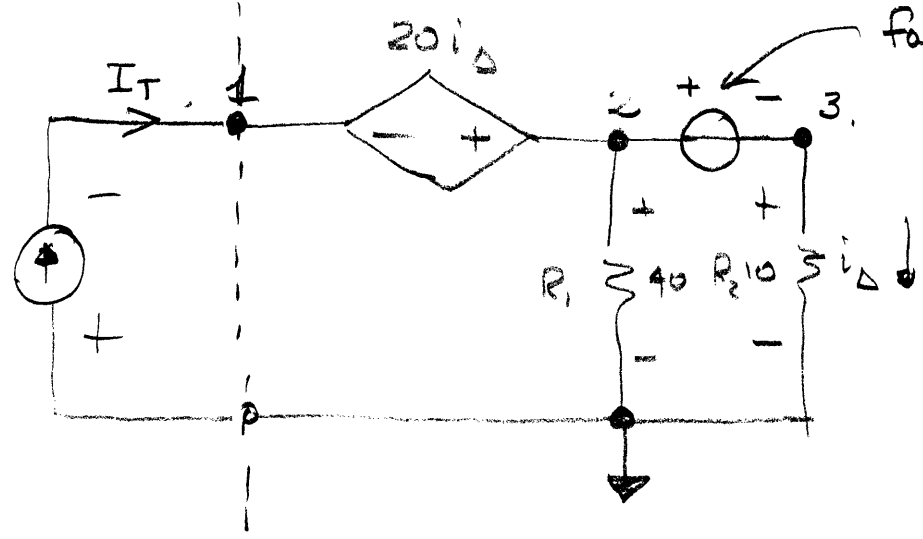
TOTAL POWER DISSIPATION 9.09E+00 WATTS

JOB CONCLUDED

TOTAL JOB TIME .72

$$R = \frac{V}{I}$$

Problem: want to know I_T .



fake zero value voltage source V_{Δ} .
i.e. a volt meter.

PSPICE Program

* Equivalent Resistance.

I1 0 1 DC 1A.

H1 2 0 Vdelta 20

fake see p.10.

Vdelta 2 3 DC 0

R1 2 0 40

R2 3 0 10

.END.

called transresistance

this is a current controlled voltage source.

**** 01/27/93 18:19:58 ***** Evaluation PSpice (Jan 1992) *****

* Equivalent Resistance calculation

**** CIRCUIT DESCRIPTION

I1 0 1 DC 1A
H1 2 1 Udelta 20
Udelta 2 3 DC 0
R1 2 0 40
R2 3 0 10
.END

ADD ,DC I1 0.1 20 0.1
↑ ↑ ↑
start stop increment
to sweep values

**** 01/27/93 18:19:58 ***** Evaluation PSpice (Jan 1992) *****

* Equivalent Resistance calculation

**** SMALL SIGNAL BIAS SOLUTION TEMPERATURE = 27.000 DEG C

NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE

(1) -8.0000 (2) 8.0000 (3) 8.0000

VOLTAGE SOURCE CURRENTS
NAME CURRENT

Udelta 8.000E-01

TOTAL POWER DISSIPATION 0.00E+00 WATTS

Note I1 was 1A

$V(1) = -8$

$R_{in} = \frac{V(1)}{I(1)} = -8$

JOB CONCLUDED

TOTAL JOB TIME .83

**** 01/27/93 18:27:07 ***** Evaluation PSpice (Jan 1992) *****

* Equivalent Resistance calculation

**** CIRCUIT DESCRIPTION

```

I1  0  1  DC  1A
H1  2  1  Udelta 20
Udelta 2  3  DC  0
R1  2  0  40
R2  3  0  10
.DC  I1  0.1  20  0.1
.PROBE
.END

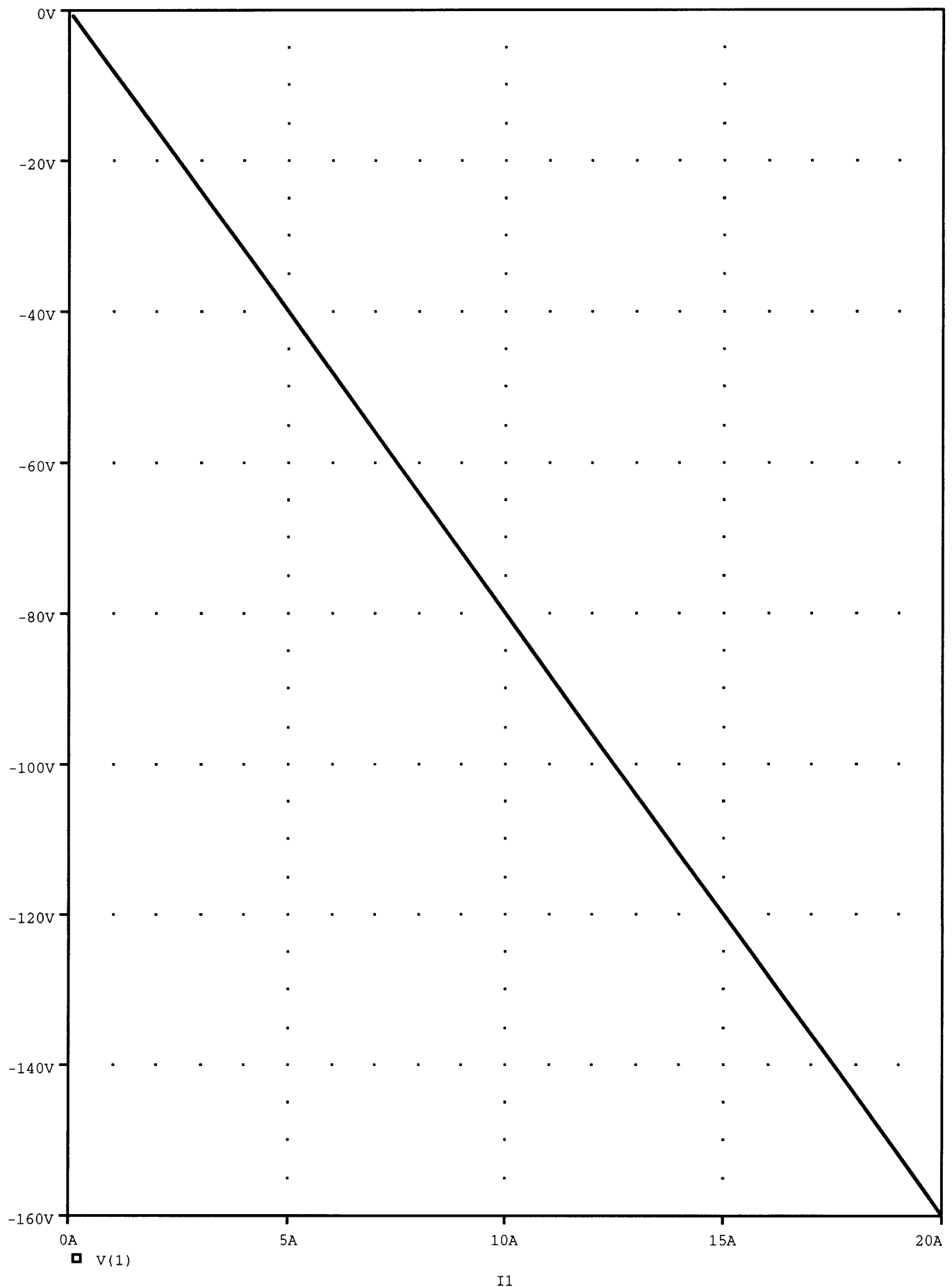
```

← now with DC sweep.

← for probe.

JOB CONCLUDED

TOTAL JOB TIME 5.37



** Equivalent Resistance calculation" 01/27/93 18:27:07 27.0°
Evaluation Probe 5.1 © 1992 MicroSim Corp.

Ref. Tuinenga p. 37

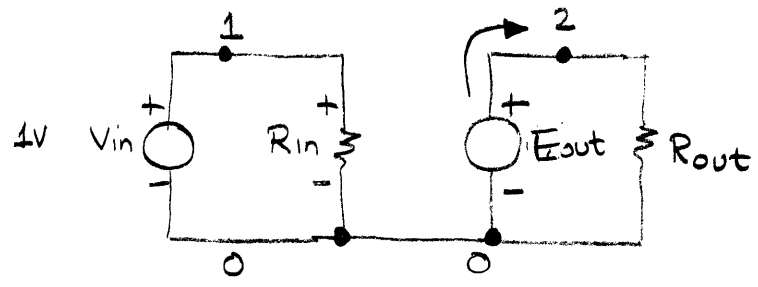
* simple gain circuit

Vin 1 0 DC 1 volt
 Rin 1 0 1 ohm
 Eout 2 0 1 0 5.0
 Rout 2 0 1 ohm

gain

current sources use a reverse notation

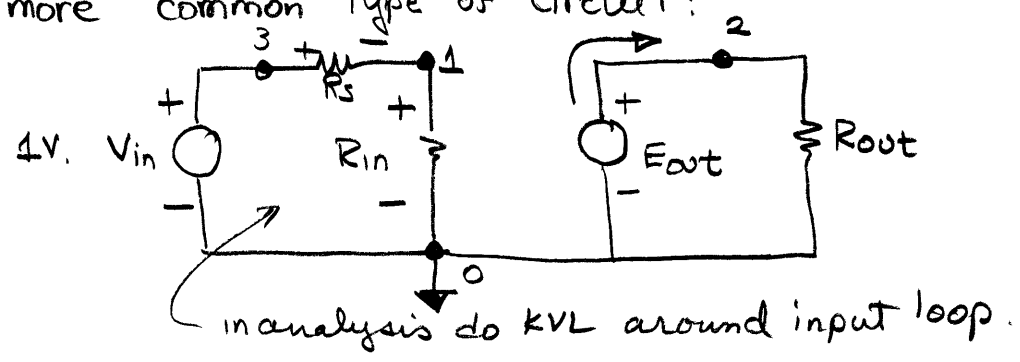
- PROBE
- TF V(2) Vin
- END



Exx voltage controlled voltage source

- E VCVS
- F CCCS
- G VCCS
- H CCVS

more common type of circuit:

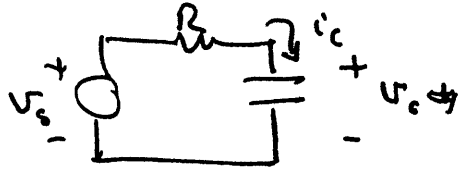


change Vin 3 0 DC 1 volt.
 add RS 3 1 600 ohms.

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unknowns i_c, v_c but $i_c = C \frac{dv_c}{dt}$

we were examining the circuit



$$\text{KVL} \Rightarrow v_s - i_c R - v_c = 0$$

but we know that $i_c = C \frac{dv_c}{dt}$

for the capacitor thus we wind up with

$$RC \frac{dv_c}{dt} + v_c = v_s(t)$$

response
source

$$\text{Suppose that } v_s = \begin{cases} 0 & t \leq 0 \\ \alpha_1 + \beta_1 t + \gamma_1 t^2 & t \geq 0 \end{cases}$$

Then we assume a solution of the same form as the source

$$v_c(t) = \begin{cases} 0 & t < 0 \\ \alpha_2 + \beta_2 t + \gamma_2 t^2 & t \geq 0 \end{cases}$$

and substitute

$$RC [\beta_2 + 2\gamma_2 t] + \alpha_2 + \beta_2 t + \gamma_2 t^2 = \alpha_1 + \beta_1 t + \gamma_1 t^2$$

and equate coefficients of like powers of t

$$\text{hence } RC \beta_2 + \alpha_2 = \alpha_1$$

$$2RC \gamma_2 + \beta_2 = \beta_1$$

$$\gamma_2 = \gamma_1$$

then

$$\beta_2 = \beta_1 - 2RC\gamma_1$$

$$RC [\beta_1 - 2RC\gamma_1] + \alpha_2 = \alpha_1$$

$$\text{or } \alpha_2 = \alpha_1 - RC[\beta_1 - 2RC\gamma_1]$$

But this was an easy example since it involved a "power-series" for the time functions — NOT VERY REALISTIC.

As we shall see later on, we can very often express ~~signals~~ complex, but important, signals as exponentials. One thing we know is that

$$\cos \omega t = \frac{e^{j\omega t} + e^{-j\omega t}}{2} \quad \text{let's use the}$$

funny signal $\frac{1}{2} e^{j\omega t}$ as a source - we shall see shortly that this is a very useful way of writing sinusoidal signals. Then from our previous example - no way can we match the source and response - unless the response varies as $\frac{1}{2} e^{j\omega t}$. So let's assume this as a response

$$RCj\omega V_C e^{j\omega t} + V_C e^{j\omega t} = \frac{1}{2} e^{j\omega t}$$

now for every time this equation can be true if

$$V_C [RCj\omega + 1] = \frac{1}{2}$$

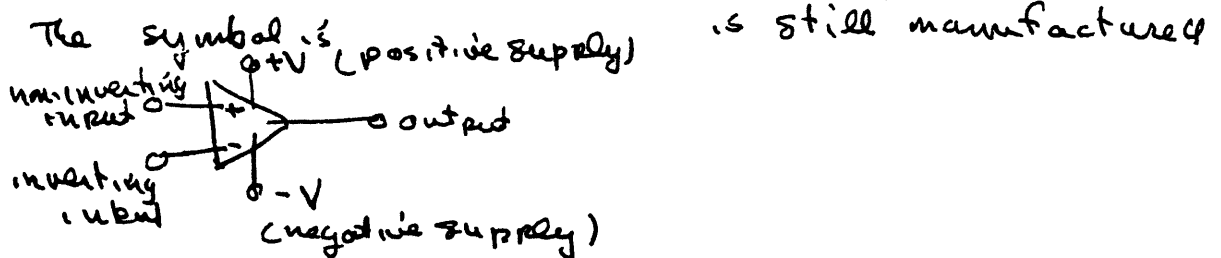
$$\text{or } V_C = \frac{\frac{1}{2}}{[1 + RCj\omega]}$$

This satisfies KVL (substitute and see)

we shall return to this another time.

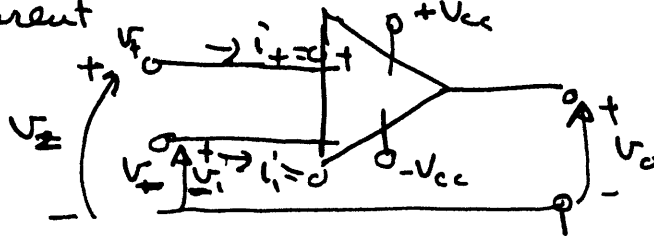
Chapter 6

Another new element - THE OPERATIONAL AMPLIFIER (OP-AMP for short). This device is ~~not~~ formed at ~~all~~ ~~single~~ ~~simple~~ not by a single simple element but ~~thousands~~ ^{hundreds} of elements within a capsule - a chip. The first ^{solid-state} one was introduced in 1968.



Just as with R, V, i , etc where we specified the devices by their terminal relationships, we do the same with the OP-AMP.

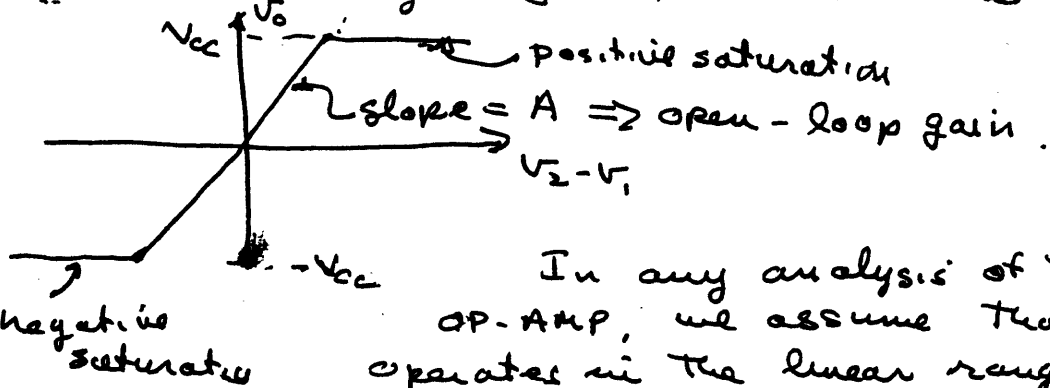
The ideal OP-AMP inputs do not conduct current



They amplify their inputs so that

$$V_0 = A(V_2 - V_1)$$

as long as $-V_{cc} \leq V_0 \leq V_{cc}$ so we can describe the OP-AMP by the "transfer-characteristic"

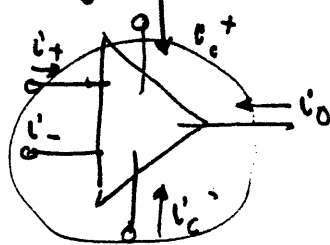


In any analysis of the OP-AMP, we assume that it operates in the linear range and the test to see if $|V_0| < V_{cc}$.

A typical value for the open loop gain is $\sim 10^5$ so if the output is just at saturation

$$|V_2 - V_1| \leq \frac{V_{cc}}{10^5} = \frac{15}{10^5} = 150 \mu\text{volts.}$$

very small. So we almost always can assume $V_2 \approx V_1$ to keep the OP-AMP in its linear region.



$$i_+ + i_- + i_c^+ + i_c^- + i_0 = 0$$

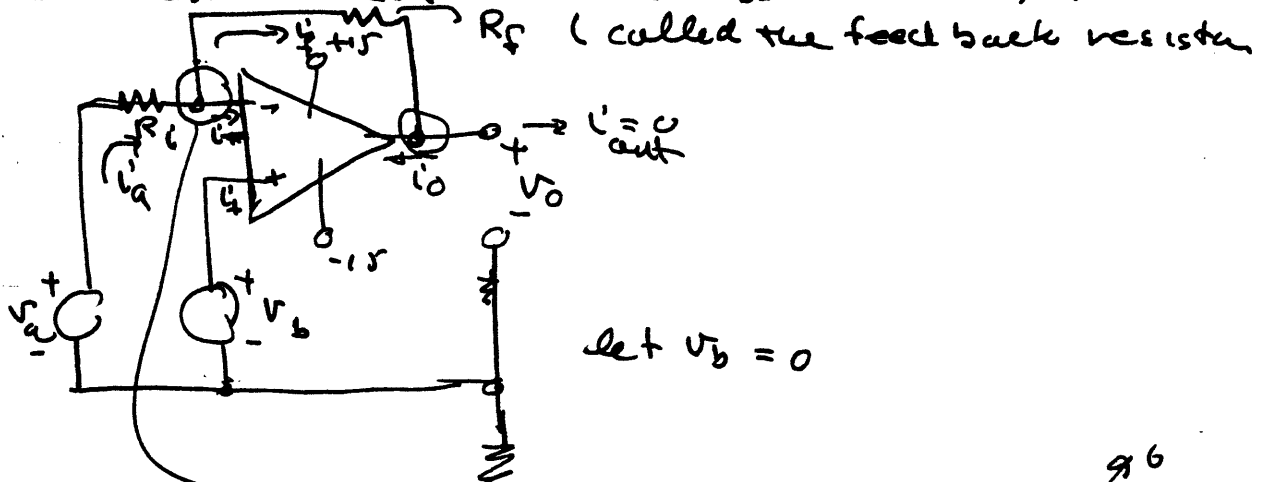
$$\text{so } i_0 = -(i_c^+ + i_c^-)$$

the supplies - supply the current for the output.

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Example 6.1 - The inverting amplifier

Why don't we use the intrinsic gain of an op-amp - It is flaky - it may be 10^5 for one chip & vary by as much as 20% from this with another. We can't rely on uniformity - and there are other reasons which will be discussed later.



$$i_a - i_- - i_f = 0 \quad , \quad i_f = i_o - i_{out} = 0$$

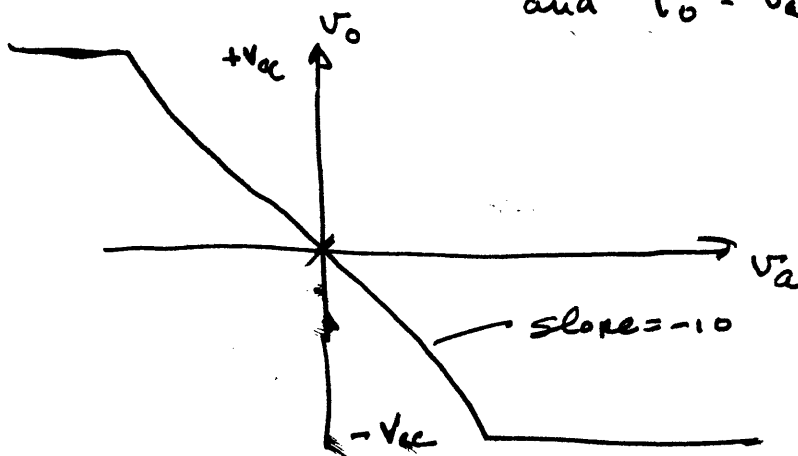
$$\text{but } i_- = 0 \text{ for ideal op-amp } \underline{i_f = i_o}$$

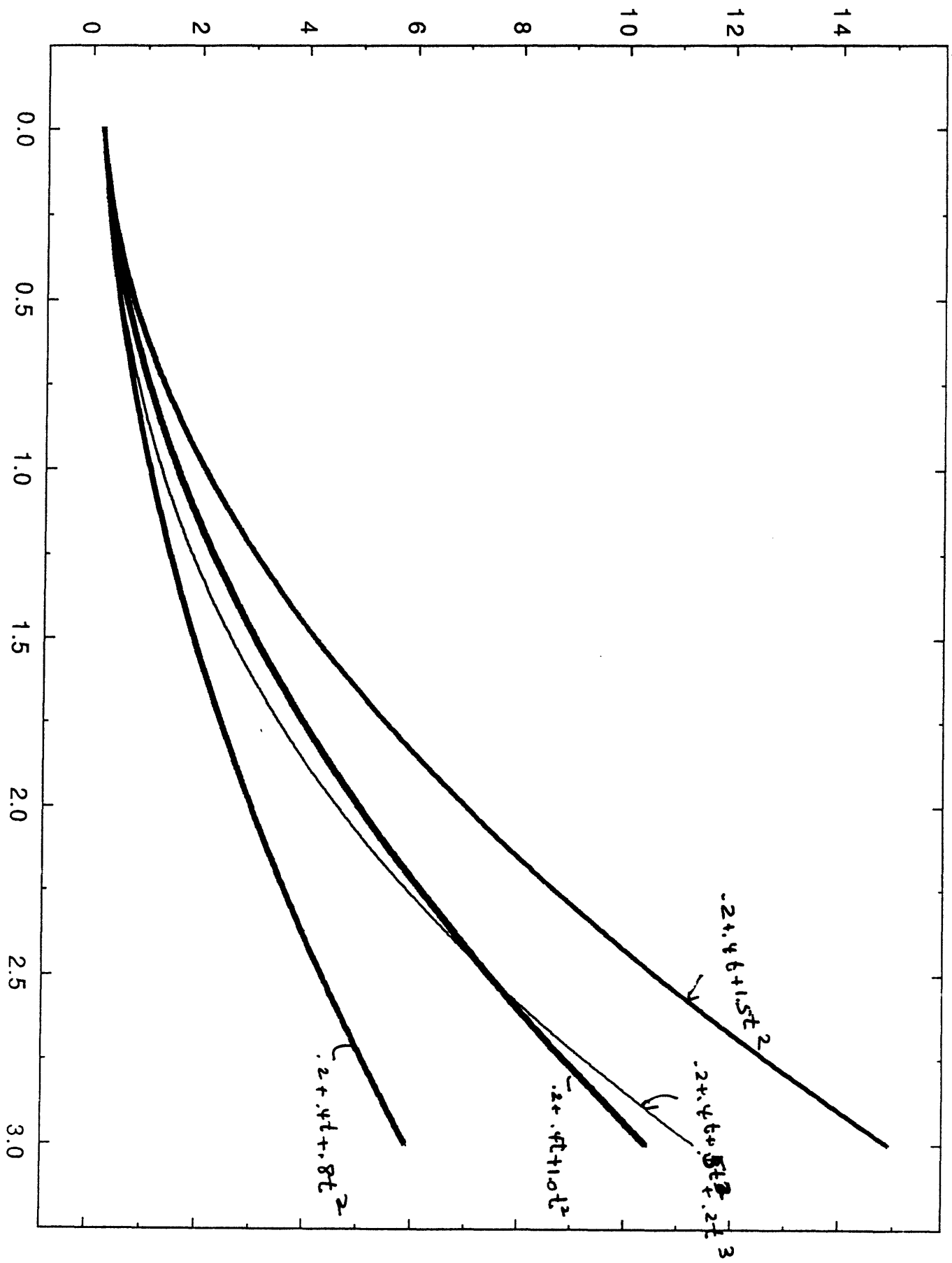
$$\text{so } i_a = i_f = i_o$$

$$\text{then since } v_a \approx v_b = 0 \quad i_a = v_a / R_i = i_o$$

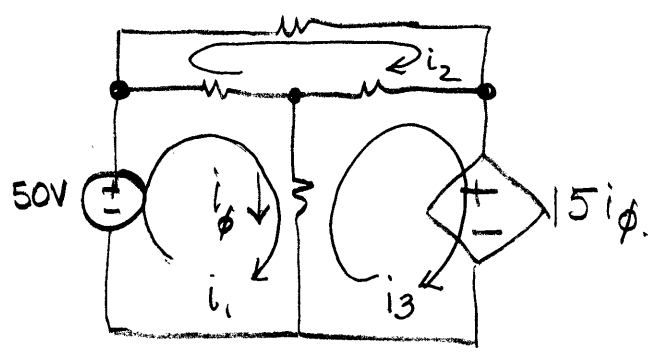
$$v_o = -i_f R_f = -v_a \times R_f / R_i$$

let $R_f / R_i = 10$ then $v_o = -10 v_a$
 and $i_o = v_a / R_i$



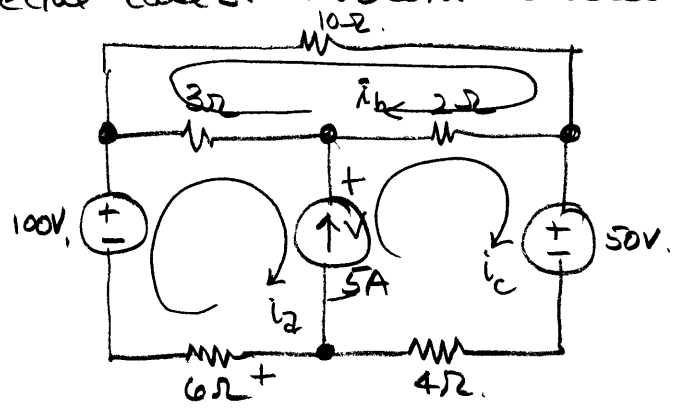


4.6 dependent sources.



three mesh currents: $i_1, i_2, i_3 \Rightarrow$ 3 equations in 4 unknowns
 supplemental equation due to i_ϕ
 $i_\phi = i_1 - i_3$
 substitute this into first three and get 3 eqns in 3 unknowns.

4.7 special cases: current sources



5 essential branches with unknown currents.
 4 essential nodes.
 need $5 - (4 - 1)$ mesh equations to solve circuit
 $5 - 3 = 2$

problem is that voltage v across 5A source is unknown

solution: write both eqns in terms of v and add

a: $-100 + 3(i_2 - i_b) + v + 6i_2 = 0$

b: $-v + 2(i_c - i_b) + 50 + 4i_c = 0$

a+b: $50 = 9i_2 - 5i_b + 6i_c$

now use constraint: $i_c - i_2 = 5A.$

comparison of methods:

both are systematic, both reduce # of equations

may not need complete solutions.

prefer: node voltage for computer analysis

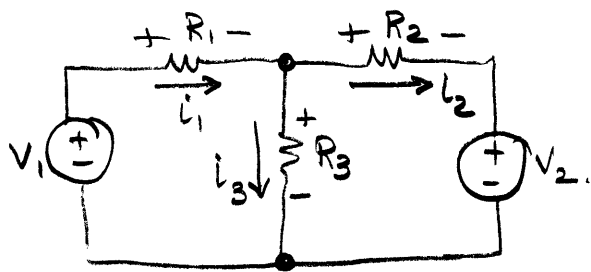
mesh current for manual analysis

4.5 mesh currents.

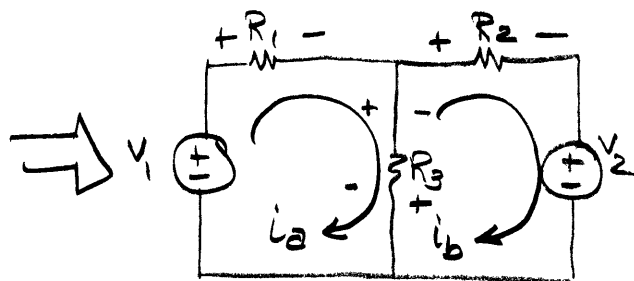
mesh - cannot have any other loops inside it

$$b - (n - 1)$$

↑
of branches. ← # of nodes.



what we have done



mesh currents i_a, i_b .

use KCL $i_1 - i_2 - i_3 = 0$ (1)

use KVL: left hand loop $-V_1 + i_1 R_1 + i_3 R_3 = 0$ (2)

use KVL: right hand loop $-i_3 R_3 + i_2 R_2 + V_2 = 0$ (3)

automatically eliminates KCL equations.

use i_a and i_b .

KVL i_a : $-V_1 + R_1 i_a + R_3 (i_a - i_b) = 0$.

KVL i_b : $+R_3 (i_b - i_a) + i_b R_2 + V_2 = 0$.

reduce to two eqns by solving for i_3 in (1) and eliminate from others.

i.e. $i_3 = i_1 - i_2$.

$$-V_1 + i_1 R_1 + (i_1 - i_2) R_3 = 0$$

$$-(i_1 - i_2) R_3 + i_2 R_2 + V_2 = 0$$

$$i_1 (R_1 + R_3) - i_2 R_3 = V_1$$

$$-i_1 R_3 + i_2 (R_2 + R_3) = -V_2$$

now rearrange:

$$i_a (R_1 + R_3) - i_b R_3 = V_1$$

$$-i_a R_3 + (R_3 + R_2) i_b = -V_2$$

now identify

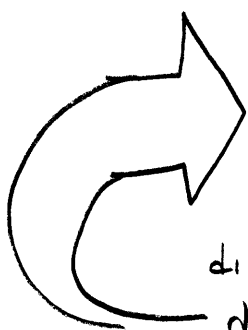
$$i_1 = i_a$$

$$i_2 = i_b$$

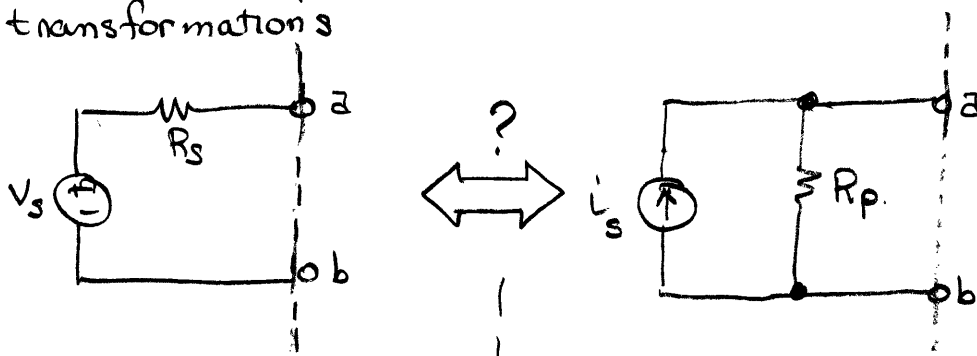
$$i_3 = i_1 - i_2 = i_a - i_b$$

difference between mesh currents

do by inspection in future!



4.9 source transformations

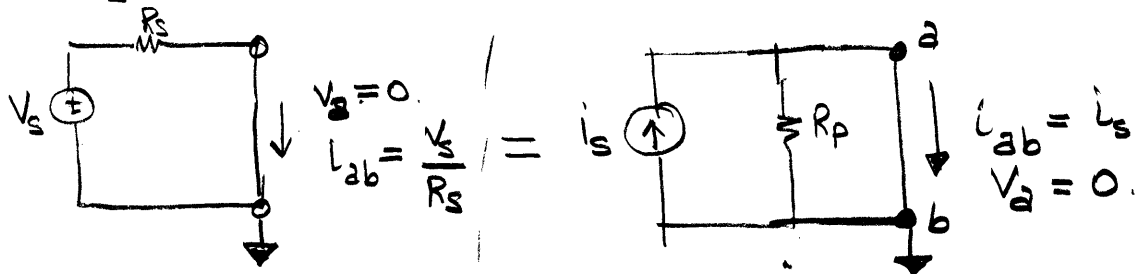


under what conditions are these equivalent at their terminals

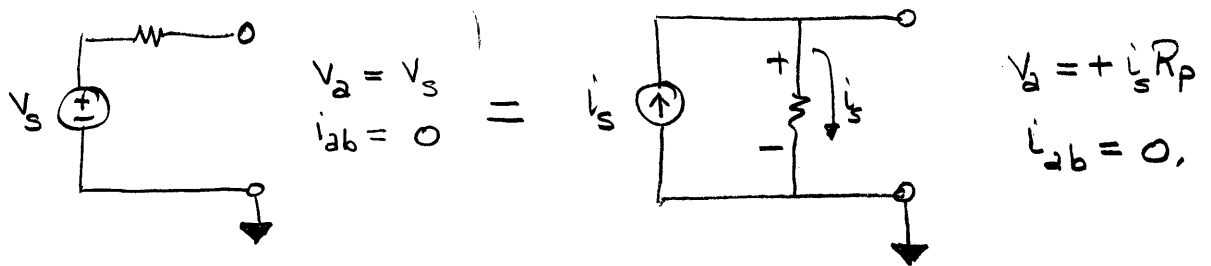
Statement if they are equivalent they must be equivalent for all values of R connected across a, b .

Natural to use extreme values: $0, \infty$

for $R_L = 0$



for $R_L = \infty$



by inspection

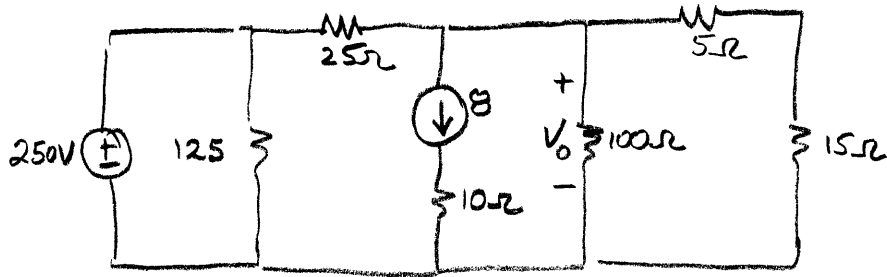
$$\frac{V_s}{R_s} = i_s \quad \text{or} \quad R_s = \frac{V_s}{i_s}$$

$$V_s = i_s R_p \quad \text{or} \quad R_p = \frac{V_s}{i_s}$$

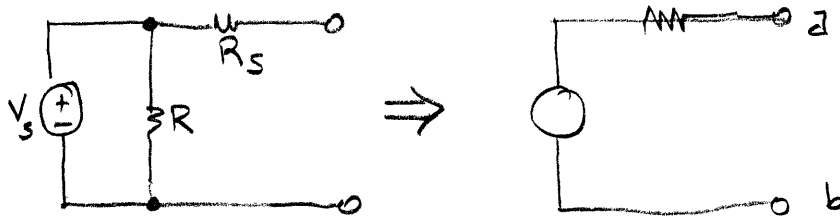
∴ if $R_s = R_p$ these circuits are equivalent!

Example 4.8

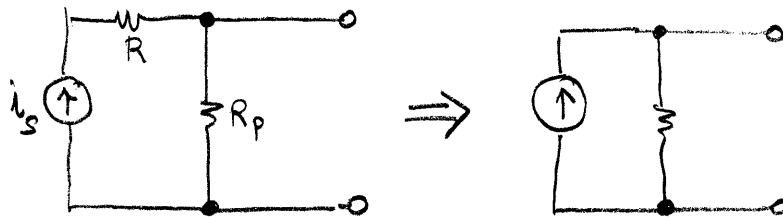
(a) Use source transformations to find v_o .



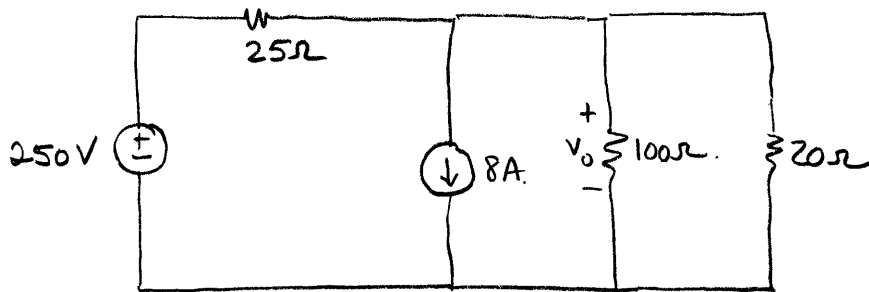
IMPORTANT RULE: If there is a resistance R in parallel with a voltage source or in series with a current source, the resistance R has no effect on the equivalent circuit.

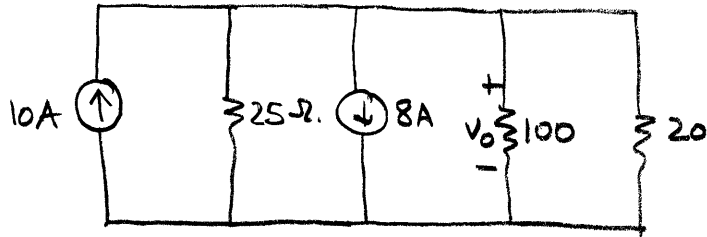


no change in output.

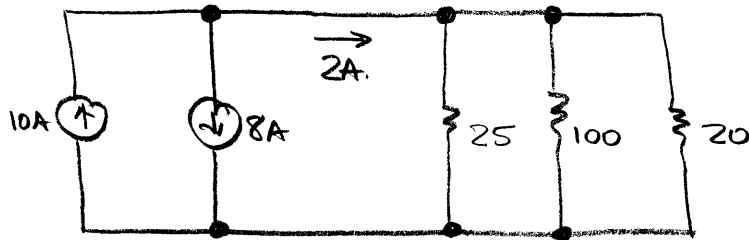


with no change.





$$i = \frac{250V}{25\Omega} = 10A$$



$$\frac{1}{R} = \frac{1}{25} + \frac{1}{100} + \frac{1}{20} = .04 + .01 + .05 = 0.10$$

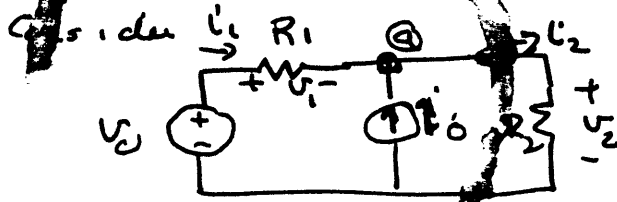
$$R = 10\Omega$$

$$V = (2A)(10\Omega) = 20V$$

2/5/93

SUPERPOSITION

The Thevenin and Norton equivalent circuits are often obtained using the concept of superposition when multiple sources are present in the circuit.



KVL of outer loop $V_0 = V_1 + V_2$
 KCL at 'a' $i_0 + i_1 = i_2$

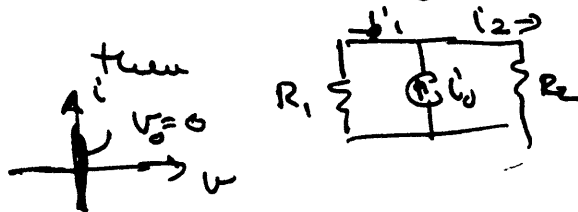
hence $V_0 = i_1 R_1 + i_2 R_2$ we can then solve for i_1 and i_2

$$i_1 = \frac{V_0}{R_1 + R_2} - i_0 \frac{R_2}{R_1 + R_2}$$

$$\text{and } i_2 = \frac{V_0}{R_1 + R_2} + i_0 \frac{R_1}{R_1 + R_2}$$

The fact is that we see the effects of the two sources as a sum. - each term is exactly proportional to the source.

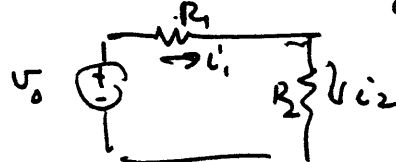
Suppose V_0 were zero (a short circuit!)



$$i_1|_{V_0=0} = -i_0 \frac{R_2}{R_1 + R_2} \text{ (current divider)}$$

$$i_2|_{V_0=0} = i_0 \frac{R_1}{R_1 + R_2}$$

now let's set $i_0 = 0$ (an open circuit)

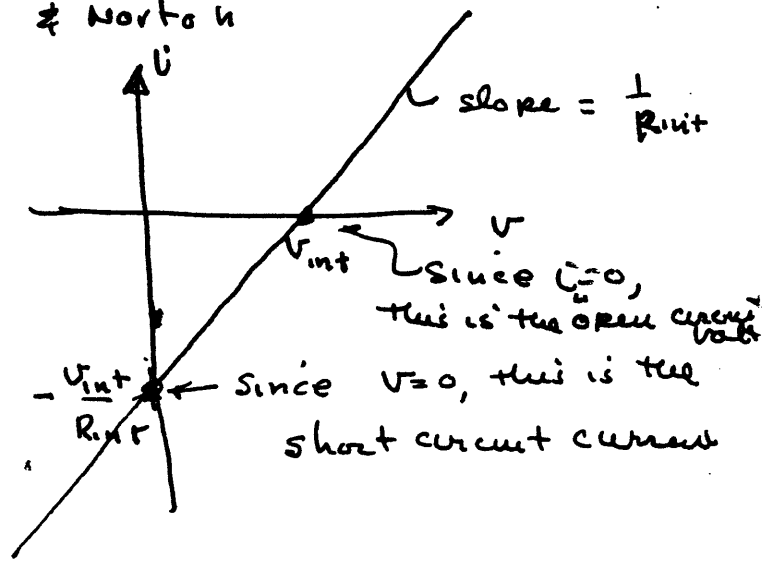
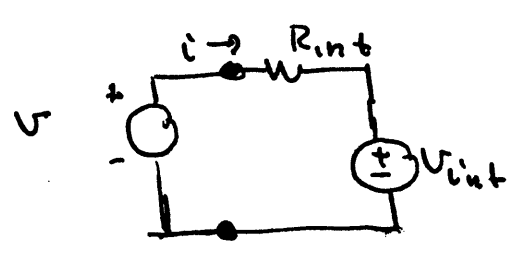


$$i_1 = i_2 = \frac{V_0}{R_1 + R_2}$$

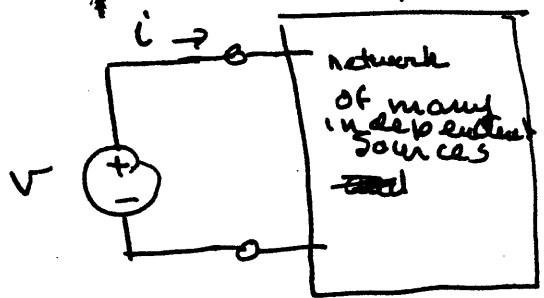
then sum is exactly what we first obtained

2/5/97

What about Thevenin & Norton



Now consider a complicated network driven by V .



$$i = G V - [a_1 V_1 + a_2 V_2 + \dots + a_N V_N + b_1 i_1 + \dots + b_M i_M]$$

these are the superposition effect of N -voltage sources (indep) and M -current sources (indep)

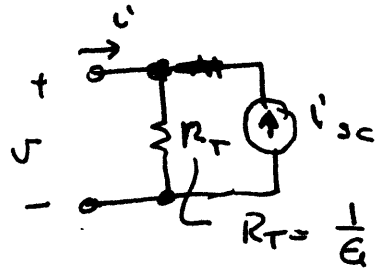
We can find these constants as follows:

- to find G , set all internal sources to zero and find i for a given V . (or set $V=1$ then $i=G$)
- to find a_n , set V , and $V_n=0$, $i_m=0$ for $n \neq 1$, all m
- b_n , set V , and $V_n=0$, $i_m=0$ for all n , $m \neq 1$

Note that if $V=0$ with all sources on we have the short circuit current when $i=0$; $V =$ the open circuit voltage

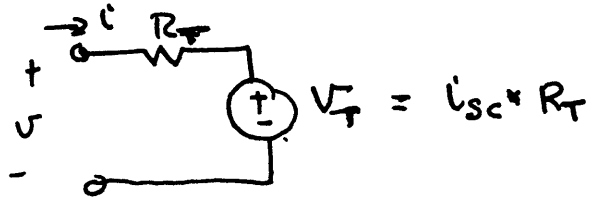
2/1/93

Thus $i = G V - i_{sc}$
→
↘ circuit →
↘ for this.



this is the Norton Equivalent circuit.

when $V = V_{oc}$ $i = 0$ so

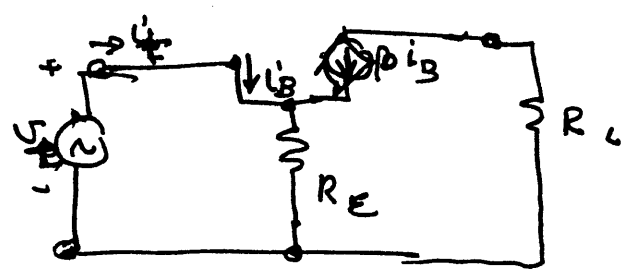


we can find $R_T = \frac{V_{oc}}{i_{sc}}$

2/5/93

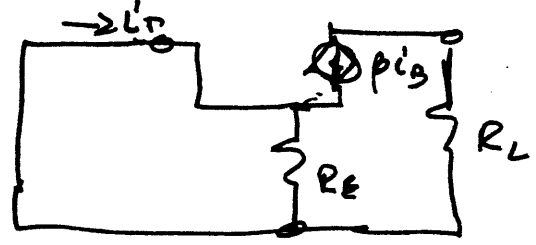
Now lets consider superposition with controlled sources

example



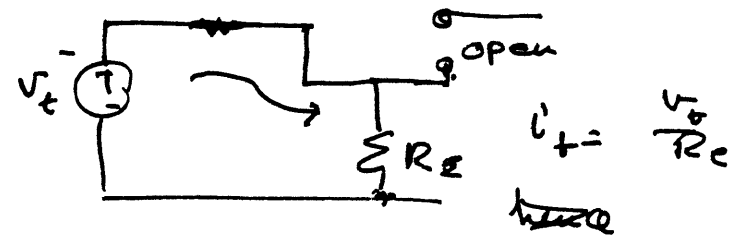
find the Thevenin equivalent of the input
Can we do the following:

- ① We apply V_T and set the current source $\beta i_B = 0$ then find the current i_T due to V_T alone
- ② Then set $V_T = 0$ and find which then makes the circuit



But this results in $i_T = -\beta i_B$.

- ③ Now suppress βi_B and use V_T alone



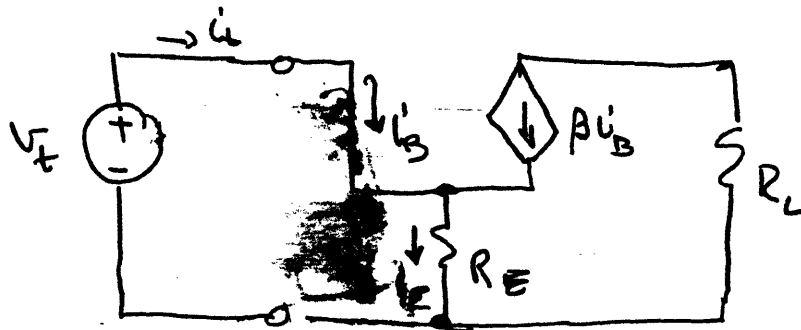
④ hence $i_T = \frac{V_T}{R_E} - \beta i_B$

NO WAY why? because the current source βi_B is a DEPENDENT source - it must exist if βi_B exists.

25/93

5

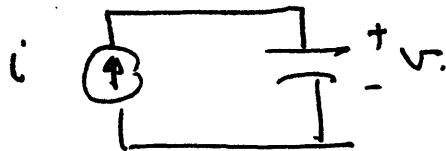
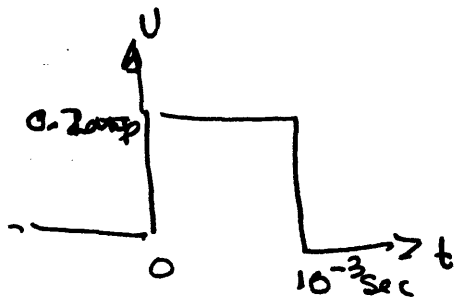
The correct solution



$$i_E = i_B, \quad i_E = i_B + \beta i_B = (1 + \beta) i_B$$

$$V_E = R_E (1 + \beta) i_B = V_t \quad \text{by KVL}$$

hence $i_B = \frac{V_t}{R_E (1 + \beta)}$ $\beta i_B = \frac{V_t}{R_E}$
 $= (1 + \beta) R_E$



$$i = C \frac{dV}{dt}$$

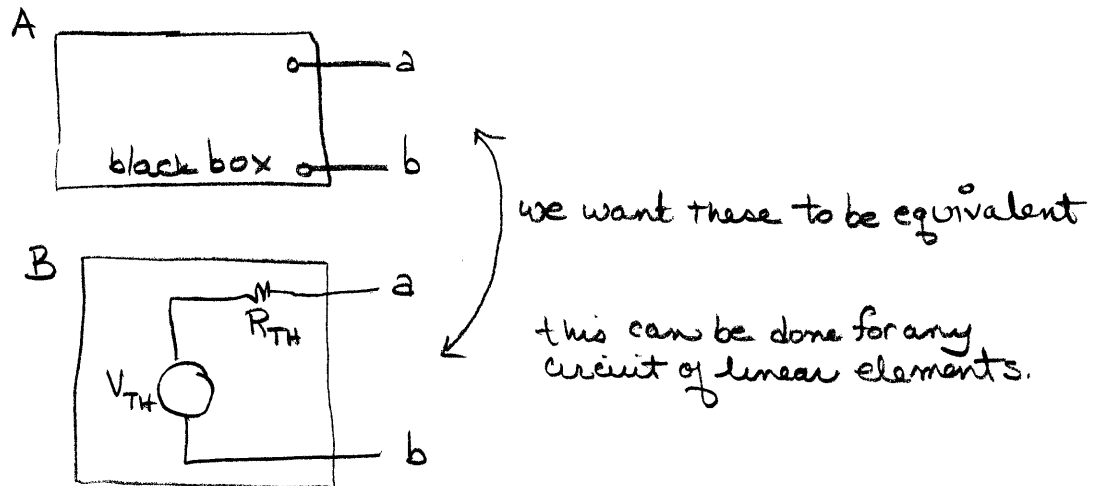
$$\int_{t_1}^{t_2} dV = \int_{t_1}^{t_2} i dt$$

$$\int_{t=-\infty}^t dV = V(t) - V(-\infty) = \frac{1}{C} \int_{-\infty}^t i(t) dt$$

$$= \frac{1}{C} \begin{cases} 0 & t < 0 \\ 0.2t & 0 \leq t \leq 10^{-3} \\ 2 \times 10^{-4} & t > 10^{-3} \end{cases}$$

hence $V(t) = V(-\infty) + \frac{1}{C} \int_{-\infty}^t i(t) dt$

4.10 Thevenin and Norton equivalent circuits

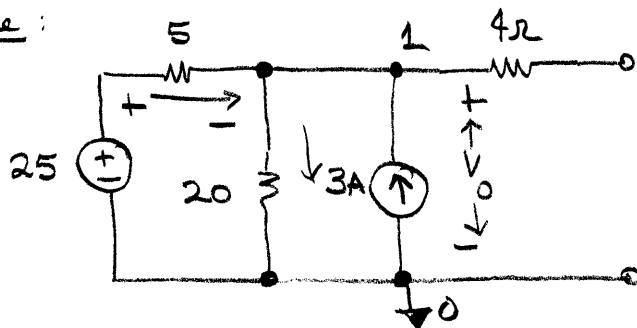


Note 1: If A & B are equivalent.

For $R_{ab} = \infty$
measure $V_{ab} = V_{TH}$

For $R_{ab} = 0$
measure $i_{ab} = \frac{V_{TH}}{R_{TH}}$

Example:



① calculate V_{oc}
no load

use KCL @ node 1 + in.

$$+ \frac{25 - V_0}{5} - \frac{V_0}{20} + 3 = 0 \Rightarrow V_{oc} = 32V$$

② calculate i_{sc}

$$+ \frac{25 - V_0}{5} - \frac{V_0}{20} + 3 - \frac{V_0}{4} = 0 \Rightarrow V_0 = 16V$$

$$i_{sc} = \frac{16}{4} = 4A$$

$$\textcircled{3} R_{TH} = \frac{V_{oc}}{i_{sc}} = \frac{32}{4} = 8\Omega$$

Norton equivalent: source transformation

$$i_N = \frac{V_{TH}}{R_{TH}}$$

and we know $R_{TH} = R_N$

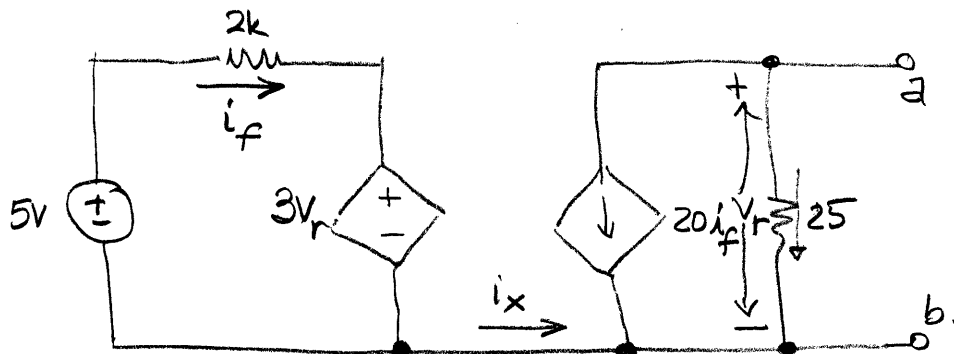
Finding R_{TH} with
in Dependent sources — don't use above method

replace voltage sources with shorts
current sources with opens.

dependent sources

1. deactivate all independent sources
2. apply a test voltage (or current) to outputs a, b

Good example



$$V_{TH} \left\{ \begin{array}{l} \textcircled{1} \text{ recognize } i_x = 0 \\ \textcircled{2} V_{oc} = V_{ab} = +i \cdot 25 = (-20i_f) \cdot 25 = -500i_f \\ \textcircled{3} i_f = \frac{5 - 3V_r}{2k} \end{array} \right.$$

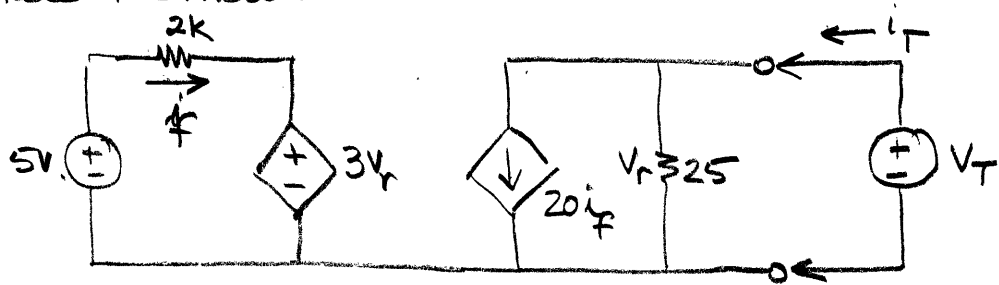
solving $V_r = -5V = V_{TH}$

$$i_{sc} \left\{ \begin{array}{l} \text{by inspection } i_{sc} = i_{ab} = -20i_f \\ V_r = 0 \text{ if } ab \text{ is a short} \Rightarrow 3V_r = 0 \text{ in input} \\ i_f = \frac{5 - 3(0)}{2k} = 2.5 \text{ mA} \end{array} \right.$$

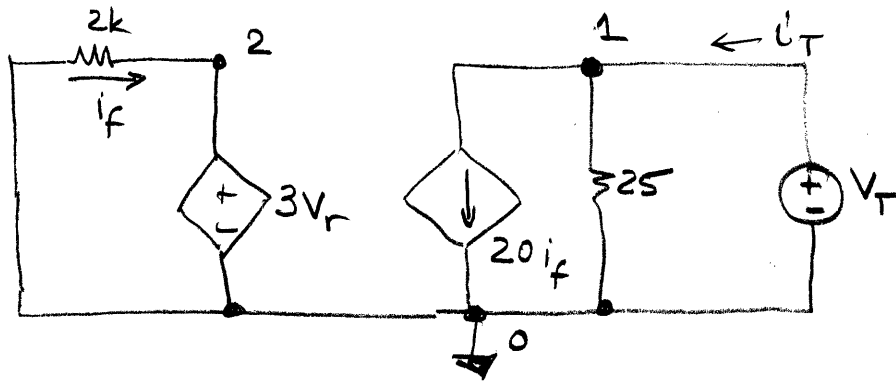
$$R_{TH} = \frac{V_{TH}}{i_{sc}} = \frac{-5}{-50 \text{ mA}} = 100 \Omega$$

$$i_{sc} = -20(2.5 \text{ mA}) = -50 \text{ mA}$$

alternate method:



all independent sources \rightarrow opens or shorts



at node 1 + out

$$-i_T + \frac{V_T}{25} + 20i_f = 0$$

at input use
Ohm's Law

$$i_f = -\frac{3V_T}{2} \text{ mA}$$

substituting.

$$-i_T + \frac{V_T}{25} + 20 \left(-\frac{3V_T}{2k} \right) = 0 \quad \text{units}$$

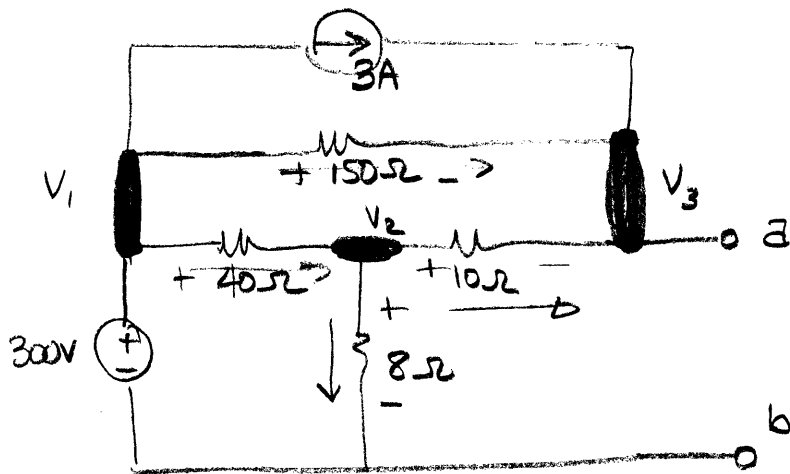
$$i_T = \frac{1}{25} V_T - \frac{60}{2000} V_T$$

$$\frac{i_T}{V_T} = \frac{1}{25} - \frac{60}{2000} = \frac{1}{100}$$

must use
alternative
method if only
resistors and
dependent sources.

$$R_{TH} = \frac{V_T}{i_T} = 100 \Omega$$

4.56.



by inspection $V_1 = +300V$.

KCL @ 3 + in $3A + \frac{300 - V_3}{150} + \frac{V_2 - V_3}{10} \cdot \frac{15}{15} = 0$

KCL @ 2 + in $\frac{300 - V_2}{40} - \frac{V_2}{8} \cdot \frac{5}{5} - \frac{V_2 - V_3}{10} \cdot \frac{4}{4} = 0$

should be $V_3 = 120V$

$$450 + 300 - \sqrt{V_3} + 15\sqrt{V_2} - 15\sqrt{V_3} = 0$$

$$300 - \sqrt{V_2} - 5\sqrt{V_2} - 4\sqrt{V_2} + 4\sqrt{V_3} = 0$$

$$15V_2 - 16V_3 = -750$$

$$-10V_2 + 4V_3 = -300$$

$$15V_2 - 16V_3 = -750$$

$$+5V_2 + 2V_3 = -150$$

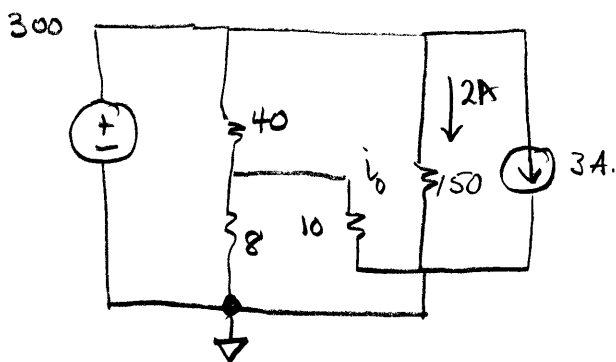
$$15V_2 - 16V_3 = -750$$

$$-15V_2 + 6V_3 = -450$$

$$-10V_3 = -1200$$

$$V_3 = +120V = V_{T1}$$

Now short output.



$$\frac{300V}{150\Omega} = 2A$$

$$8 \parallel 10 = \frac{8 \cdot 10}{8 + 10} = \frac{80}{18} = \frac{40}{9}$$

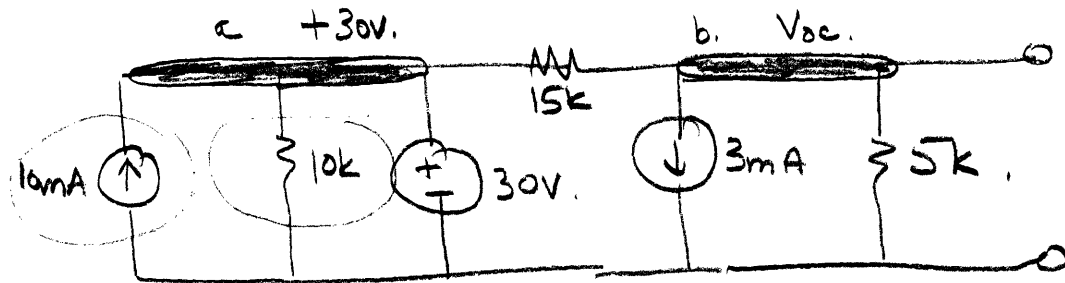
$$i = \frac{\epsilon}{R} = \frac{300}{40 + \frac{40}{9}} = \frac{300}{\frac{360 + 40}{9}} = \frac{2700}{400} = \frac{27}{4}$$

$$i_0 = \frac{8}{8 + 10} \cdot \frac{27}{4} = \frac{2 \cdot 3}{2} = 3A$$

$$i_{TOT} = 3 + 2 + 3 = 8A$$

Go back and clear up examples

4.58



No Source transformations

KCL at b
+ out

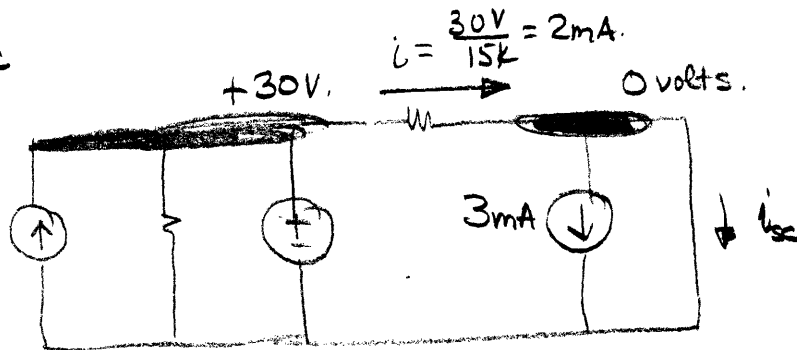
$$\frac{V_{oc} - 30}{15} + 3mA + \frac{V_{oc}}{5k} = 0.$$

$$V_{oc} - 30 + 45 + 3V_{oc} = 0.$$

$$4V_{oc} = -15.$$

$$V_{oc} = -\frac{15}{4}$$

Now do i_{sc}



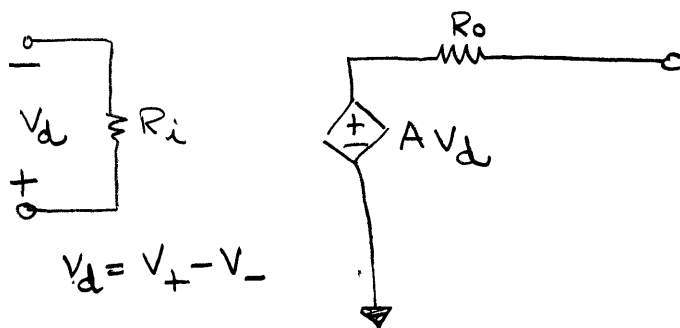
$$i_{sc} = -1mA$$

$$R_T = \frac{V_{oc}}{i_{sc}} = \frac{-45/4}{-1mA} =$$

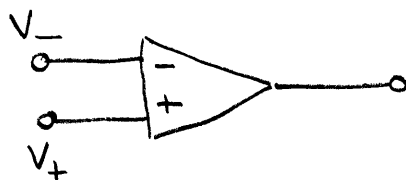
$$V_T = iR_T = 3.75V.$$

6.7 equivalent circuits for the operational amplifier

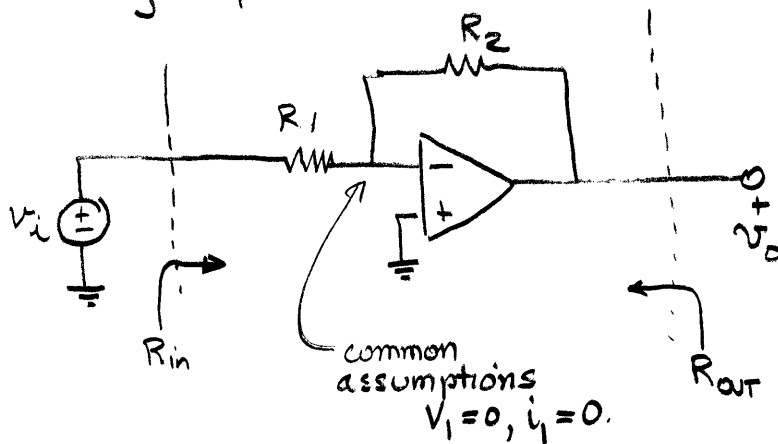
ideal op-amp



symbol



linear inverting amplifier

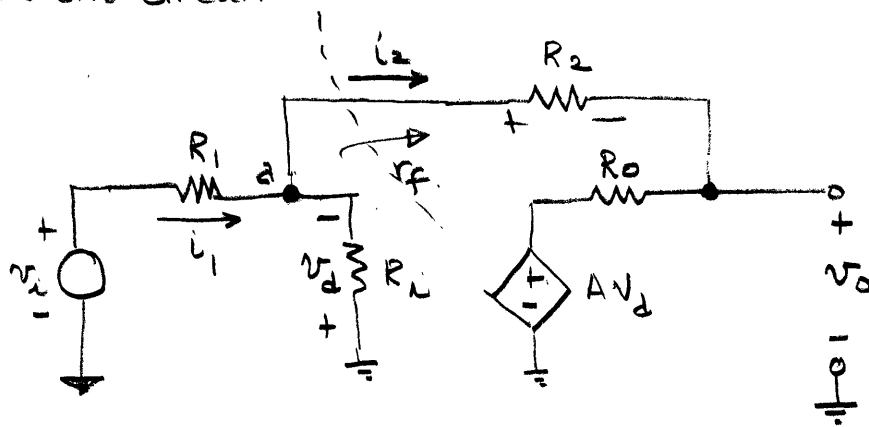


$$A_v \approx -\frac{R_2}{R_1}$$

$$R_{in} \approx R_1$$

$$R_o \approx 0$$

equivalent circuit



Simple analysis

b.

for an ideal op-amp $R_i \rightarrow \infty$, $V_d \rightarrow 0$

$$i_1 = \frac{v_i - (-V_d)}{R_1} = \frac{v_i + V_d}{R_1}$$

$$i_2 = \frac{-V_d - v_o}{R_2}$$

using KCL at a $-i_1 + i_2 = 0$ or $i_1 = i_2$.

$$\frac{v_i + V_d}{R_1} = \frac{-V_d - v_o}{R_2}$$

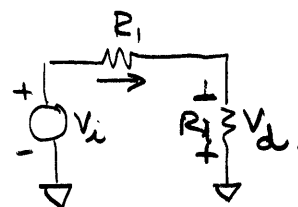
$$\text{or } \frac{R_2}{R_1} = -\frac{v_o}{v_i}$$

$$\Rightarrow A_v = -\frac{R_2}{R_1} \text{ for an ideal op-amp}$$

This is a classical result for an inverting amplifier
Typically pick R_1, R_2 so $|A_v| < 50$ and $R_2 < 100k\Omega$.

Input impedance of the inverting amplifier

$$r_i = \frac{v_i}{i_1}$$



KVL around input $-v_i + i_1 R_1 - V_d = 0$.

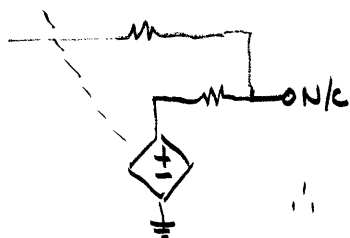
(for an ideal op-amp)

$$\Rightarrow r_i = \frac{v_i}{i_1} = \frac{i_1 R_1}{i_1} = R_1$$

for a non-ideal op-amp no output connected

KVL around feedback loop

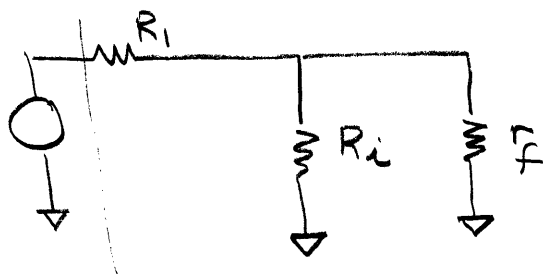
$$+V_d + i_2 R_2 + i_2 R_o + A V_d = 0$$



$$V_d (1 + A) = -i_2 (R_2 + R_o)$$

$$\therefore r_f = -\frac{V_d}{i_2} = \frac{R_2 + R_o}{1 + A_d}$$

input circuit



$$\begin{aligned} \Rightarrow R_{IN} &= R_1 + R_i \parallel R_f = R_1 + \frac{R_i R_f}{R_i + R_f} \\ &= R_1 + \frac{R_i \left(\frac{R_2 + R_o}{1 + A_d} \right)}{R_i + \frac{R_2 + R_o}{1 + A_d}} = R_1 + \frac{R_i (R_2 + R_o)}{1 + A_d} \frac{1 + A_d}{R_i (1 + A_d) + R_2 + R_o} \end{aligned}$$

$$R_{IN} = R_1 + \frac{R_i (R_2 + R_o)}{R_i (1 + A_d) + (R_2 + R_o)}$$

in practice $R_2 = 10k$, $R_o = 100\Omega$, $R_i = 100k\Omega$, $A_d = 10^5$

$$\text{then } R_{IN} = R_1 + \frac{(10^5)(10^4 + 10^2)}{10^5(1 + 10^5) + (10^4 + 10^2)} \quad \frac{110100}{10000110100}$$

$$= R_1 + 1.1 \times 10^{-5}$$

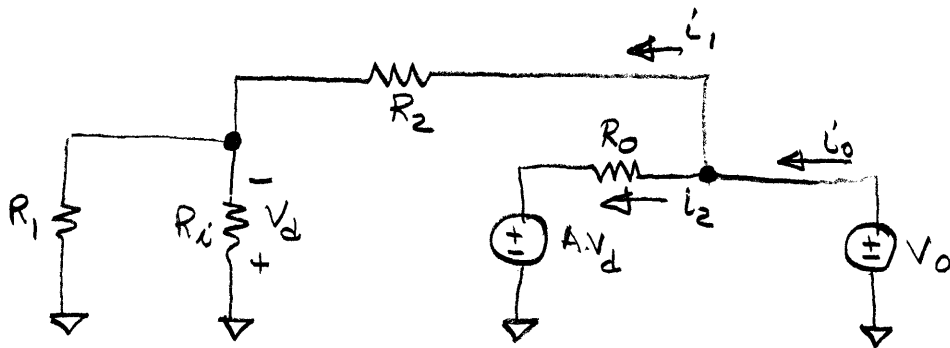
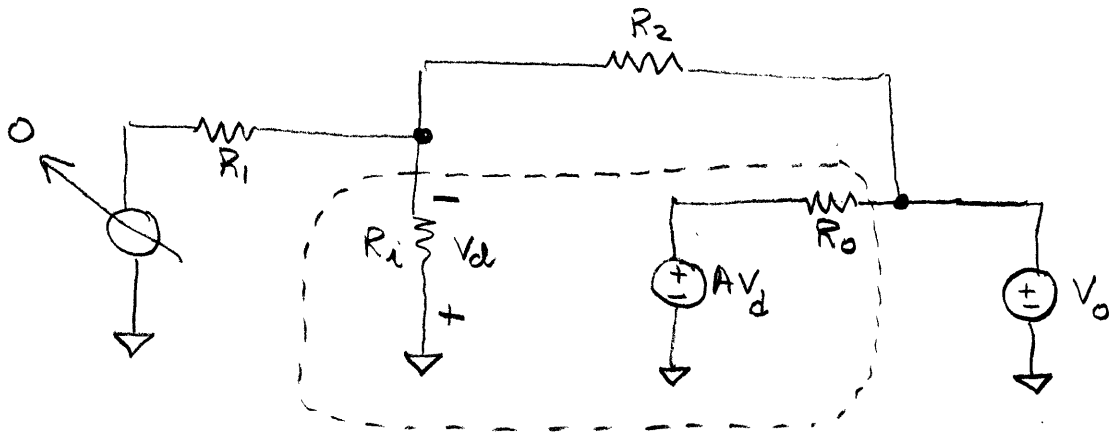
Output impedance of the inverting amplifier

procedure is very important

set $v_i = 0$

insert a test voltage source at output

measure current drawn from test source



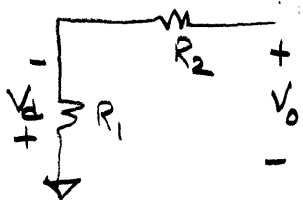
$$i_0 = i_1 + i_2$$

$$\text{where } i_1 = \frac{V_0}{R_2 + R_1 \parallel R_i} \approx \frac{V_0}{R_2 + R_1}$$

$$i_2 = \frac{V_0 - AV_d}{R_0}$$

$$i_0 = i_1 + i_2 = \frac{V_0}{R_1 + R_2} + \frac{V_0 - AV_d}{R_0} \quad (1)$$

Again for $R_i \gg R_1$ very large.



$$-V_d = \frac{R_1}{R_1 + R_2} V_0 \quad (2)$$

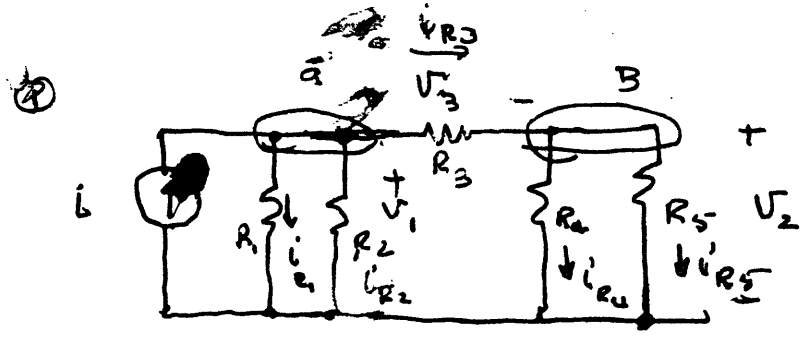
$$\frac{1}{r_o} = \frac{i_o}{V_o} = \frac{1}{V_o} \frac{V_o}{R_1 + R_2} + \frac{1}{V_o} \frac{V_o - AV_d}{R_o}$$

$$= \frac{1}{R_1 + R_2} + \frac{1}{R_o} - \frac{A}{R_o} \frac{V_d}{V_o}$$

$$= \frac{1}{R_1 + R_2} + \frac{1}{R_o} - \frac{A}{R_o} \left(\frac{-R_1}{R_1 + R_2} \right) \frac{V_o}{V_o}$$

$$= \frac{1}{R_1 + R_2} + \frac{1 + A \left(\frac{R_1}{R_1 + R_2} \right)}{R_o}$$

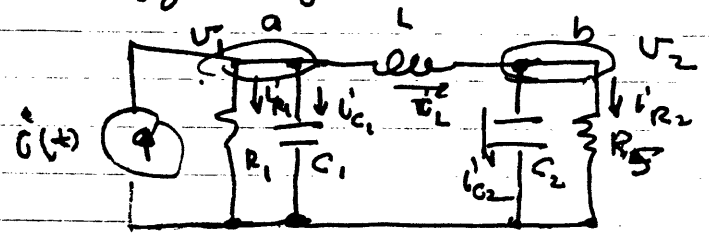
for an ideal op-amp $A \rightarrow \infty$ $\frac{1}{r_o} \rightarrow \infty$
so $r_o \rightarrow 0$



$$i = i_{R_1} + i_{R_2} + i_{R_3} = \frac{V_1}{R_1} + \frac{V_1}{R_2} + \frac{V_1 - V_2}{R_3}$$

$$i_{R_3} = i_{R_4} + i_{R_5} \Rightarrow \frac{V_1 - V_2}{R_3} = \frac{V_2}{R_4} + \frac{V_2}{R_5}$$

now solve for V_1 and V_2 .
 of course we could have simplified this circuit quite a bit as we know $R_1 || R_2$ and $R_4 || R_5$.
 But now let's look at a circuit with identical topology (layout) but different elements



$$V_L = L \frac{di_L}{dt}$$

$$\text{and so } i_L = \frac{1}{L} \int V_L dt$$

$$V_L = V_1 - V_2$$

at node a

$$i = i_{R_1} + i_{C_1} + i_L = \frac{V_1}{R_1} + C_1 \frac{dV_1}{dt} + \frac{1}{L} \int (V_1 - V_2) dt$$

at node b

$$i_L = \frac{1}{L} \int (V_1 - V_2) dt = i_{C_2} + i_{R_5} = C_2 \frac{dV_2}{dt} + \frac{V_2}{R_5}$$

This is called an integro-differential equation. We can wish to find a nice simple solution like for the resistor manifestation of the topology. In fact there is a simple approach for a very special kind of a time function, $i(t)$.

(a)

in matrix form for resistor circuits

$$\begin{bmatrix} \left(\frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3}\right) & -\frac{1}{R_3} \\ -\frac{1}{R_3} & \left(\frac{1}{R_3} + \frac{1}{R_4} + \frac{1}{R_5}\right) \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} i \\ 0 \end{bmatrix}$$

matrix form for L, R, C. with $i = I e^{j\omega t}$

$$\begin{bmatrix} \left(\frac{1}{R_1} + \left(\frac{1}{j\omega C_1}\right) + \frac{1}{j\omega L}\right) & -\frac{1}{j\omega L} \\ -\frac{1}{j\omega L} & \frac{1}{R_5} + \left(\frac{1}{j\omega C_2}\right) + \frac{1}{j\omega L} \end{bmatrix} \begin{bmatrix} \hat{v}_1 \\ \hat{v}_2 \end{bmatrix} = \begin{bmatrix} I \\ 0 \end{bmatrix}$$

Let $\frac{1}{R_1} = G_1$, $\frac{1}{R_2} = G_2$, $\frac{1}{R_3} = G_3$, $\frac{1}{R_4} = G_4$, $\frac{1}{R_5} = G_5$

$$\begin{bmatrix} (G_1 + G_2 + G_3) & -G_3 \\ -G_3 & (G_4 + G_5 + G_3) \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} i \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} (G_1 + j\omega C_1 + \frac{1}{j\omega L}) & -\frac{1}{j\omega L} \\ -\frac{1}{j\omega L} & (G_5 + j\omega C_2 + \frac{1}{j\omega L}) \end{bmatrix} \begin{bmatrix} \hat{v}_1 \\ \hat{v}_2 \end{bmatrix} = \begin{bmatrix} I \\ 0 \end{bmatrix}$$

we find \hat{v}_1 & \hat{v}_2 but the complete solution is

$$v_1 = \hat{v}_1 e^{j\omega t}$$

$$v_2 = \hat{v}_2 e^{j\omega t}$$

②

Lets use a source $i(t) = I e^{j\omega t} = I \cos \omega t + j I \sin \omega t$ as we once did before. Again we assume that the voltage must also vary with time as $e^{j\omega t}$ with a constant multiplier to be determined.

So $v_1(t) = \hat{V}_1 e^{j\omega t}$ and $v_2(t) = \hat{V}_2 e^{j\omega t}$ $\hat{V}_{1,2} \neq \hat{V}_{1,2}(t)$ [Volts]

Now we substitute these into our ~~node~~ equations

$$I e^{j\omega t} = \frac{\hat{V}_1 e^{j\omega t}}{R_1} + j\omega C_1 \hat{V}_1 e^{j\omega t} + \frac{1}{j\omega L} [\hat{V}_1 e^{j\omega t} - \hat{V}_2 e^{j\omega t}]$$

$$\frac{1}{j\omega L} [\hat{V}_1 e^{j\omega t} - \hat{V}_2 e^{j\omega t}] = j\omega C_2 \hat{V}_2 e^{j\omega t} + \frac{\hat{V}_2 e^{j\omega t}}{R_2}$$

Notice that everywhere time enters as $e^{j\omega t}$ and we can cancel this factor throughout.

$$I = \frac{\hat{V}_1}{R_1} + \frac{\hat{V}_1}{(1/j\omega C_1)} + \frac{\hat{V}_1 - \hat{V}_2}{j\omega L}$$

$$\frac{\hat{V}_1 - \hat{V}_2}{j\omega L} = \frac{\hat{V}_2}{(1/j\omega C_2)} + \frac{\hat{V}_2}{R_2}$$

Now compare the two sets of equations

see that	$(\frac{1}{j\omega C_1})$	plays the role of	R_2
	$j\omega L$	" " " "	R_3
	$(\frac{1}{j\omega C_2})$	" " " "	R_4

$\frac{[\text{Volts}]}{[\text{amps}]}$ was called Z for a resistor

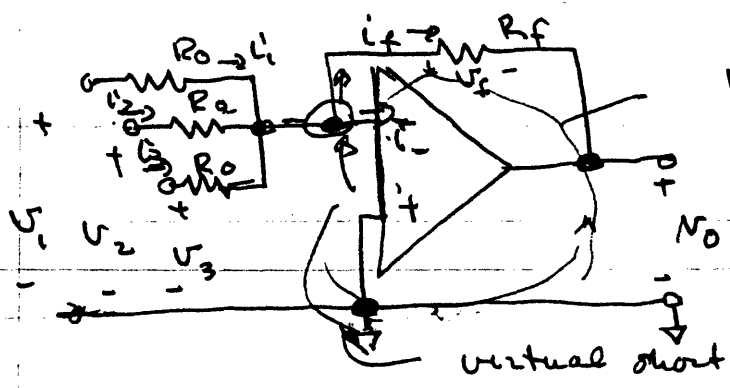
but $\frac{[\text{Volts}]}{[\text{amps}]} = \cancel{Z} j\omega L$ is reactance

or $= \cancel{Z} (1/j\omega C)$ is reactance.

to return once more

③

More on OP-AMP CIRCUITS



KVL $\Rightarrow V_o + V_f = 0$
 $V_o = -V_f = i_f R_f$

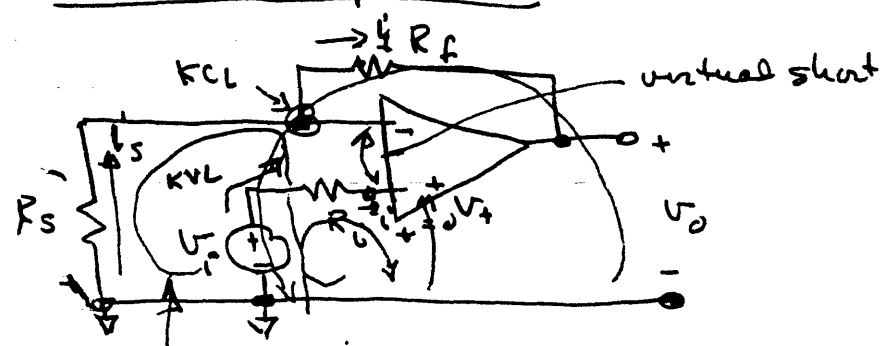
for ideal op amp $i_- = i_+ = 0$
 $i_1 + i_2 + i_3 = i_f + i_f$

$\therefore \frac{V_1}{R_0} + \frac{V_2}{R_0} + \frac{V_3}{R_0} = i_f$ hence

$-(V_1 + V_2 + V_3) \frac{R_f}{R_0} = V_o$ ~~the~~ or the system acts as an analog adder. In fact we could add as many inputs as we desire. We can also have

$V_o = -10V_1 + V_2$ or any linear combination we choose.

Another amplifier circuit



$V_+ = V_i$ since $i_+ = 0$
 therefore $V_- = V_i$

KVL $-R_s i_s - V_- = 0$

so $i_s = -\frac{V_-}{R_s} = -\frac{V_i}{R_s}$

again $i_f = i_s = -\frac{V_i}{R_s}$

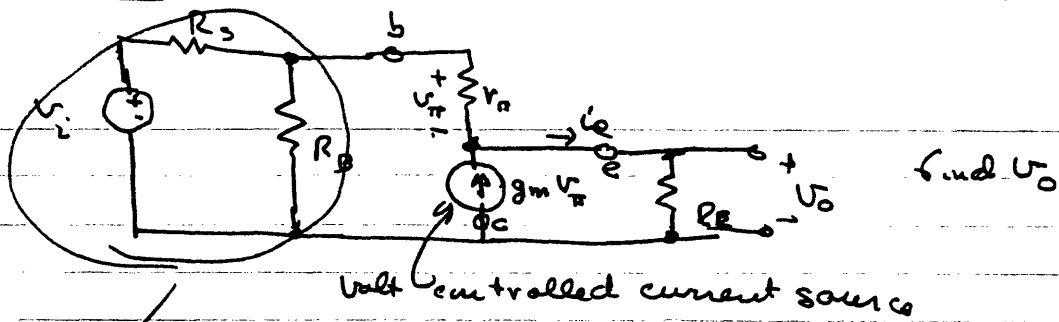
④ Now take KVL through V_o, R_f, V_-

$$V_o + i_f R_f - V_- = 0$$

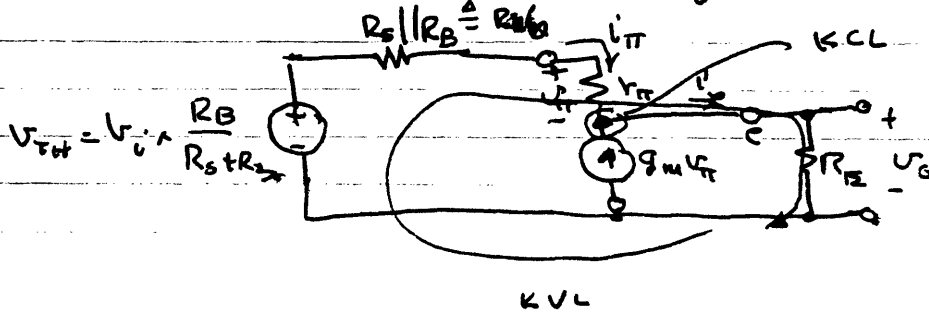
$$V_o - \frac{R_f}{R_s} V_i - V_i = 0 \quad \text{or} \quad V_o = V_i \left(1 + \frac{R_f}{R_s} \right)$$

NOTE that this is non-inverting /

Example (called an emitter follower (using a transistor)



convert to Thevenin equivalent



$$V_{TH} - i_{\pi} R_{TH} - v_{\pi} - i_e R_E = 0$$

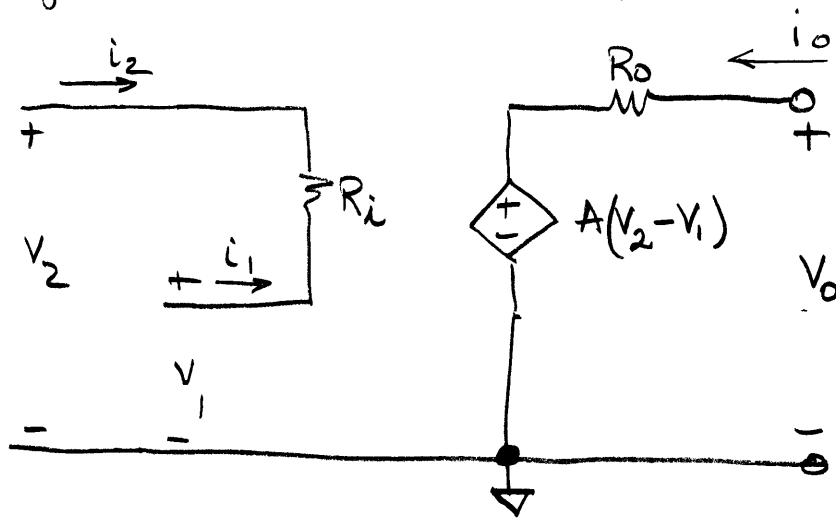
$$i_e = g_m v_{\pi} + i_{\pi} = (g_m r_{\pi} + 1) i_{\pi}$$

$$V_{TH} - i_{\pi} [R_{TH} + R_{\pi} + R_E (g_m r_{\pi} + 1)] = 0$$

$$i_{\pi} = \frac{V_{TH}}{R_{TH} + r_{\pi} + (1 + g_m r_{\pi}) R_E}$$

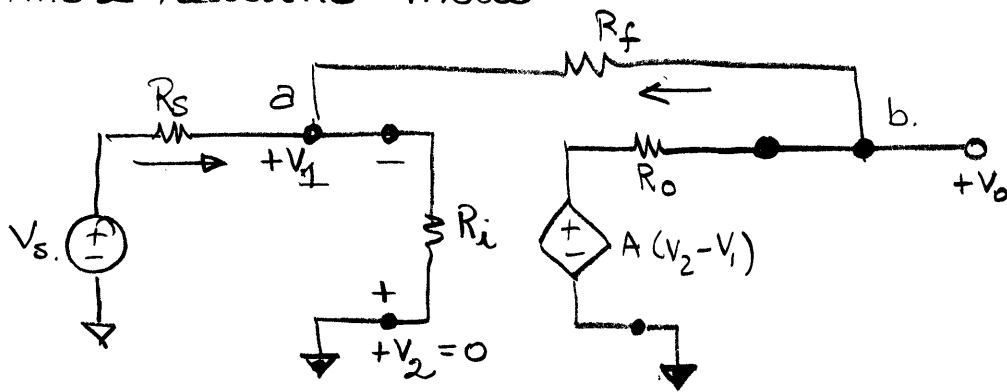
$$V_o = i_e R_E = \frac{R_E (g_m r_{\pi} + 1) V_{TH}}{R_{TH} + r_{\pi} + (1 + g_m r_{\pi}) R_E}$$

6.7 Equivalent circuits for the operational amplifier



$\mu A 740$
 $R_i = 2 \times 10^6$
 $A = 10^5$
 $R_o = 75$

input impedance of the inverting op-amp circuit using the more realistic model.



$$\text{KCL @ } a \quad + \text{ in} \quad \frac{V_s - V_1}{R_s} - \frac{V_1}{R_i} + \frac{V_0 - V_1}{R_f} = 0$$

$$\text{KCL @ } b \quad + \text{ in} \quad -\frac{V_0 - V_1}{R_f} - \frac{V_0 - A(V_2 - V_1)}{R_o} = 0$$

$$V_1 \left(-\frac{1}{R_s} - \frac{1}{R_i} - \frac{1}{R_f} \right) + V_0 \left(\frac{1}{R_f} \right) = \frac{1}{R_s} V_s$$

$$V_1 \left(+\frac{1}{R_f} - \frac{A}{R_o} \right) + V_0 \left(-\frac{1}{R_f} - \frac{1}{R_o} \right) = 0$$

$$V_o = \frac{-A + \frac{R_o}{R_f}}{\frac{R_s}{R_f} \left(1 + A + \frac{R_o}{R_i}\right) + \left(\frac{R_s}{R_i} + 1\right) + \frac{R_o}{R_f}} V_s$$

as $A \rightarrow \infty$ $V_o \rightarrow \frac{-A}{\frac{R_s}{R_f} A} V_s = -\frac{R_f}{R_s} V_s$

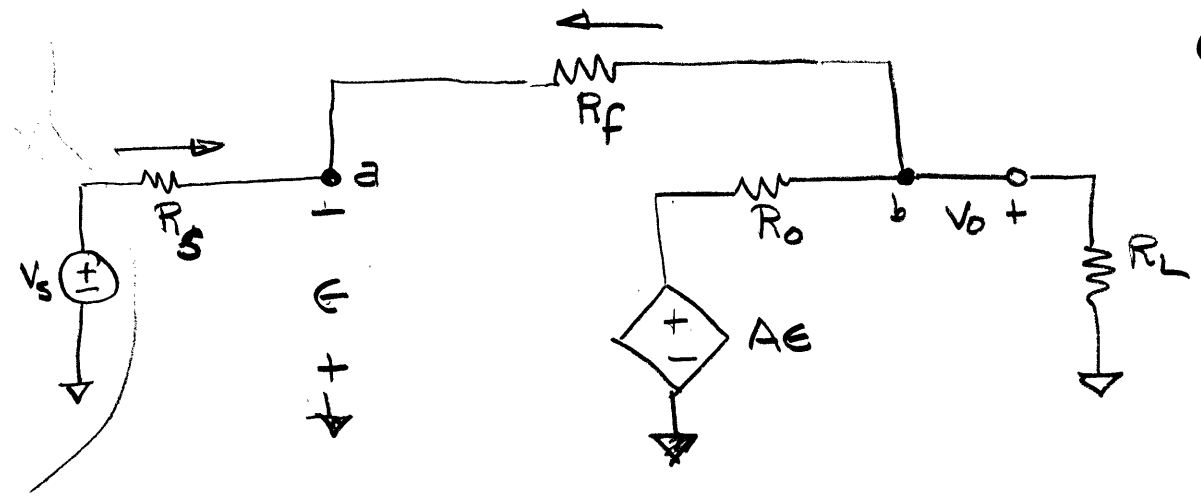
out of curiosity what is V_i ?

$$V_i = \frac{\begin{bmatrix} \frac{1}{R_s} V_s & \frac{1}{R_f} \\ 0 & -\frac{1}{R_f} - \frac{1}{R_o} \end{bmatrix}}{\begin{bmatrix} \left(-\frac{1}{R_s} - \frac{1}{R_i} - \frac{1}{R_f}\right) & \frac{1}{R_f} \\ \frac{1}{R_f} - \frac{A}{R_o} & -\frac{1}{R_f} - \frac{1}{R_o} \end{bmatrix}} = \frac{\frac{1}{R_s} \left(-\frac{1}{R_f} - \frac{1}{R_o}\right) V_s}{\begin{matrix} \left(-\frac{1}{R_s} - \frac{1}{R_i} - \frac{1}{R_f}\right) \left(\frac{1}{R_f} - \frac{1}{R_o}\right) \\ -\left(\frac{1}{R_f}\right) \left(\frac{1}{R_f} - \frac{A}{R_o}\right) \end{matrix}}$$

$$V_i = \frac{-\frac{1}{R_s R_s} - \frac{1}{R_s R_o}}{-\frac{1}{R_s R_f} - \frac{1}{R_i R_f} - \frac{1}{R_f^2} + \frac{1}{R_s R_o} + \frac{1}{R_i R_o} + \frac{1}{R_o R_f} - \frac{1}{R_f^2} + \frac{A}{R_o R_f}} V_s$$

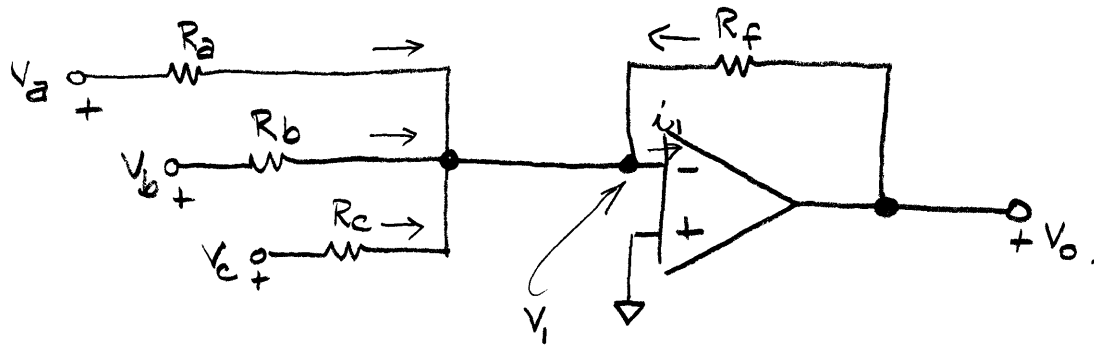
as $A \rightarrow \infty$ $V_i \rightarrow 0$

(c)



KCL @ a + in $+ \underline{V_s + \epsilon}$

6.4. The summing amplifier



KCL at inverting input terminal since, $V_1 \rightarrow 0$

$$\frac{V_a - V_1}{R_a} + \frac{V_b - V_1}{R_b} + \frac{V_c - V_1}{R_c} + \frac{V_o - V_1}{R_f} - i_1 = 0$$

Ideal op amp

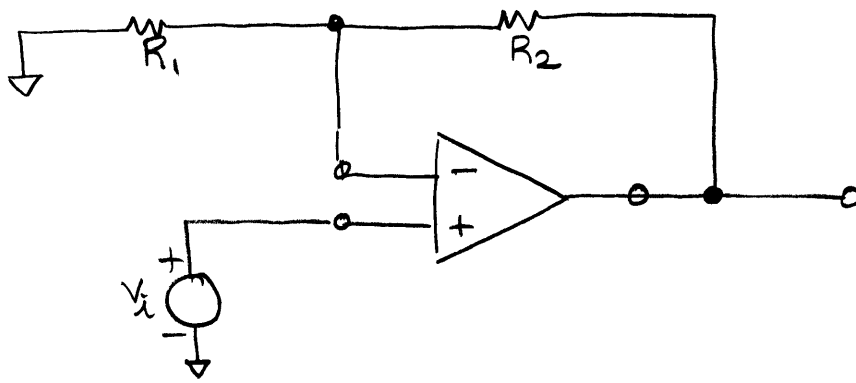
$$\therefore \frac{V_a}{R_a} + \frac{V_b}{R_b} + \frac{V_c}{R_c} + \frac{V_o}{R_f} = 0.$$

$$V_o = -R_f \left(\frac{V_a}{R_a} + \frac{V_b}{R_b} + \frac{V_c}{R_c} \right).$$

suppose $R_a = R_b = R_c = R_s$.

$$V_o = -\frac{R_f}{R_s} (V_a + V_b + V_c).$$

Linear non-inverting amplifier



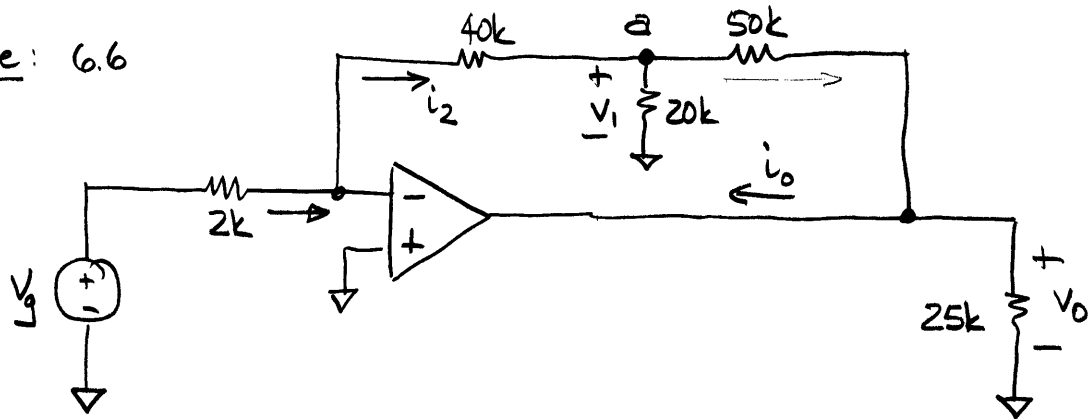
differences

$$A_v \cong 1 + \frac{R_2}{R_1}$$

$$R_N \cong \frac{A R_i}{1 + \frac{R_2}{R_1}}$$

$$R_{out} \cong 0.$$

Example: 6.6



Assume ideal op-amp. $V_g = 0.15$ volt Calculate V_1, V_0, i_2 .

use KCL at inverting input of op-amp. - in

$$-\frac{0.15 - 0}{2} + \frac{0 - V_1}{40} = 0$$

$$-\frac{0.15}{2} - \frac{V_1}{40} = 0 \quad V_1 = -3V$$

use KCL at node a. + out

$$\frac{V_1 - 0}{40} + \frac{V_1}{20} + \frac{V_1 - V_0}{50} = 0$$

$$\frac{V_1}{40} + \frac{V_1}{20} + \frac{V_1}{50} - \frac{V_0}{50} = 0$$

$$V_1 \left(\frac{1}{4} + \frac{2}{4} + \frac{1}{5} \right) = \frac{V_0}{5}$$

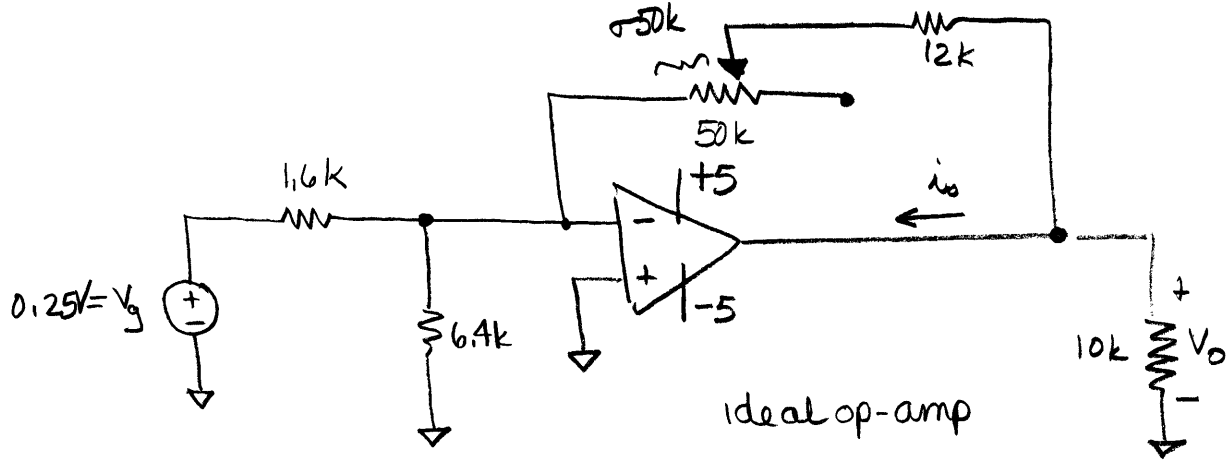
$$V_1 \left(\frac{3}{4} + \frac{1}{5} \right) = \frac{V_0}{5}$$

$$V_0 = 5V_1(0.95) = 5(-3)(0.95) = -14.25$$

use Ohm's Law

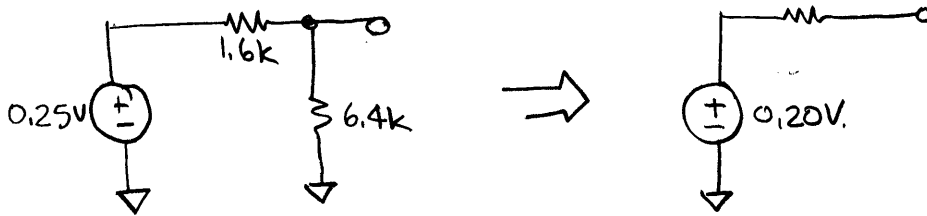
$$i_2 = \frac{0 - V_1}{40k} = \frac{-(-3)}{40k} = 0.075 \text{ mA} = 75 \mu\text{A}$$

6.8



- (a) Find the range of σ for which the op-amp does not saturate.
 (b) Find i_o when $\sigma = 0.272$

Thevenize the input circuit

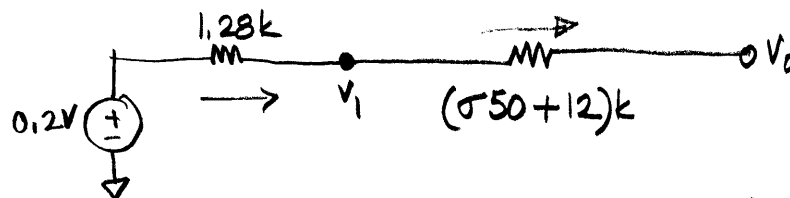


$$V_{oc} = \frac{6.4}{1.6+6.4} \cdot 0.25 = \frac{6.4}{8.0} \cdot 0.25 = 0.20V$$

$$i_{sc} = \frac{0.25V}{1.6k} = 0.15625 \text{ mA}$$

$$R = \frac{V_{oc}}{i_{sc}} = 1.28k$$

Then



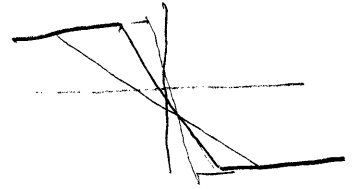
using KCL at the inverting input.

$$\frac{0.2 - 0}{1.28k} = \frac{0 - V_o}{(\sigma 50 + 12)k}$$

$$V_o = -\frac{(12 + \sigma 50)}{1.28} \cdot 0.2V$$

6.8 (cont.) the amplifier will saturate at $\pm 5V$,

$$V_o = -5V = -\frac{(12 + \sigma 50)}{1.28} (0.2)$$



solving for σ $\sigma = 0.4$

\therefore operational amplifier will not saturate for $0 \leq \sigma \leq 0.4$

When $\sigma = 0.272$

$$V_o = -\frac{(12 + 0.272(50))}{1.28} (0.2) = -4V.$$

\Rightarrow using KCL at output node.

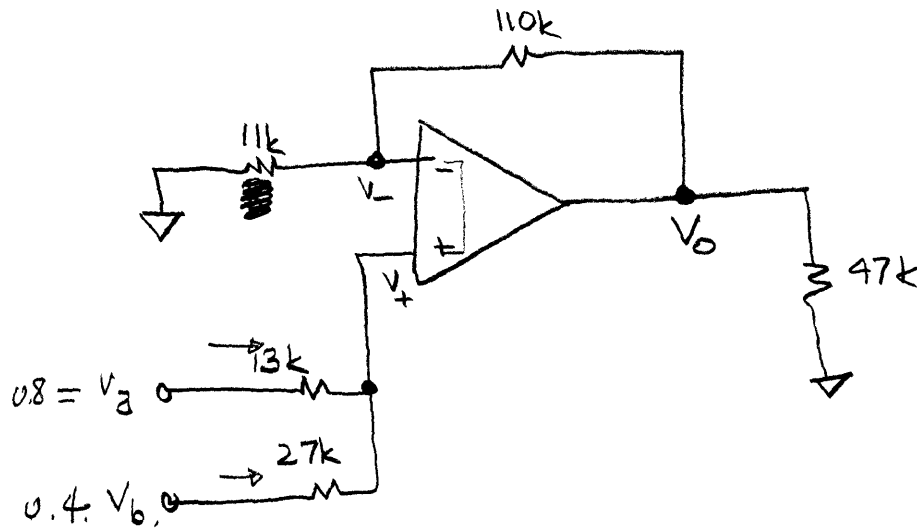
$$-\frac{0 - V_o}{(0.272)50 + 12} + i_o + \frac{V_o}{10} = 0$$

$$\frac{V_o}{25.6} + i_o + \frac{V_o}{10} = 0.$$

$$i_o = -\frac{V_o}{10} - \frac{V_o}{25.6} = 0.556 \text{ mA.}$$

6.21 The op-amp is ideal $V_a = 0.8\text{V}$,
 $V_b = 0.4\text{V}$.

Calculate V_o , i_a , i_b



ideal so $V_+ = V_- = V_g$ source.
input current = ϕ

$$\text{since } i_{in} = 0 \quad V_- = \frac{11k}{11k + 110k} V_o$$

$$\text{but } V_+ = V_- = \frac{11k}{11k + 110k} V_o.$$

$$V_o = \frac{110k + 11k}{11k} V_+ \Rightarrow V_o = \frac{121}{11} V_+ = 11 V_+$$

What is V_+ ?

$$\text{Use KCL} \quad \frac{V_a - V_+}{13k} + \frac{V_b - V_+}{27k} = 0.$$

$$27V_a - 27V_+ + 13V_b - 13V_+ = 0.$$

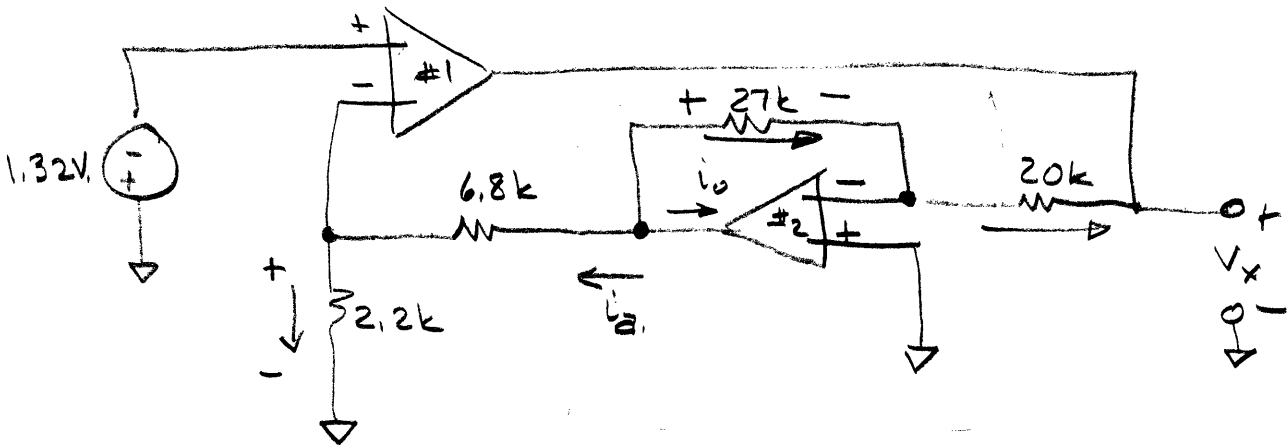
$$27V_a + 13V_b = 40V_+$$

$$V_+ = \frac{27V_a}{40} + \frac{13}{40} V_b$$

$$V_+ = V_-$$

$$V_o = 11(V_+) = 7.37 \text{ volts.}$$

6.39 op amps are ideal.



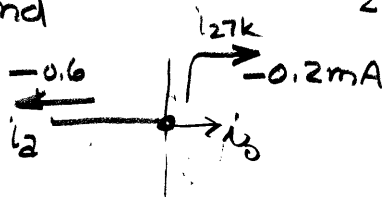
reasoning $V_{+ \#1} = -1.32V,$
 $V_{- \#1} = -1.32V,$

\Rightarrow current thru $2.2k$ resistor is $\frac{-1.32V}{2.2k} = -0.6mA$

by inspection $i_2 = -0.6mA.$

$$V_{o \#2} = -0.6mA (2.2k + 6.8k) = -5.4V.$$

i_{27k} resistor using virtual ground $\frac{(-5.4V) - (0)}{27k} = -0.2mA$



$$i_0 + i_2 + i_{27k} = 0$$

$$\begin{aligned} i_0 &= -i_2 - i_{27k} \\ &= -(-0.6) - (-0.2) \\ &= +0.8mA. \end{aligned}$$

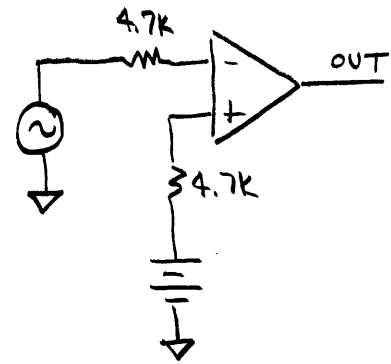
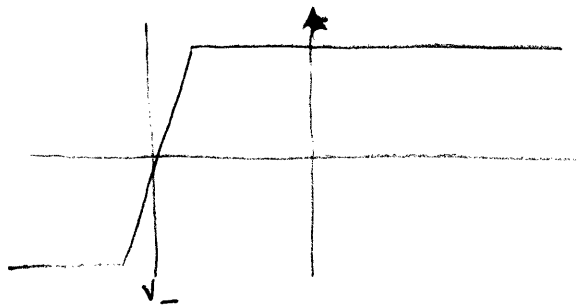
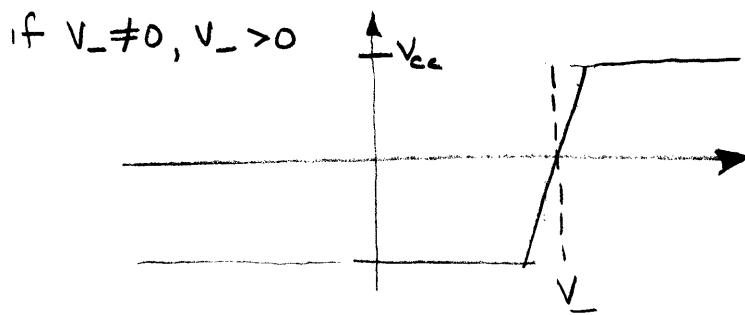
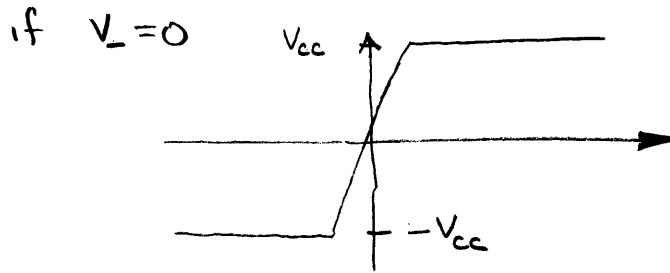
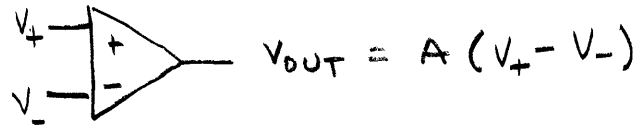
What's V_x ?

$$V_{-} = V_x + i_{27k} 20k.$$

$$0 = V_x + (-0.2mA)(20k) = 4V.$$

comparator - determine which of two signals is larger
 - know when a signal exceeds a given threshold

simplest comparator - high-gain differential amplifier



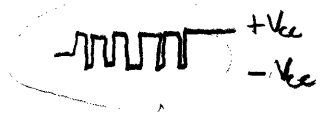
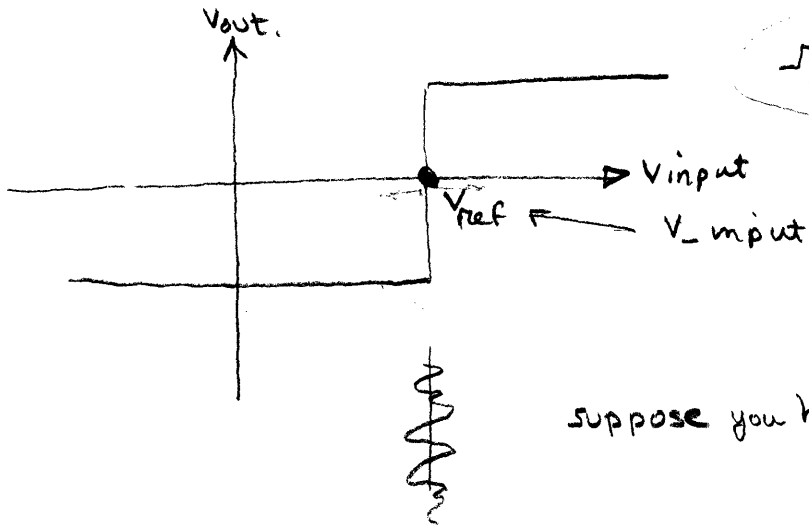
excellent for alarms

op-amps are usually not good comparators - use specialized IC chips such as LM311 with better output circuits

Never use negative feedback for a comparator - unstable.

need high gain for comparator
 lower gain reduces comparator action

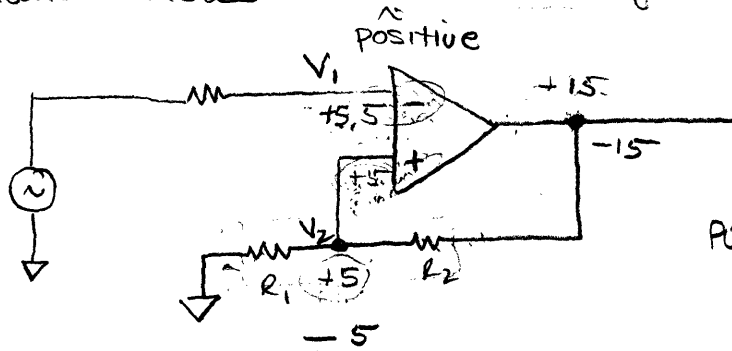
problems with noise



Comparator requires clean signal.

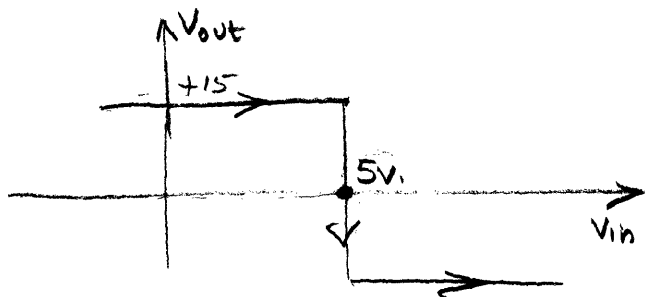
suppose you have 5V input with 0.1 volt noise

How to handle noise - use feedback to get hysteresis.

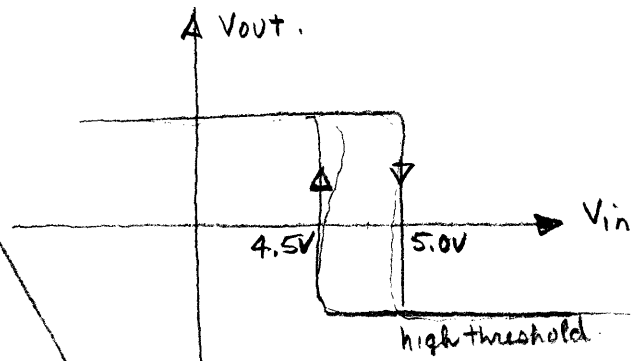


POSITIVE FEEDBACK!

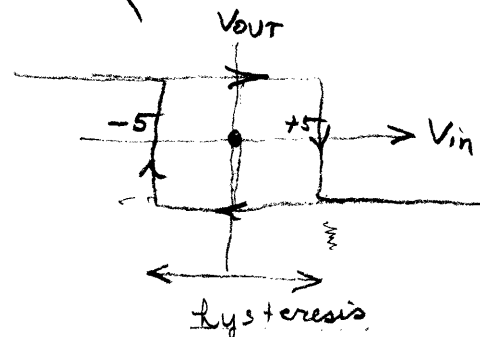
no feedback.



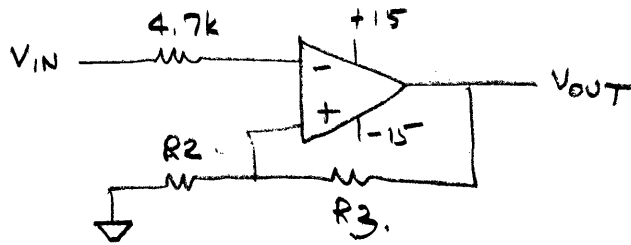
V_i case 1 < 5V,
case 2 = 5V,
case 3 > 5V.



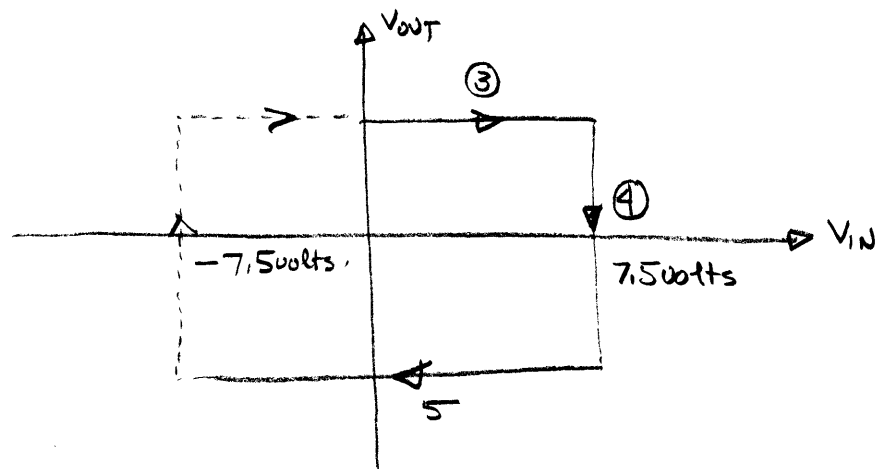
this is hysteresis



Schmitt trigger.



1. If $V_{IN} = 0$, $V_{OUT} = +15$.
2. If $R_2 = R_3$, then $V_+ = 7.5$ volts forcing $V_{OUT} = +15$ volts
3. If the input voltage V_{IN} rises to $+7.5$ volts, no change in V_{OUT}
4. When input rises to 7.50001 volts, output switches to -15 .
and V_+ changes to -7.5 V,
5. V_{IN} drops to -7.5 volts.



You can change switch points by changing ratio of R_2 and R_3 ,

i.e.
$$V_{\text{switch}} = \frac{R_2}{R_2 + R_3}$$

NON-LINEAR OP-AMP CIRCUITS

READING ASSIGNMENT: Horowitz, pgs. 124-127.

Abstract:

This laboratory will examine the principles and operation of non-linear op-amp circuits. The Schmitt trigger exhibits hysteresis and is often used to "square up" analog signals. The comparator is often used to monitor the presence or absence of analog signals. Effectively, these circuits convert analog signals into 0's or 1's. The performance of these circuits in the presence of simulated "noise" will be examined.

As a pre-lab exercise, you should determine the switching points and output voltages for the comparator and Schmitt trigger circuits and the voltage and resistor values needed to modify the Schmitt trigger. Remember to connect $+V_{CC}$ to +15 V and $-V_{CC}$ to -15 V.

Part 1 - The Comparator and Noise

When an op-amp is used without feedback, it is said to be "open-loop". Under these conditions the gain of the amplifier is $A(IN^+ - IN^-)$ where A is on the order of 100,000. For $(IN^+ - IN^-) > +150 \mu V$, the theoretical output is higher than $+V_{CC}$ and the output will saturate at +15 V. For $(IN^+ - IN^-) < -150 \mu V$, the theoretical output is lower than $-V_{CC}$ and the output will saturate at -15 V. The region of linear operation is very small and, for the most part, the amplifier's output will saturate at either +15 V or -15 V, depending on which of its inputs is greater. This type of circuit is known as a "comparator" because it compares the two input voltages to see which is greater and produces an output which is one of two states (+15 V or -15 V), depending on the result of the comparison. The circuits used in this part compare the input voltage at the inverting input to a "reference" voltage at the non-inverting input. Other configurations are possible; the reference may be on the inverting input and both the reference and input voltages may be any voltage between $+V_{CC}$ and $-V_{CC}$.

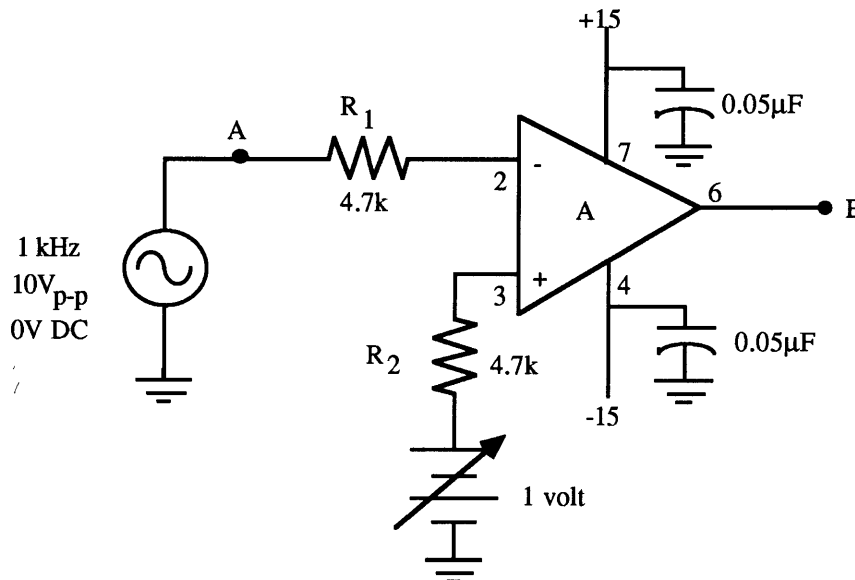


Figure 1 - Comparator circuit

- (1) Build the comparator circuit of Fig.1.
- (2) Display points A and B simultaneously on the oscilloscope and record each waveform in Table 8.1.
- (3) Carefully note the phase difference between A and B and note the two switching points.
- (4) Set the DC offset to +3 V. To do this, set the scope channel connected to point A to 2 V/cm. A +3 V DC offset will make the triangle wave jump up 1.5 cm when the mode is switched from AC to DC.
- (5) Record the waveforms in Table 8.2 and make note of the phase difference between A and B.
- (6) Repeat step 5 for a DC offset of -3 V.

A "noisy" signal can be thought of as the sum of a desired signal and other, unwanted signals. The result is a signal which generally follows the desired one, but which deviates from it. If a noisy signal is fed into a comparator, the noise will cause unwanted changes of state at the output as the desired signal crosses zero volts.

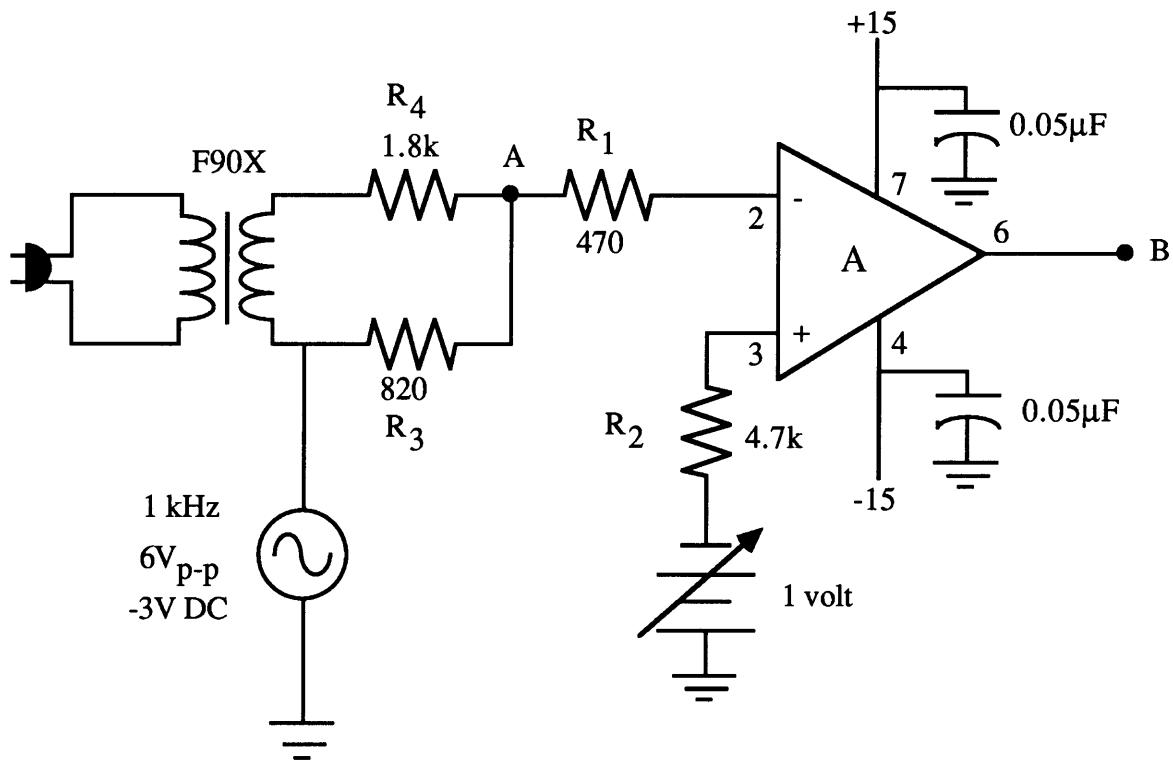


Figure 2 - Signal + "Noise" generator

- (1) Disconnect the signal generator from your circuit and adjust its output to that shown in Fig.2.
- (2) Build the circuit shown in Fig.2. Plug in the transformer. The transformer produces a sine wave at 60 Hz, which is added to the 1 KHz from the signal generator.
- (3) If the composite signal at A is not around 14 V_{p-p} you have not connected the circuit properly.
- (4) Display the waveforms at A and B and record them in Table 8.3 making special note of the phase difference between them. It will not be possible to get an absolutely stable trace on the oscilloscope.
- (5) Make note of exactly what takes place when the waveform at B changes state.

Part 2 - The Schmitt Trigger and Noise

The amplifiers you built in Lab 6 and 7 used negative feedback - a resistor feeding the output signal back to the inverting input. By using positive feedback - a resistor feeding the output back to the non-inverting input - the two switching points can be moved further apart. Consider the circuit of Fig.3 and assume that the input is zero, that the output is +15 V, and that $R_2 = R_3$. R_2 and R_3 set the voltage at the non-inverting input to +7.5 V, $(IN^+ - IN^-) > 0$, and the output is indeed forced to +15 V. If we raise the input to +7.50015 V, then $A(IN^+ - IN^-) = -15$ V and the output switches to -15 V. This changes the voltage at the non-inverting input to -7.5 V which makes $(IN^+ - IN^-)$ very negative, maintaining the output at -15 V. The output will stay at -15 V until the input drops to 7.50015 V which will make $A(IN^+ - IN^-) = +15$ V, setting the output to +15 V, setting the non-inverting input to +7.5 V. This makes $(IN^+ - IN^-)$ very positive, maintaining the output at +15 V. We can summarize the operation of the circuit by saying that, when the input goes above the upper switching point, the output will go negative and stay negative until the input goes below the lower switching point. This characteristic is called "hysteresis" and this type of circuit is called a "Schmitt trigger".

PLEASE CALL A TEACHING ASSISTANT TO CHECK YOUR DATA BEFORE CONTINUING.

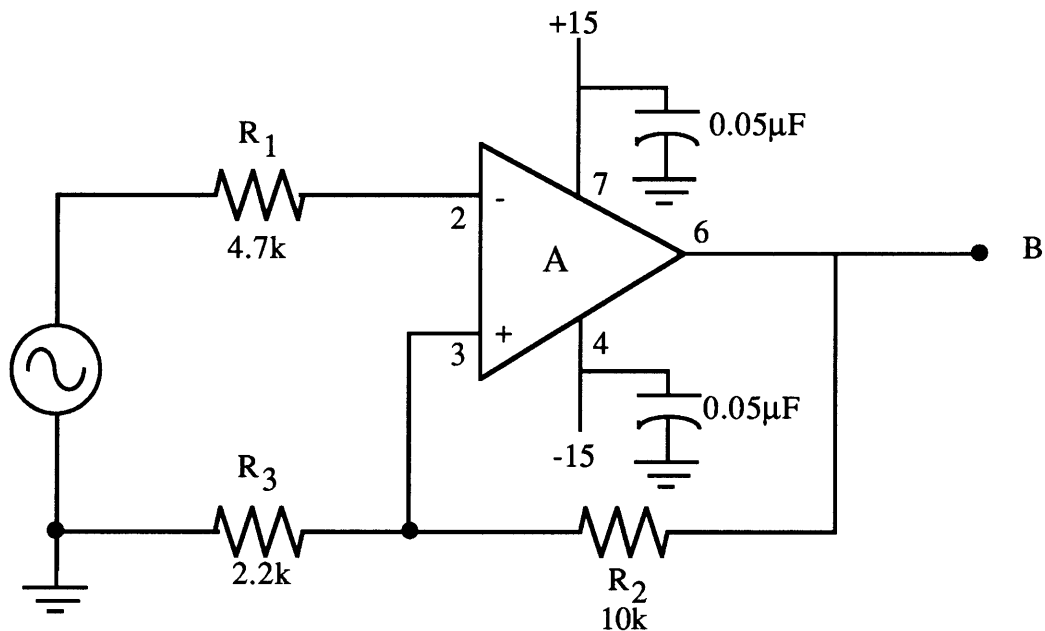


Figure 3 - Schmitt trigger

- (1) Build the Schmitt trigger circuit of Fig. 3 with $R_2 = 10K$ and $R_3 = 2.2K$.
- (2) Display points A and B simultaneously on the oscilloscope and record each waveform in Table 8.4.
- (3) Carefully note their phase difference and the two switching points.
- (4) Slowly vary the DC offset between +3 V and -3 V and observe what happens at point B.

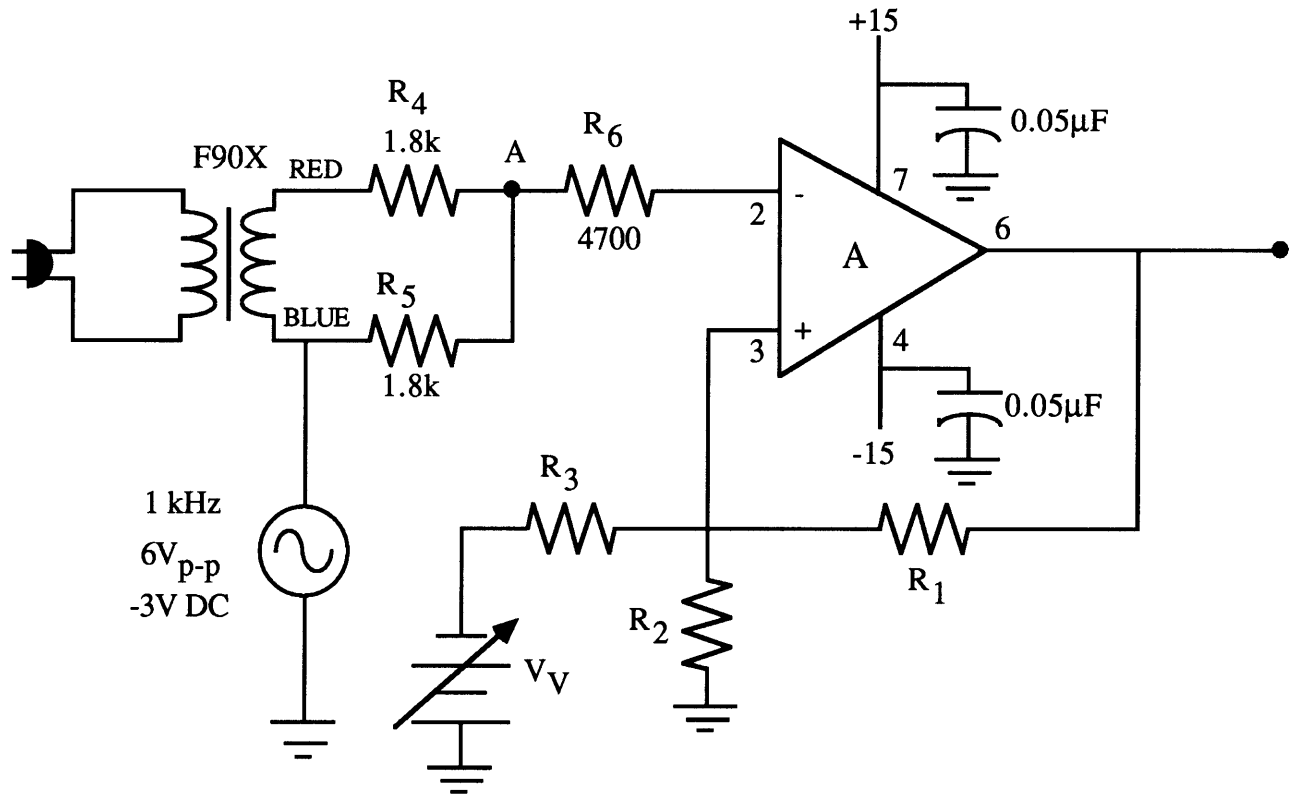


Figure 4

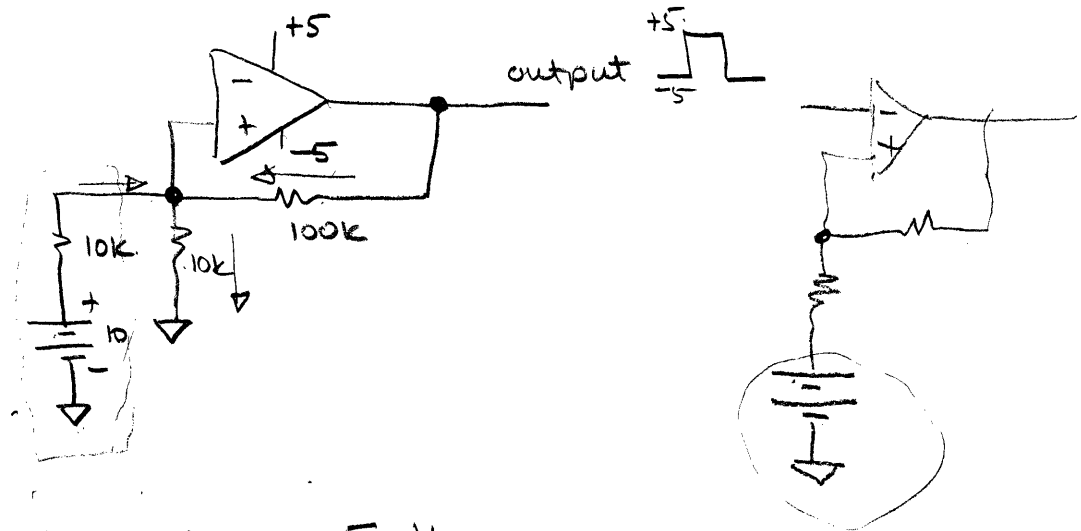
The Schmitt trigger can be used to eliminate signal noise.

- (1) Disconnect the signal generator from your circuit and set it as shown in Fig. 4.
- (2) Build the circuit shown in Fig. 4 and plug in the transformer. Select a variable supply voltage and standard values for R_1 , R_2 , and R_3 so that the switching points are +1 V and -7 V.
- (3) If the composite signal at A is not around 14 V_{p-p} you have not connected the circuit properly.
- (4) Display the waveforms at A and B and record them in Table 8.5 making special note of their phase difference. It will not be possible to get an absolutely stable trace on the oscilloscope.
- (5) Make note of exactly what takes place when the waveform at B changes state.

Questions:

1. (a) What are the two switching points?
(b) Describe what point B does as the triangle wave goes from its lowest to highest and back to its lowest voltage.
(c) Explain why the relative phase acts as it does when you change the DC offset.
2. (a) Describe the input waveform.
(b) Describe why point B changes state several times before stabilizing.
(c) Why does this sort of comparator have problems with a "noisy" signal?
3. (a) Calculate the switching points without using your experimental data.
(b) What switching points are indicated by the scope?
(c) Why aren't they the same as your calculated values?
(d) Explain why the signal at point B acts as it does when you change the DC offset.
4. (a) Show your calculations for R_1 , R_2 , R_3 , and V_v .
(b) How is the output different from that seen in Part 1?
(c) Why is a Schmitt trigger better at handling signals which contain undesirable noise?
(d) Are both R_2 and R_3 really needed?

sample calculation



+in

$$+ \frac{10 - V_+}{10k} - \frac{V_+}{10k} + \frac{5 - V_+}{100k} = 0.$$

$$100 - 10V_+ - 10V_+ + 5 - V_+ = 0.$$

$$105 - 21V_+ = 0.$$

$$V_+ = \frac{105}{21} \quad \text{for positive output.}$$

$$\frac{10 - V_+}{10k} - \frac{V_+}{10k} + \frac{-5 - V_+}{100k} = 0.$$

$$100 - 10V_+ - 10V_+ - 5 - V_+ = 0$$

$$95 - 21V_+ = 0.$$

$$V_+ = \frac{95}{21}$$

Real opamps

Symmetry

if you ground V_- and V_+ you expect 0 output.

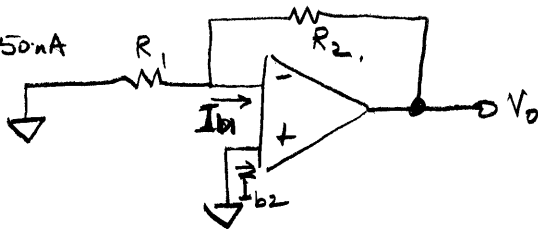
Input offset current

This is NOT true with real op-amps.

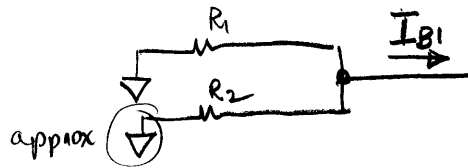
difference in input currents when you make $V_o = 0$.

bias current in input transistors.

typically 50pA - 50nA

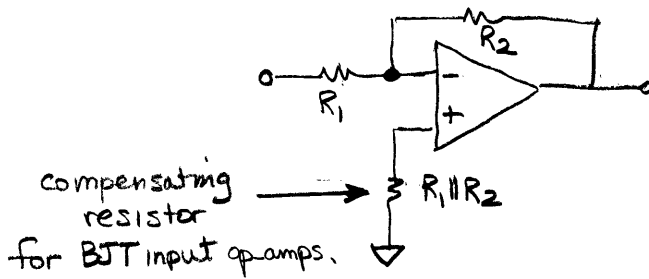


If V_o small, $V_d = V_+ - V_- \cong -I_{b1} R_1 \parallel R_2$ differential input voltage

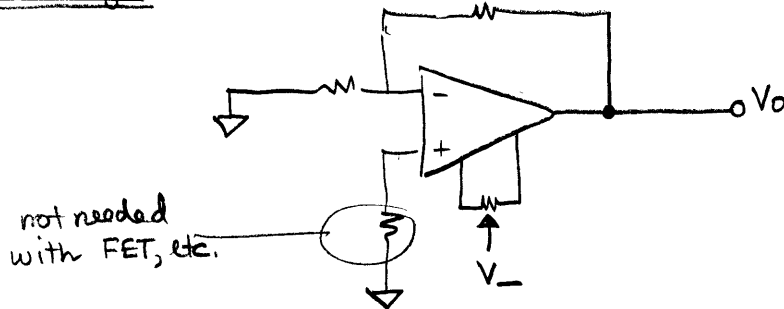


output offset voltage $V_o = A V_d \leq 1\text{mV}$ in practice

practical solution connect a resistor $R_p = R_1 \parallel R_2$ from V_+ to ground.



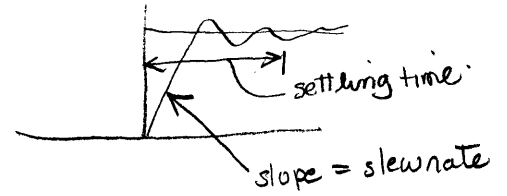
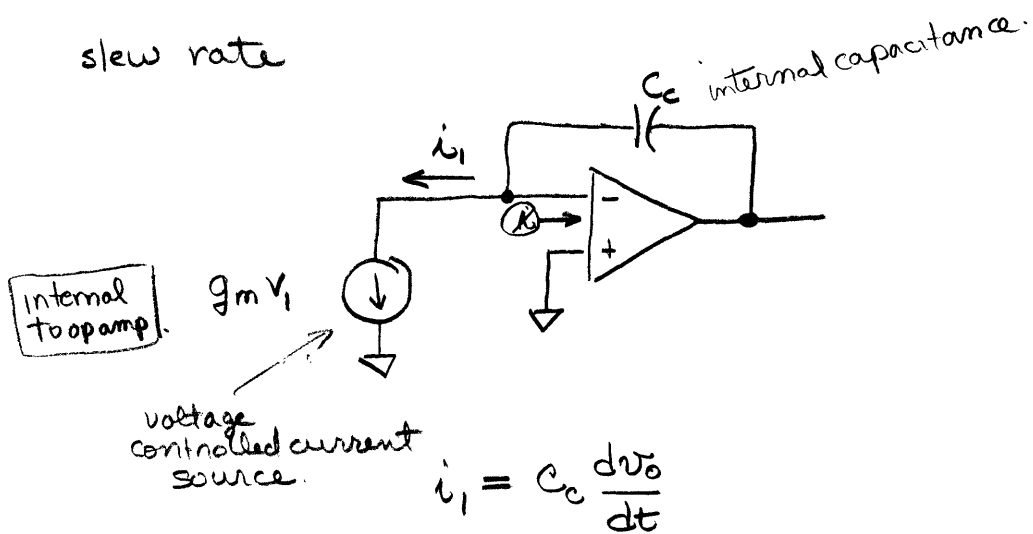
input offset voltage



voltage that must be applied to make $V_o = 0$ when $V_d = 0$.

unity gain bandwidth

slew rate



$$i_i = C_c \frac{dV_o}{dt}$$

$$S.R. \triangleq \frac{dV_o}{dt}$$

$$\Rightarrow S.R. = \frac{i_i}{C_c}$$

for the 741 $C_c = 30\text{pf}$, $i_i = 20\mu\text{A}$.

$$SR = \frac{20 \times 10^{-6}}{30 \times 10^{-12}} \cong 0.67 \frac{V}{\mu\text{sec}}$$

general purpose op-amp
741, 702, 709

B₁ - FET FET's for input, BJT's elsewhere.
LF 351, etc.

Special
AD380 high slew rate $500 \frac{V}{\mu\text{sec}}$.

①

we were discussing linear systems at our last meeting

$$\boxed{L.S.} \\ y = f(x)$$

example $y = \frac{dx}{dt} + \dots$

$$x = a_0 \frac{dy}{dt} + a_1 \frac{d^2y}{dt^2} + \dots + a_N \frac{d^Ny}{dt^N}$$

↑ source response.

if x_1 is the source, we find the response is y_1
 if Ax_1 is the source, we find the response is Ay_1

$$A(x_1) = a_1 \frac{dy_1}{dt} + a_2 \frac{d^2y_1}{dt^2} + \dots + a_N \frac{d^Ny_1}{dt^N}$$

if x_2 is the source we then find the response is

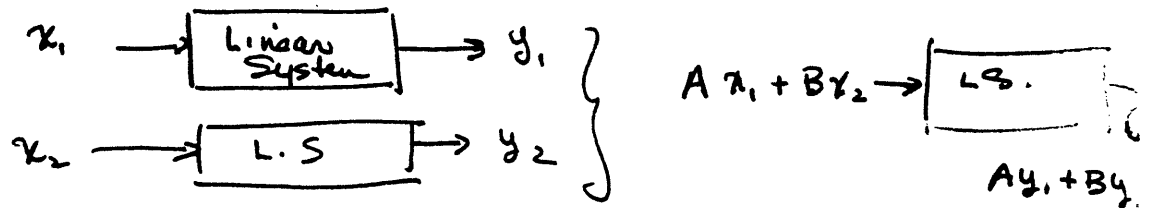
then if Bx_2 is the source " " " " " " is By_2

if $Ax_1 + Bx_2$ is the source

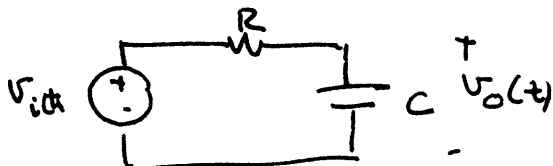
$$A(x_1) + B(x_2) = a_1 \left[\frac{dy_1}{dt} + B \frac{dy_2}{dt} \right] + a_2 \left[A \frac{dy_1}{dt} + B \frac{dy_2}{dt} \right] + \dots$$

hence it has the solution $Ay_1 + By_2$

Summary



Now how does that relate to the example we had last week?



$$v_i(t) = RC \frac{dv_o}{dt} + v_o$$

we found that

$$v_i(t) = V_3 \cos \omega t$$

then trying $v_o = A \cos \omega t + B \sin \omega t$

$$v_o(t) = \frac{V_3 \cos \omega t}{1 + (RC\omega)^2} + \frac{V_3 (RC\omega) \sin \omega t}{1 + (RC\omega)^2}$$

If we used the imaginary source

$$v_i(t) = V_s e^{j\omega t} \quad \text{to find } v_o(t) = ?$$

$$e^{j\omega t} = \cos \omega t + j \sin \omega t$$

we found

$$v_o(t) = \left(\frac{j\omega C}{R + j\omega C} \right) V_s e^{j\omega t} = \frac{V_s (1 - j\omega RC) e^{j\omega t}}{(R\omega C)^2 + 1}$$

$$v_o(t) = \frac{V_s \cos \omega t}{1 + (RC\omega)^2} + \frac{V_s RC \sin \omega t}{1 + (RC\omega)^2}$$

$$+ j \left[\frac{V_s \sin \omega t}{1 + (RC\omega)^2} - \frac{V_s RC \cos \omega t}{1 + (RC\omega)^2} \right]$$

I observed that the real part of $v_o(t) \Rightarrow \text{Re}\{v_o(t)\}$ is exactly the correct solution of the $V_s \cos \omega t$ source.

Note $v_o(t) = \underbrace{V_s \cos \omega t}_{\text{input 1}} + j \underbrace{V_s \sin \omega t}_{\text{input 2}}$

to L.S. L.T.!

the j acts like a tag and produces an output which has j multiplying it.

linear, time invar.

Rules

- 1 If we have a source $v_i(t) = V_s \cos \omega t$
- 2 change it to $v_i(t) = V_s e^{j\omega t}$
- 3 then solve LTI system
- 4 the real part of the solution is due to the ~~real~~ source $\cos \omega t$

New Rules

- 1 if we have a source $v_i(t) = V_s \sin \omega t$
- 2 we change it to $v_i(t) = V_s e^{j\omega t} = V_s \cos \omega t + j V_s \sin \omega t$
- 3 then solve LTI system, $v_o(t)$
- 4 Take the imaginary part of the solution

General Rule

$$v_o(t) = V_s \cos(\omega t + \phi) = \frac{V_s}{\sqrt{2}} e^{j(\omega t + \phi)} + \frac{V_s}{\sqrt{2}} e^{-j(\omega t + \phi)}$$

③

Then we can use $v_i(t) = \sqrt{2} V_s e^{j(\omega t + \phi)} = \sqrt{2} \frac{V_s}{\sqrt{2}} e^{j\phi} e^{j\omega t}$
 as a source, again taking the real part of the result

Phasors

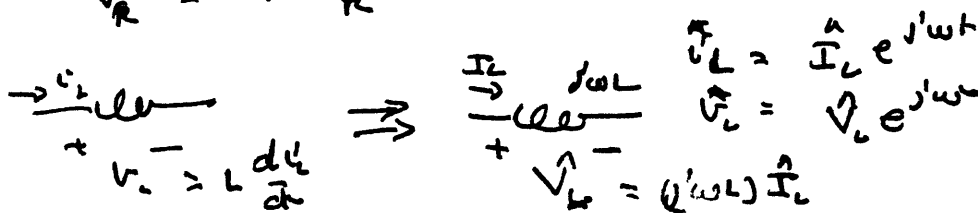
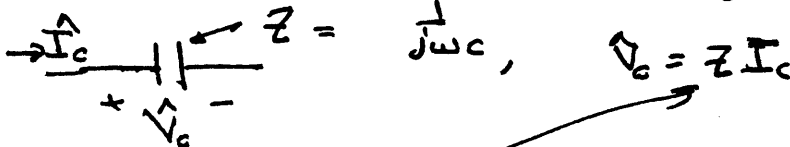
S.S.S.S with $e^{j\omega t}$ sources

The terminal relations

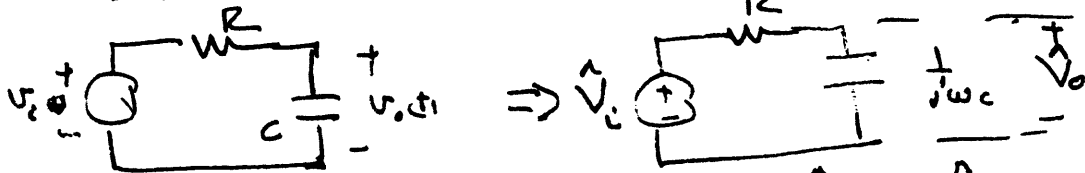
$$i_c = c \frac{dv_c}{dt} \Rightarrow \hat{I}_c e^{j\omega t} = j\omega c \hat{V}_c e^{j\omega t}$$

\hat{I}_c & \hat{V}_c are called phasors.

$$\hat{I}_c = j\omega c \hat{V}_c \text{ or } \hat{V}_c = \left(\frac{1}{j\omega c}\right) \hat{I}_c$$



Now let's return to our circuit



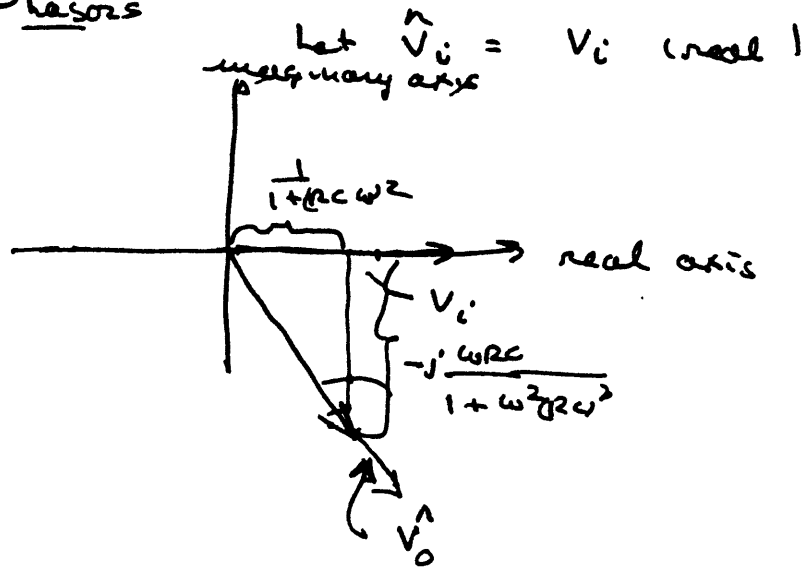
$$\hat{V}_o = \left(\frac{1 - j\omega RC}{1 + (R\omega C)^2} \right) \hat{V}_i$$

$$\hat{V}_o = \frac{\frac{1}{j\omega c} \hat{V}_i}{R + \frac{1}{j\omega c}} = \frac{\hat{V}_i}{1 + jR\omega c}$$

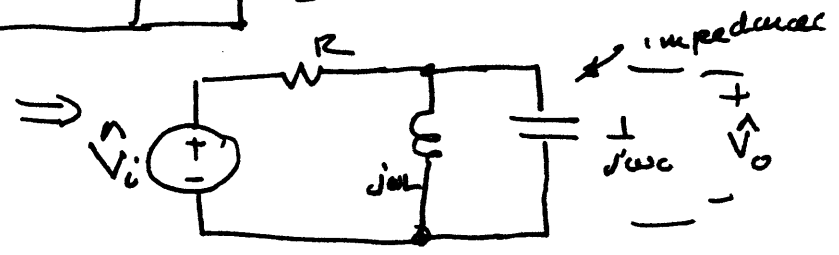
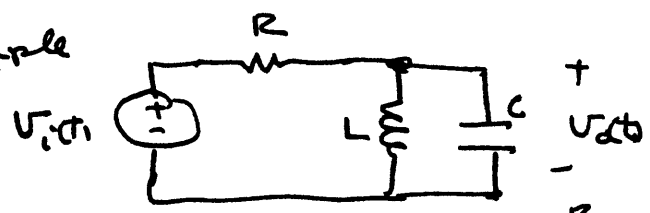
Voltage divider!

then $v_o(t) = \hat{V}_o e^{j\omega t}$, $v_o(t) = \text{Re}\{v_o(t)\}$

Phasors



Example



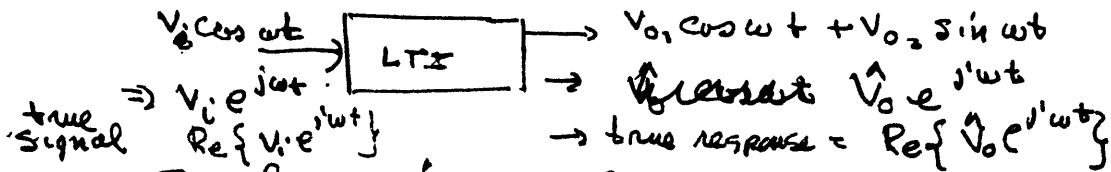
use voltage divider

$$\hat{V}_0 = \hat{V}_i \frac{(j\omega L \parallel \frac{1}{j\omega C})}{R + (j\omega L \parallel \frac{1}{j\omega C})} =$$

$$j\omega L \parallel \frac{1}{j\omega C} = \frac{(j\omega L)(\frac{1}{j\omega C})}{j\omega L + \frac{1}{j\omega C}} = \frac{j\omega L}{1 - \omega^2 LC}$$

so $\hat{V}_0 = \frac{V_i \left(\frac{j\omega L}{1 - \omega^2 LC} \right)}{\left(R + \frac{j\omega L}{1 - \omega^2 LC} \right)}$

We have been studying the sinusoidal-steady-state response of linear systems.



Two forms of complex numbers

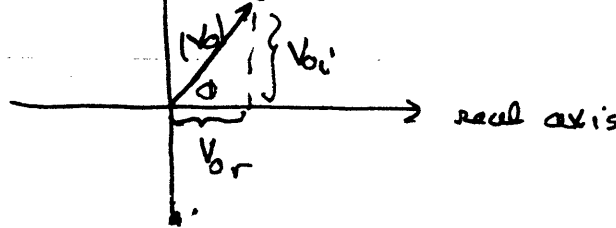
- Rectangular

$$\text{Re}\{\hat{V}_0\} = V_{or}$$

$$\hat{V}_0 = V_{or} + j V_{oi}$$

$$\text{Im}\{\hat{V}_0\} = V_{oi} \quad (\text{not to include } j!!)$$

- Polar



$$\hat{V}_0 = |V_0| e^{j\phi} = |V_0| [\cos\phi + j\sin\phi]$$

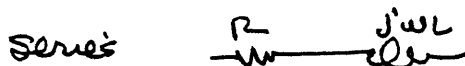
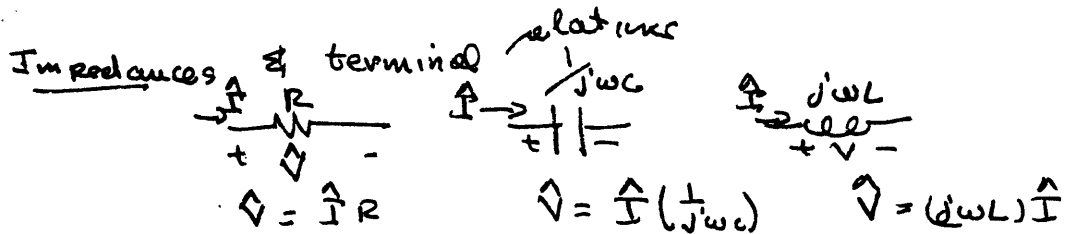
$$V_{or} = V_0 \cos\phi$$

$$V_{oi} = V_0 \sin\phi$$

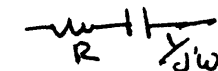
①
$$\text{Re}\{\hat{V}_0 e^{j\omega t}\} = \text{Re}\{(V_{or} + jV_{oi})(\cos\omega t + j\sin\omega t)\}$$

$$= V_{or} \cos\omega t - V_{oi} \sin\omega t$$
 ↗ equivalent (equal)

②
$$\text{Re}\{\hat{V}_0 e^{j\omega t}\} = \text{Re}\{V_0 e^{j\phi} e^{j\omega t}\} = V_0 \cos(\omega t + \phi)$$



$$Z = R + jwL$$

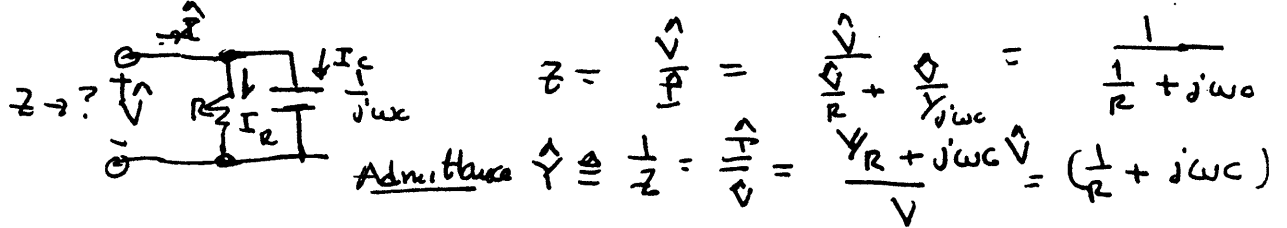


$$R + \frac{1}{jwc} = R - \frac{j}{wc}$$

$\text{Re}\{Z\}$ called Resistance

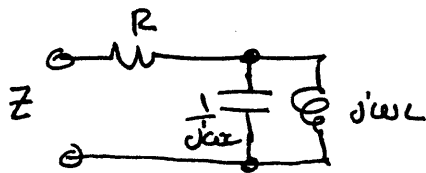
$\text{Im}\{Z\}$ called Reactance $\left\{ \begin{array}{l} + \text{ sign called Inductive React} \\ - \text{ sign called Capacitive } \end{array} \right.$

parallel elements



$\text{Re}\{\hat{Y}\}$ called conductance, (here = $\frac{1}{R}$)

$\text{Im}\{\hat{Y}\}$ called susceptance, (here = ωC)



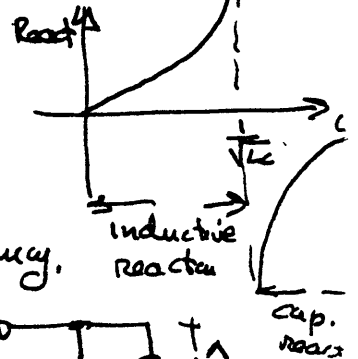
$$Z = R + \frac{1}{j\omega C} \parallel j\omega L$$

$$= R + \frac{L/C}{\frac{1}{j\omega C} + j\omega L}$$

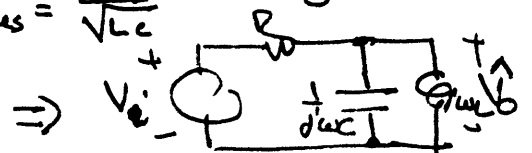
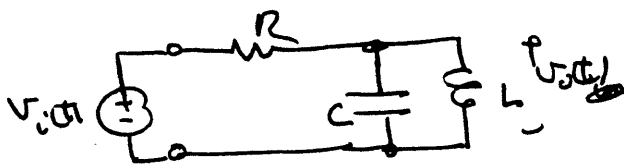
$$= R + \frac{j\omega L}{1 - \omega^2 LC}$$

$$\text{Re}\{Z\} = R$$

$$\text{Im}\{Z\} = \frac{\omega L}{1 - \omega^2 LC}$$



The frequency where $\text{Im}\{Z\} \rightarrow \infty$ is called the resonant frequency.
 $2\pi f_{res} = \frac{1}{\sqrt{LC}}$



phasor domain version

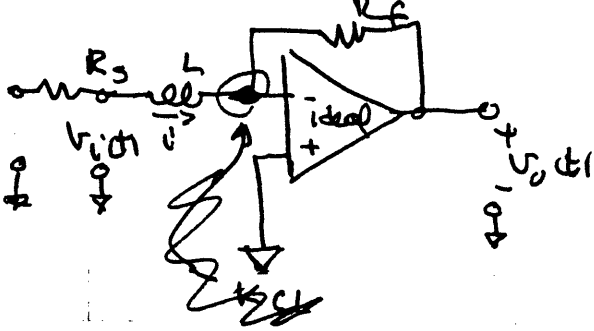
voltage divider $\hat{V}_o = \frac{j \text{Im}\{Z\}}{\text{Re}\{Z\} + j \text{Im}\{Z\}} V_i$

at $\omega = \omega_{res} = \frac{1}{\sqrt{LC}} \quad \hat{V}_o = V_i$

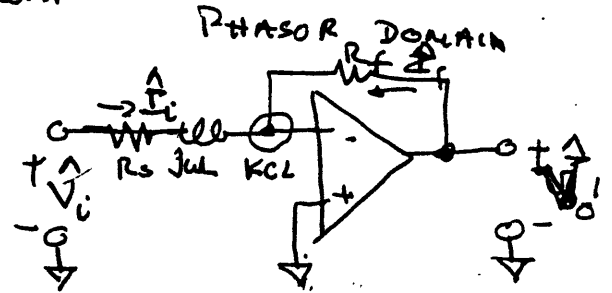
2/19/93

(3)

OP-AMP in Phasor domain



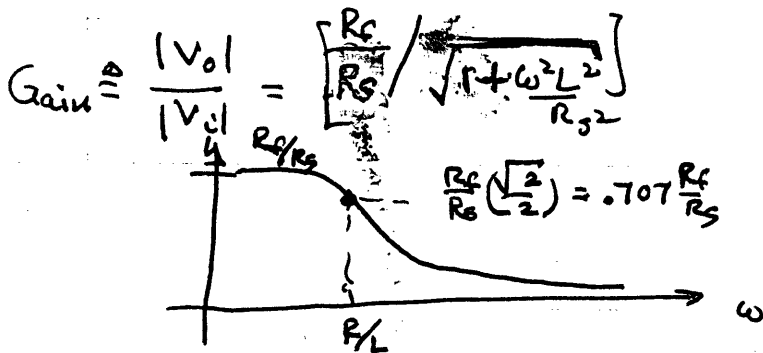
⇒



$$+ \hat{I}_i + \hat{I}_f = 0$$

$$\hat{I}_f = -\hat{I}_i = -\frac{\hat{V}_i}{R_s + j\omega L}$$

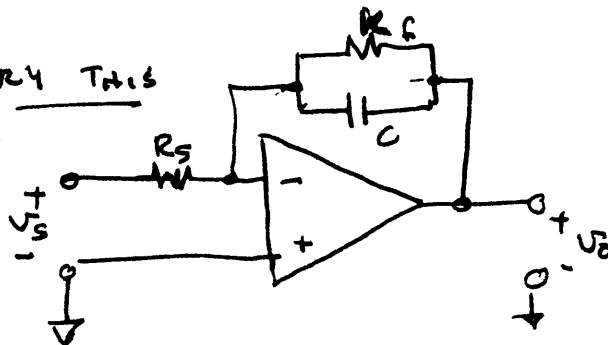
$$\hat{V}_o = + \hat{I}_f R = -\frac{R_f}{R_s + j\omega L} \hat{V}_i$$



$$= \frac{j\omega R L}{R_s + j\omega L} \cdot \frac{-R_f}{R_s + j\omega L} V_i$$

$$= \frac{-R_f (R_s - j\omega L)}{R_s^2 + \omega^2 L^2} V_i$$

TRY THIS



⇒ PHASOR DOMAIN VIEW OF CIRCUIT?

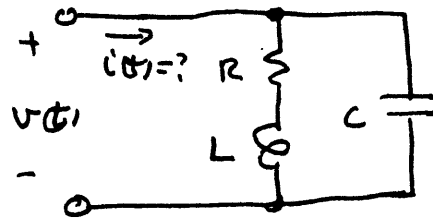
REVIEW

- ① Sinusoidal steady state
- ② $\cos \omega t \rightarrow e^{j\omega t}$
- ③ Redraw circuit in phasor domain
- ④ solve for "output" in terms of "input phasor"
- ⑤ multiply output phasor by $e^{j\omega t}$
- ⑥ take real-part to get solution as a function of time

2/19/93

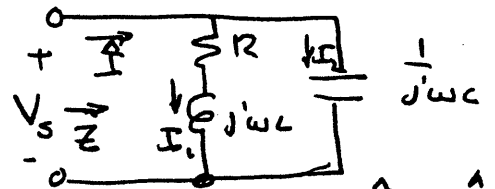
(4)

Another circuit



$$v(t) = V_s \cos \omega t$$

PHASOR DOMAIN



$$\hat{I} = ? = \hat{I}_1 + \hat{I}_2$$

$$\hat{I}_1 = \frac{V_s}{R + j\omega L}, \quad \hat{I}_2 = \frac{V_s}{j\omega C}$$

$$\hat{I} = V_s \left[\frac{1}{R + j\omega L} + j\omega C \right]$$

$$\hat{Z} = \frac{\hat{V}_s}{\hat{I}} = \frac{1}{\frac{1}{R + j\omega L} + j\omega C}$$

$$= \frac{R + j\omega L}{1 + j\omega RC - \omega^2 LC}$$

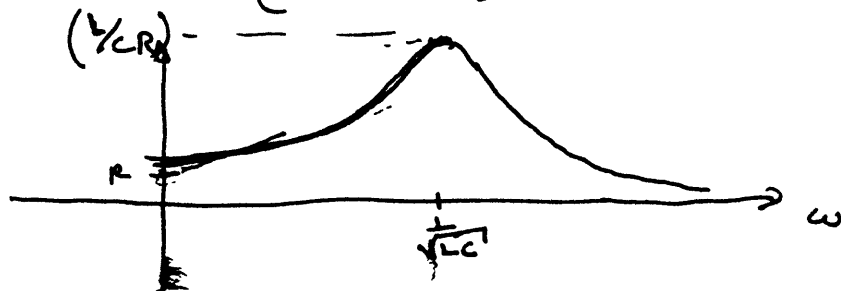
$$Z = \frac{(R + j\omega L)[(1 - \omega^2 LC) - j\omega RC]}{(1 - \omega^2 LC)^2 + \omega^2 R^2 C^2} = \frac{R(1 - \omega^2 LC) + R\omega^2 LC}{(1 - \omega^2 LC)^2 + \omega^2 R^2 C^2}$$

$$Z = R + jX$$

$$+ j \frac{[\omega L(1 - \omega^2 LC) - \omega R^2 C]}{(1 - \omega^2 LC)^2 + \omega^2 R^2 C^2}$$

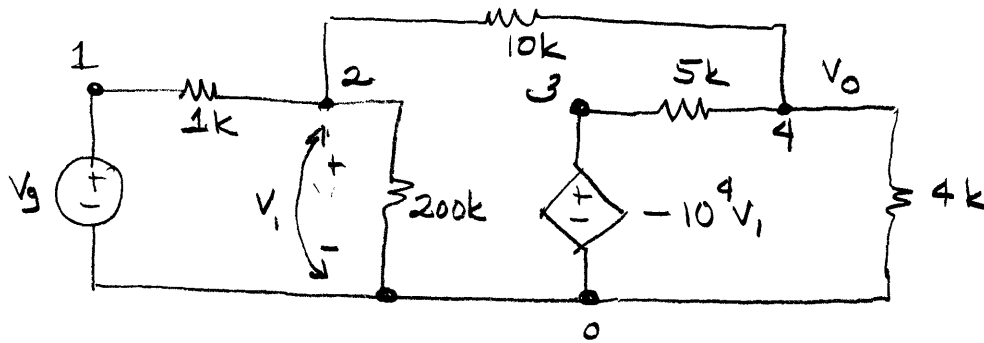
$$R = \text{Resistance} = \frac{R(1 - \omega^2 LC) + R\omega^2 LC}{(1 - \omega^2 LC)^2 + \omega^2 R^2 C^2} = \frac{R}{(1 - \omega^2 LC)^2 + \omega^2 R^2 C^2}$$

$$X = \text{Reactance} = \frac{\omega L(1 - \omega^2 LC) - \omega R^2 C}{(1 - \omega^2 LC)^2 + \omega^2 R^2 C^2}$$



for $\omega = 0$ $j\omega L = 0$, $j\omega C = 0$  (all that's left)

PSpice model of op amp.



```

Vg 1 0 DC 1
Rs 1 2 1000
Ri 2 0 200e3 → ∞
Rf 2 4 10e3
E1 3 0 2 0 -10e3 → -∞
Ro 3 4 5e3 → 0
R2 4 0 4e3
.END

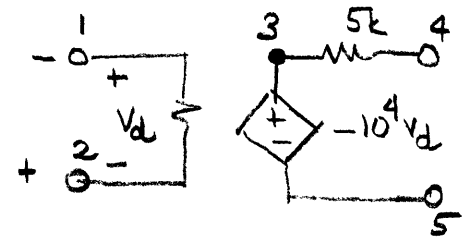
```

OP AMP SUBCIRCUIT

```

.SUBCKT OPAMP 1 2 4 5
R1 2 1 200e3
E1 3 5 2 1 10e3
Ro 3 4 5e3
.ENDS OPAMP

```

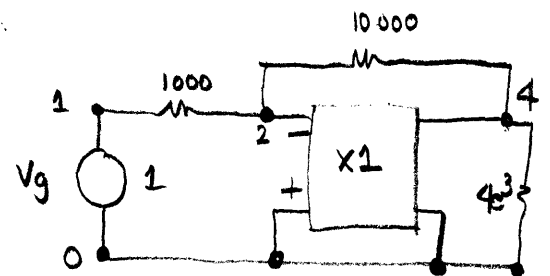


overall program

```

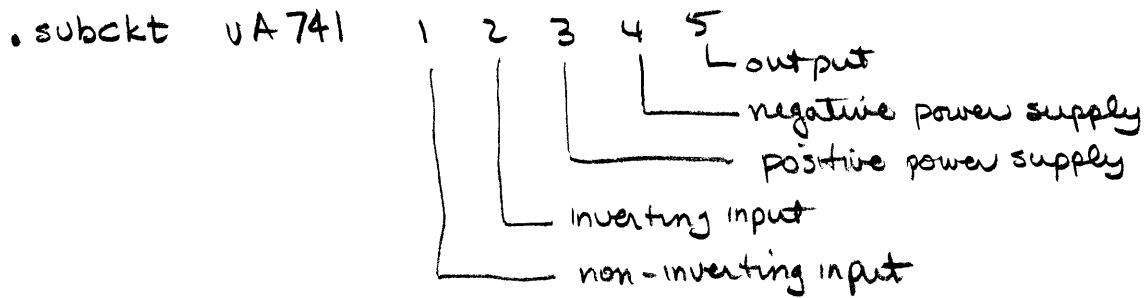
Vg 1 0 DC 1
Rs 1 2 1000
Rf 2 4 10e3
R1 4 0 4e3
.SUBCKT OPAMP 1 2 4 5
{
.ENDS OPAMP
X1 2 0 4 0 OPAMP
.END

```



using a uA741 model.

requires explicit power supplies



```
X1 0 2 5 6 4  
VCC1 5 0 DC 12  
VEE1 0 6 DC 12
```

```
.LIB EVAL.LIB  
← start  
← stop  
← increment  
.DC VG 0.5 0.5 1  
.PROBE  
.END
```

Step response.

```
T1 V1 T2 V2 T2 V3  
V1 1 0 PWL(0 0 1e-6 21 1000e-6 21)
```

```
.TRAN 20e-6 3000e-6  
# #
```

**** 02/21/93 23:03:52 **** Evaluation PSpice (Jan 1992) ****

Simple op-amp analysis using voltage controlled voltage source

**** CIRCUIT DESCRIPTION

```
Vg 1 0 DC 1
Rs 1 2 1000
Ri 2 0 200e3
Rf 2 4 10e3
E1 3 0 2 0 -10e3
Ro 3 4 5e3
R1 4 0 4e3
.probe
.end
```

**** 02/21/93 23:03:52 **** Evaluation PSpice (Jan 1992) ****

Simple op-amp analysis using voltage controlled voltage source

**** SMALL SIGNAL BIAS SOLUTION TEMPERATURE = 27.000 DEG C

NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE

(1) 1.0000 (2) .0027 (3) -27.4180 (4) -9.9697

VOLTAGE SOURCE CURRENTS

NAME CURRENT

Vg -9.973E-04

TOTAL POWER DISSIPATION 9.97E-04 WATTS

JOB CONCLUDED

TOTAL JOB TIME 1.22

**** 02/21/93 23:08:33 ***** Evaluation PSpice (Jan 1992) *****

Simple op-amp analysis using voltage controlled voltage source

**** CIRCUIT DESCRIPTION

```
*****
Vg  1  0  DC  1
Rs  1  2  1000
Rf  2  4  10e3
R1  4  0  4e3
.SUBCKT OPAMP 1 2 4 5
R1  2  1  200e3
E1  3  5  2  1  10e3
Ro  3  4  5e3
.ENDS OPAMP
X1  2  0  4  0  OPAMP
.probe
.end
```

**** 02/21/93 23:08:33 ***** Evaluation PSpice (Jan 1992) *****

Simple op-amp analysis using voltage controlled voltage source

**** SMALL SIGNAL BIAS SOLUTION TEMPERATURE = 27.000 DEG C

NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE

(1) 1.0000 (2) .0027 (4) -9.9697 (X1.3) -27.4180

VOLTAGE SOURCE CURRENTS

NAME CURRENT

Vg -9.973E-04

TOTAL POWER DISSIPATION 9.97E-04 WATTS

JOB CONCLUDED

TOTAL JOB TIME .90

**** 02/21/93 23:16:04 ***** Evaluation PSpice (Jan 1992) *****

Simple op-amp analysis using 741 library model

**** CIRCUIT DESCRIPTION

```
Vg 1 0 DC 1
Rs 1 2 1000
Rf 2 4 10e3
R1 4 0 4e3
X1 0 2 5 6 4 uA741
VCC1 5 0 DC 12
VEE1 0 6 DC 12
.LIB EVAL.LIB
.DC Vg 0 1 0.1
.probe
.end
```

**** 02/21/93 23:16:04 ***** Evaluation PSpice (Jan 1992) *****

Simple op-amp analysis using 741 library model

**** Diode MODEL PARAMETERS

```
X1.dx
IS 800.000000E-18
RS 1
```

**** 02/21/93 23:16:04 ***** Evaluation PSpice (Jan 1992) *****

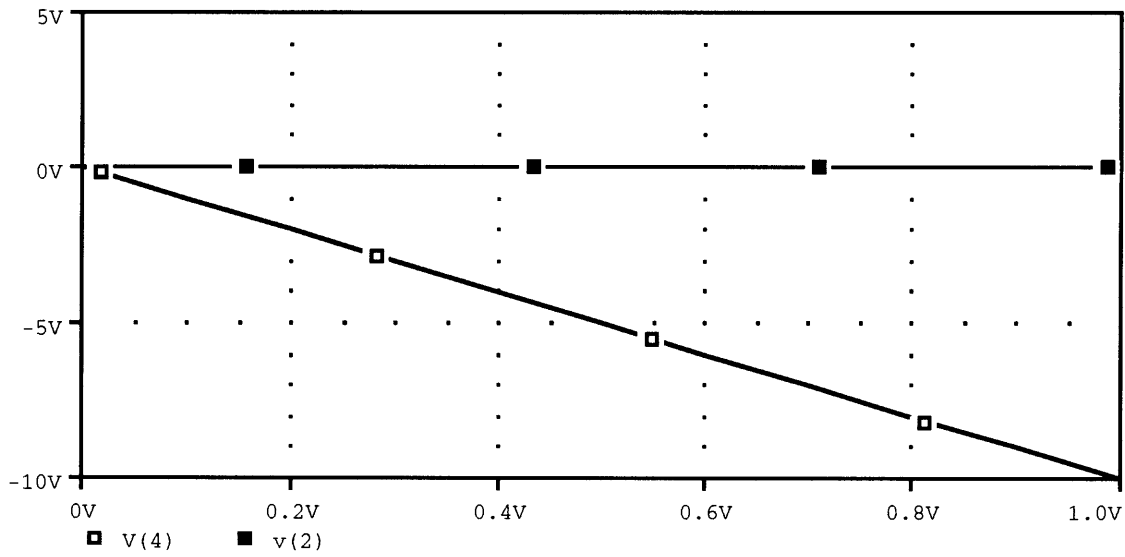
Simple op-amp analysis using 741 library model

**** BJT MODEL PARAMETERS

```
X1.qx
NPN
IS 800.000000E-18
BF 93.75
NF 1
BR 1
NR 1
```

JOB CONCLUDED

TOTAL JOB TIME 3.35



"Simple op-amp analysis using 741 library model" 02/21/93 23:16:04 27.0°
 Evaluation Probe 5.1 © 1992 MicroSim Corp.

**** 02/21/93 23:23:05 ***** Evaluation PSpice (Jan 1992) *****

Schmitt trigger using uA741 model

**** CIRCUIT DESCRIPTION

```
Vg 1 0 DC 1
Rs 1 2 1000
Ra 3 0 1e3
Rb 3 4 10e3
R1 4 0 4e3
X1 3 2 5 6 4 uA741
VCC1 5 0 DC 12
VEE1 0 6 DC 12
.LIB EVAL.LIB
.DC Vg 0 12 0.1
.probe
.end
```

**** 02/21/93 23:23:05 ***** Evaluation PSpice (Jan 1992) *****

Schmitt trigger using uA741 model

**** Diode MODEL PARAMETERS

```
X1.dx
IS 800.000000E-18
RS 1
```

**** 02/21/93 23:23:05 ***** Evaluation PSpice (Jan 1992) *****

Schmitt trigger using uA741 model

**** BJT MODEL PARAMETERS

```
X1.qx
NPN
IS 800.000000E-18
BF 93.75
NF 1
BR 1
NR 1
```

JOB CONCLUDED

TOTAL JOB TIME 22.80

**** 02/21/93 23:33:53 ***** Evaluation PSpice (Jan 1992) *****

Schmitt trigger using uA741 model

**** CIRCUIT DESCRIPTION

```
*****
Vg 1 0 PWL(0 0 100u 12)
Rs 1 2 1000
Ra 3 0 1e3
Rb 3 4 10e3
R1 4 0 4e3
X1 3 2 5 6 4 uA741
VCC1 5 0 DC 12
VEE1 0 6 DC 12
.LIB EVAL.LIB
.TRAN 1u 100u
.probe
.end
```

**** 02/21/93 23:33:53 ***** Evaluation PSpice (Jan 1992) *****

Schmitt trigger using uA741 model

**** Diode MODEL PARAMETERS

```
*****
X1.dx
IS 800.000000E-18
RS 1
```

**** 02/21/93 23:33:53 ***** Evaluation PSpice (Jan 1992) *****

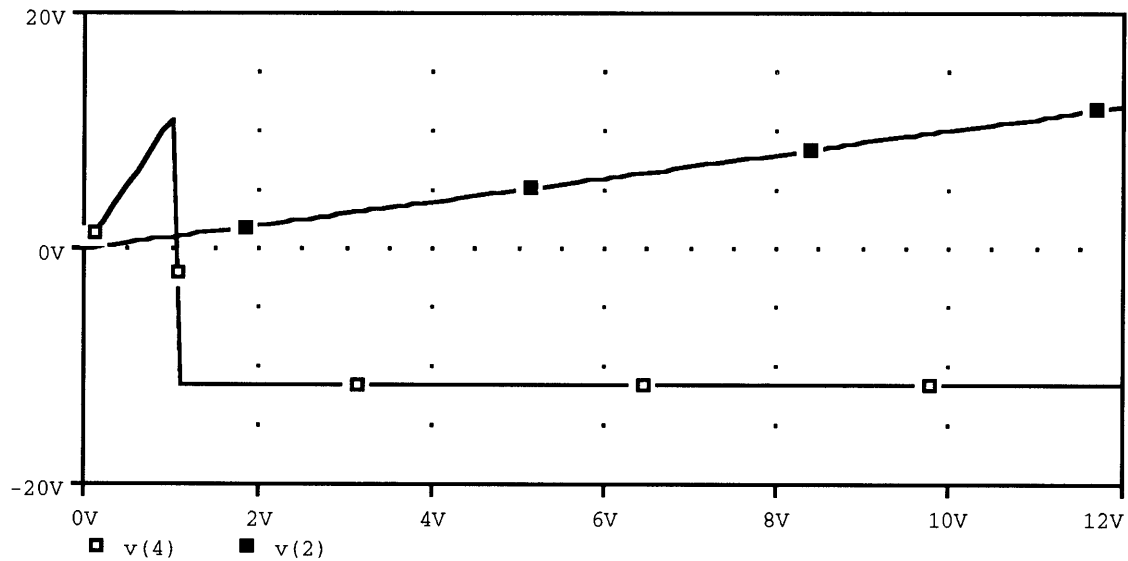
Schmitt trigger using uA741 model

**** BJT MODEL PARAMETERS

```
*****
X1.qx
NPN
IS 800.000000E-18
BF 93.75
NF 1
BR 1
NR 1
```

**** 02/21/93 23:33:53 ***** Evaluation PSpice (Jan 1992) *****

Schmitt trigger using uA741 model



"Schmitt trigger using uA741 model" 02/21/93 23:23:05 27.0°
 Evaluation Probe 5.1 © 1992 MicroSim Corp.

**** INITIAL TRANSIENT SOLUTION TEMPERATURE = 27.000 DEG C

NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE

(1) 0.0000 (2)-79.76E-06 (3)-99.49E-06 (4)-297.1E-06
(5) 12.0000 (6) -12.0000 (X1.6) 8.773E-06 (X1.7) -.0308
(X1.8) -.0308 (X1.9) 0.0000 (X1.10) -.6078 (X1.11) 11.9600
(X1.12) 11.9600 (X1.13) -.5939 (X1.14) -.5939 (X1.53) 11.0000
(X1.54) -11.0000 (X1.90) -.6104 (X1.91) 40.0000 (X1.92) -40.0000
(X1.99) 0.0000

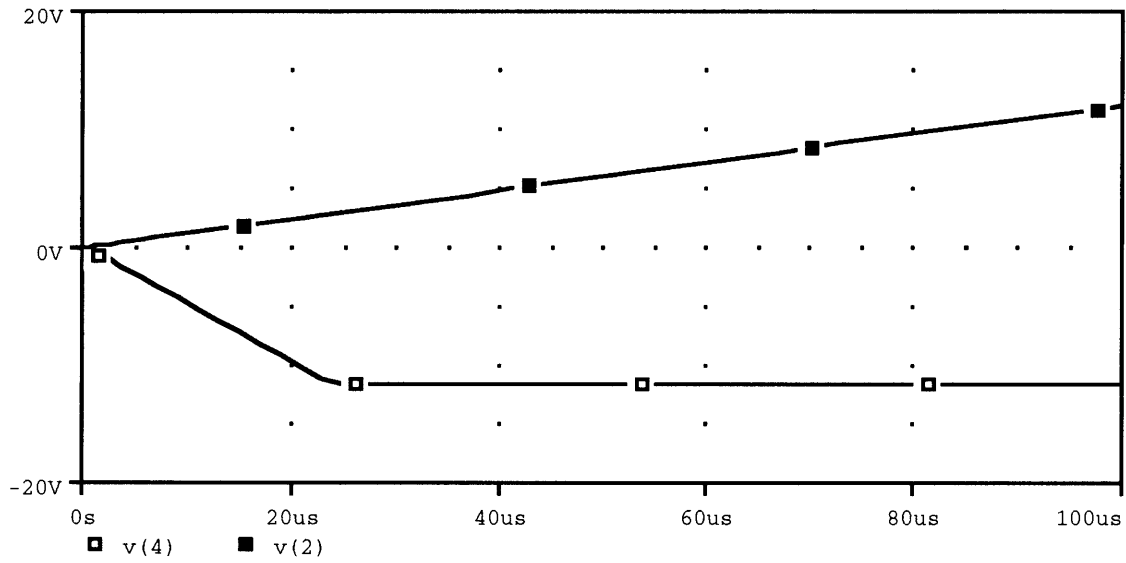
VOLTAGE SOURCE CURRENTS

NAME	CURRENT
Vg	-7.976E-08
VCC1	-1.337E-03
VEE1	-1.337E-03
X1.vb	8.773E-11
X1.vc	1.100E-11
X1.ve	1.100E-11
X1.vlim	-6.104E-04
X1.vlp	-4.061E-11
X1.vln	-3.939E-11

TOTAL POWER DISSIPATION 3.21E-02 WATTS

JOB CONCLUDED

TOTAL JOB TIME 10.53



Time
"Schmitt trigger using uA741 model" 02/21/93 23:33:53 27.0°
Evaluation Probe 5.1 © 1992 MicroSim Corp.

$$v(t) \leftrightarrow \text{Re}\{e^{j\omega t}\}$$

where the $e^{j\omega t}$ is assumed.

The real (as opposed to complex) time-dependent waveform can be written as $v \cos(\omega t + \theta) = \text{Re}\{v e^{j\omega t + \theta}\}$ where Re denotes the real part of the rectangular form obtained using the Euler identity.

A complex voltage $V(t) = V_m \cos(\omega t + \theta)$ can be written in phasor form as

$$\hat{V} = |V| e^{j\theta} = V_m e^{j\theta}$$

where the vertical bars denote the magnitude of V and $e^{j\omega t}$ is assumed.

Do problems 3-13, 3-14, 3-15 and 3-17

The advantages of phasor notation will be shown in the following section in which ac problems will be easily solved using Ohm's Law and complex currents, voltages and impedances expressed in phasor form.

14.8 AC circuits, phasors, impedance

The real voltage (or any other type of waveform) is the real part of the phasor voltage $v = \text{Re}\{\hat{v} e^{j\omega t}\}$, etc.

	instantaneous	phasor
R:	$v = iR$	$\hat{v} = R\hat{i}$
L:	$v = L \frac{di}{dt}$	$\hat{v} = j\omega L \hat{i}$
C:	$i = C \frac{dv}{dt}$	$\hat{i} = j\omega C \hat{v}$

where $\omega = 2\pi f$ radians/second and f is in Hertz.

$$\hat{v} = R\hat{i} + j\omega L\hat{i} + \frac{\hat{i}}{j\omega C} = \left(R + j\omega L + \frac{1}{j\omega C} \right) \hat{i}$$

The input impedance is then given by

$$\hat{Z} = \frac{\hat{v}}{\hat{i}} = R + j\left(\omega L - \frac{1}{\omega C}\right)$$

The circuit is in series resonance when

$$\omega L - \frac{1}{\omega C} = 0$$

The frequency for which this occurs is the resonant frequency ω_0 and is given by

$$\omega_0 L - \frac{1}{\omega_0 C} = 0$$

Therefore,

$$\omega_0 = \frac{1}{\sqrt{LC}}$$

and

$$f_0 = \frac{1}{2\pi\sqrt{LC}}$$

The input admittance is simply the reciprocal of the impedance

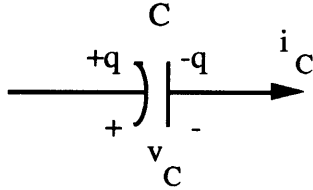
$$\hat{Y} = \frac{\hat{i}}{\hat{v}} = \frac{1}{\hat{Z}}$$

48.11 Capacitors

A capacitor can be simply defined by the relationship

$$q=Cv$$

where C is the capacitance in farads, q is the charge on the plates and v is the voltage between the plates; however, just like an inductor the voltage current relationship for a capacitor cannot be written without using integrals or derivatives.



Using the above definitions we can write the "Ohm's Law" for a capacitor as

$$i_C = \frac{dq}{dt} = C \frac{dv}{dt}$$

or, in integral form, as

$$v(t) = v(t_0) + \frac{1}{C} \int_{t_0}^t i_C(t) dt$$

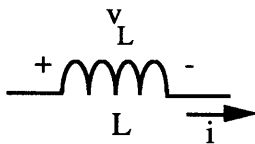
The energy stored in the capacitor can be computed as

$$W_C = \int_{t_0}^t v(t)i(t) dt = \int_{v(t_0)}^{v(t)} v \left(C \frac{dv}{dt} \right) dt = \int_{v(t_0)}^{v(t)} Cv dv$$

which is usually written in the more useful form

$$W_C = \frac{1}{2}C [v^2(t) - v^2(t_0)] \text{ joules}$$

48.12 Inductance



An inductor, unlike a simple resistor, requires a differential or integration relation to describe the relationship between voltage and current. For the inductor, this form of "Ohm's Law" is

$$v_L = L \frac{di}{dt}$$

or, in integral form,

$$i(t) = i(t_0) + \frac{1}{L} \int_{t_0}^t v_L(t) dt$$

The energy stored in the inductor is

$$W_L = \int_{t_0}^t p(t) dt = \int_{i(t_0)}^{i(t)} \left(L \frac{di}{dt} \right) (i dt) = \int_{i(t_0)}^{i(t)} Li di$$

which is more commonly written in the more useful form

$$W_L = \frac{1}{2}L [i^2(t) - i^2(t_0)] \text{ joules}$$

48.13 Combining inductances and capacitances

Inductors and capacitors obey rules very similar to resistors for combining. Remember that you CANNOT combine inductors AND capacitors. You can only combine like components.

For inductors in series:

$$L_{\text{equivalent}} = \sum_{n=1}^N L_n$$

For inductors in parallel:

$$L_{\text{equivalent}} = \frac{1}{\sum_{n=1}^N \frac{1}{L_n}}$$

For capacitors in series:

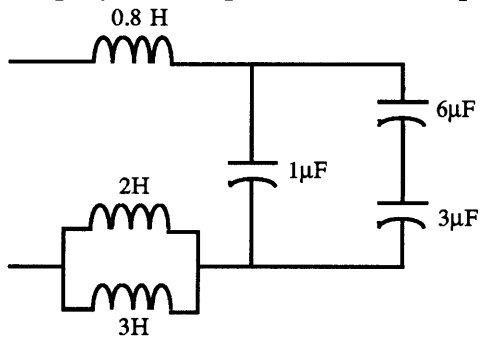
$$C_{\text{equivalent}} = \frac{1}{\sum_{n=1}^N \frac{1}{C_n}}$$

For capacitors in parallel:

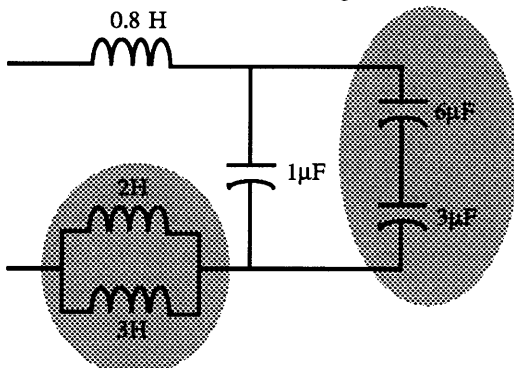
$$C_{\text{equivalent}} = \sum_{n=1}^N C_n$$

Example:

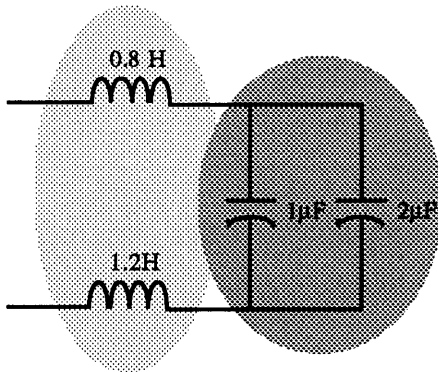
Simplify the complex network of capacitors and inductors shown below.



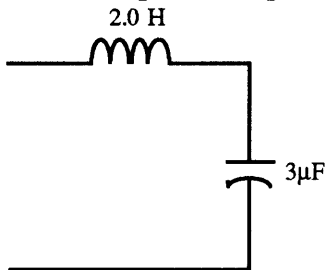
which can be reduced using the above expressions



Combining the two series capacitors and the two parallel inductances:



Where the parallel capacitances and series inductors can again be combined to give:

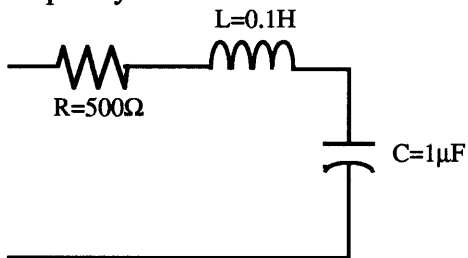


The series combination of the inductances in this last circuit may not be possible for certain applications.

48.17 Series Circuits

Example:

If the frequency is $\omega=1000$ radians/second, determine the input impedance and the resonant frequency



$$\hat{Z} = 500 + j(10^3)(0.1) - j \frac{1}{(10^3)(10^{-6})} = 500 + j100 - j1000$$

$$\hat{Z} = 500 - j900 = 1029 \angle -60.9^\circ$$

$$|\hat{Z}| = 1029 \Omega$$

$$\omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{(10^{-1})(10^{-6})}} = 3162 \frac{\text{radians}}{\text{second}}$$

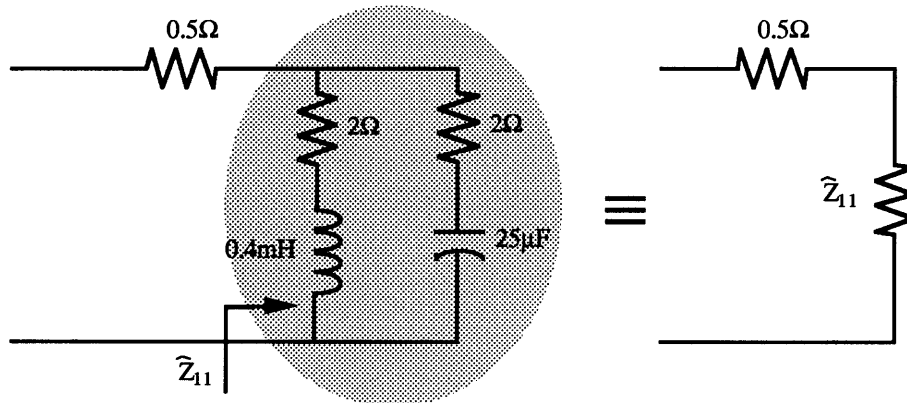
$$f_0 = \frac{1}{2\pi\sqrt{LC}} = \frac{1}{2\pi\sqrt{(10^{-1})(10^{-6})}} = 503 \text{ Hz}$$

Do problem 48-6 HINT: It is a series circuit.

48.18 Parallel Circuits

Example:

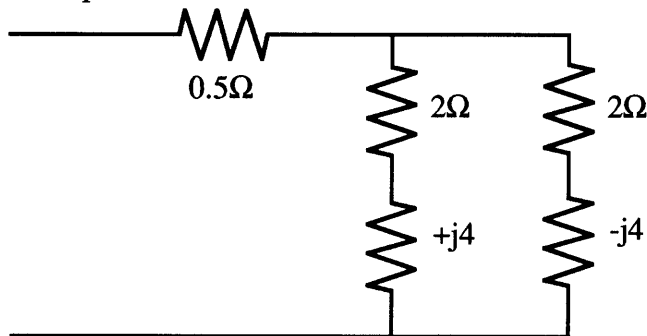
At a frequency of $\omega=10^4$ radians/second, determine the input impedance of the circuit shown below.



$$j\omega L = j(10^4)(0.4 \times 10^{-3}) = j4 \Omega$$

$$\frac{1}{j\omega C} = \frac{1}{j(10^4)(25 \times 10^{-6})} = \frac{1}{j0.25} = -j4 \Omega$$

The equivalent circuit is then



This is essentially two complex impedances in parallel with an equivalent parallel impedance given by

$$\hat{Z}_{11} = \frac{\hat{Z}_1 \times \hat{Z}_2}{\hat{Z}_1 + \hat{Z}_2} = \frac{(2+j4)(2-j4)}{(2+j4) + (2-j4)} = \frac{4+16}{4} = 5 \Omega$$

The input impedance of this circuit is the parallel impedance added to the 0.5Ω series resistance, i.e.

$$\hat{Z}_{IN} = 0.5 + \hat{Z}_{11} = 0.5 + 5 = 5.5 \Omega$$

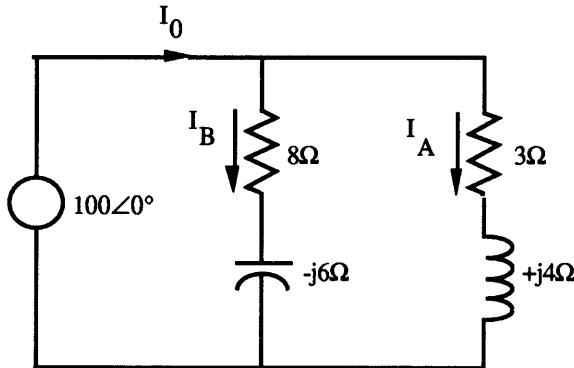
Since the input impedance is real, this circuit is at resonance. The input admittance is

$$\hat{Y}_{IN} = \frac{1}{\hat{Z}_{IN}} = \frac{1}{5.5} = 0.182 \text{ mhos}$$

Do problem 48-9

Example:

Find I_A and I_B as real currents in the circuit shown below where the source voltage is specified to be 100 volts at a phase angle of 0°



Using the Euler identity $Ve^{j(\omega t+\theta)} = V\cos(\omega t+\theta) + jV\sin(\omega t+\theta)$

$$\hat{I}_A = \frac{\hat{V}}{\hat{Z}} = \frac{100\angle 0^\circ}{3+j4} = \frac{100\angle 0^\circ}{5\angle 53.2^\circ} = 20\angle -53.2^\circ$$

$$\hat{I}_B = \frac{\hat{V}}{\hat{Z}} = \frac{100\angle 0^\circ}{8-j6} = \frac{100\angle 0^\circ}{10\angle -36.8^\circ} = 10\angle +36.8^\circ$$

$$\hat{I}_0 = \hat{I}_A + \hat{I}_B = 20\angle -53.2^\circ + 10\angle +36.8^\circ$$

These currents must be combined vectorially as shown in the diagram below:

$$= 20(e^{-j53.2^\circ}) + 10(e^{+j36.8^\circ})$$

$$= 20(\cos 53.2^\circ - j\sin 53.2^\circ) + 10(\cos 36.8^\circ + j\sin 36.8^\circ)$$

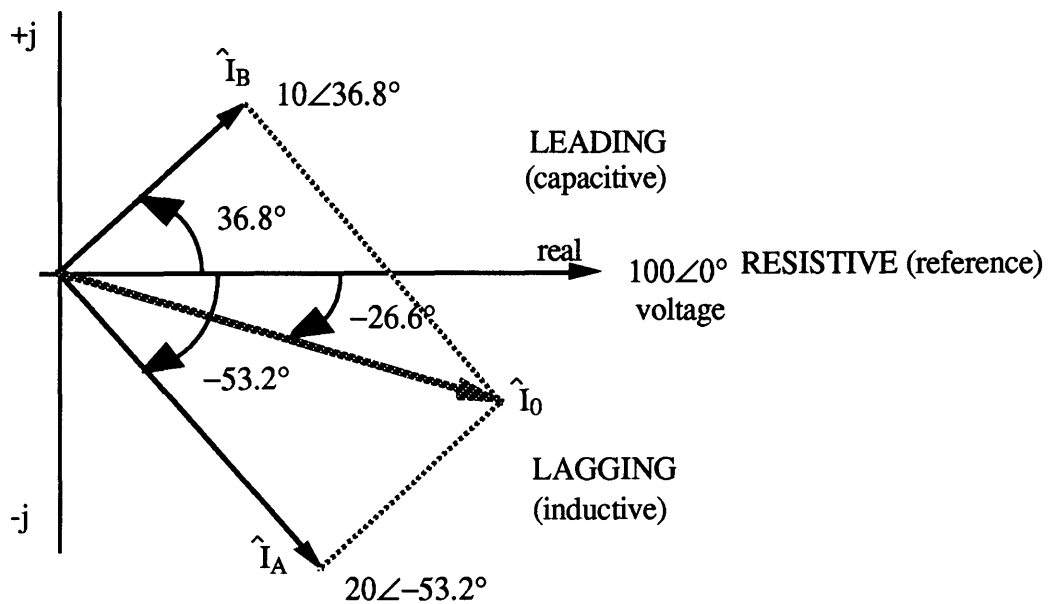
$$= 20\cos 53.2^\circ - j20\sin 53.2^\circ + 10\cos 36.8^\circ + j10\sin 36.8^\circ$$

$$= 11.98 - j16.01 + 8 + j5.99$$

$$= 19.98 - j10.02$$

$$= 22.35\angle -26.6^\circ$$

Phasor diagram:



Recalling that $Re\{e^{j\omega t}\} = Re\{\cos\omega t + j\sin\omega t\} = \cos\omega t$, we can write the time dependent voltages in the circuit as

$$v(t) = 100 \cos(\omega t + 0^\circ)$$

$$i_A(t) = 20 \cos(\omega t - 53.2^\circ)$$

$$i_B(t) = 10 \cos(\omega t + 36.8^\circ)$$

$$i_0(t) = 22.35 \cos(\omega t - 26.6^\circ)$$

where the voltages and currents are now instantaneous.

CIRCUITS 14

Given: $3\cos(10t) - 4\sin(10t-45^\circ) + X(t) = 0$ $X(t)$ is

- (a) $6.4\cos(10t)$
- (b) $1.0\cos(10t-135^\circ)$
- (c) $6.4\cos(10t+154^\circ)$
- (d) $1.0\cos(10t+135^\circ)$
- (e) $6.4\cos(10t-154^\circ)$

Solve the problem using phasors. Before using the Euler identity to convert the expression into phasor form, we must use the identity $\sin\theta = \cos(\theta-90^\circ)$ to convert the expression $4\sin(10t-45^\circ) = 4\cos(10t-45^\circ-90^\circ) = +4\cos(10t-135^\circ)$. Substituting this into the given equation:

$$3\cos(10t) - 4\cos(10t-135^\circ) + X(t) = 0$$

Converting to phasor form:

$$3\angle 0^\circ - 4\angle -135^\circ + X = 0$$

Solving for X and converting back to real:

$$X = -3\angle 0^\circ + 4\angle -135^\circ = -3 + (-2.828 - j2.828) = -5.828 - j2.828 = 6.478\angle -154^\circ$$

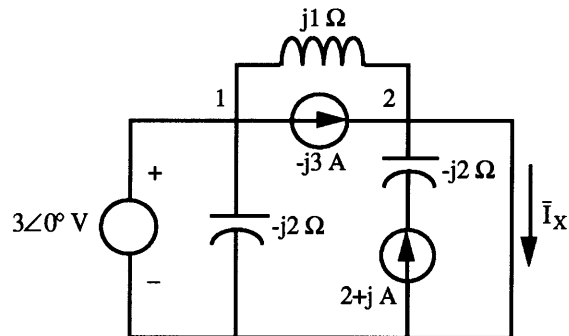
$$X = \text{Re}\{X\} = \text{Re}\{6.478\angle -154^\circ\} = 6.478\cos(10t-154^\circ)$$

The correct answer is (e).

CIRCUITS 21

\bar{I}_X is

- (a) $2.7 - j6.2$ amps
- (b) $2.7 + j6.2$ amps
- (c) $2 + j3$ amps
- (d) $2 - j3$ amps
- (e) $5.4\angle -68^\circ$



Solution:

The trick of this problem is to notice the short from node 2 to the circuit common (the voltage reference). Because of this short the voltage at node 2 is zero and the voltage at node 1 (and across the $j1 \Omega$ inductor) is 3 volts.

Using KCL at node 2

$$\bar{I}_X = (2+j) - j3 + \frac{3}{j} = 2 - j5 = 5.4\angle -68^\circ$$

The correct answer is (e).

**** 02/22/93 22:50:00 ***** Evaluation PSpice (Jan 1992) *****

Low pass op-amp filter analysis using 741 library model

**** CIRCUIT DESCRIPTION

```
Vg 1 0 AC 100m
Rs 1 2 1000
Rf 2 4 10e3
C 2 4 0.0001micro
R1 4 0 4e3
X1 0 2 5 6 4 uA741
VCC1 5 0 DC 12
VEE1 0 6 DC 12
.LIB EVAL.LIB
.AC DEC 10 0.1 10000000
.PLOT AC vm(1) vm(4)
.probe
.end
```

**** 02/22/93 22:50:00 ***** Evaluation PSpice (Jan 1992) *****

Low pass op-amp filter analysis using 741 library model

**** Diode MODEL PARAMETERS

```
      X1.dx
      IS 800.000000E-18
      RS 1
```

**** 02/22/93 22:50:00 ***** Evaluation PSpice (Jan 1992) *****

Low pass op-amp filter analysis using 741 library model

**** BJT MODEL PARAMETERS

X1.qx
NPN
IS 800.000000E-18
BF 93.75
NF 1
BR 1
NR 1

**** 02/22/93 22:50:00 ***** Evaluation PSpice (Jan 1992) *****

Low pass op-amp filter analysis using 741 library model

**** SMALL SIGNAL BIAS SOLUTION TEMPERATURE = 27.000 DEG C

NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE

(1) 0.0000 (2) 18.22E-06 (4) 998.1E-06 (5) 12.0000
(6) -12.0000 (X1.6)-19.34E-06 (X1.7) .0682 (X1.8) .0682
(X1.9) 0.0000 (X1.10) -.6077 (X1.11) 11.9600 (X1.12) 11.9600
(X1.13) -.5938 (X1.14) -.5938 (X1.53) 11.0000 (X1.54) -11.0000
(X1.90) 1.3431 (X1.91) 40.0000 (X1.92) -40.0000 (X1.99) 0.0000

VOLTAGE SOURCE CURRENTS
NAME CURRENT

Vg 1.822E-08
VCC1 -1.337E-03
VEE1 -1.337E-03
X1.vb -1.934E-10
X1.vc 1.100E-11
X1.ve 1.100E-11
X1.vlim 1.343E-03
X1.vlp -3.866E-11
X1.vln -4.135E-11

TOTAL POWER DISSIPATION 3.21E-02 WATTS

**** 02/22/93 22:50:00 ***** Evaluation PSpice (Jan 1992) *****

Low pass op-amp filter analysis using 741 library model

**** AC ANALYSIS

TEMPERATURE = 27.000 DEG C

LEGEND:

*: VM(1)

+: VM(4)

FREQ VM(1)

(*)----- 1.0000E-01 1.0000E+00 1.0000E+01 1.0000E+02 1.0000E+03

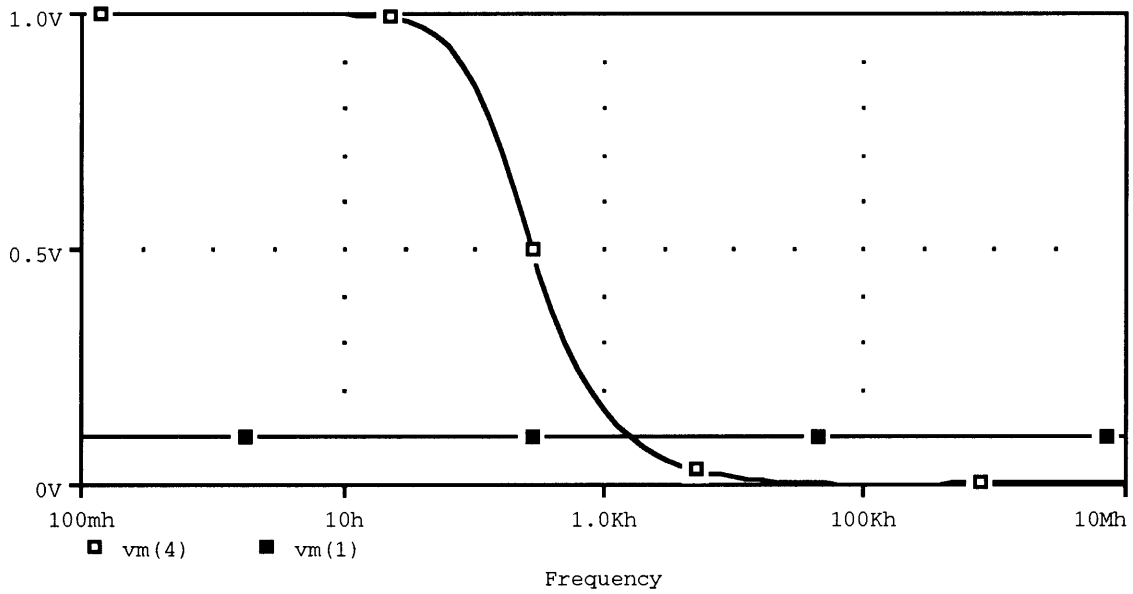
(+)----- 1.0000E-03 1.0000E-02 1.0000E-01 1.0000E+00 1.0000E+01

FREQ	VM(1)	VM(4)	VM(1)	VM(4)	VM(1)	VM(4)
1.000E-01	1.000E-01	*	.	.	+	.
1.259E-01	1.000E-01	*	.	.	+	.
1.585E-01	1.000E-01	*	.	.	+	.
1.995E-01	1.000E-01	*	.	.	+	.
2.512E-01	1.000E-01	*	.	.	+	.
3.162E-01	1.000E-01	*	.	.	+	.
3.981E-01	1.000E-01	*	.	.	+	.
5.012E-01	1.000E-01	*	.	.	+	.
6.310E-01	1.000E-01	*	.	.	+	.
7.943E-01	1.000E-01	*	.	.	+	.
1.000E+00	1.000E-01	*	.	.	+	.
1.259E+00	1.000E-01	*	.	.	+	.
1.585E+00	1.000E-01	*	.	.	+	.
1.995E+00	1.000E-01	*	.	.	+	.
2.512E+00	1.000E-01	*	.	.	+	.
3.162E+00	1.000E-01	*	.	.	+	.
3.981E+00	1.000E-01	*	.	.	+	.
5.012E+00	1.000E-01	*	.	.	+	.
6.310E+00	1.000E-01	*	.	.	+	.
7.943E+00	1.000E-01	*	.	.	+	.
1.000E+01	1.000E-01	*	.	.	+	.
1.259E+01	1.000E-01	*	.	.	+	.
1.585E+01	1.000E-01	*	.	.	+	.
1.995E+01	1.000E-01	*	.	.	+	.
2.512E+01	1.000E-01	*	.	.	+	.
3.162E+01	1.000E-01	*	.	.	+	.
3.981E+01	1.000E-01	*	.	.	+	.
5.012E+01	1.000E-01	*	.	.	+	.
6.310E+01	1.000E-01	*	.	.	+	.
7.943E+01	1.000E-01	*	.	.	+	.
1.000E+02	1.000E-01	*	.	.	+	.
1.259E+02	1.000E-01	*	.	.	+	.
1.585E+02	1.000E-01	*	.	.	+	.
1.995E+02	1.000E-01	*	.	.	+	.
2.512E+02	1.000E-01	*	.	.	+	.
3.162E+02	1.000E-01	*	.	.	+	.
3.981E+02	1.000E-01	*	.	.	+	.
5.012E+02	1.000E-01	*	.	.	+	.
6.310E+02	1.000E-01	*	.	.	+	.
7.943E+02	1.000E-01	*	.	.	+	.

1.000E+03	1.000E-01	*	.	.	+	.	.
1.259E+03	1.000E-01	*	.	.	+	.	.
1.585E+03	1.000E-01	*	.	.	+	.	.
1.995E+03	1.000E-01	*	.	.	+	.	.
2.512E+03	1.000E-01	*	.	.	+	.	.
3.162E+03	1.000E-01	*	.	.	+	.	.
3.981E+03	1.000E-01	*	.	.	+	.	.
5.012E+03	1.000E-01	*	.	.	+	.	.
6.310E+03	1.000E-01	*	.	.	+	.	.
7.943E+03	1.000E-01	*	.	.	+	.	.
1.000E+04	1.000E-01	*	.	.	+	.	.
1.259E+04	1.000E-01	*	.	.	+	.	.
1.585E+04	1.000E-01	*	.	.	+	.	.
1.995E+04	1.000E-01	*	.	.	+	.	.
2.512E+04	1.000E-01	*	.	.	+	.	.
3.162E+04	1.000E-01	*	.	.	+	.	.
3.981E+04	1.000E-01	*	.	.	+	.	.
5.012E+04	1.000E-01	*	.	.	+	.	.
6.310E+04	1.000E-01	*	.	.	+	.	.
7.943E+04	1.000E-01	*	.	.	+	.	.
1.000E+05	1.000E-01	*	.	.	+	.	.
1.259E+05	1.000E-01	*	.	.	+	.	.
1.585E+05	1.000E-01	*	.	.	+	.	.
1.995E+05	1.000E-01	*	.	.	+	.	.
2.512E+05	1.000E-01	*	.	.	+	.	.
3.162E+05	1.000E-01	*	.	.	+	.	.
3.981E+05	1.000E-01	*	.	.	+	.	.
5.012E+05	1.000E-01	*	.	.	+	.	.
6.310E+05	1.000E-01	*	.	.	+	.	.
7.943E+05	1.000E-01	*	.	.	+	.	.
1.000E+06	1.000E-01	*	.	.	+	.	.
1.259E+06	1.000E-01	*	.	.	+	.	.
1.585E+06	1.000E-01	*	.	.	+	.	.
1.995E+06	1.000E-01	*	.	.	+	.	.
2.512E+06	1.000E-01	*	.	.	+	.	.
3.162E+06	1.000E-01	*	.	.	+	.	.
3.981E+06	1.000E-01	*	.	.	+	.	.
5.012E+06	1.000E-01	*	.	.	+	.	.
6.310E+06	1.000E-01	*	.	.	+	.	.
7.943E+06	1.000E-01	*	.	.	+	.	.
1.000E+07	1.000E-01	*	.	.	+	.	.

JOB CONCLUDED

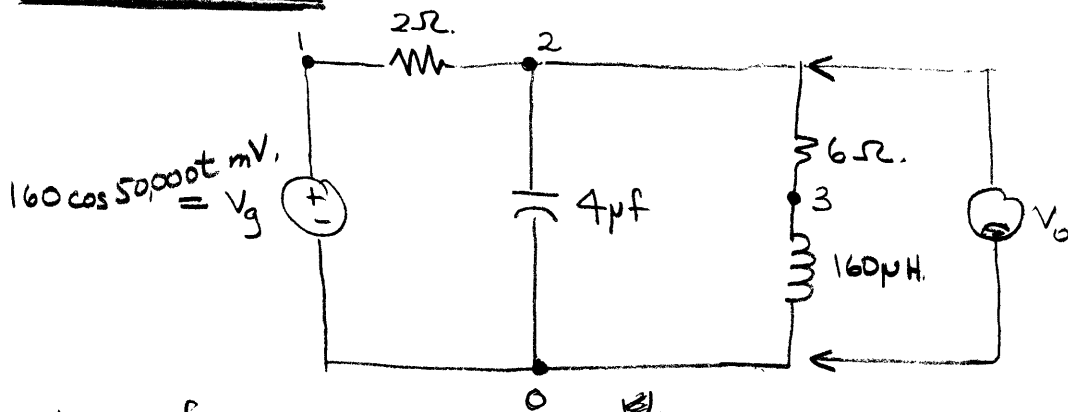
TOTAL JOB TIME 9.77



"Low pass op-amp filter analysis using 741 library model" 02/22/93 22:50:00 27.0°
 Evaluation Probe 5.1 © 1992 MicroSim Corp.

modified 10.36.

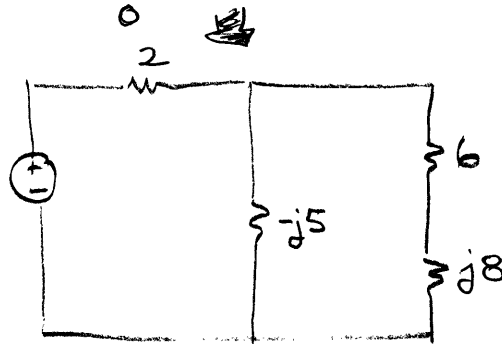
$$f = \frac{50,000}{2\pi} = 7957.$$



at one frequency
(given).

$$160 \angle 0^\circ$$

$$\omega = 50,000$$



modified 10.36.

Vg 1 @ AC 160mV

R1 1 2 2

C1 2 0 4u

R2 2 3 6

L1 3 0 160u

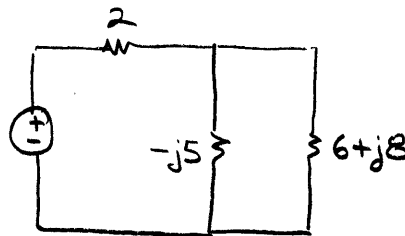
.AC LOG 10 10 10000

.PROBE

.END.

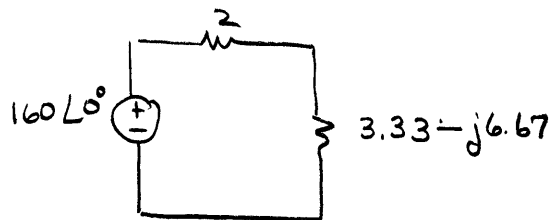
$$\frac{1}{j\omega C} = \frac{1}{j(50000)(4 \times 10^{-6})} = -j5$$

$$j\omega L = j(50000)(160 \times 10^{-6}) = j8$$



$$\frac{(-j5)(6+j8)}{-j5 + 6 + j8} = \frac{40 - j30}{6 + j3}$$

$$= (3.33, -6.67)$$

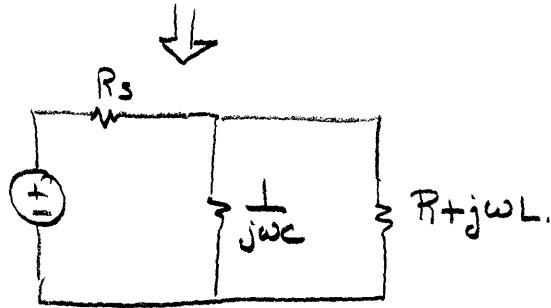
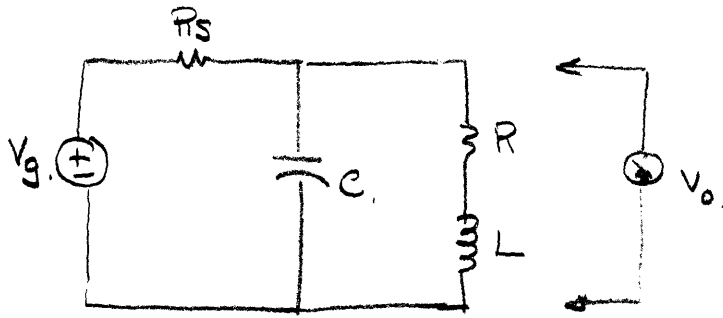


$$V_0 = \frac{3.33 - j6.67 (160 \angle 0^\circ)}{2 + 3.33 - j6.67} = \frac{3.33 - j6.67}{5.33 - j6.67} (160 \angle 0^\circ)$$

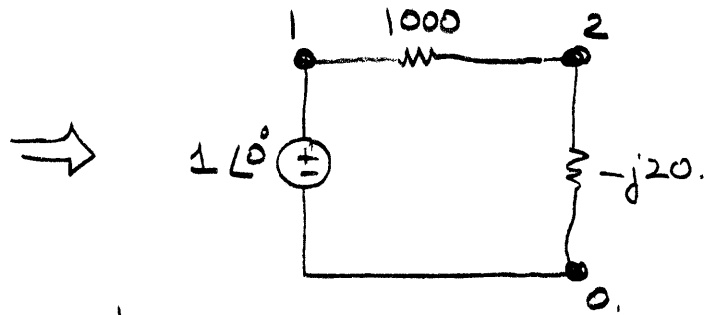
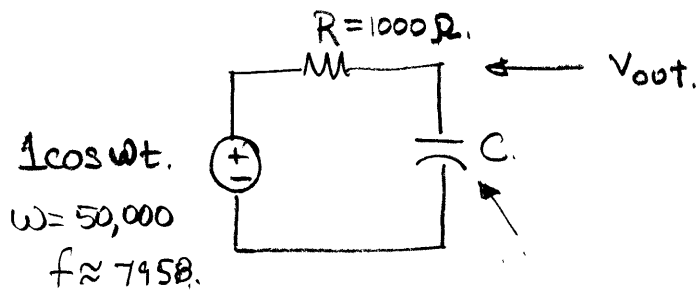
$$= (0.853, -0.182) (160 \angle 0^\circ)$$

$$= (136.59, -29.19) \text{ mV}$$

$$= 139.67 \angle -12^\circ$$



$$\begin{aligned}
 \frac{1}{j\omega C} \parallel (R + j\omega L) &= \frac{\frac{1}{j\omega C} (R + j\omega L)}{\frac{1}{j\omega C} + R + j\omega L} = \frac{R + j\omega L}{1 + j\omega RC - \omega^2 LC} \\
 &= \frac{R + j\omega L}{(1 - \omega^2 LC) + j\omega RC} \\
 &= \frac{(R + j\omega L) [(1 - \omega^2 LC) - j\omega RC]}{(1 - \omega^2 LC)^2 + \omega^2 R^2 C^2} \\
 &= \frac{R(1 - \omega^2 LC) + j\omega L(1 - \omega^2 LC) - j\omega R^2 C + \omega^2 R C}{(1 - \omega^2 LC)^2 + \omega^2 R^2 C^2} \\
 &= \frac{R + j\omega L(1 - \omega^2 LC) - j\omega R^2 C}{(1 - \omega^2 LC)^2 + \omega^2 R^2 C^2} \\
 &= \frac{R}{(1 - \omega^2 LC)^2 + \omega^2 R^2 C^2} + j \frac{\omega L(1 - \omega^2 LC) - \omega R^2 C}{(1 - \omega^2 LC)^2 + \omega^2 R^2 C^2}
 \end{aligned}$$



$$RC = 1 \text{ msec.}$$

$$C = \frac{1 \times 10^{-3}}{1000} = 1 \text{ pf.}$$

$$\frac{1}{j\omega C} = \frac{1}{j 50,000 (10^{-6})} = -j20$$

at one frequency

$$V_{out} = \frac{-j20}{1000 - j20} \cdot 1$$

$$= (4 \times 10^{-4}, -2 \times 10^{-2})$$

$$V_{out} \approx 0.02 \angle -88.85^\circ$$

Pspice Analysis

RC circuit

Vg 1 0 AC 1 volt. PWL(0 0 1e-6 1).

R1 1 2 1000

C1 2 0 1p

⇒ • AC DEC 10 1 1000,000

⇒ • TRAN ~~20e-6~~ 2000e-6

• PROBE

• END.

⇒ • DC Vg. 0 1 0.1

**** 02/24/93 22:03:50 ***** Evaluation PSpice (Jan 1993) *****

modified problem 10.36 w=50,000 radians/second

**** CIRCUIT DESCRIPTION


```
Vg 1 0 AC 160mvolt
R1 1 2 2
C1 2 0 4u
R2 2 3 6
L1 3 0 160u
.AC DEC 10 10 100000
.PROBE
.END
```

**** 02/24/93 22:03:50 ***** Evaluation PSpice (Jan 1993) *****

modified problem 10.36 w=50,000 radians/second

**** SMALL SIGNAL BIAS SOLUTION TEMPERATURE = 27.000 DEG C

NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE

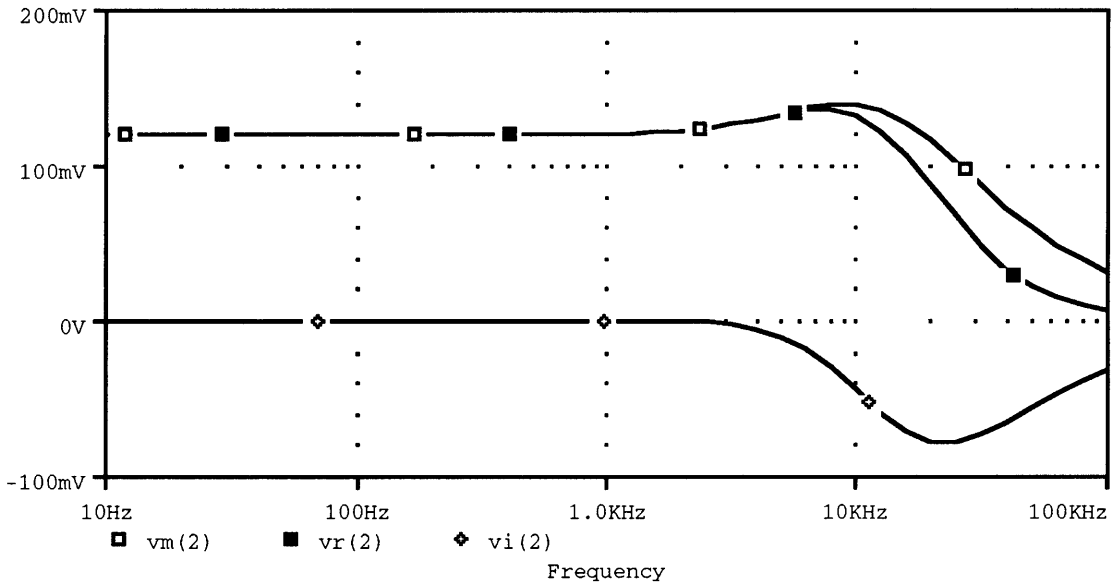
(1) 0.0000 (2) 0.0000 (3) 0.0000

VOLTAGE SOURCE CURRENTS
NAME CURRENT

Vg 0.000E+00

TOTAL POWER DISSIPATION 0.00E+00 WATTS

JOB CONCLUDED



"modified problem 10.36 w=50,000 radians/second" 02/24/93 22:03:50 27.0°
 Evaluation Probe 5.3 © 1993 MicroSim Corp.

**** 02/24/93 22:48:45 ***** Evaluation PSpice (Jan 1993) *****

Example SPICE analysis using RC circuit

**** CIRCUIT DESCRIPTION

```
Vg 1 0 AC 1volt PWL(0 0 1e-6 1)
R1 1 2 1000
C1 2 0 1u
.AC DEC 10 1 1000000
.TRAN 20e-6 10000e-6
.DC Vg 0 1 0.1
.PROBE
.END
```

**** 02/24/93 22:48:45 ***** Evaluation PSpice (Jan 1993) *****

Example SPICE analysis using RC circuit

**** SMALL SIGNAL BIAS SOLUTION TEMPERATURE = 27.000 DEG C

NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE

(1) 0.0000 (2) 0.0000

VOLTAGE SOURCE CURRENTS
NAME CURRENT

Vg 0.000E+00

TOTAL POWER DISSIPATION 0.00E+00 WATTS

**** 02/24/93 22:48:45 ***** Evaluation PSpice (Jan 1993) *****

Example SPICE analysis using RC circuit

**** INITIAL TRANSIENT SOLUTION TEMPERATURE = 27.000 DEG C

NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE

(1) 0.0000 (2) 0.0000

VOLTAGE SOURCE CURRENTS

NAME CURRENT

Vg 0.000E+00

TOTAL POWER DISSIPATION 0.00E+00 WATTS

JOB CONCLUDED

TOTAL JOB TIME 5.63

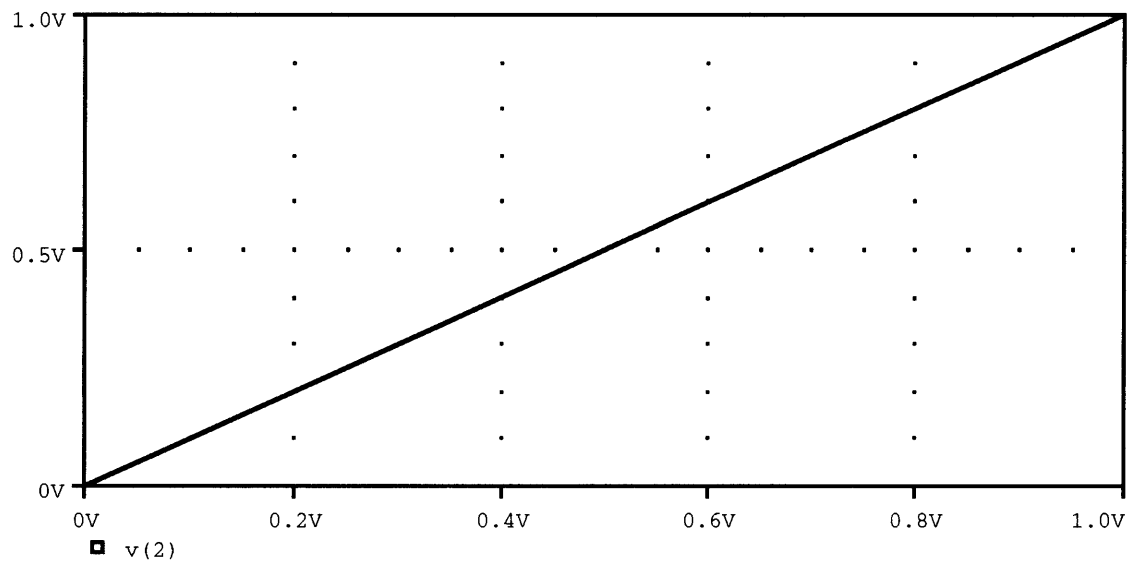
**** 02/24/93 22:48:51 ***** Evaluation PSpice (Jan 1993) *****

.PROBE

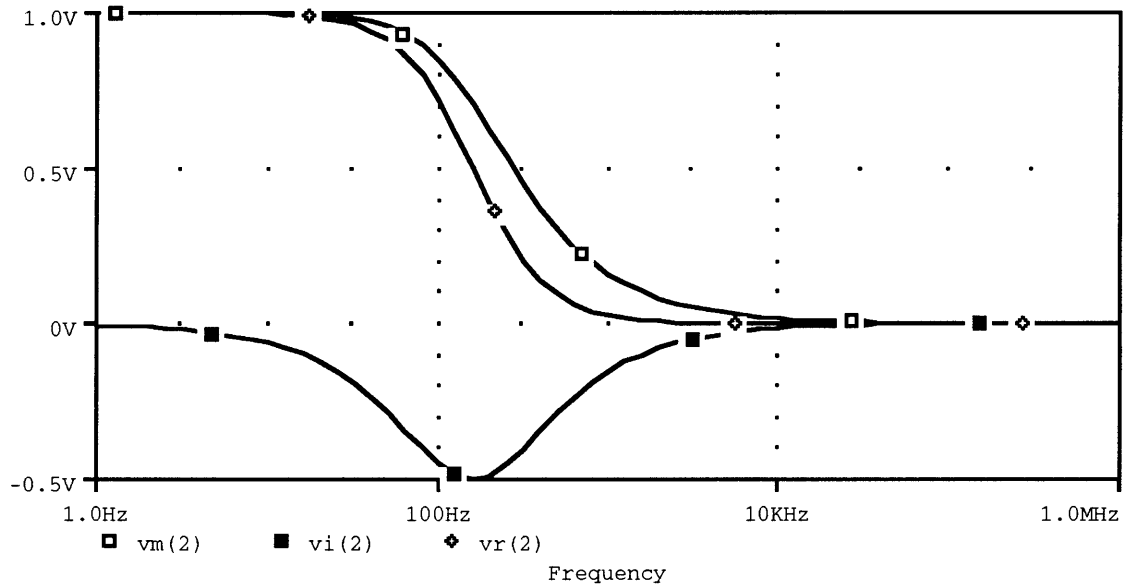
**** CIRCUIT DESCRIPTION

.END

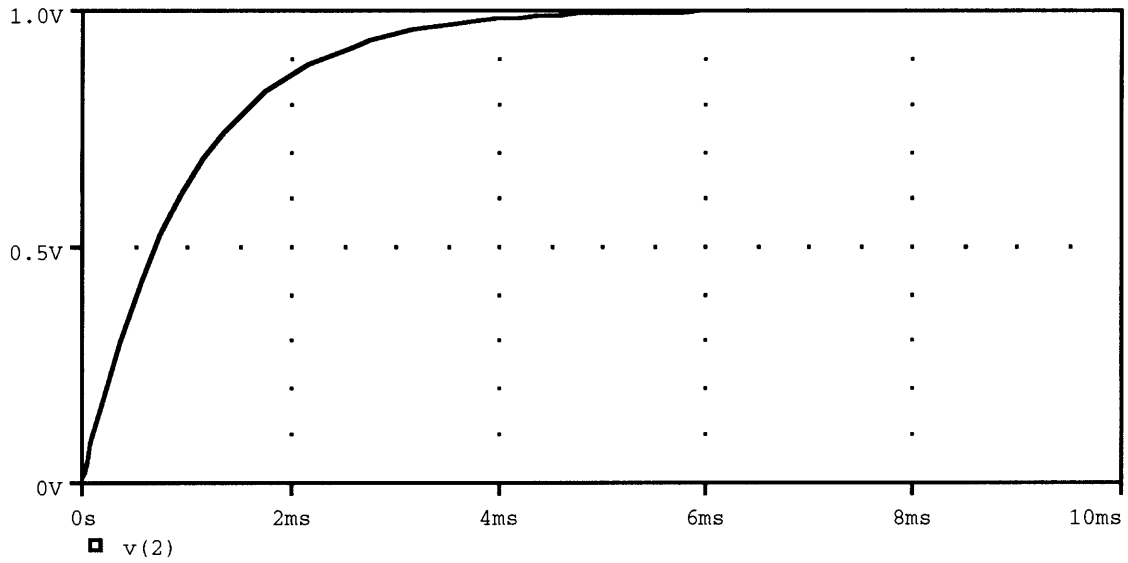
WARNING -- There are no devices in this circuit, (this message will be printed if there are blank lines after the last .END statement)



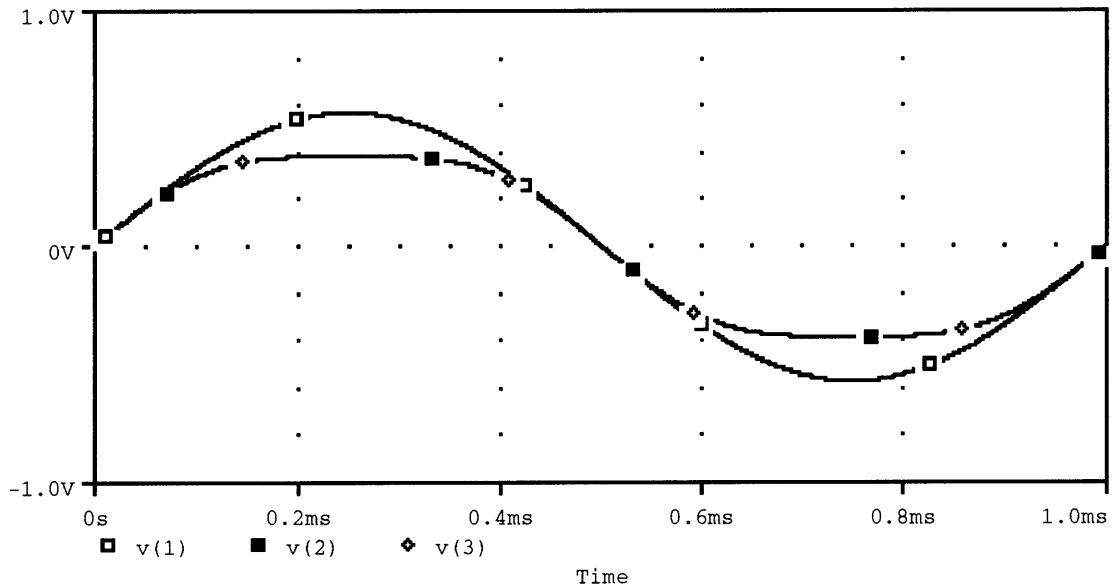
"Example SPICE analysis using RC circuit" 02/24/93 22:44:44 27.0°
Evaluation Probe 5.3 © 1993 MicroSim Corp.



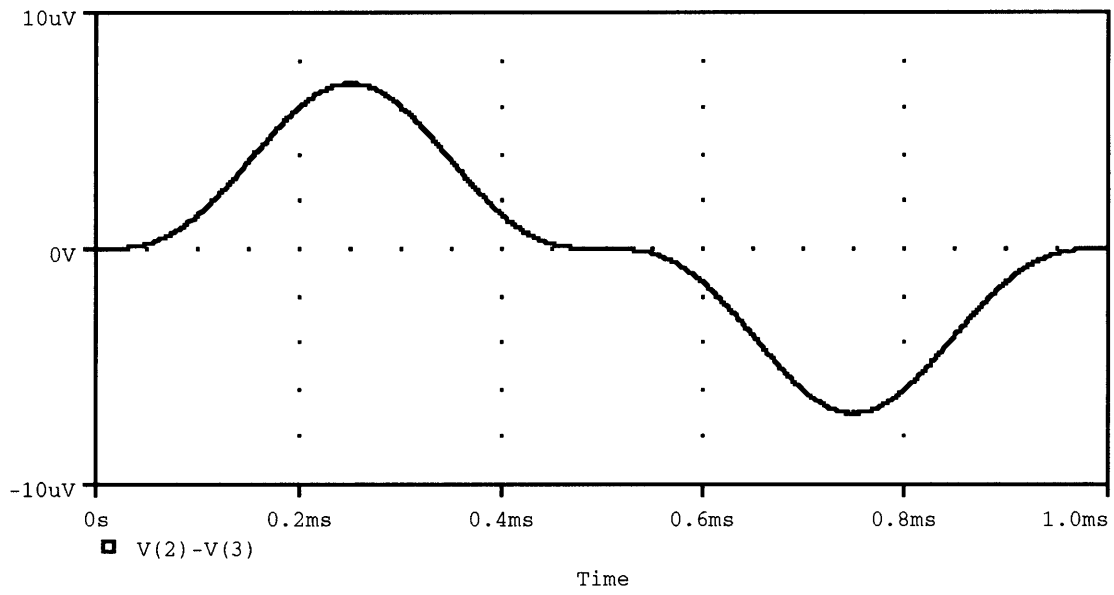
"Example SPICE analysis using RC circuit" 02/24/93 22:44:44 27.0°
 Evaluation Probe 5.3 © 1993 MicroSim Corp.



Time
"Example SPICE analysis using RC circuit" 02/24/93 22:48:45 27.0°
Evaluation Probe 5.3 © 1993 MicroSim Corp.



"Example 3 showing superposition of waveforms" 02/24/93 22:55:30 27.0°
 Evaluation Probe 5.3 © 1993 MicroSim Corp.



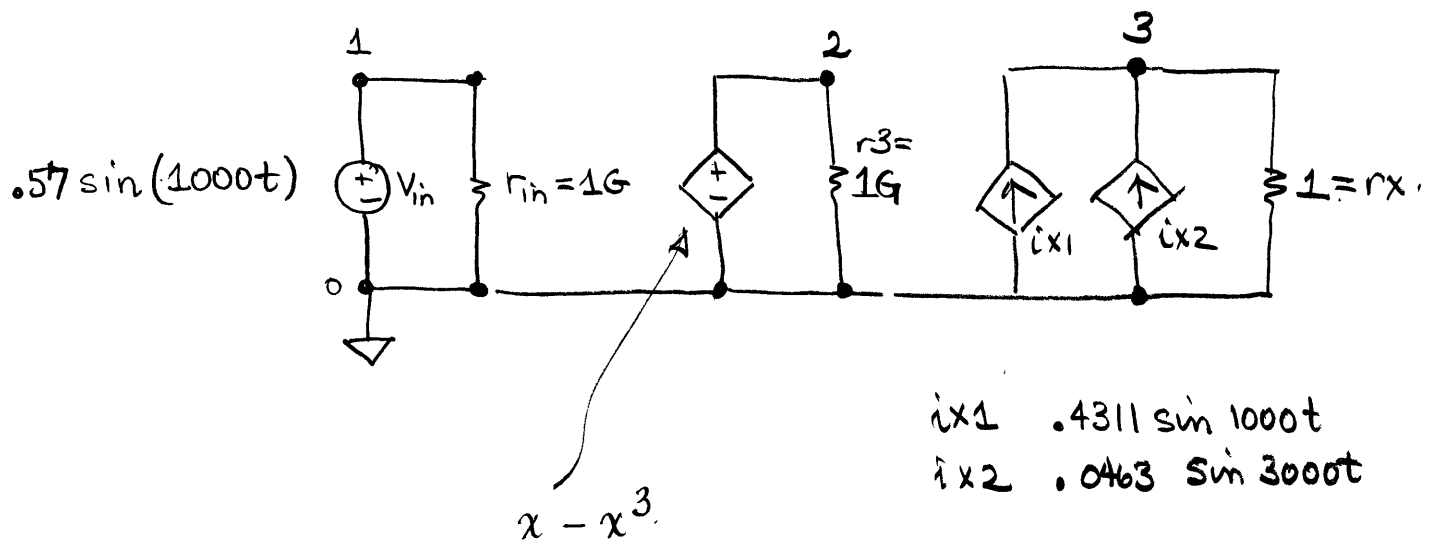
"Example 3 showing superposition of waveforms" 02/24/93 22:55:30 27.0°
Evaluation Probe 5.3 © 1993 MicroSim Corp.

```

Vin 1 0 sin (0 .57 1000)
rin 1 0 1G
e3 2 0 poly(1) (1,0) 0 1 0 -1
r3 2 0 1G
ix1 0 3 sin (0 .4311 1000)
ix3 0 3 sin (0 .0463 3000)
rx 3 0 1.

```

- tranv 1 μ 1m.
- probe
- end.



```

poly(1) (1,0) 0 1 0 -1
          ↑   ↑   x0 x1 x2 x3
          control input v(1) - v(0).
          1 controlling input

```

**** 02/24/93 22:55:30 ***** Evaluation PSpice (Jan 1993) *****

Example 3 showing superposition of waveforms

**** CIRCUIT DESCRIPTION

```
Vin 1 0 sin(0 0.57 1000)
Rin 1 0 1G
e3 2 0 poly(1) (1,0) 0 1 0 -1
r3 2 0 1G
ix1 0 3 sin(0 .4311 1000)
ix3 0 3 sin(0 .0463 3000)
rx 3 0 1
.TRAN 1u 1m
.PROBE
.END
```

**** 02/24/93 22:55:30 ***** Evaluation PSpice (Jan 1993) *****

Example 3 showing superposition of waveforms

**** INITIAL TRANSIENT SOLUTION TEMPERATURE = 27.000 DEG C

NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE

(1) 0.0000 (2) 0.0000 (3) 0.0000

VOLTAGE SOURCE CURRENTS
NAME CURRENT

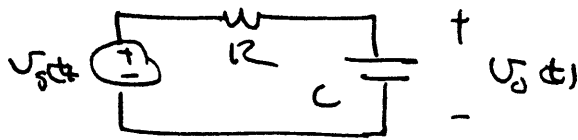
Vin 0.000E+00

TOTAL POWER DISSIPATION 0.00E+00 WATTS

JOB CONCLUDED

TOTAL JOB TIME 38.08

We have been considering the linear differential equation which satisfies Kirchoff's laws for an R-C circuit



$$V_0(t) = RC \frac{dV_C}{dt} + V_C \quad \leftarrow \text{first-order diff eq}$$

... We ~~examined~~ ^{solved} the case for $V_0(t) = V_0 u(t)$
 using two different methods

- ① Separation of variables
 - works easily for first-order circuits
- ② solution by superposition

$$V_0(t) = V_0'(t) + V_{on}(t)$$

where the two sources are

- ① the constant V_0
- ② the zero source (actually an impulse response)

particular solution \rightarrow

$$V_0 = RC \frac{dV_0'}{dt} + V_0'$$

homogeneous equation

$$0 = RC \frac{dV_{on}}{dt} + V_{on}$$

add these up

which is analogous

to impulse driven.

$$V_0 = RC \frac{dV_0}{dt} + (V_0' + V_{on}) = V_0$$

The solution was found to be

$$V_0(t) = \begin{cases} V_0 (1 - e^{-t/RC}) & t \geq 0 \end{cases}$$

called the time constant

let's examine an RL circuit:



$$V_s(t) = V_0 u(t)$$

$$V_s(t) = Ri + L \frac{di}{dt}$$

So we find i , then use

$$\frac{V_s}{R} = i + \left(\frac{L}{R}\right) \frac{di}{dt} \Rightarrow V_s = V_0 + RC \frac{dV_0}{dt}$$

time constants.

let's use our 2nd method

PARTICULAR SOLUTION

- ① what is the steady-state? since we have a constant source (V_0) we know $di/dt = 0$ for steady-state

hence $i' = V_0/R$

② $0 = Ri_h + L \frac{di_h}{dt}$ ← homogeneous equation

HOMOGENEOUS

try $i_h = I e^{st}$

> TRANSIENT

— IMPULSE

$$0 = R I e^{st} + L S I e^{st}$$

hence $s = -R/L$ and I is to be determined.

$$i = i' + i_h = \frac{V_0}{R} + I e^{-t/(L/R)} \quad t \geq 0$$

at $t = 0^+$ $i(0) = \frac{V_0}{R} + I$ for $t = 0^-$, $i = 0$

hence $i(0^+) = \frac{V_0}{R} + I$

this jump means $\frac{di}{dt} \rightarrow \infty$ which requires ∞ voltage & that's not what our source is

hence $i(0^+) = 0 = \frac{V_0}{R} + I$, $I = -V_0/R$

3a

$$\frac{d^n y}{dt^n} + a_1 \frac{d^{n-1} y}{dt^{n-1}} + a_2 \frac{d^{n-2} y}{dt^{n-2}} + \dots + a_n y = x(t)$$

homogeneous $x(t) \Rightarrow 0$. and it is known that there will be n independent solutions, $y_n^{(1)}(t)$ and there is a particular solution $y_p(t)$.

The total solution is

$$y(t) = C_1 y_n^{(1)}(t) + C_2 y_n^{(2)}(t) + \dots + C_n y_n^{(n)}(t) + y_p(t)$$

The homogeneous (transient) solutions are always of the form $y = e^{st}$. Thus.

$$\frac{d^m y}{dt^m} = C s^m e^{st} \quad \dots \text{substituting}$$

gives us

$$C e^{st} (s^m + a_1 s^{n-1} + a_2 s^{n-2} + \dots + a_n) = 0$$

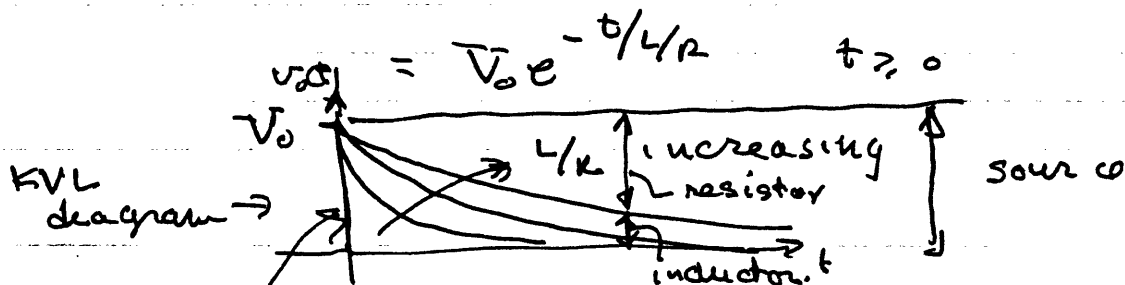
characteristic equation $\rightarrow s^n + a_1 s^{n-1} + a_2 s^{n-2} + \dots + a_n = 0$ this must be zero.

the values of s (there are n -roots) are called the natural frequencies of the system.

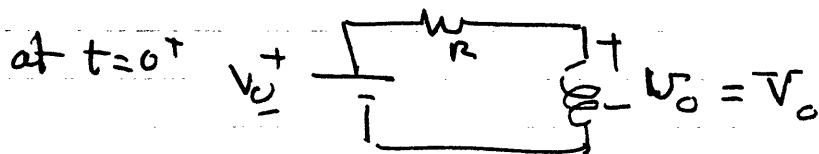
EEAP 243

finally $i = \frac{V_0}{R} (1 - e^{-t/L/R})$ $t \geq 0$ called the time constant

and $v_L = L \frac{di}{dt} = L \left(\frac{R}{L} V_0 \right) e^{-t/L/R}$



at $t=0$ all of the voltage is across the inductor so no current can flow ($v_R = 0$)

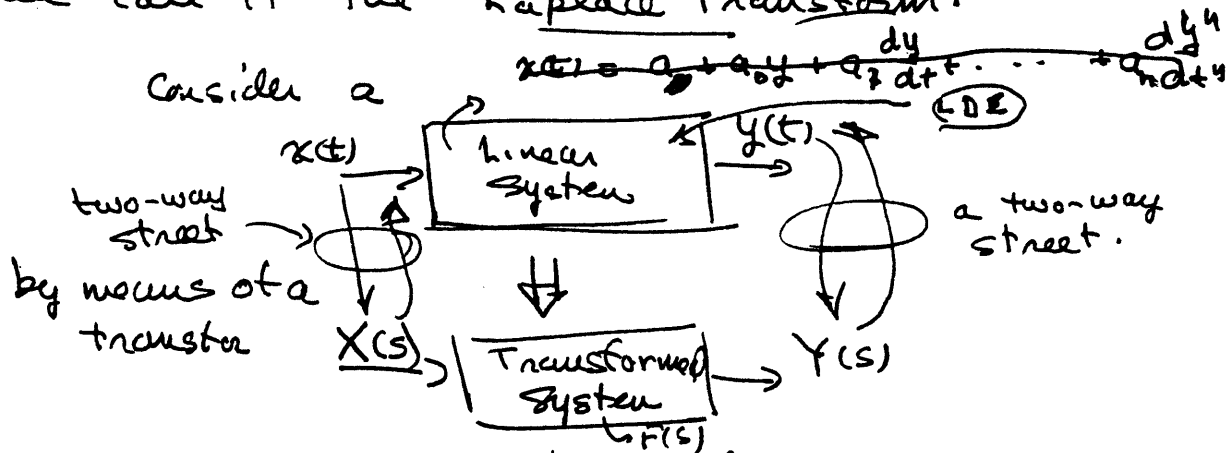


Now what can we do to deal with more complicated circuits

① continue to find the homogeneous + particular solutions

→ ② find other means

It turns out that there exists a very effective method for solving linear diff. eq with constant coefficients which utilizes the concept of transforms - in this case we call it the Laplace Transform.



in the straight forward case we find $Y(s) = X(s) F(s)$

2/26/93

PP 601-625

(4)

Then we can find $y(t)$ by transforming back — called the inverse transform. Here's how it works

$$X(s) = \int_0^{\infty} x(t) e^{-st} dt$$

also we write this symbolically as

$$X(s) = \mathcal{L}\{x(t)\}$$

where s is a ^{complex} constant in this integration

~~Ex:~~ let's take a specific case
let's choose $x(t) = u(t) = \begin{cases} 0 & t < 0 \\ 1 & t \geq 0 \end{cases}$

$$\begin{aligned} \text{then } X(s) &= \int_0^{\infty} u(t) e^{-st} dt = \int_0^{\infty} e^{-st} dt = \\ &= -\frac{1}{s} \left[e^{-st} \Big|_0^{\infty} \right] \end{aligned}$$

so as long as the $\text{Re}\{s\} > 0$ the value at ∞ is zero.

$$\text{let } s = \sigma + j\omega$$

$$e^{-\sigma t} e^{-j\omega t} \Big|_0^{\infty} = -1 + e^{-\sigma \infty} e^{-j\omega \infty}$$

↑
goes to zero
↑
magnit
↑
is uni

So we get $X(s) = \frac{1}{s}$ for $x(t) = u(t)$

called a transform pair

$x(t)$	$X(s)$
$u(t)$	$\frac{1}{s}$
$\delta(t)$	1

2/20/93

5

If we find an $X(s) = \frac{1}{s}$ we know that we ~~can~~ have a $y(t) = u(t)$. That is the two are uniquely related.

Let's use an impulse for $x(t)$.

$$X(s) = \int_0^{\infty} f(t) e^{-st} dt = \int_0^{\infty} f(t) dt = 1$$

the impulse in the integrand causes it to be evaluated at the position of the impulse.

Next let's consider $y(t) = \frac{dx}{dt}$ to find $Y(s)$

$$Y(s) = \mathcal{L}\{y(t)\} = \int_0^{\infty} \left(\frac{dx}{dt}\right) e^{-st} dt$$

and integrate by parts let $u = e^{-st}$, $du = -se^{-st} dt$
 $dv = \left(\frac{dx}{dt}\right) dt$

$$\begin{aligned} Y(s) &= \int_0^{\infty} \frac{dx}{dt} e^{-st} dt = x e^{-st} \Big|_0^{\infty} - \int_0^{\infty} x(-s) e^{-st} dt \\ &= -x(\infty) + x(0) + s \int_0^{\infty} x(t) e^{-st} dt \\ &= \cancel{-x(\infty)} + s X(s) - x(0) \end{aligned}$$

example $v(t) = L \frac{di}{dt}$

$$V(s) = \mathcal{L}\{v(t)\} = \mathcal{L}\left\{L \frac{di}{dt}\right\} = Ls I(s) - L i(0)$$

$$\text{so } V(s) = Ls I(s) - L i(0)$$

if $i(0) = 0$ and $i(t) = u(t)$

$$I(s) = \frac{1}{s}$$

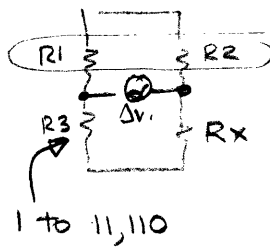
then $V(s) = Ls \left(\frac{1}{s}\right) = L \uparrow$ constant

$v(t) = L f(t) \leftarrow$ transform pair.

notes about PSpice HW

Not too long!

You should.



$$R2/R1 = .001, .01, \dots, 1000$$

at extremes
4 → 5.

null by setting $R_x = \frac{R_2}{R_1} R_3$

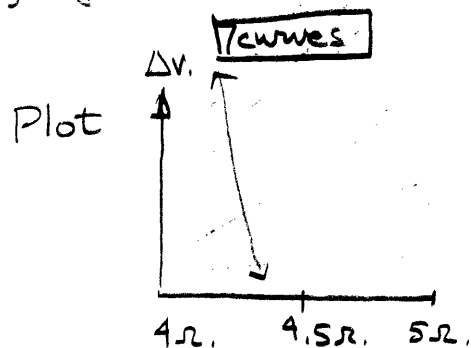
.001, .01, .1, 1, 10, 100, 1000

$R_x = 4$ $\frac{R_2}{R_1} = .001, \dots, 1000$

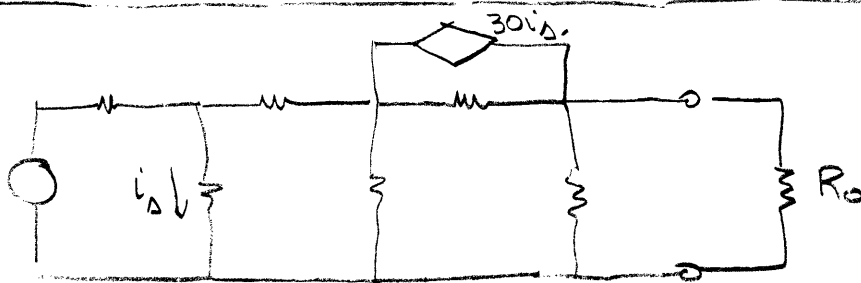
$R_x = 5$ $= .001, \dots, 1000$

How linear is ΔV ?

R_3 adjustable



4.79



Program.

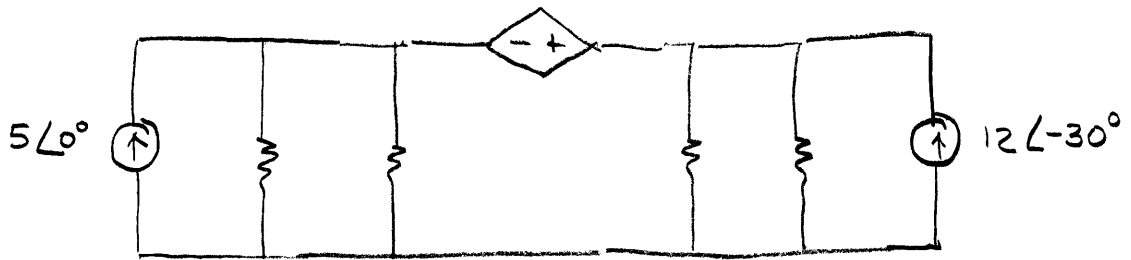
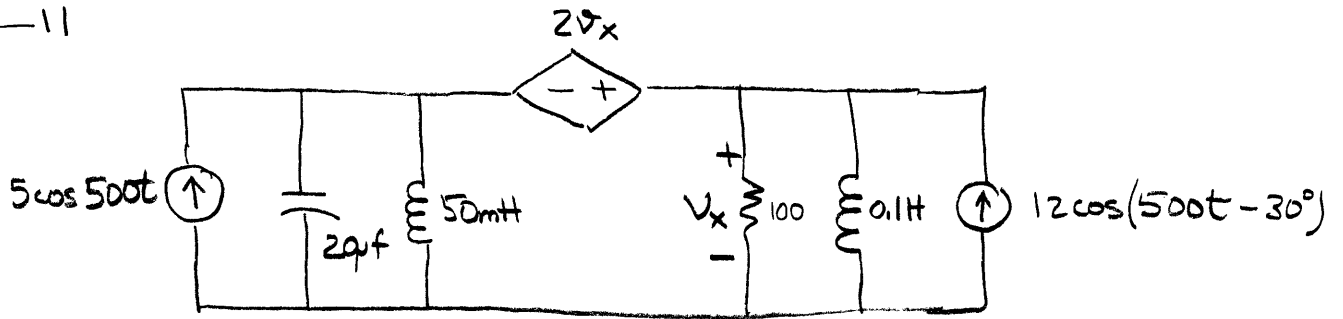
Answer (a), (b), (c).

Laplace transform problems.

15.7, 15.13 — simple math
 15.19, 15.20 } — RLC circuit
 15.21, 15.22 }

15.23, 15.24, 15.25. partial fractions

P11.-11



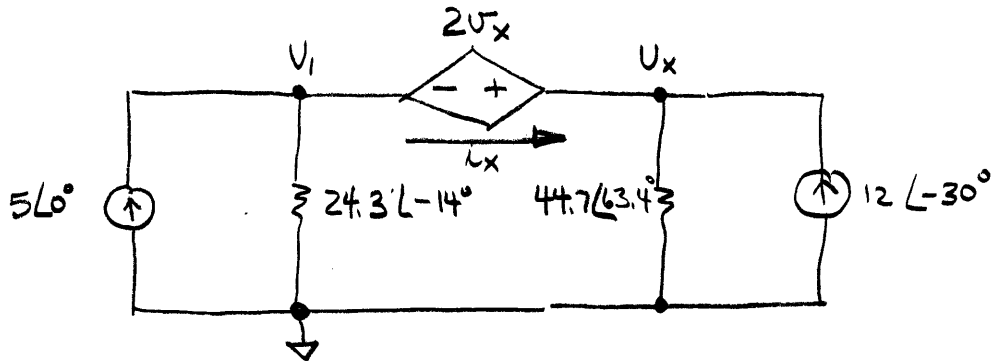
$$j\omega L = j(500)(50 \times 10^{-3}) = 25 \Omega$$

$$\frac{1}{j\omega C} = \frac{1}{j(500)(20 \times 10^{-6})} = -j100$$

$$j\omega L = j(500)(0.1) = j50$$

$$\frac{(100)(j50)}{100 + j50} = 20 + j40 = 44.7 \angle 63.4^\circ$$

$$\frac{(25)(-j100)}{25 + (-j100)} = \frac{-j2500}{25 - j100} = (23.5, -5.88) = 24.3 \angle -14^\circ$$



+out @ 1

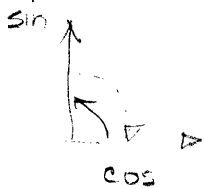
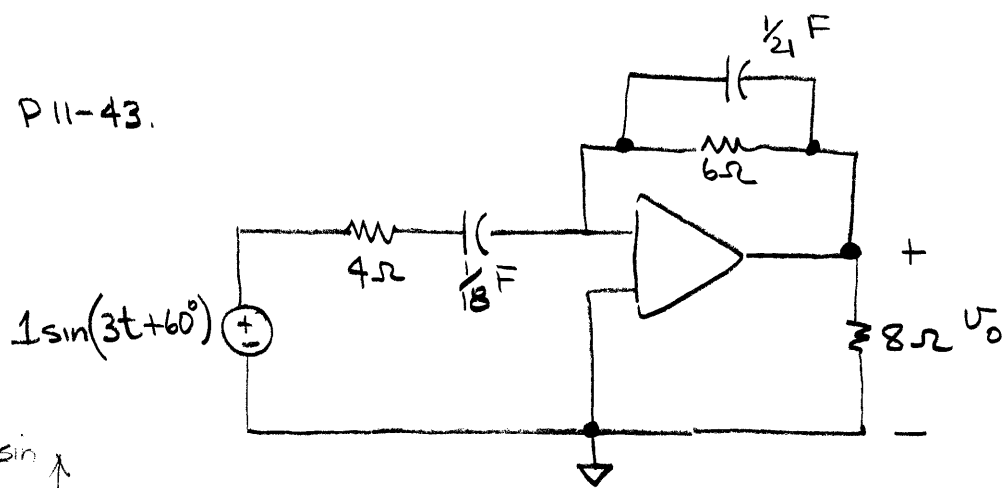
$$-5 \angle 0^\circ + \frac{V_1}{24.3 \angle -14^\circ} + I_x = 0$$

+out @ 2

$$-I_x + \frac{V_x}{44.7 \angle 63.4^\circ} - 12 \angle -30^\circ = 0$$

$$V_1 + 2V_x = V_x$$

P11-43.

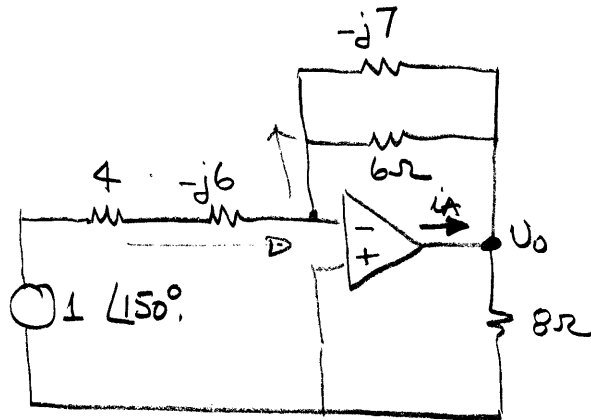


$$\sin(x - 90^\circ) = \cos x$$

$$\sin(3t + 150^\circ - 90^\circ) = \cos(3t + 150^\circ)$$

$$\frac{1}{j\omega C} = \frac{1}{j(3)(\frac{1}{8})} = -j6$$

$$\frac{1}{j\omega C} = \frac{1}{j3(\frac{1}{21})} = -j7$$



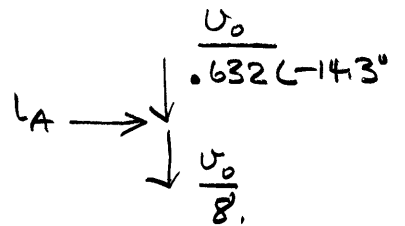
$$\frac{(-j7)(6)}{6 - j7} = \frac{-j42}{6 - j7} = (3.46, -2.96)$$

$$\frac{1 \angle 150^\circ}{4 - j6} - \frac{0 - U_o}{(3.46, -2.96)} = 0$$

$$\frac{1 \angle 150^\circ}{4 - j6} + \frac{U_o}{(3.46, -2.96)} = 0$$

$$U_o = -\frac{1 \angle 150^\circ}{4 - j6} (3.46, -2.96) = (.612, -.156)$$

$$U_o = .632 \angle -14.3^\circ$$



$$\frac{U_o}{(3.46, -2.96)} + i_A = \frac{U_o}{8}$$

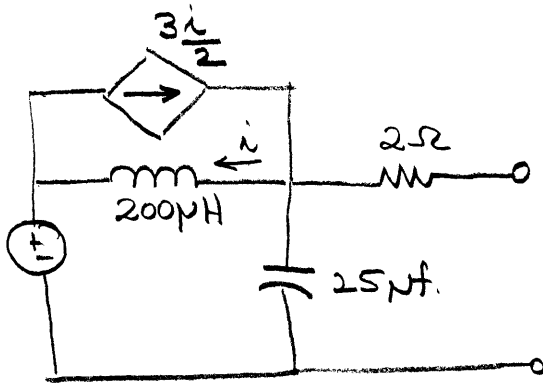
$$i_A = \frac{U_o}{8} - \frac{U_o}{(3.46, -2.96)} = (-.0479, -.0809) = .094 \angle -121^\circ$$

AP 11-1

CD - player output.

$$\omega = 10,000$$

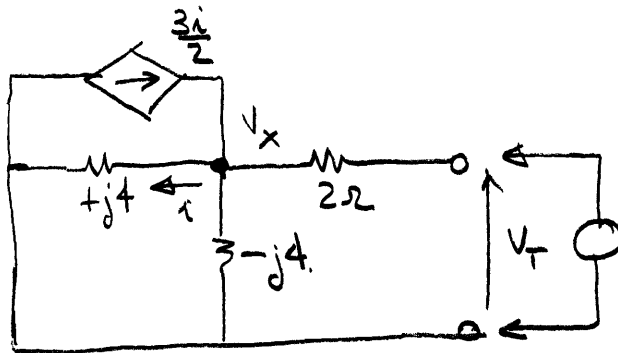
$$v_s = 10 \cos(\omega t + 53.1^\circ)$$



$$\frac{1}{j\omega C} = \frac{1}{j(10,000)(25 \times 10^{-6})} = -j4$$

$$j\omega L = j(200 \times 10^{-6})(10,000) = +j4$$

R_T out



$$+ \frac{3}{2} \left(\frac{v_x}{j4} \right) - \frac{v_x}{j4} - \frac{v_x}{j4} + \frac{v_T - v_x}{2} = 0$$

$$\left(\frac{3}{j8} - \frac{1}{2} \right) v_x + v_T = 0$$

$$v_x = \frac{v_T}{\frac{1}{2} - \frac{3}{j8}}$$

$$I_T = \frac{v_T - v_x}{2} = \frac{v_T - \frac{v_T}{\frac{1}{2} - \frac{3}{j8}}}{2}$$

$$Z_T = \frac{v_T}{I_T} = \frac{v_T}{\frac{1}{2} \left(v_T - \frac{v_T}{\frac{1}{2} - \frac{3}{j8}} \right)} = \frac{2 \left(\frac{1}{2} - \frac{3}{j8} \right)}{\frac{1}{2} - \frac{3}{j8} - 1}$$

$$= \frac{2 \left(\frac{1}{2} + j\frac{3}{8} \right)}{-\frac{1}{2} + j\frac{3}{8}} = \frac{2(4 + j3)}{(-4 + j3)} = (-0.56 - j1.92)$$

$$= 2 \angle 106^\circ$$

**** 03/04/93 07:04:51 ***** Evaluation PSpice (Jan 1993) *****

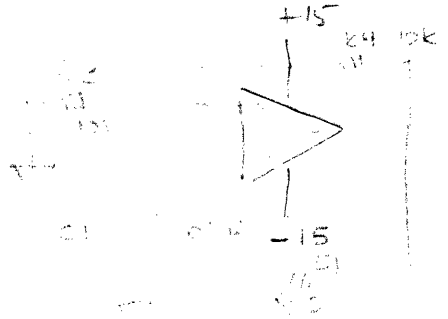
LAB 4 OSCILLATOR

**** CIRCUIT DESCRIPTION

```

C1  2  0  0.001u IC=0.1
R4  4  3  10K
R2  2  4  5K
R3  3  0  10K
X1  3  2  5  6  4  uA741
VCC 5  0  DC  15
VEE 6  0  DC -15
.LIB EVAL.LIB
.TRAN 10u 100u  UIC
.PROBE
.END

```



**** 03/04/93 07:04:51 ***** Evaluation PSpice (Jan 1993) *****

LAB 4 OSCILLATOR

**** Diode MODEL PARAMETERS

```

X1.dx
IS 800.000000E-18
RS 1

```

**** 03/04/93 07:04:51 ***** Evaluation PSpice (Jan 1993) *****

LAB 4 OSCILLATOR

**** BJT MODEL PARAMETERS

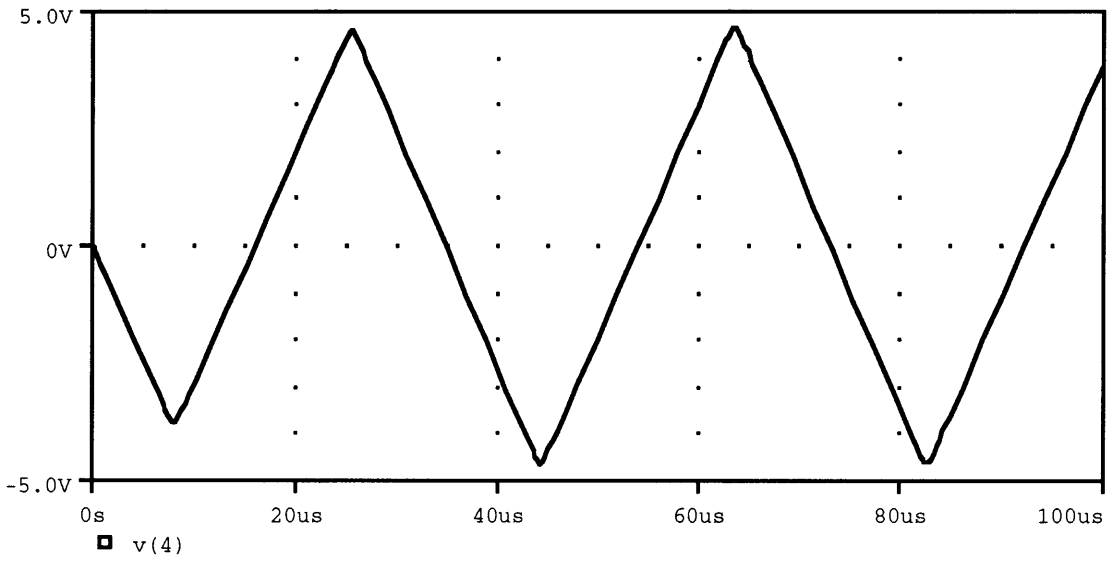
```

X1.qx
NPN
IS 800.000000E-18
BF 93.75
NF 1
BR 1
NR 1

```

JOB CONCLUDED

TOTAL JOB TIME 23.93



Time
"LAB 4 OSCILLATOR" 03/04/93 07:04:51 27.0°
Evaluation Probe 5.3 © 1993 MicroSim Corp.

$C = 1.001$
741.

**** 03/04/93 07:10:52 ***** Evaluation PSpice (Jan 1993) *****

LAB 4 OSCILLATOR

**** CIRCUIT DESCRIPTION

```
C1 2 0 0.01u IC=0.1
R4 4 3 10K
R2 2 4 5K
R3 3 0 10K
X1 3 2 5 6 4 uA741
VCC 5 0 DC 15
VEE 6 0 DC -15
.LIB EVAL.LIB
.TRAN 10u 1000u UIC
.PROBE
.END
```

**** 03/04/93 07:10:52 ***** Evaluation PSpice (Jan 1993) *****

LAB 4 OSCILLATOR

**** Diode MODEL PARAMETERS

```
X1.dx
IS 800.000000E-18
RS 1
```

**** 03/04/93 07:10:52 ***** Evaluation PSpice (Jan 1993) *****

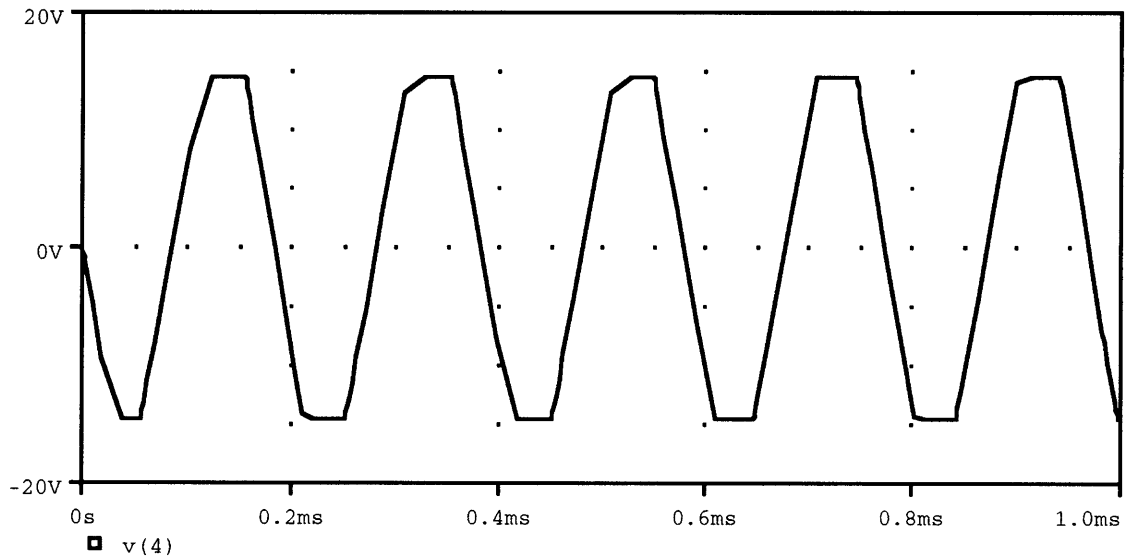
LAB 4 OSCILLATOR

**** BJT MODEL PARAMETERS

```
X1.qx
NPN
IS 800.000000E-18
BF 93.75
NF 1
BR 1
NR 1
```

JOB CONCLUDED

TOTAL JOB TIME 57.33



Time

"LAB 4 OSCILLATOR" 03/04/93 07:10:52 27.0°
Evaluation Probe 5.3 © 1993 MicroSim Corp.

C = ,01
741

**** 03/04/93 07:14:51 ***** Evaluation PSpice (Jan 1993) *****

LAB 4 OSCILLATOR

**** CIRCUIT DESCRIPTION

```
*****
C1  2  0  0.1u  IC=0.1
R4  4  3  10K
R2  2  4  5K
R3  3  0  10K
X1  3  2  5  6  4  uA741
VCC 5  0  DC  15
VEE 6  0  DC -15
.LIB EVAL.LIB
.TRAN 10u 10000u  UIC
.PROBE
.END
```

**** 03/04/93 07:14:51 ***** Evaluation PSpice (Jan 1993) *****

LAB 4 OSCILLATOR

**** Diode MODEL PARAMETERS

```
*****
X1.dx
  IS 800.000000E-18
  RS 1
```

**** 03/04/93 07:14:51 ***** Evaluation PSpice (Jan 1993) *****

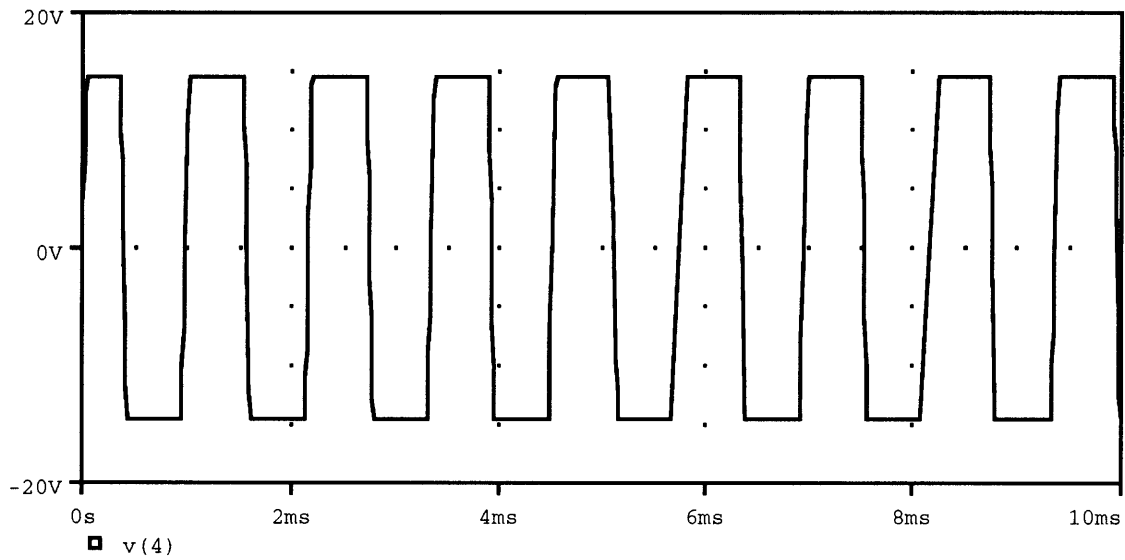
LAB 4 OSCILLATOR

**** BJT MODEL PARAMETERS

```
*****
X1.qx
  NPN
  IS 800.000000E-18
  BF 93.75
  NF 1
  BR 1
  NR 1
```

JOB CONCLUDED

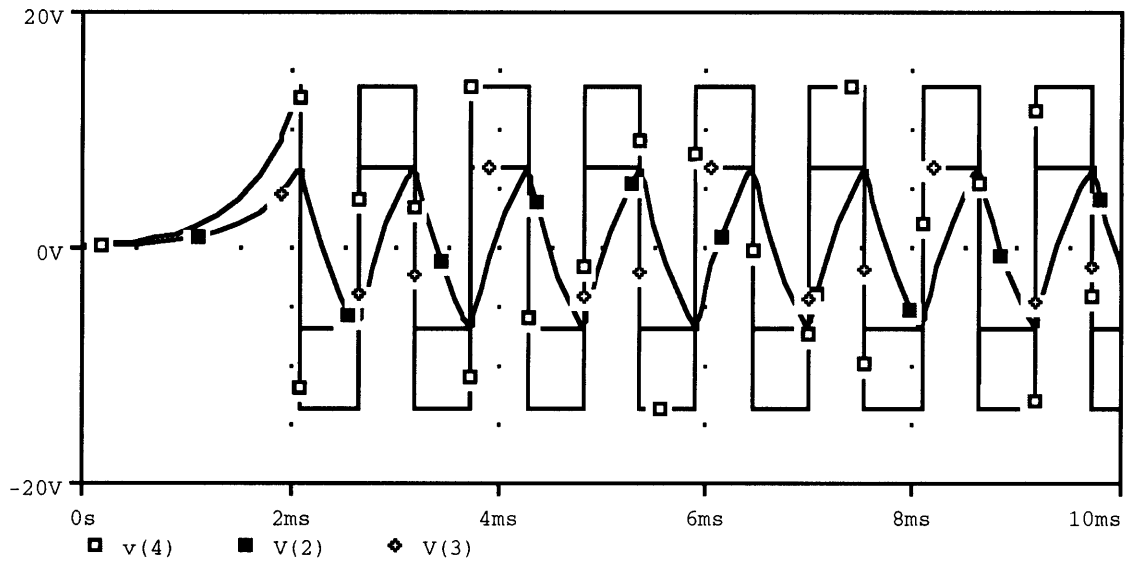
TOTAL JOB TIME 101.72



Time

"LAB 4 OSCILLATOR" 03/04/93 07:14:51 27.0°
Evaluation Probe 5.3 © 1993 MicroSim Corp.

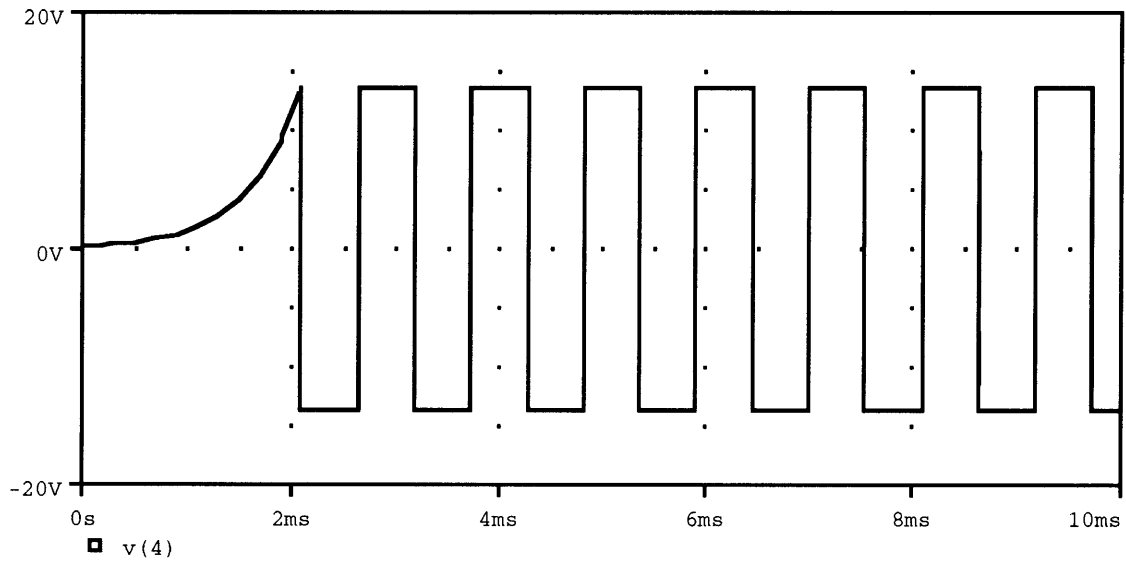
$C = 0.1$
741



Time

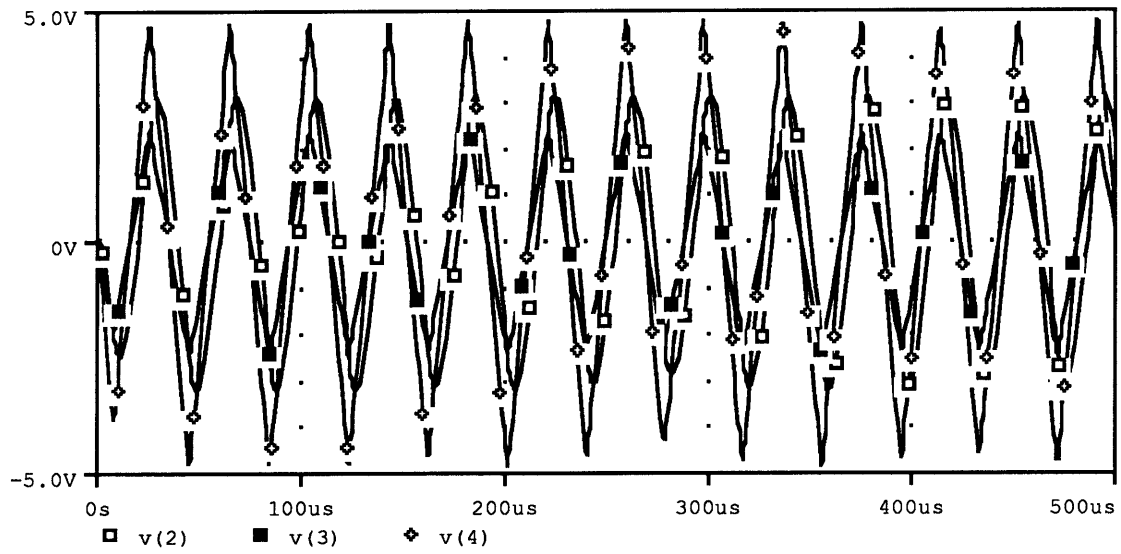
"LAB 4 OSCILLATOR" 03/04/93 07:42:12 27.0°
 Evaluation Probe 5.3 © 1993 MicroSim Corp.

LM318.



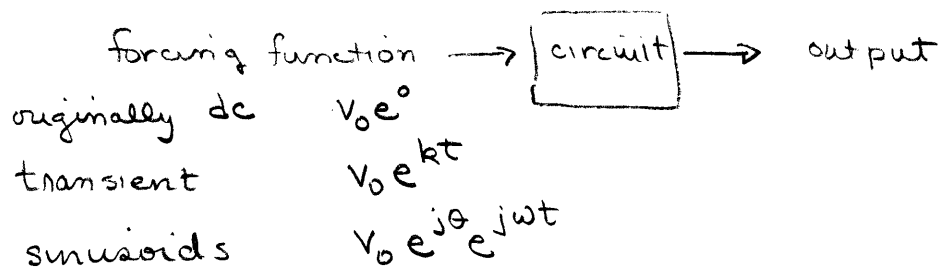
Time
"LAB 4 OSCILLATOR" 03/04/93 07:42:12 27.0°
Evaluation Probe 5.3 © 1993 MicroSim Corp.

LM318.



Time
"LAB 4 OSCILLATOR" 03/03/93 17:09:18 27.0°
Evaluation Probe 5.3 © 1993 MicroSim Corp.

analysis



response
in general $V_0 e^{j\theta} e^{\underbrace{(\sigma + j\omega)t}_{\text{complex number}}}$

dc $s = 0$

transient
(exponential) $s = \sigma$

sinusoidal $s = j\omega$

exponential sinusoid $s = \sigma + j\omega$

mathematically

do the problem in the transform domain

$$v(t) = \frac{1}{2\pi j} \int_{\sigma_0 - j\infty}^{\sigma_0 + j\infty} e^{st} v(s) ds.$$

bilateral
Laplace transform

σ governs convergence

express $v(t)$ as the sum (integral)
of an infinite number of vanishingly small
terms with complex frequency $\sigma + j\omega$

$$V(s) = \int_{-\infty}^{\infty} e^{-st} v(t) u(t) dt = \int_0^{\infty} e^{-st} v(t) dt.$$

one-sided Laplace transform
Laplace transform.

use definition $V(s) = \int_0^{\infty} e^{-st} v(t) dt = \mathcal{L}[v(t)].$

$$v(t) = \frac{1}{2\pi j} \int_{\sigma_0 - j\infty}^{\sigma_0 + j\infty} e^{st} V(s) ds = \mathcal{L}^{-1}[V(s)].$$

$$v(t) \iff V(s)$$

one-to-one transform.

we will not do this everytime. lot's easier than it looks.

unit step function

$$\mathcal{L}[u(t)] = \int_0^{\infty} e^{-st} u(t) dt = \int_0^{\infty} e^{-st} dt = -\frac{1}{s} e^{-st} \Big|_0^{\infty} = \frac{1}{s}.$$

impulse

$$\mathcal{L}[\delta(t-t_0)] = \int_0^{\infty} e^{-st} \delta(t-t_0) dt = e^{-st_0}$$

$t_0 > 0^-$

$$\delta(t-t_0) \iff e^{-st_0}$$

$$\delta(t) \iff 1.$$

exponential

$$\mathcal{L}[e^{-\alpha t} u(t)] = \int_0^{\infty} e^{-\alpha t} e^{-st} dt = -\frac{1}{s+\alpha} e^{-(s+\alpha)t} \Big|_0^{\infty} = \frac{1}{s+\alpha}$$

$$e^{-\alpha t} u(t) \iff \frac{1}{s+\alpha}$$

initial conditions

we know $v(t) \leftrightarrow V(s)$.

$$\mathcal{L}\left\{\frac{dv}{dt}\right\} = \int_0^{\infty} e^{-st} \frac{dv}{dt} dt = \int_0^{\infty} e^{-st} dv,$$

$$= e^{-st} v \Big|_{0^-}^{\infty} - \int_{0^-}^{\infty} -s e^{-st} v(t) dt,$$

$$= e^{-st} v \Big|_{0^-}^{\infty} + s \int_0^{\infty} e^{-st} v(t) dt,$$

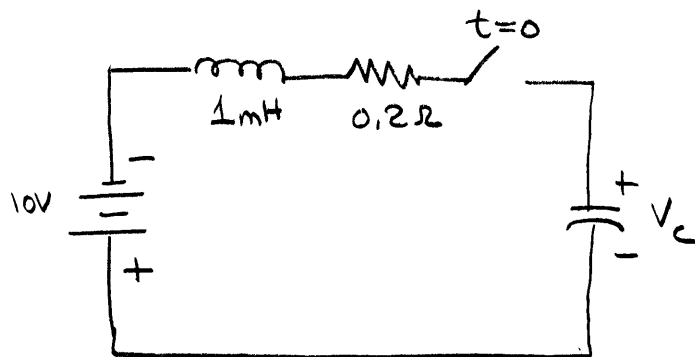
$$= 0 - v(0^-) + sV(s).$$

$$\mathcal{L}\left\{\frac{dv}{dt}\right\} = sV(s) - v(0^-).$$

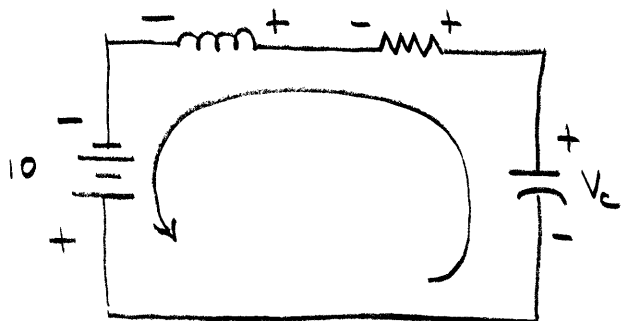
#5

P77

(5.19)

Engineering Circuit
Analysis with
PSpice and Probe

for switch closed

we will solve for $i(t)$.

use KVL $+10 - L \frac{di}{dt} - iR + V_c = 0$.

where $V_c = \frac{1}{C} \int_0^t i(x) dx$

How do we get Laplace transform of $V_c(t)$?

$$\mathcal{L} \left[\int_0^t i(x) dx \right] = \int_0^\infty e^{-st} \left[\int_0^t i(x) dx \right] dt$$

Now we integrate by parts. $\int_0^\infty u dw = u w \Big|_0^\infty - \int_0^\infty w du$

$$u = \int_0^t i(x) dx$$

$$du = i(t) dt$$

$$dw = e^{-st} dt$$

$$w = \frac{e^{-st}}{-s} = -\frac{1}{s} e^{-st}$$

$$\mathcal{L} \left[\int_0^t i(x) dx \right] = \left[\int_0^t i(x) dx \right] \left[-\frac{e^{-st}}{s} \right] \Big|_0^\infty + \int_0^\infty \frac{e^{-st}}{s} i(t) dt$$

$$\text{as } t \rightarrow \infty \quad e^{-st} \rightarrow 0$$

$$\text{as } t \rightarrow 0 \quad \int_0^t i(x) dx \rightarrow 0 \quad + \frac{1}{s} I(s)$$

back to our problem:

$$10 - L \frac{di}{dt} - iR + \frac{1}{C} \int_0^t i(x) dx = 0.$$

$$10 - L [sI(s) - i(0^-)] - I(s)R + \frac{1}{C} \left[\frac{1}{s} I(s) \right] = 0.$$

before switch closes $i(0^-) = 0.$

$$10 - sL I(s) - RI(s) + \frac{1}{sC} I(s) = 0.$$

$$10 + I(s) \left(\frac{1}{sC} - R - sL \right) = 0.$$

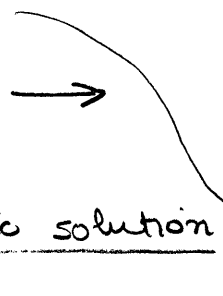
$$I(s) = \frac{-10}{\frac{1}{sC} - R - sL}$$

$$= \frac{-10sC}{1 - sRC - s^2LC}$$

$$I(s) = \frac{-10s(10^3 \times 10^{-6})}{10^3 - s(0.2)(10^3 \times 10^{-6}) - s^2(1 \times 10^{-3})(10^3) \times 10^{-6}}$$

$$= \frac{-10s}{10^3 - 0.2s - 10^{-3}s^2} = \frac{-10,000s}{10^6 - 200s - s^2}$$

don't know how to do this yet



do quadratic solution

$$= \frac{10,000s}{s^2 + 200s - 10^6}$$

$$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$s = \frac{-200 \pm \sqrt{(200)^2 - 4(1)(10^6)}}{2} = -100 \pm \frac{1}{2} \sqrt{1990}$$

What is this?

$$I(s) = \frac{+10,000s}{[s - (-100 + j995)][s - (-100 - j995)]}$$

What is this?

$$= \frac{+10,000s}{(s+100 - j995)(s+100 + j995)}$$

$$= \frac{a}{s+100-j995} + \frac{b}{s+100+j995}$$

$$a(s+100+j995) + b(s+100-j995) = -10000s.$$

$$as + bs = +10,000s,$$

$$a+b = +10,000$$

$$a(100+j995) + b(100-j995) = 0.$$

$$a = -b \frac{(100-j995)}{(100+j995)}$$

$$-b \frac{(100-j995)}{(100+j995)} + b = +10000.$$

$$b = \frac{+10,000}{-\frac{100-j995}{100+j995} + 1} = \frac{+10,000}{-\frac{(100-j995) + (100+j995)}{100+j995}}$$

$$= \frac{+10,000(100+j995)}{-100+j995+100+j995}$$

$$= \frac{+10,000(100+j995)}{j1990.}$$

$$b = \frac{-10,000j(100+j995)}{1990} = -j503(100+j995)$$

$$b = +5000 - j503$$

$$a + b = +10,000$$

$$a = -b + 10,000 = -5000 + j503 + 10,000 = +5000 + j503$$

$$I(s) = \frac{+5000 + j503}{s + 100 - j995} + \frac{+5000 - j503}{s + 100 + j995}$$

recall $\mathcal{L}^{-1} \left[\frac{1}{s+a} \right] = e^{-at}$.

$$\mathcal{L}^{-1} [I(s)] = \left[(+5000 + j503) e^{-(100-j995)t} + (+5000 - j503) e^{-(100+j995)t} \right] u(t)$$

$$= e^{-100t} \left[(+5000 + j503) e^{-j995t} + (+5000 - j503) e^{+j995t} \right]$$

$$= e^{-100t} \left[+5000 (e^{-j995t} + e^{+j995t}) + j503 (e^{-j995t} - e^{+j995t}) \right]$$

$$= e^{-100t} \left[+5000 \cdot 2\cos(995t) + j503 (-2j \sin 995t) \right]$$

$$= e^{-100t} \left[+10000 \cos(995t) + 1006 \sin 995t \right]$$

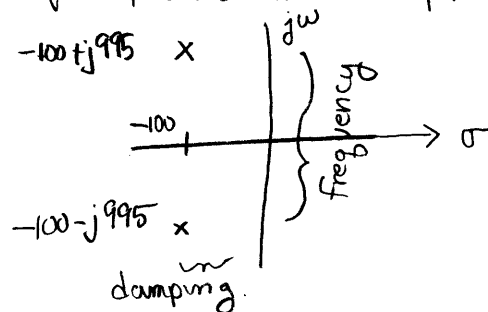
$$e^{j\theta} = \cos\theta + j\sin\theta$$

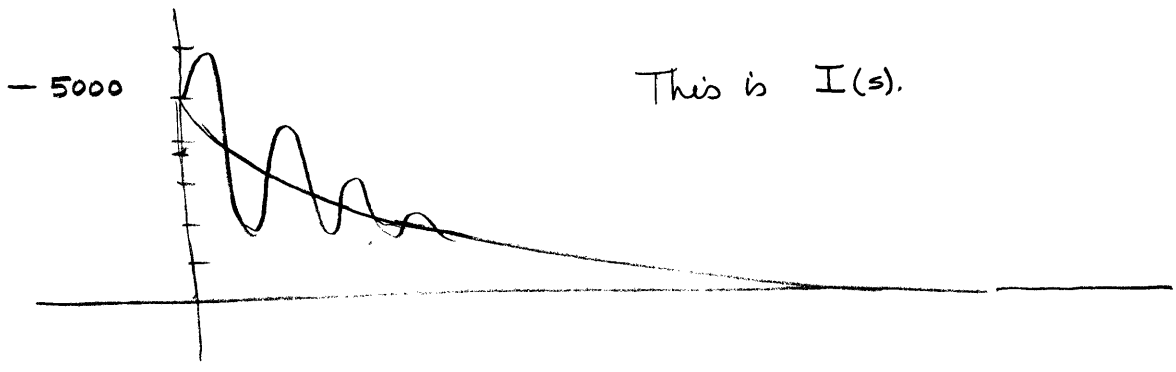
$$e^{-j\theta} = \cos\theta - j\sin\theta$$

$$e^{j\theta} - e^{-j\theta} = 2j \sin\theta$$

$$e^{j\theta} + e^{-j\theta} = 2\cos\theta$$

The poles may be plotted in the complex domain as





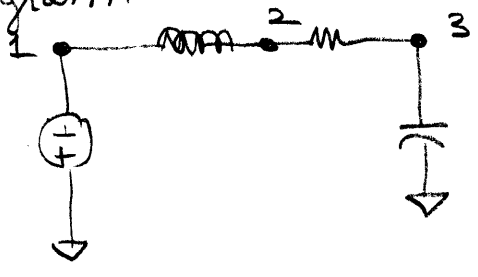
This is I(s).

Plan to do simulation of this.

$$t = \frac{1}{100} = 10 \text{ msec.}$$

everything done in 30 milliseconds

PSpice program.



```

RLC circuit
VS 0 1 PWL 0,0 1,1
L 1 2 1m
R 2 3 0.2
C 3 0 1000u
• tnom 30m 30m.
• probe
• end.

```

**** 03/04/93 07:56:36 ***** Evaluation PSpice (Jan 1993) *****

CLASSROOM DEMO RLC CIRCUIT

**** CIRCUIT DESCRIPTION

```
Vs 0 1 PWL 0,0 1u,10
L1 1 2 1m
R1 2 3 0.2
C1 3 0 1000u
.TRAN 30m 30m
.PROBE
.END
```

**** 03/04/93 07:56:36 ***** Evaluation PSpice (Jan 1993) *****

CLASSROOM DEMO RLC CIRCUIT

**** INITIAL TRANSIENT SOLUTION TEMPERATURE = 27.000 DEG C

NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE NODE VOLTAGE

(1) 0.0000 (2) 0.0000 (3) 0.0000

VOLTAGE SOURCE CURRENTS

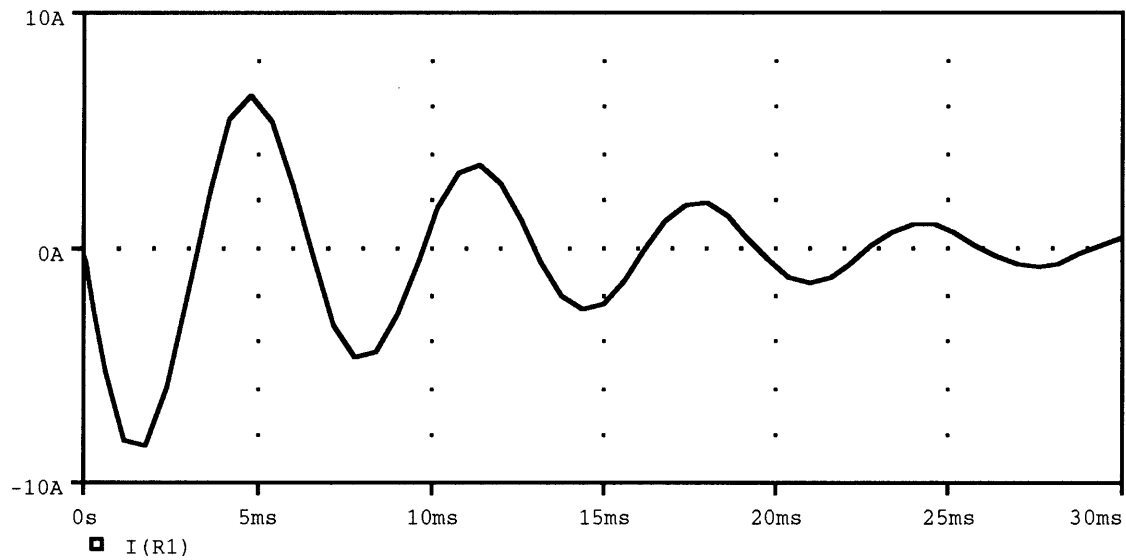
NAME CURRENT

Vs 0.000E+00

TOTAL POWER DISSIPATION 0.00E+00 WATTS

JOB CONCLUDED

TOTAL JOB TIME 3.98



Time

"CLASSROOM DEMO RLC CIRCUIT"

03/04/93 07:56:36

27.0°

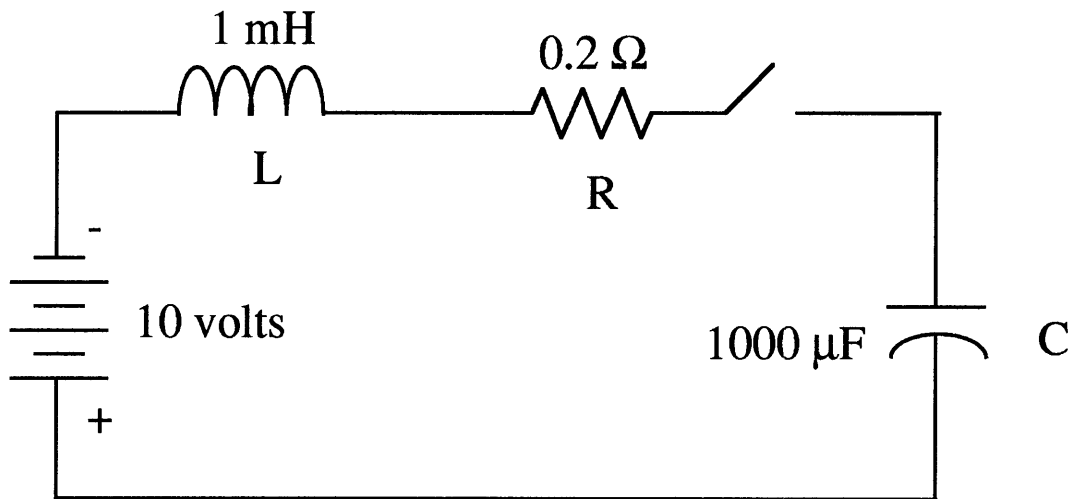
Evaluation Probe 5.3 © 1993 MicroSim Corp.

INS TCP/IP PrintServer 20

<i>Print engine name:</i>	PrintServer 20
<i>Print engine version:</i>	17
<i>Printer firmware version:</i>	32
<i>Server Adobe PostScript version:</i>	48.3
<i>Server software version:</i>	V2.0
<i>Server network node:</i>	crawford
<i>Server name:</i>	crawford
<i>Server job number:</i>	28
<i>Client software version:</i>	WRL-1.0
<i>Client network node:</i>	util
<i>Client name:</i>	flm
<i>Client job name:</i>	prob_soln.ps.732547382
<i>Submitted at:</i>	Fri Mar 19 08:28:20 1993
<i>Printed at:</i>	Fri Mar 19 08:28:20 1993

flm@util
prob_soln.ps.732547382

Solve for the current in the following circuit using Laplace transform techniques.



Use KVL to write the equation for i . I chose to have the current go in a counterclockwise direction to coincide with current flow from the positive terminal of the battery.

The problem with the example done in class was that the voltage across the capacitor did not obey the passive sign convention. If you go around the above circuit counterclockwise you should get the equation:

$$+V_c + Ri + L\frac{di}{dt} - 10u(t) = 0$$

where

$$V_c = \frac{1}{C} \int_0^t i(x) dx$$

Substituting this expression for V_C into the above equation:

$$\frac{1}{C} \int_0^t i(x) dx + Ri + L\frac{di}{dt} - 10u(t) = 0$$

Taking the Laplace transform of the above equation gives:

$$\frac{1}{C} \frac{I(s)}{s} + RI(s) + L(sI(s) - i(0^-)) - \frac{10}{s} = 0$$

which was obtained using the Laplace transform relationships for the derivative and integral of a function, i.e.

$$i(t) \leftrightarrow I(s)$$

$$\int_0^t i(x) dx \leftrightarrow \frac{I(s)}{s}$$

$$\frac{di}{dt} \leftrightarrow sI(s) - i(0^-)$$

Since $i(0^-) = 0$ this reduces to:

$$\frac{I(s)}{sC} + RI(s) + LsI(s) - \frac{10}{s} = 0$$

Solving for $I(s)$:

$$I(s) = \frac{\frac{10}{s}}{sL + R + \frac{1}{sC}} = \frac{\frac{10}{L}}{s^2 + s\frac{R}{L} + \frac{1}{LC}} = \frac{\frac{10}{0.001}}{s^2 + s\frac{0.2}{0.001} + \frac{1}{0.001(1000 \times 10^{-6})}} = \frac{10,000}{s^2 + 200s + 10^6}$$

You can factor the denominator using the quadratic formula

$$s = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} = \frac{-200 \pm \sqrt{(200)^2 - 4(1)(10^6)}}{2(1)} = -100 \pm j995$$

and, after substituting into the above expression for I(s):

$$I(s) = \frac{10,000}{(s + 100 + j995)(s + 100 - j995)}$$

Expanding by partial fractions gives:

$$I(s) = \frac{10,000}{(s + 100 + j995)(s + 100 - j995)} = \frac{A}{s + 100 + j995} + \frac{B}{s + 100 - j995}$$

Equating the coefficients of s:

$$s^1: A + B = 0$$

$$s^0: (100 - j995)A + (100 + j995)B = 10000$$

which can be solved to give $A = +j2.51$ and $B = -j2.51$. The final expression for I(s) is:

$$I(s) = \frac{+j5.03}{(s + 100 + j995)} + \frac{-j5.03}{(s + 100 - j995)}$$

Inverse Laplace transforming using the relationship

$$e^{-at}u(t) \leftrightarrow \frac{1}{s+a}$$

yields

$$i(t) = j5.03e^{-(100+j995)t}u(t) - j5.03e^{-(100-j995)t}u(t) = -j5.03e^{-100t}[e^{-j995t} - e^{+j995t}]u(t)$$

which can be further simplified using the Euler identities

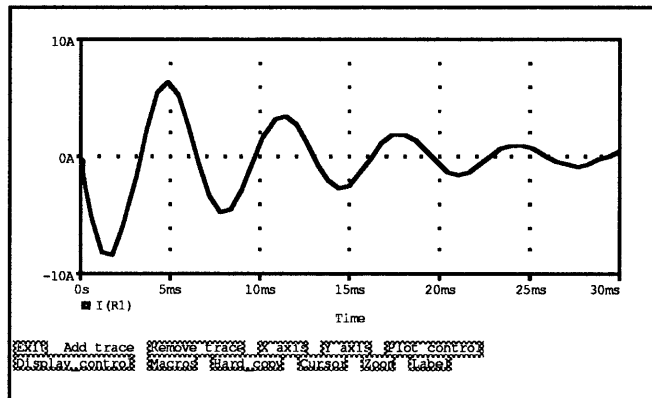
$$e^{j\theta} - e^{-j\theta} = 2j\sin\theta \quad \text{and} \quad e^{j\theta} + e^{-j\theta} = 2\cos\theta$$

to give the final result for i(t), i.e.

$$i(t) = -j5.03e^{-100t}[2j\sin(995t)]u(t) = +10.06e^{-100t}\sin(995t)u(t)$$

A PSpice simulation of the circuit was done:

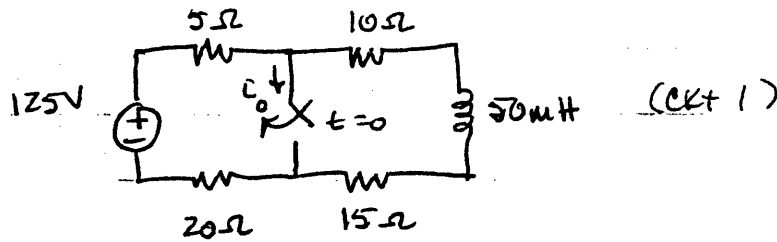
```
Vs 0 1 PWL 0,0 1u,10
L1 1 2 1m
R1 2 3 0.2
C1 3 0 1000u
.TRAN 30m 30m
.PROBE
.END
```



Note that the simulation result is the negative of the Laplace transform result because PSpice measures the current through the resistor using node 2 as the positive node whereas we used node 3 as the positive node for R in our calculations. Furthermore, I did not use an actual unit step but only an approximation to one using the PWL (piece-wise linear) source command.

①

Problem 8.3 - Natural Response of an Inductor

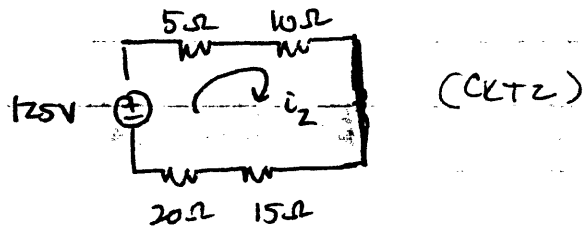


Recitation Solution (for a, b)

a) (1) After a long time, an inductor in a circuit with a DC voltage becomes a short

(2) The current across an inductor cannot change instantaneously. ($i_L(0^-) = i_L(0^+)$)

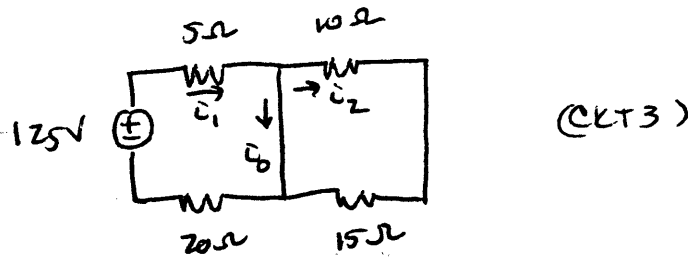
So the circuit before the switch is thrown looks like this



The current in this circuit is $i_2 = \frac{125V}{50\Omega} = 2.5A = i_L(0^-)$

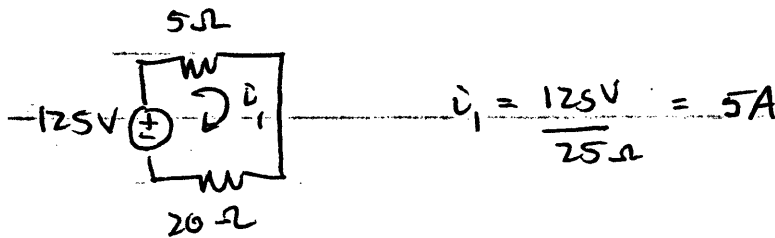
When the switch is closed, a short will appear ~~across~~ across the middle of the circuit and it will look as follows:

②



for time $t=0^+$. What was previously termed i_2 will flow on the right hand side of the circuit and this will be subtracted from i_1 to obtain i_0 ($i_0 = i_1 - i_2$).

i_1 is the current on the left side of the circuit and is defined by the following circuit



So $i_0(0^+) = i_1 - i_2 = 5A - 2.5A = 2.5A$.

The current on the inductor side of the circuit will exponential die out so the remaining current will simply be i_1 . So $i_0(\infty) = i_1 = 5A$.

③

b) For part b), in order to find the current $i(t)$ I used the natural response charge equation for an RL circuit. It is

$$i(t) = I_0 e^{-t/\tau}$$

where $\tau = \frac{L}{R}$. It is derived in section

8.1 of the text. Using this equation:

$$\tau = \frac{L}{R} = \frac{50 \times 10^{-3}}{25} = 2 \text{ms}$$

(R = resistance in inductive portion of the circuit)

$$i_2 = 2.5 e^{-t/2\text{ms}} = 2.5 e^{-500t} \text{ A} \quad t \geq 0$$

$$i_1 = 5 \text{ A} \quad t \geq 0 \quad (\text{no inductor here})$$

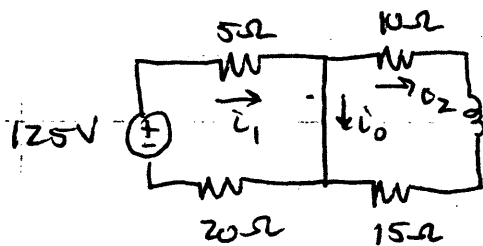
$$i_0 = i_1 - i_2 = 5 - 2.5 e^{-500t} \quad t \geq 0$$

(4)

Dr Gruber's Solution (for a, b)

Dr Gruber used the same analysis to find $i_2 = i_L(0^-)$. $i_2 = \frac{125}{50} = 2.5 \text{ A}$ from CKT2. ($i_2 = i_L(0^-)$)

His analysis after the switch closed is slightly different, but gives the same result. The circuit he used is as follows



Looking at the left side of the circuit, i_1 has to equal 5A by KVL

$$125\text{V} = (5 + 20)i_1 \quad i_1 = 5\text{A}$$

So

$$i_0 + i_2 = i_1 = 5\text{A}$$

$$(1) \quad i_0 = 5 - i_2$$

Now do KVL on the right side

$$0 = 25i_2 + L \frac{di_2}{dt}$$

(voltage across short)

⑥

$$i_2(0^-) = 2.5$$

Now he assumes that $i_2 = I e^{st}$ so

$$0 = 25 I e^{st} + 50 \times 10^{-3} s I e^{st}$$

$$s = \frac{-25}{50 \times 10^{-3}} = -500$$

$$\therefore i_2 = I e^{-500t} \quad \text{at } t=0, i_2 = 2.5$$

$$\underline{2.5 = I}$$

$$i_2 = 2.5 e^{-500t}$$

$$\text{and } i_0^{(t)} = 5 - i_2 = 5 - 2.5 e^{-500t}$$

$$i_0(0) = 5 - 2.5 e^0 = 2.5 \text{ A}$$

$$i_0(\infty) = 5 - 2.5 e^{-\infty} = 5 \text{ A}$$

c) Part c is the same for both.

- in how many microseconds will $i_0(t) = 3 \text{ A}$?

$$3 = 5 - 2.5 e^{-500t}$$

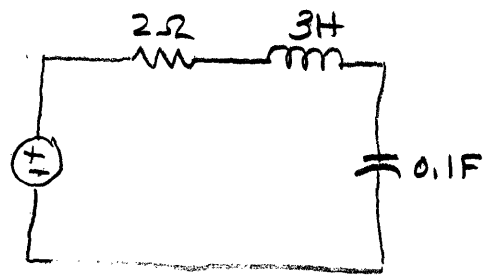
$$\ln -2 = \ln -2.5 e^{-500t}$$
$$\ln 0.8 = \ln e^{-500t}$$

$$-500t = \ln 0.8$$

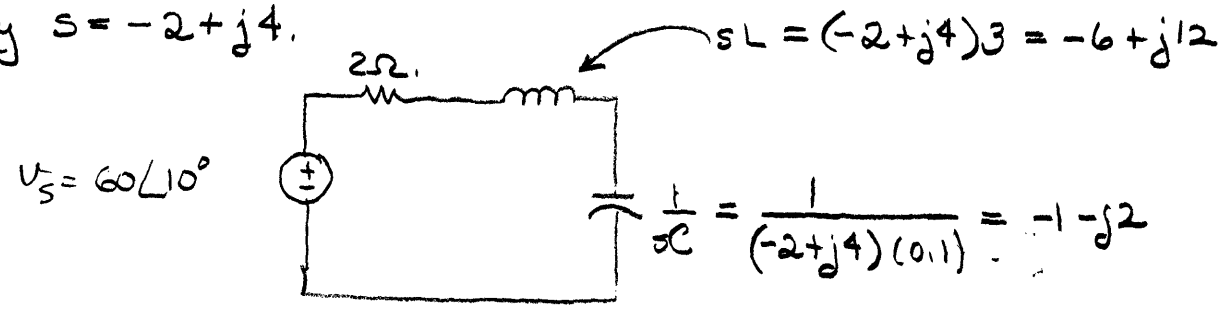
$$t = 446.28 \mu\text{s.}$$

Example

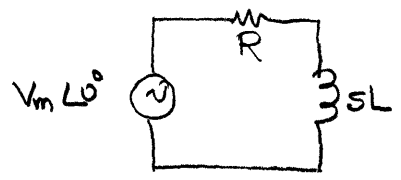
$$v(t) = 60e^{-2t} \cos(4t + 10^\circ)$$



identify $s = -2 + j4$.



12-5 Frequency response as a function of σ



$$\hat{I} = \frac{V_m L^0}{R + sL}$$

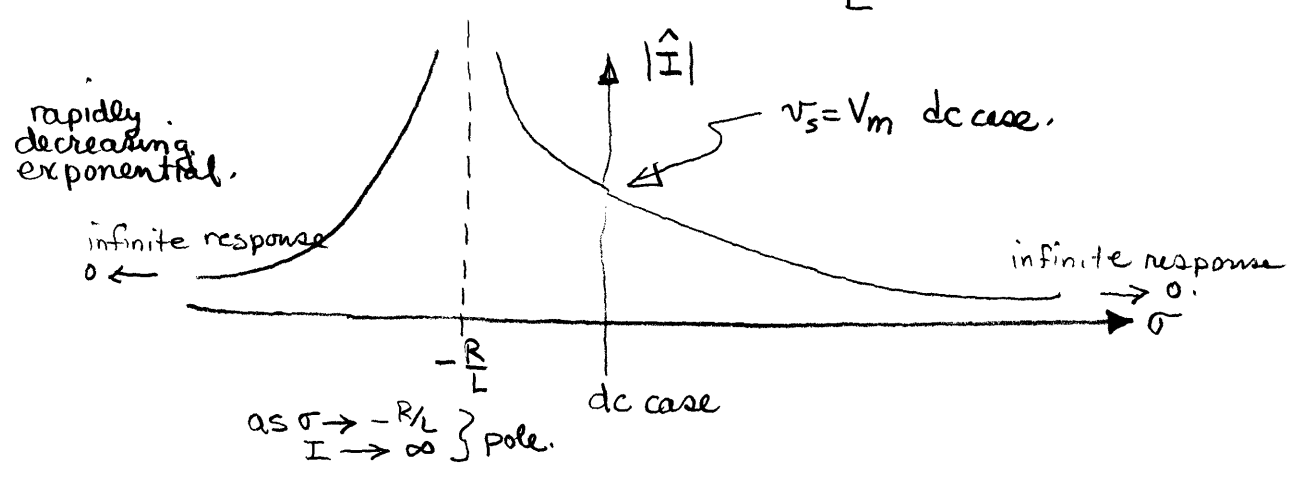
what happens when $\omega \rightarrow 0$, $s = \sigma + j\omega$
sources of form $v_s = V_m e^{\sigma t}$

$$\hat{I} = \frac{V_m}{R + \sigma L} = \frac{V_m}{L} \frac{1}{\sigma + R/L}$$

form $\frac{1}{s+a}$

inverse transforming

$$i(t) = \frac{V_m}{L} e^{-\frac{R}{L}t}$$



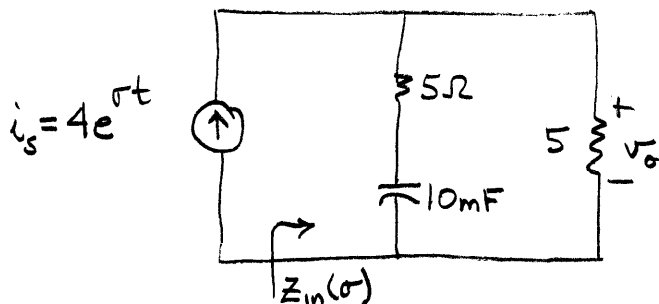
Example: desire $i(t) = 1e^{\sigma t}$ at $s = \sigma + j\beta$

$$1 = \frac{V_m}{\sigma + 1}$$

$$V_m = \sigma + 1$$

This current will produce a current of 1A amplitude

Example:



calculate 'input impedance

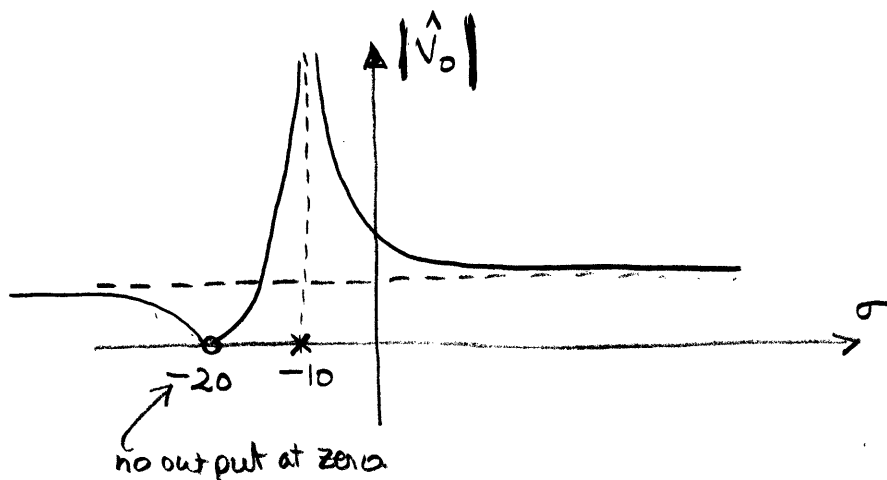
$$Z_{in}(\sigma) = 5 \parallel \left(5 + \frac{1}{sC} \right) = 5 \parallel \left(5 + \frac{1}{\sigma \cdot 0.01} \right) = \frac{5(5 + 0.01\sigma)}{5 + 5 + 0.01\sigma}$$

$$Z_{in}(\sigma) = 2.5 \frac{\sigma + 20}{\sigma + 10}$$

in the frequency domain

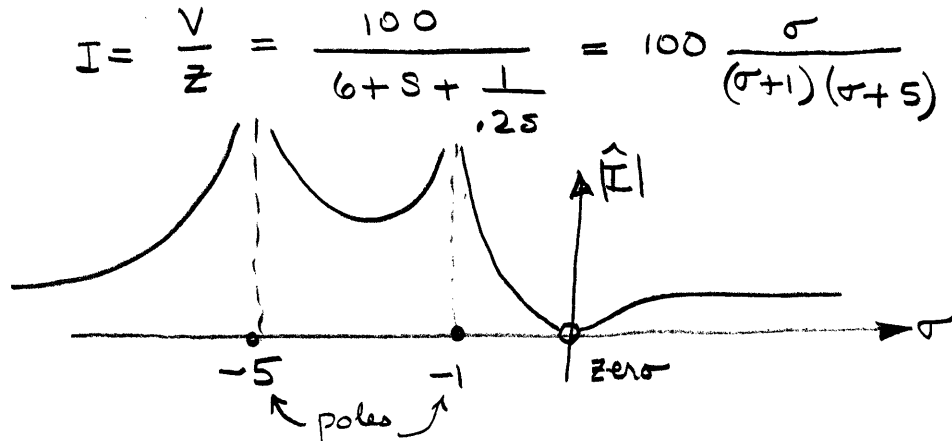
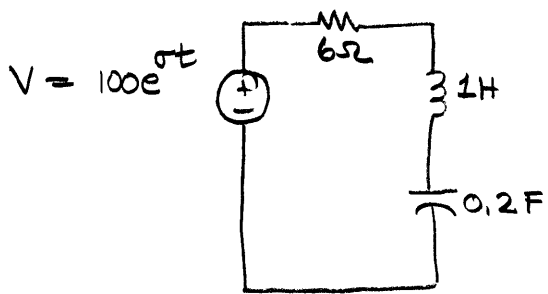
$$\hat{V}_o = I_s Z_{in} = (4) 2.5 \frac{\sigma + 20}{\sigma + 10} = 10 \frac{\sigma + 20}{\sigma + 10}$$

nice form for response



time domain voltage.

$$10 \frac{\sigma + 20}{\sigma + 10} e^{\sigma t}$$



forced response for $\sigma = -3$ is $\hat{I} = 100 \frac{-3}{(-3+1)(-3+5)} = 100 \frac{-3}{(-2)(+2)} = +75A$

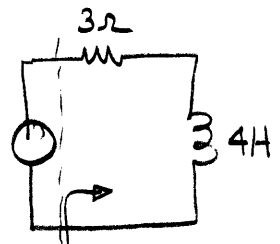
$$i(t) = 75e^{-3t}$$

this is forced response.

natural response when no forcing function

12-6 The complex frequency plane.

let's consider what happens when both σ, ω are non-zero

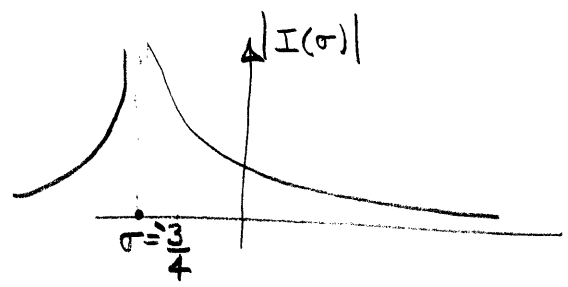


$$Z(s) = 3 + 4s$$

plot response as function of σ
for $\omega = 0$ $Z(\sigma) = 3 + 4\sigma$

$$I(s) = \frac{V(s)}{3 + 4\sigma}$$

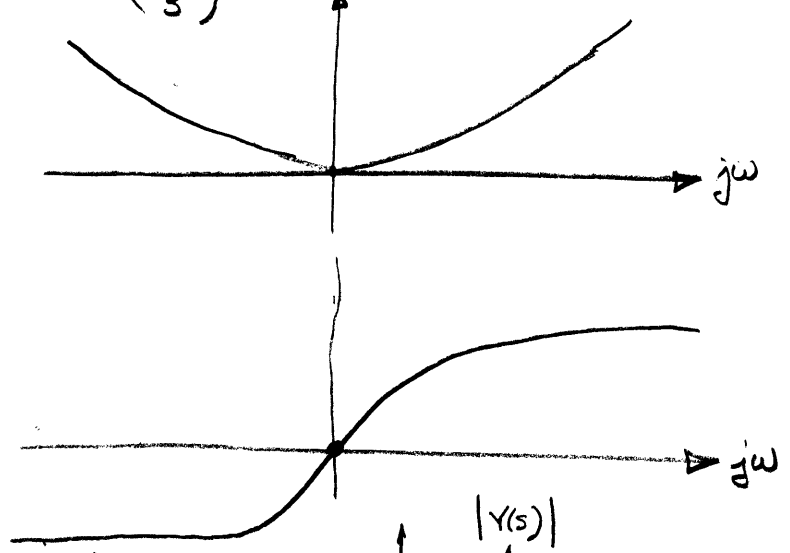
↑
pole at $\sigma = -\frac{3}{4}$



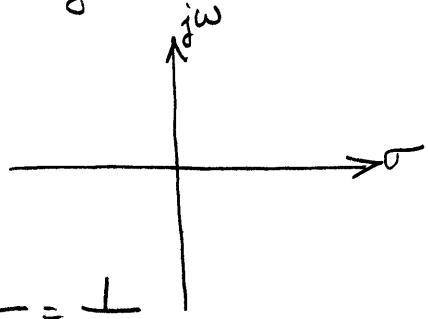
plot response as function of $j\omega$
for $\sigma = 0$ $Z(j\omega) = 3 + j4\omega$

$$|Z(j\omega)| = \sqrt{9 + 16\omega^2}$$

$$\angle Z(j\omega) = \tan^{-1}\left(\frac{4\omega}{3}\right)$$

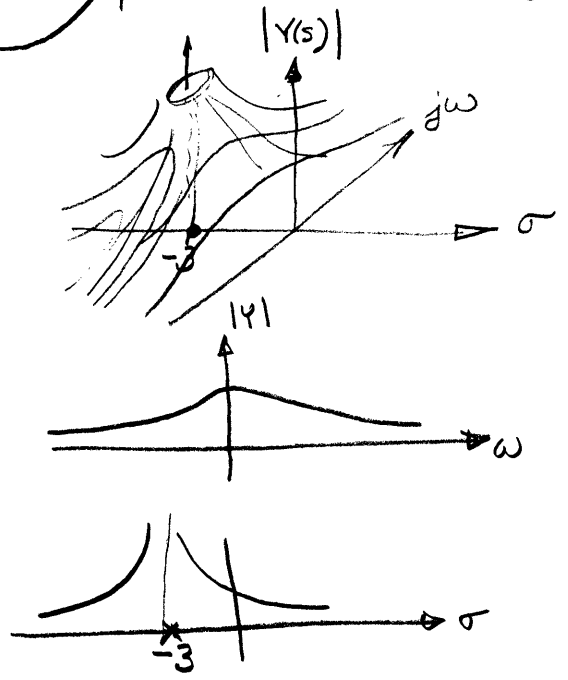


consider plotting in two dimensions

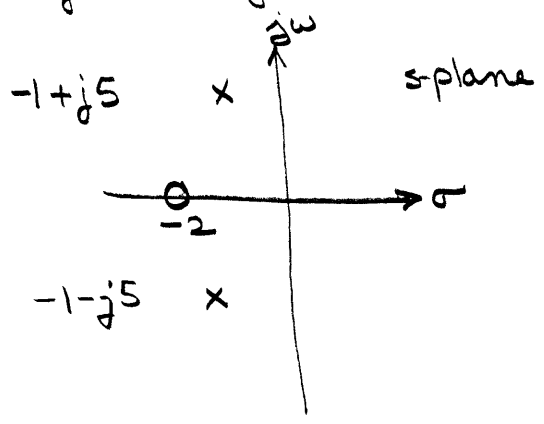


$$Y(s) = \frac{1}{Z(s)} = \frac{1}{s+3}$$

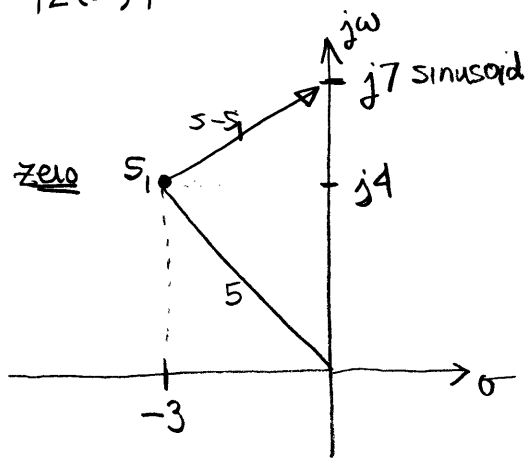
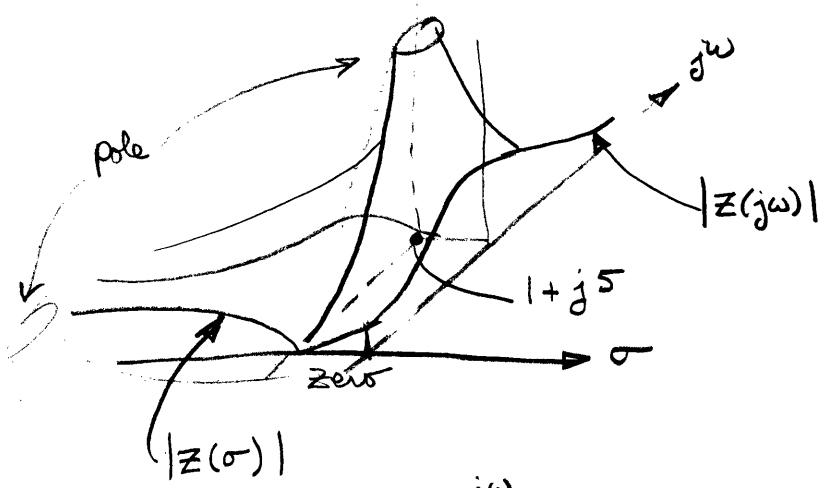
$$|Y(s)| = \frac{1}{\sqrt{(\sigma+3)^2 + \omega^2}}$$



Suppose you are given

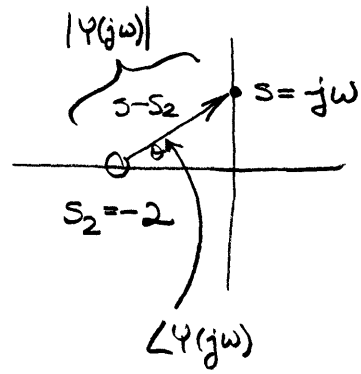


$$Z(s) = k \frac{s+2}{(s+1-j5)(s+1+j5)} = k \frac{s+2}{s^2+2s+26}$$

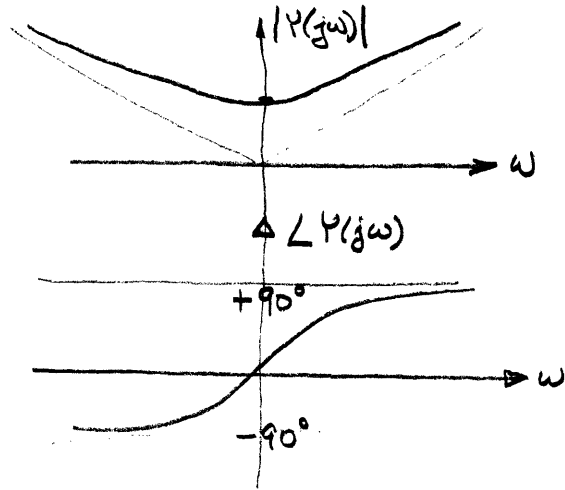


$$s_1 = -3 + j4 = 5 \angle 126.9^\circ$$

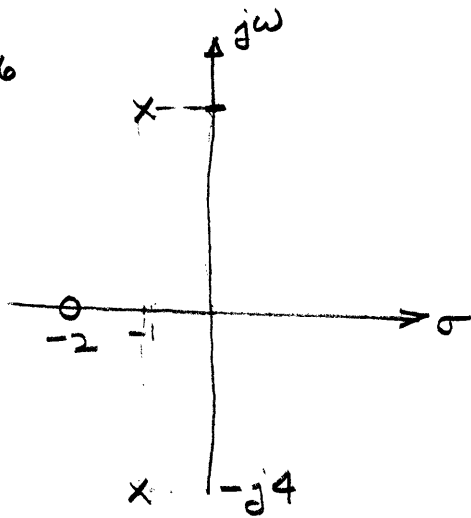
suppose $Y(s) = s+2$



$$I(s) = \frac{V(s)}{Z(s)} = Y(s) V(s).$$



Problem 16
P. 374.



$$H(s) = k \frac{s+2}{(s+1-j4)(s+1+j4)}$$

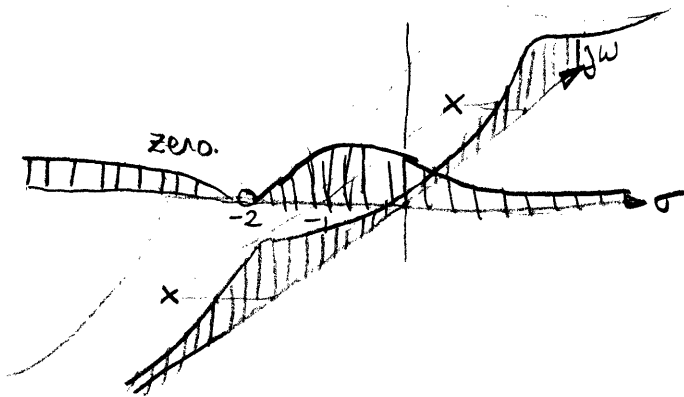
$$= k \frac{s+2}{s^2+2s+17}$$

$$(s+a)(s+a^*)$$

$$s^2+(a+a^*)s+|a|^2$$

$$(1-j4)(1+j4) = 1-j^2 4^2 + 16$$

sketch $H(s)$ vs. σ $\omega=0$
vs. ω $\sigma=0$.



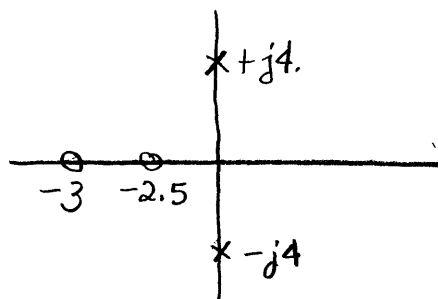
Problem 17

$$H(s) = \frac{10s^2 + 55s + 75}{s^2 + 16} = \frac{(s-3)(s-2.5)}{(s+j4)(s-j4)}$$

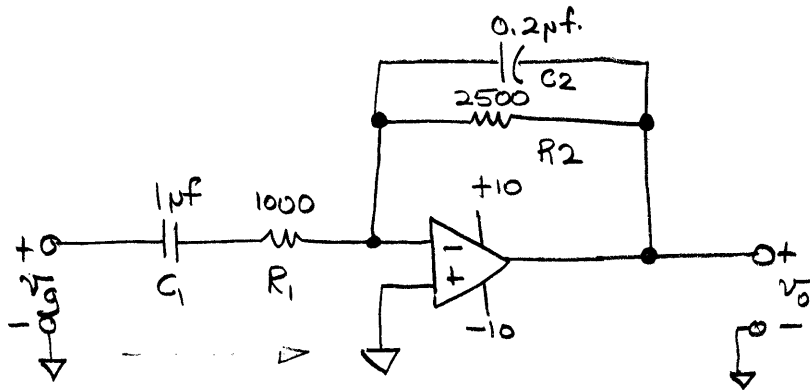
$$\frac{-55 \pm \sqrt{(55)^2 - 4(10)(75)}}{2(10)} = \frac{-55 \pm 5}{20} = -3, -2.5$$

$$s^2 = -16$$

$$s = \pm j4$$



16.51



$$\frac{1}{sC} = \frac{1}{s(1.2 \times 10^{-6})}$$

$$= \frac{5 \times 10^6}{s}$$

no energy stored initially

$$V_g = 6000t u(t)$$

find (a) $V_o(t)$ (b) v_o

(c) how long it takes to saturate

(d) — v_g .

KCL

$$\frac{V_g - 0}{Z_i} - \frac{V_o - 0}{Z_f} = 0$$

$$V_o = -\frac{Z_f}{Z_i} V_g$$

$$Z_f = \frac{(2500) \left(\frac{5 \times 10^6}{s} \right)}{2500 + \frac{5 \times 10^6}{s}} = \frac{\frac{12.5 \times 10^9}{s}}{2500 + \frac{5 \times 10^6}{s}} = \frac{12.5 \times 10^9}{5 \times 10^6 + 2500s}$$

$$Z_f = \frac{5 \times 10^6}{s + 2000}$$

$$Z_i = \frac{1}{s(1 \times 10^{-6})} + 1000 = \frac{10^6}{s} + 1000 = \frac{10^6 + 1000s}{s} = 10^3 \left(\frac{s + 1000}{s} \right)$$

$$\int_0^t 6000 dx \rightarrow \frac{6000}{s}$$

$$6000t u(t) \rightarrow \frac{6000}{s^2}$$

$$V_g = \frac{6000}{s^2}$$

$$V_o(s) = -\frac{\frac{5 \times 10^6}{s + 2000}}{10^3 \left(\frac{s + 1000}{s} \right)} \frac{6000}{s^2} = \frac{(5 \times 10^6)(6000) \frac{s}{s^2}}{10^3 (s + 1000)(s + 2000)}$$

$$V_o(s) = \frac{-30 \times 10^6 s}{s(s + 1000)(s + 2000)}$$

$$(b) \quad v_o(s) = \frac{A}{s} + \frac{B}{s+1000} + \frac{C}{s+2000} = \frac{-30 \times 10^6}{s(s+1000)(s+2000)}$$

$$A(s+1000)(s+2000) + Bs(s+2000) + Cs(s+1000) = -30 \times 10^6$$

$$A(s^2 + 3000s + 2 \times 10^6) + B(s^2 + 2000s) + C(s^2 + 1000s) = -30 \times 10^6$$

$$s^2: \quad A + B + C = 0$$

$$s^1: \quad 3000A + 2000B + 1000C = 0 \quad 3A + 2B + C = 0$$

$$s^0: \quad 2 \times 10^6 A = -30 \times 10^6 \quad \therefore A = -15$$

$$\begin{array}{r} B + C = 15 \\ 2B + C = 45 \end{array}$$

$$B = 30$$

$$C = 15 - B = 15 - 30 = -15$$

$$V_o(s) = \frac{-15}{s} + \frac{30}{s+1000} - \frac{15}{s+2000}$$

$$v_o(t) = -15u(t) + 30e^{-1000t}u(t) - 15e^{-2000t}u(t)$$

(c) op-amp saturates when it reaches ± 10 volts.

$$\text{at } t=0^+ \quad -15 + 30 - 15 = 0$$

$$t \rightarrow \infty \quad v_o(t) \rightarrow -15$$

$$\text{let } x = e^{-1000t}$$

$$-15 + 30x - 15x^2 = -10$$

$$15x^2 - 30x + 5 = 0$$

$$x = \frac{30 \pm \sqrt{(30)^2 - 4(15)(5)}}{2(15)} = \frac{30 \pm 24.5}{30} = 1 \pm 0.816$$

$$= 1.816, \quad \boxed{0.184} \leftarrow \text{this is the one.}$$

$$0.184 = e^{-1000t}$$

$$-1.7 = \ln 0.184 = -1000t$$

$$1.7 \text{ms} = t$$

1.7ms to saturate

[d] let $v_g = mt$ $V_g = \frac{m}{s^2}$

/k

$$V_0 = \frac{-5 \times 10^3 s}{(s+1000)(s+2000)} \cdot \frac{m}{s^2} = \frac{-5000 m}{s(s+1000)(s+2000)}$$

final value less than -10 volts.

initial value

$$\lim_{s \rightarrow \infty} s F(s) = \lim_{t \rightarrow 0^+} f(t)$$

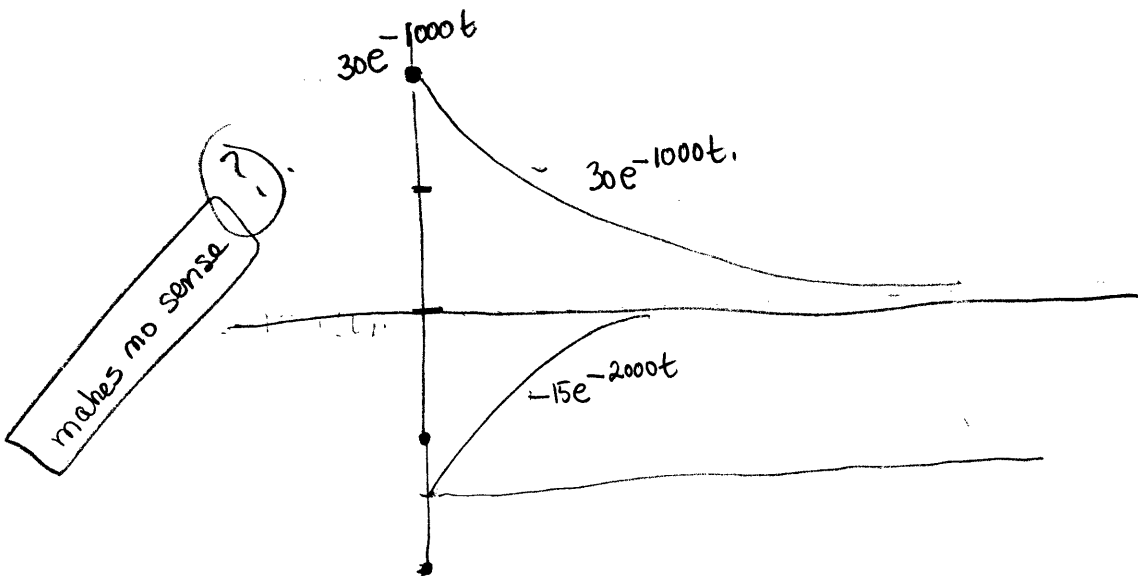
final value

$$\lim_{s \rightarrow 0} s F(s) = \lim_{t \rightarrow \infty} f(t)$$

$$\lim_{s \rightarrow 0} \frac{-5000 m \cancel{s}}{\cancel{s}(s+1000)(s+2000)} = \frac{-5000 m}{2 \times 10^6} = -\frac{5 m}{2000}$$

$$-\frac{5m}{2000} = -10$$

$$m = 4000 \text{ V/s}$$



3/9/93

1A

finish up chapter 15

15.5 Operational Transforms

$$\mathcal{L}[f(t)] = \int_0^{\infty} f(t) e^{-st} dt.$$

$$\text{if } \mathcal{L}[f(t)] = F(s) \quad \text{then } \mathcal{L}[kf(t)] = kF(s)$$

$$\begin{aligned} \text{if } \mathcal{L}[f_1(t)] &= F_1(s) & \mathcal{L}[f_1(t) + f_2(t)] &= F_1(s) + F_2(s). \\ \text{and } \mathcal{L}[f_2(t)] &= F_2(s) \end{aligned}$$

$$\begin{aligned} \text{if } \mathcal{L}[f(t)] &= F(s) \\ \mathcal{L}\left[\frac{df(t)}{dt}\right] &= sF(s) - f(0^-) \end{aligned}$$

$$\text{if } \mathcal{L}[f(t)] = F(s). \quad \mathcal{L}\left[\int_0^t f(x) dx\right] = \frac{F(s)}{s}.$$

translation in the time domain

what is $\mathcal{L}[f(t-a)u(t-a)]$?

$$\begin{aligned} \mathcal{L}[f(t-a)u(t-a)] &= \int_0^{\infty} u(t-a) f(t-a) e^{-st} dt \\ &= \int_a^{\infty} f(t-a) e^{-st} dt. \end{aligned}$$

$$\begin{aligned} \text{let } x &= t-a & t &= x+a & dt &= dx. \\ &= \int_0^{\infty} f(x) e^{-s(x+a)} dx \\ &= e^{-as} \int_0^{\infty} f(x) e^{-sx} dx = e^{-as} F(s). \end{aligned}$$

shift in time \rightarrow multiplication in s .

works backwards.

$$F(s+a) \rightarrow \mathcal{L}[e^{-at} f(t)]$$

scale changing

$$\mathcal{L}[f(at)] = \frac{1}{a} F\left(\frac{s}{a}\right).$$

initial and final value theorems.

$$\lim_{t \rightarrow 0^+} f(t) = \lim_{s \rightarrow \infty} sF(s).$$

initial value

$$\lim_{t \rightarrow \infty} f(t) = \lim_{s \rightarrow 0} sF(s).$$

final value
only if $f(\infty)$ exists, i.e.
all poles in left-half of
s-plane.

HW: 15.19, 15.30, 15.32.

Example

15.23 a)
$$F(s) = \frac{8s^2 + 37s + 32}{(s+1)(s+2)(s+4)}.$$

$$s^2 + 3s + 2.$$

all poles in LHP.

$$sF(s) = \frac{8s^3 + 37s^2 + 32s}{s^3 + 7s^2 + 14s + 8}$$

initial value $\lim_{s \rightarrow \infty} sF(s) = 8.$

final value $\lim_{s \rightarrow 0} sF(s) = 0.$

Example: 15:30

$$I_0(s) = \frac{V_{dc}/L}{s^2 + (R/L)s + (1/LC)}$$

initial value $\lim_{s \rightarrow \infty} sI_0(s) = \lim_{s \rightarrow \infty} \frac{s V_{dc}/L}{s^2 + (R/L)s + 1/LC} \rightarrow 0.$

final value $\lim_{s \rightarrow 0} sI_0(s) = \lim_{s \rightarrow 0} \frac{s V_{dc}/L}{s^2 + (R/L)s + 1/LC} = 0.$

Ch. 16

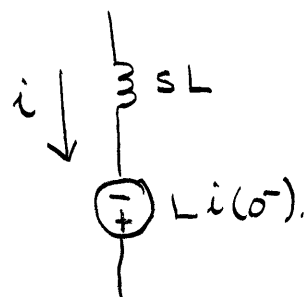
16.1

inductors and capacitors in the s-domain

$$\text{for an inductor } v = L \frac{di}{dt}$$

$$V(s) = L [sI - i(0^-)]$$

$$= sL I - i(0^-)L$$

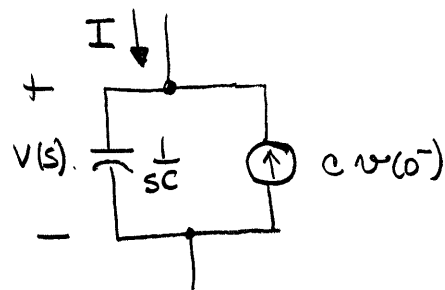


for a capacitor

$$i = C \frac{dv}{dt}$$

$$I(s) = C [sV(s) - v(0^-)]$$

$$= sC V(s) - C v(0^-)$$

no $\delta(t)$

no Thevenin.

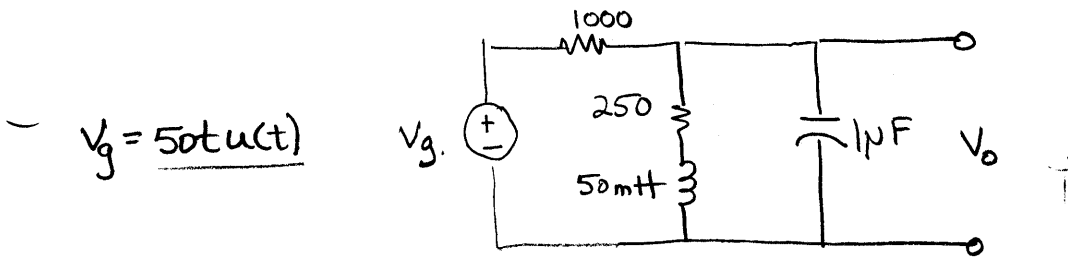
16.6 poles & zeros.

16.14, 16.18 make before break switches

16.31, 16.34 initial & final value

16.52, 16.53 op amps.

Example 17.2.



use KCL $\frac{V_g - V_o}{1000} + \frac{V_o}{250 + .05s} + \frac{V_o s}{10^6} = 0.$

$$V_o = \frac{1000(s+5000)V_g}{s^2 + 6000s + 25E6} \quad \leftarrow V_g(s) = \frac{50}{s^2}$$

$$H(s) = \frac{V_o}{V_g} = \frac{1000(s+5000)}{s^2 + 6000s + 25E6}$$

poles: $-3000 \pm j4000$

zeros: -5000

by partial fractions

$$V_o(s) = \frac{K_1}{s + 3000 - j4000} + \frac{K_1^*}{s + 3000 + j4000} + \frac{K_2}{s^2} + \frac{K_3}{s}$$

$$K_1 = 5\sqrt{5} \times 10^{-4} \angle 79.7^\circ$$

$$K_2 = 10$$

$$K_3 = -4 \times 10^{-4}$$

time domain

$$v_o(t) = \left[\underbrace{10\sqrt{5} \times 10^{-4} e^{-3000t} \cos(4000t + 79.7^\circ)}_{\text{transient term determined by poles of } H(s)} + \underbrace{10t - 4 \times 10^{-4}}_{\text{steady state}} \right] u(t)$$

see book p. 692.

chapter 17 The transfer function

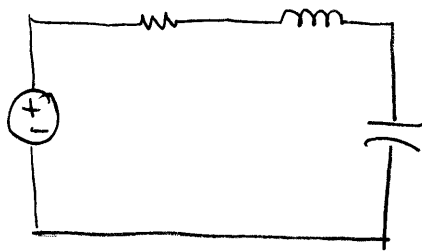
review before convolution

17.1 superposition linear, lumped-parameter systems.

17.2 transfer function

s domain ratio of $\frac{\text{output (response)}}{\text{input (source)}}$

series RLC circuit



$$H(s) = \frac{Y(s)}{X(s)} \quad \leftarrow \begin{array}{l} \text{output} \\ \text{input} \end{array}$$

$$\text{we got } I(s) = \frac{10000}{s^2 + 200s + 10^6}$$

$$\text{but } V(s) = 10/s$$

$$H(s) = \frac{10000 \cdot \frac{s}{10}}{s^2 + 200s + 10^6}$$

$$= \frac{1000s}{s^2 + 200s + 10^6}$$

$$\therefore Y(s) = H(s) X(s)$$

rational functions of s.

poles of $H(s)$ → transient component of total response

poles of $X(s)$ → steady state solution

Hayt 12-4 Z(s) and Y(s)

Let's consider only the inductor:



$$v(t) = V_m e^{\sigma t} \cos(\omega t + \theta)$$

$$= \text{Re} \{ V_m e^{\sigma t} e^{j(\omega t + \theta)} \}$$

$$= \text{Re} \{ V_m e^{j\theta} e^{j\omega t + \sigma t} \}$$

$$v(t) = \text{Re} \{ \hat{V}_m e^{(\sigma + j\omega)t} \}$$

In a similar fashion

$$i(t) = \text{Re} \{ \hat{I} e^{(\sigma + j\omega)t} \}$$

$$v(t) = L \frac{di}{dt}$$

$$\text{Re} \{ \hat{V}_m e^{(\sigma + j\omega)t} \} = L \text{Re} \{ (\sigma + j\omega) \hat{I} e^{(\sigma + j\omega)t} \}$$

in the complex domain

$$\hat{V}_m e^{(\sigma + j\omega)t} = L(\sigma + j\omega) \hat{I} e^{(\sigma + j\omega)t}$$

$$s \triangleq \sigma + j\omega$$

$$\hat{V}_m e^{st} = sL \hat{I} e^{st}$$

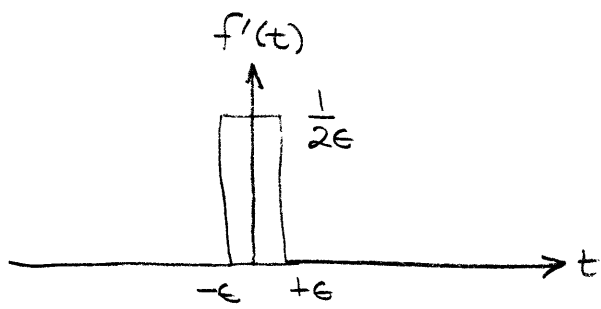
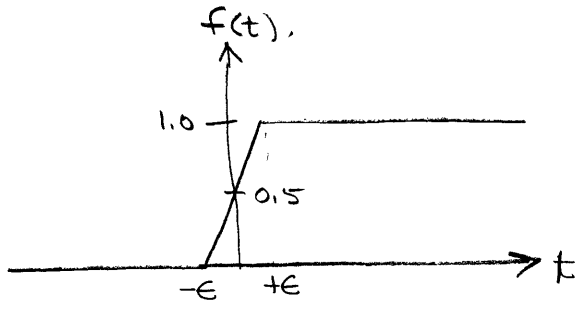
$$\frac{\hat{V}_m}{\hat{I}} = sL \quad \text{complex impedance of an inductor}$$

without detail

	R	L	C
Z(s)	R	sL	1/sC

3/11/93

Impulse function (607, 608, 609).
Impulsive sources (660, 666).



Dirac delta function

$$\lim_{\epsilon \rightarrow 0} f'(t) = \delta(t)$$

Area under curve is always 1.

$$\text{i.e. } \int_{-\infty}^{\infty} \delta(t) dt = 1$$

There are any number of mathematical definitions, e.g.

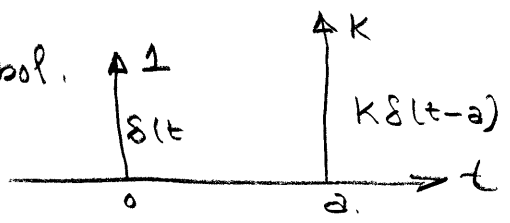
$$f(t) = \frac{k}{2\epsilon} e^{-\frac{|t|}{\epsilon}}$$

The one most commonly used is

$$\int_{-\infty}^{\infty} k \delta(t) dt = k$$

$$\delta(t) = 0 \text{ for } t \neq 0.$$

graphical symbol.



sifting property of the impulse function

$$\int_{-\infty}^{\infty} f(t) \delta(t-a) dt = \int_{a-\epsilon}^{a+\epsilon} f(t) \delta(t-a) dt$$

since $\delta(t-a) = 0$ except at $t=a$

$$= \int_{a-\epsilon}^{a+\epsilon} f(a) \delta(t-a) dt = f(a) \int_{a-\epsilon}^{a+\epsilon} \delta(t-a) dt$$

$f(t) \approx f(a)$ since $\delta(t-a)$ is zero everywhere else.

= f(a).

What is the Laplace transform of $\delta(t)$?

$$\mathcal{L}\{\delta(t)\} = \int_{0^-}^{\infty} \delta(t) e^{-st} dt = \int_{0^-}^{\infty} \delta(t) dt = 1$$

since $e^{-st} = 1$ for $s=0$.

You can also use the Laplace transform to define the integral and derivative of $\delta(t)$.

$$\mathcal{L}\left\{\frac{d\delta(t)}{dt}\right\} = s \underset{\substack{\uparrow \\ \text{transform of } \delta(t)}}{1} \quad \text{no initial conditions} = s$$

this is the transform of a doublet.

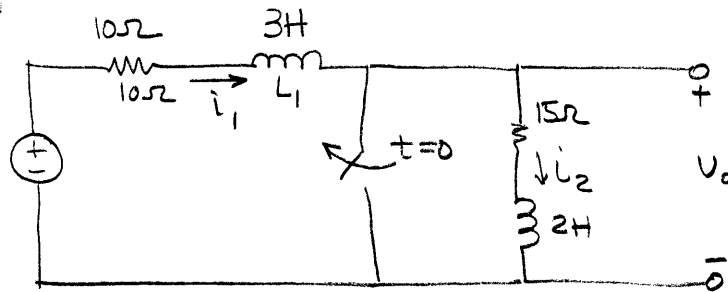
$$\mathcal{L}\left\{\int_0^+ \delta(x) dx\right\} = \frac{1}{s} \leftarrow \text{transform of } \delta(t)$$

which is the transform of $u(t)$.

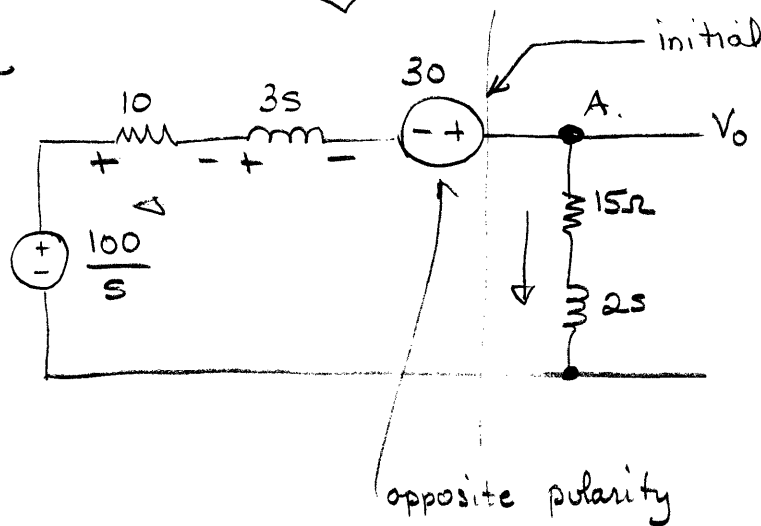
16.4 The Impulse function in circuit analysis

1/2

modeling



s-domain



condition on inductor
 $v = L \frac{di}{dt}$
 $V = L[sI - i(0^-)]$
 $= sLI - \underbrace{Li(0^-)}_{\text{a voltage}}$

once you understand the above circuit

use KCL at node A.

$$\frac{V_0}{2s+15} + \frac{(V_0-30)}{10+3s} - \frac{100}{s} = 0$$

solving for $V_0 = \frac{40(s+7.5)}{s(s+5)} + \frac{12(s+7.5)}{s+5}$ } bigger than 1 divide out.

partial fraction exp.

$$= \frac{60}{s} - \frac{20}{s+5} + 12 + \frac{30}{s+5}$$

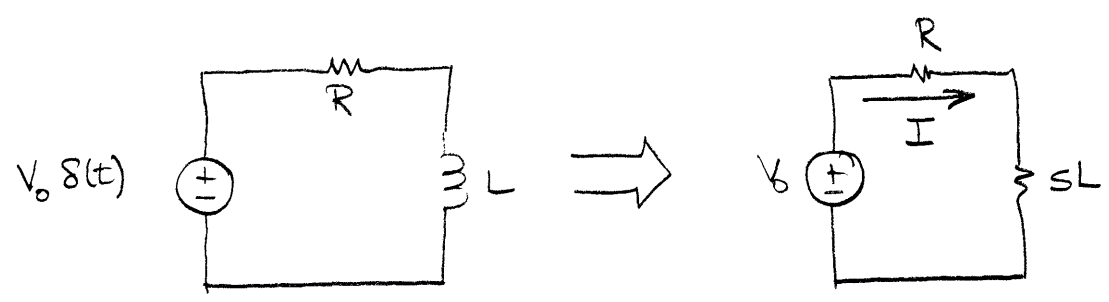
$\frac{1 \times 12}{s+5} \frac{s+7.5}{s+5} = \frac{2.5 \times 12 = 30}{s+5}$

$$= 60u(t) + 10e^{-5t} u(t) + 12\delta(t)$$

$$\frac{1}{s+a} \rightarrow e^{-at}$$

constant currents creates this impulse

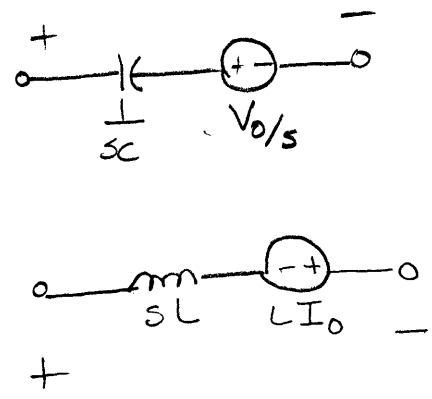
Impulsive driving sources



$$I = \frac{V_0}{R + sL} = \frac{V_0/L}{s + R/L}$$

inverse transforming $i(t) = \frac{V_0}{L} e^{-\frac{R}{L}t} u(t).$

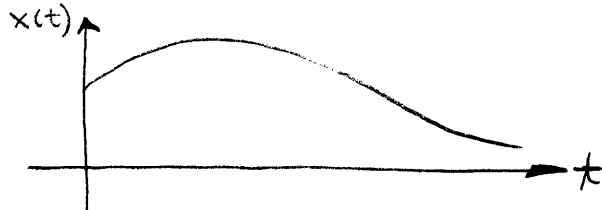
You must watch out for initial conditions on inductors and capacitors



17.4 The transfer function and the convolution integral

Assumptions: linear
time-invariant

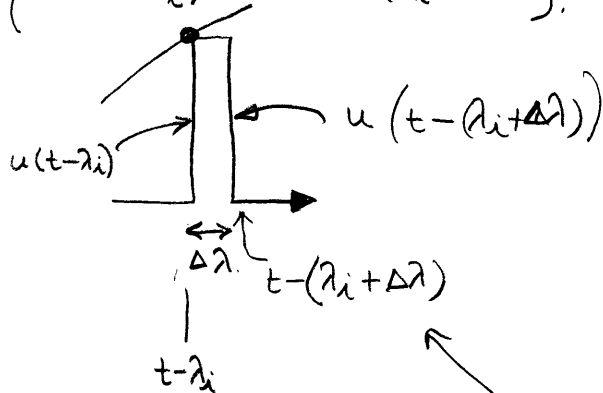
will use superposition



approximate $x(t)$ as a series of rectangular pulses of uniform width $\Delta\lambda$



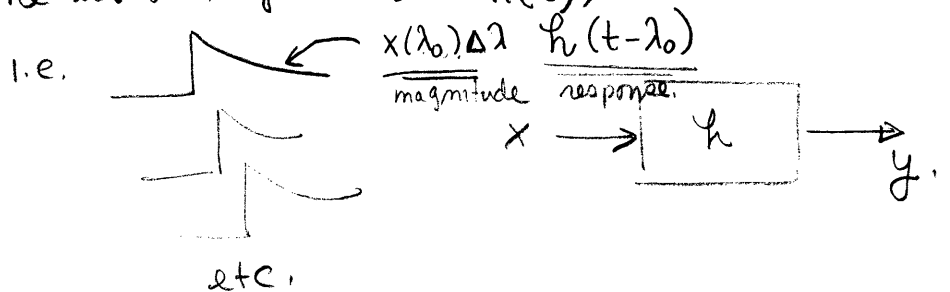
$$x_i(t) = x(\lambda_i) \left\{ u(t-\lambda_i) - u(t-(\lambda_i+\Delta\lambda)) \right\}$$



what happens as $\Delta\lambda \rightarrow 0$. and we write as an impulse of area $f(t-\lambda)\Delta\lambda$

i.e. $x(t) = x(\lambda_0)\Delta\lambda\delta(t-\lambda_0) + x(\lambda_1)\Delta\lambda\delta(t-\lambda_1) + \dots$

response of each one for a system is $h(t)$.



using linearity and superposition

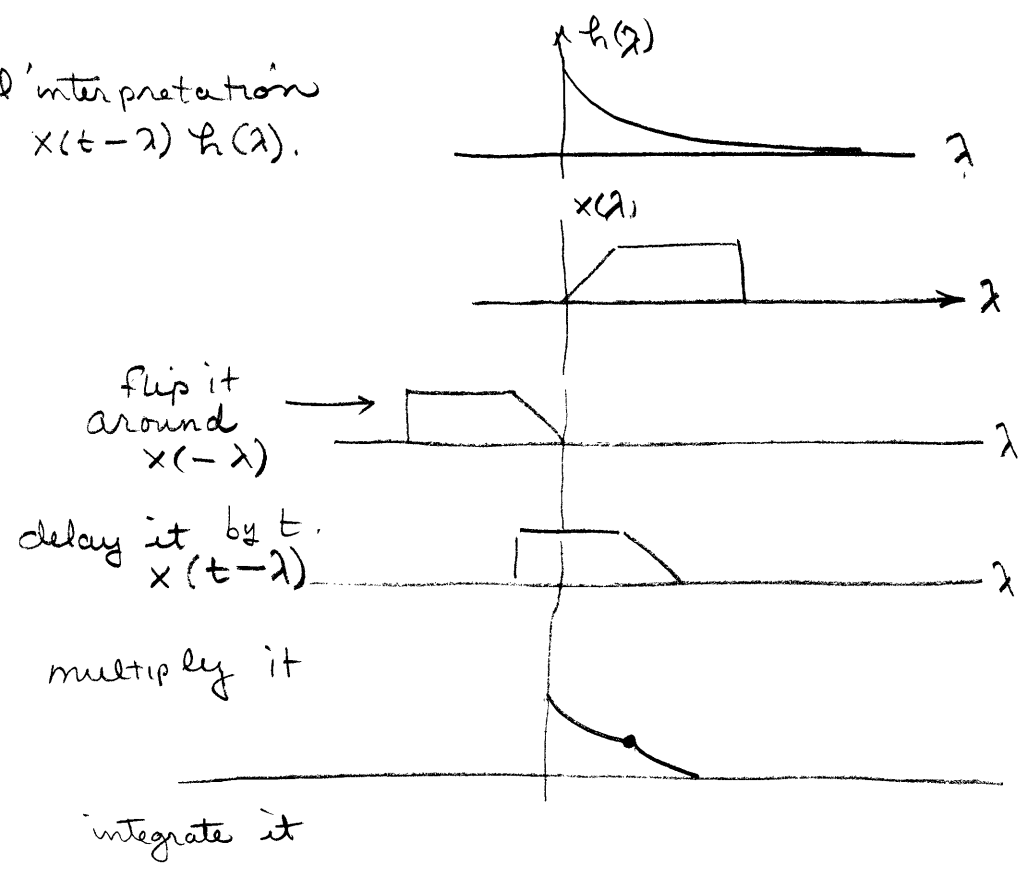
$$y(t) = \sum_{i=0}^{\infty} x(\lambda_i)\Delta\lambda h(t-\lambda_i) \rightarrow \int_0^{\infty} x(\lambda)h(t-\lambda) d\lambda$$

This is the convolution integral

$$y(t) = \int_0^{\infty} x(\lambda) h(t-\lambda) d\lambda = \int_0^{\infty} x(t-\lambda) h(\lambda) d\lambda$$

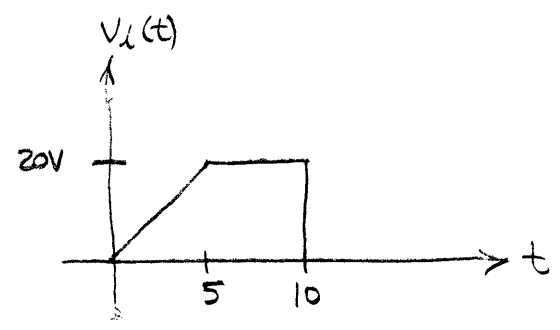
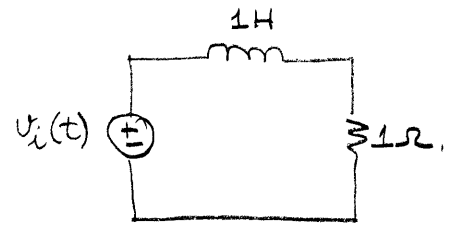
$$= x(t) * h(t).$$

graphical interpretation of $x(t-\lambda) h(\lambda)$.

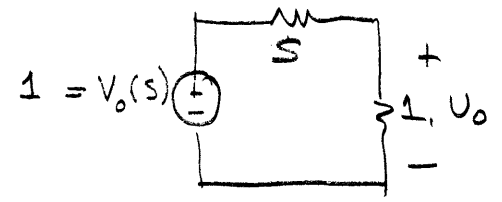


Example 17.3

use convolution to find $v_o(t)$



in the s-domain

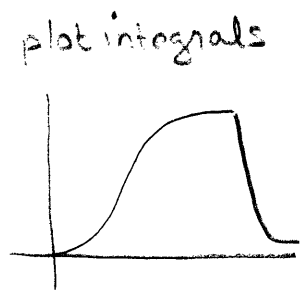
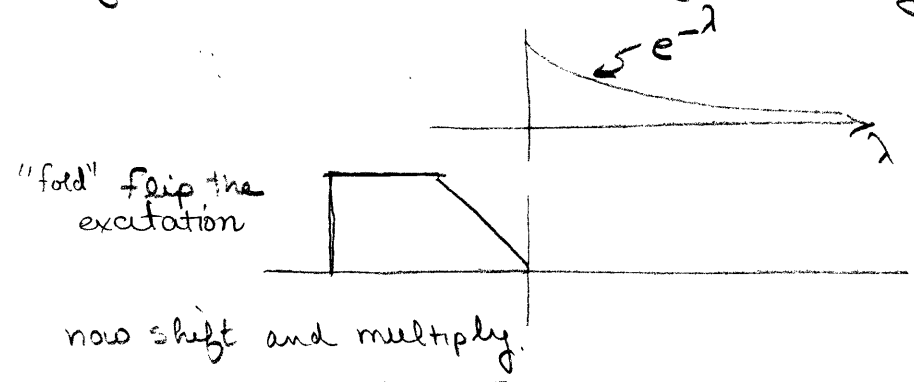


What is unit impulse response? Let source = $\delta(t)$, then $V(s) = 1$.

$$V_o(s) = \underbrace{\frac{1}{s+1}}_{i(s)} \cdot \underbrace{1}_{1\Omega} = \frac{1}{s+1}$$

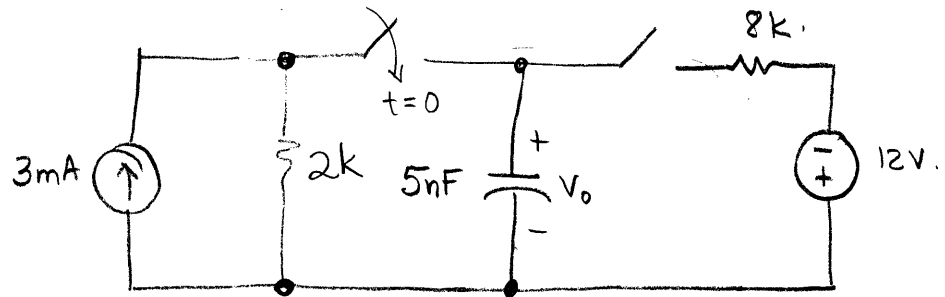
The impulse response is then $\mathcal{L}^{-1}\left\{\frac{1}{s+1}\right\} = e^{-t} u(t)$.

Let's try to figure out the response graphically

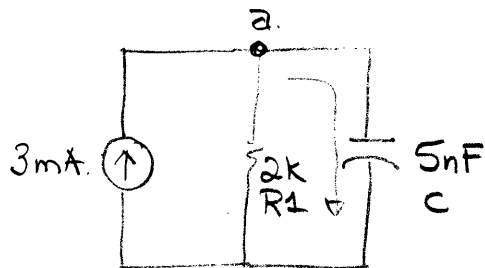


Some transient problems.

8.58



at $t=0$.



$$i = C \frac{dv}{dt}$$

KCL @ a.

$$+3\text{mA} - \frac{V_c}{\underbrace{2\text{k}}_{R_1}} - C \frac{dV_c}{dt} = 0.$$

$$C \frac{dV_c}{dt} + \frac{V_c}{R_1} = 3\text{mA}.$$

$$\frac{dV_c}{dt} + \frac{V_c}{R_1 C} = \frac{3\text{mA}}{C}.$$

Steady state:

$$V_c = (3\text{mA})(R_1) = (3\text{mA})(2\text{k}) = 10\text{V}$$

transient:

$$R_1 C = (2 \times 10^3)(5 \times 10^{-9}) \\ = 10 \times 10^{-6}$$

$$\frac{dV_c}{dt} + \frac{V_c}{10 \times 10^{-6}} = 0.$$

$$\text{let } V_c = A e^{st}.$$

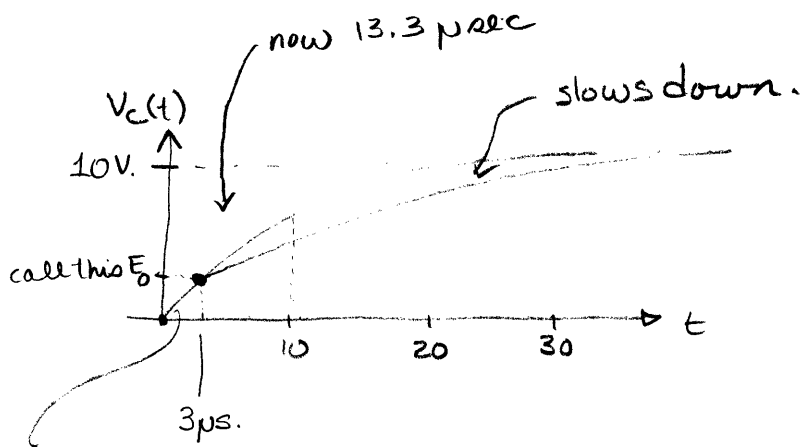
$$A s e^{st} + \frac{A e^{st}}{10 \times 10^{-6}} = 0.$$

$$s = -\frac{1}{10 \times 10^{-6}}.$$

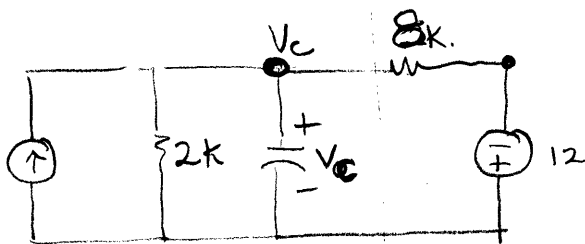
$$V_c(t) = A e^{-\frac{t}{10 \times 10^{-6}}} + 10\text{V}.$$

at $t=0$ $V_c(0) = 0$

$A = -10$ $V_c(t) = 10e^{-\frac{t}{10 \times 10^{-6}}} + 10$ volts.



was 10µsec



$$R_2 C = (8 \times 10^3)(5 \times 10^{-9}) = 40 \times 10^{-6}$$

still KCL but V_0 has an initial condition E_0 .

$$+3mA - \frac{V_c}{R_1} - C \frac{dV_c}{dt} + \frac{V_c - (-12)}{R_2} = 0$$

$$3mA - \frac{V_c}{R_1} - C \frac{dV_c}{dt} + \frac{V_c}{R_2} + \frac{12}{R_2} = 0 \quad \frac{12V}{8K}$$

$$3mA + \frac{12}{R_2} = C \frac{dV_c}{dt} + V_c \left(\frac{1}{R_1} - \frac{1}{R_2} \right)$$

$$\frac{dV_c}{dt} + V_c \left(\frac{1}{R_1 C} - \frac{1}{R_2 C} \right) = \frac{3mA + \frac{12}{R_2}}{5nF} = \frac{3mA + 1.5mA}{5nF}$$

$$\frac{dV_c}{dt} + V_c \left(\frac{1}{10} - \frac{1}{40} \right) \frac{1}{10^{-6}} = 0.9 \times 10^6$$

dc Final value

$$V_c = \frac{0.9 \times 10^6}{\frac{1}{10} - \frac{1}{40} \times 10^6}$$

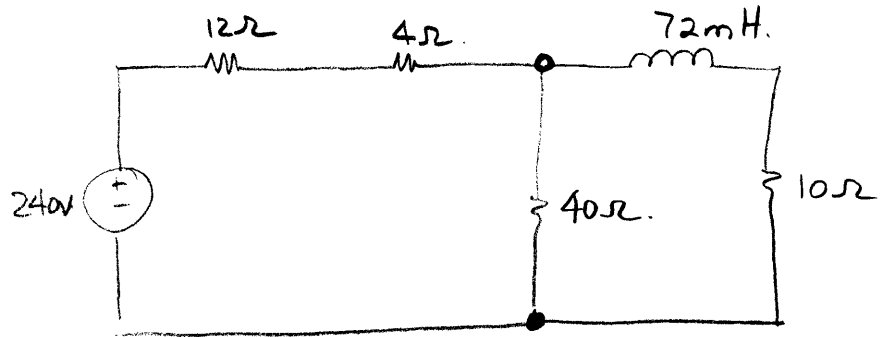
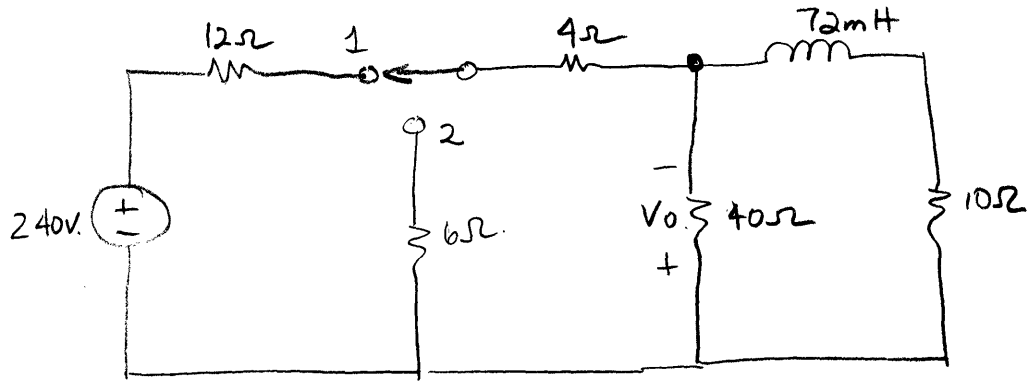
$$= \frac{0.9}{0.1 - 0.025} = \frac{0.9}{0.075} = 12 \text{ volts}$$

$$\frac{4.5 \times 10^{-3} \frac{10^9}{10^9}}{5 \times 10^9 \frac{10^9}{10^9}}$$

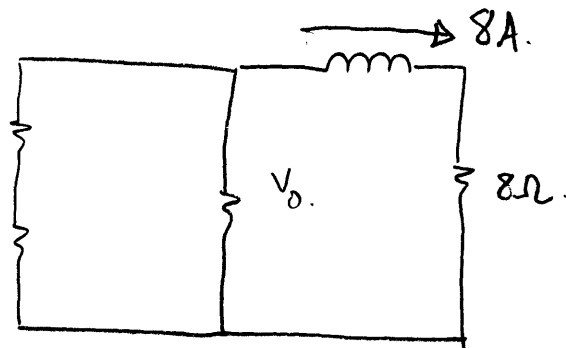
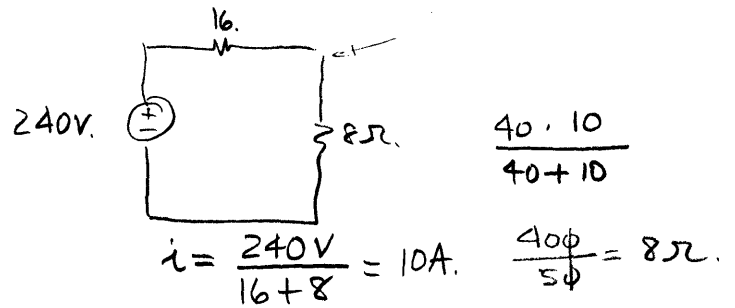
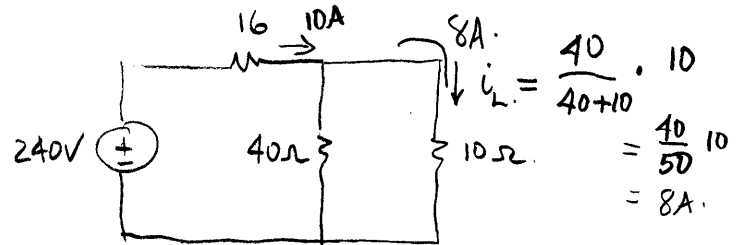
$$\frac{4.5}{5} \times 10^6$$

8.6.

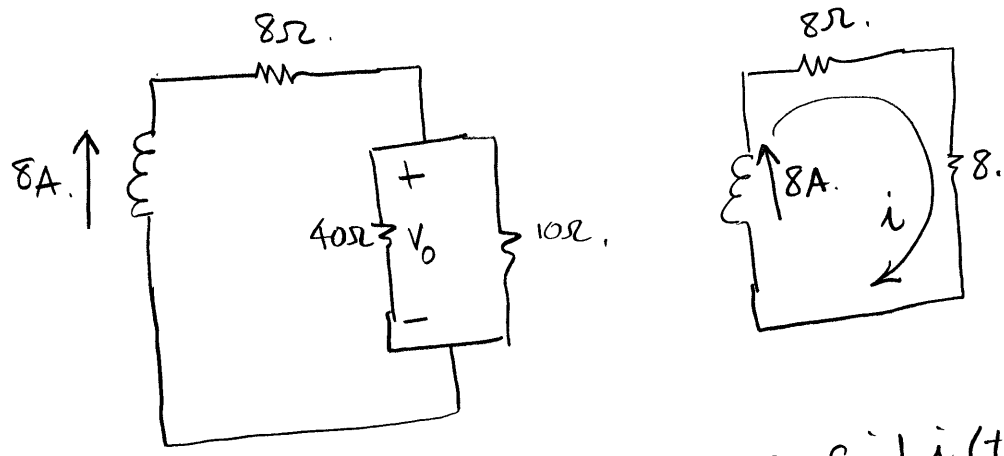
13.



do the simple way.



$$\frac{40 \cdot 10}{40 + 10} = 8$$



to get $V_0(t)$ find $i(t)$.

do KVL

$$L \frac{di}{dt} + iR_1 + iR_2 = 0.$$

$$L \frac{di}{dt} + i 8\Omega = 0.$$

$$\frac{di}{dt} + i \frac{8\Omega}{L} = 0.$$

$$\frac{di}{dt} + i \frac{1}{4R} = 0.$$

$$\frac{L}{R} = \frac{72 \times 10^{-3}}{16} = 4.5 \text{ mS.}$$

$$\frac{di}{dt} + \frac{i}{4.5 \text{ msec.}} = 0.$$

looks like st.

$$Ae^{st}$$

$$sAe^{st} + \frac{Ae^{st}}{4.5 \text{ msec.}} = 0$$

$$s = -\frac{1}{4.5 \text{ msec}}$$

$$i(t) = Ae^{-\frac{t}{4.5 \text{ msec.}}} \quad A = 8.$$

$$i(t) = 8e^{-\frac{t}{4.5 \text{ m.}}}$$

$$V_0(t) = 8i(t) = 64e^{-t/4.5 \text{ m.}}$$

Quiz #1 review

Natural Response of R-LC circuits (pp 347-350)

SERIES

$$Ri + L \frac{di}{dt} + \frac{1}{C} \int i dt = V(t) \quad (\text{no initial charge on } C)$$

let's take the L-transform of this equation

$$I(s) [R + Ls + \frac{1}{Cs}] = \frac{V_0(s)}{s/L}$$

$$I(s) = \frac{V_0(s)}{s^2 + \frac{R}{L}s + \frac{1}{LC}}$$

We set $V_0(s) = \delta$, ^{impulse} then

if $s^2 + \frac{R}{L}s + \frac{1}{LC} = 0$ we can have a response even without a source. ^{after impulse is gone} This

is called the characteristic equation for this circuit.

$$s = -\frac{R}{2L} \pm j \sqrt{\frac{1}{LC} - \left(\frac{R}{2L}\right)^2}$$

where I've written this assuming $\frac{1}{LC} > \left(\frac{R}{2L}\right)^2$

Then ^{with}

we can also use the form

$$\mathcal{L}^{-1} \left\{ \frac{s + \alpha}{(s + \alpha)^2 + \beta^2} \right\} = e^{-\alpha t} \cos \beta t$$

$$I(s) = \frac{s/L}{s^2 + (R/L)s + 1/LC} = \frac{\frac{1}{L}(s + \alpha)}{s^2 + 2\alpha s + \alpha^2 + \beta^2} - \frac{\frac{1}{L}\alpha}{(\alpha + \alpha)^2 + \beta^2}$$

where $\alpha = \frac{R}{2L}$, $\beta^2 = \frac{1}{LC} - \left(\frac{R}{2L}\right)^2$

$$i(t) = \frac{1}{L} \left[e^{-\alpha t} \cos \beta t - \frac{\alpha}{\beta} e^{-\alpha t} \sin \beta t \right] \quad t \geq 0$$

impulse response of series RLC circuit.

inverse xform example

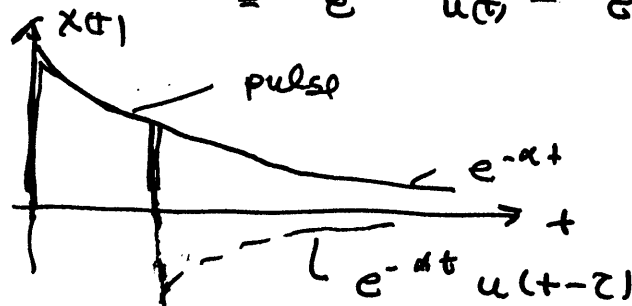
$$X(s) = \frac{1 - e^{-(\alpha+1)T}}{s+\alpha} = \frac{1}{s+\alpha} - \frac{e^{-\alpha T}}{s+\alpha} e^{-sT}$$

Recall the xform pair

$$y(t-T) \Leftrightarrow Y(s) e^{-sT}$$

$$\text{hence } x(t) = e^{-\alpha t} u(t) - e^{-\alpha T} e^{-\alpha(t-T)} u(t-T)$$

$$= e^{-\alpha t} u(t) - e^{-\alpha t} u(t-T)$$



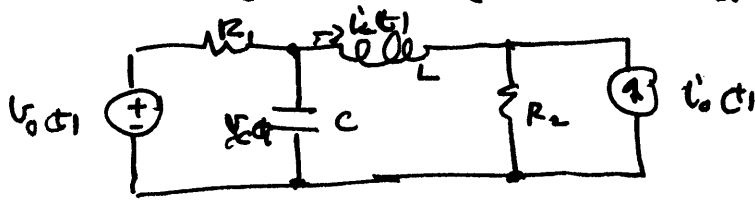
what is the region of convergence?

since $x(s)$ has no poles, it is the entire s -plane - this is a result of the fact that $\int_0^{\infty} x(t) e^{-st} dt$ is finite for any s since $x(t)$ exists only over a finite range.

The s -domain response of LTI circuits have a simple structure. The structure like $\frac{1}{s+\alpha}$ is called a single-order pole at $s = -\alpha$.

Understanding the nature of this structure in more detail will help you to design complex systems - such as control systems, sensors and actuators.

let's look at a two-source circuit



$$v_0(t) = 3 \quad t > 0$$

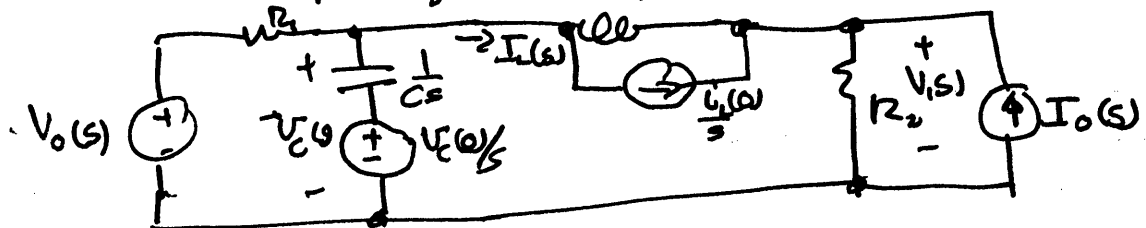
$$i_0(t) = 4e^{-t} \quad t > 0$$

$$v_C(0) = -1$$

$$i_L(0) = 2$$

$$R_1 = 0.5, \quad R_2 = 1, \quad L = 1 \text{ H}, \quad C = 0.5 \text{ F}$$

in the frequency domain



$$V_1(s) = \frac{R_2 (s^2 + s \frac{1}{R_1 C} + \frac{1}{L C})}{s^2 + s (\frac{1}{R_1 C} + \frac{R_2}{L}) + \frac{1}{L C} (1 + \frac{R_2}{R_1})} I_0(s)$$

$$+ \frac{\frac{R_2}{R_1} + \frac{1}{L C}}{s^2 + s (\frac{1}{R_1 C} + \frac{R_2}{L}) + \frac{1}{L C} (1 + \frac{R_2}{R_1})} V_0(s)$$

$$+ \frac{s \frac{R_2}{L}}{s^2 + s (\frac{1}{R_1 C} + \frac{R_2}{L}) + \frac{1}{L C} (1 + \frac{R_2}{R_1})} \cdot \frac{v_C(0)/s}{s}$$

$$+ \frac{s^2 R_2 + s \frac{R_2}{R_1} C}{s^2 + s (\frac{1}{R_1 C} + \frac{R_2}{L}) + \frac{1}{L C} (1 + \frac{R_2}{R_1})} \frac{i_L(0)/s}{s}$$

We note that each source has the same frequency domain denominator.

We can generalize this result for any LTI system

$$Y(s) = \sum_{m=1}^M H_{om}(s) X_m(s) + \sum_{n=1}^N H_{in}(s) \frac{\lambda_n(0)}{s}$$

where $Y(s)$ is the \mathcal{L} -transform of the ~~output~~ object we
 $X_m(s)$ is the \mathcal{L} -transform of the m^{th} independent source

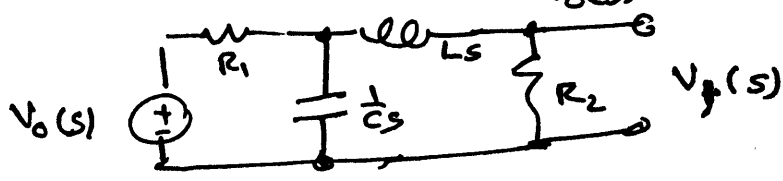
$\frac{\lambda_n(s)}{s}$ is the effect of initial condx.

$H_{em}(s), H_{in}(s)$ give the relationship between sources and/or initial conditions with the output.

The $\sum_{n=1}^N H_{in}(s) \frac{\lambda_n(s)}{s} \Rightarrow$ Zero input response (ZIR)
 Not a function of the sources called natural response.
 $\sum_{m=1}^M H_{em} \lambda_m(s) \Rightarrow$ Zero state response (ZSR)

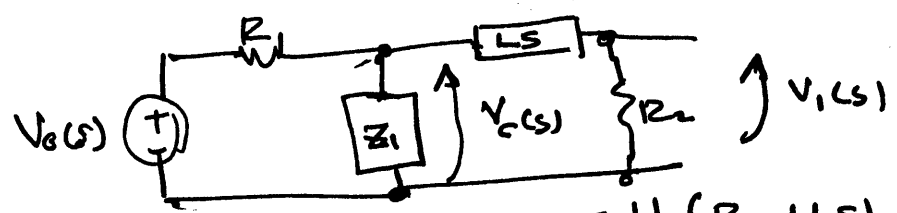
The system function is defined by the s-domain ratio of the desired output to an input.

Note the ZSR for $\frac{V_1(s)}{V_0(s)}$ is derived from



$$V_1(s) = \left(\frac{R_2}{Ls + R_2} \right) \left[\frac{1}{Cs} \frac{(R_2 + Ls)}{\left(\frac{1}{Cs} + R_2 + Ls \right)} \right] V_0(s)$$

$$\left[R_1 + \frac{\frac{1}{Cs} (R_2 + Ls)}{\frac{1}{Cs} + R_2 + Ls} \right]$$



$$V_0(s) = \frac{Z_1 \parallel (R_2 + Ls)}{R_1 + Z_1 \parallel (R_2 + Ls)}$$

$$V_1(s) = \left(\frac{R_2}{R_2 + Ls} \right) V_0(s)$$

$$\frac{V_1(s)}{V_0(s)} = \frac{\frac{R_2}{R_1 C}}{s^2 + s \left(\frac{1}{R_1 C} + \frac{R_2}{L} \right) + \frac{1}{LC} \left(1 + \frac{R_2}{R_1} \right)}$$

← Hem: $\frac{R_2}{R_1 C}$

①

Def 14.8 from last time

$$y(t) = \int_0^t h(\tau) f(t-\tau) d\tau$$

basically the output is the sum of the responses to a continuous stream of impulses which form the input function

(This is 17.22 of text)

$$y(t) = h(t) * f(t)$$

usually more useful in s-domain

$$Y(s) = H(s) F(s)$$

we've actually used this the way we defined $H(s)$,

i.e. $H(s) = \frac{Y(s)}{F(s)}$

Let's prove these are equivalent

$$H(s) = \int_0^\infty h(\tau) e^{-s\tau} d\tau = \mathcal{L}[h(t)]$$

multiplying both sides by $F(s)$.

$$H(s) F(s) = \int_0^\infty h(\tau) e^{-s\tau} F(s) d\tau$$

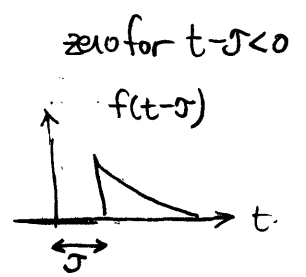
Remember that

$$\mathcal{L}[f(t-\tau)] = e^{-s\tau} F(s)$$

substituting

$$H(s) F(s) = \int_0^\infty h(\tau) \mathcal{L}[f(t-\tau)] d\tau = \int_0^\infty h(\tau) \left[\int_0^\infty f(t-\tau) e^{-st} dt \right] d\tau$$

delayed by τ .



Now reverse order of integration

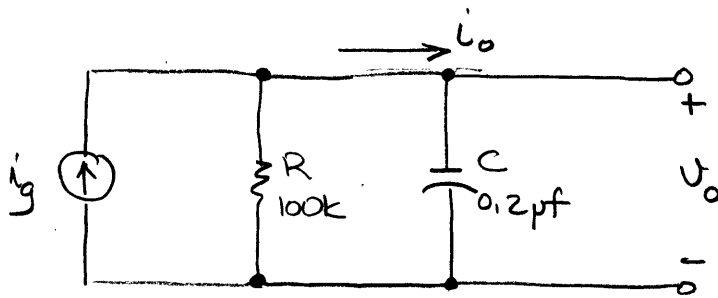
$$= \int_0^\infty e^{-st} \left[\int_0^t h(\tau) f(t-\tau) d\tau \right] dt$$

zero for $t-\tau < 0$ or $\tau > t$

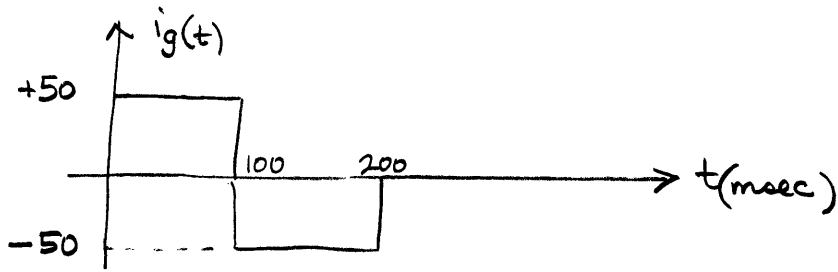
$$= \mathcal{L} \left[\int_0^t h(\tau) f(t-\tau) d\tau \right]$$

Problem 17-19

13



find V_o if i_g is as given



[a] Analyzing the circuit.

$$I_g(s) = \frac{V_o}{R} + \frac{V_o}{\frac{1}{sC}} = \frac{V_o}{10^5} + \frac{V_o s}{\frac{1}{.2 \times 10^{-6}}} = \frac{V_o}{10^5} + \frac{V_o s}{50 \times 10^5}$$

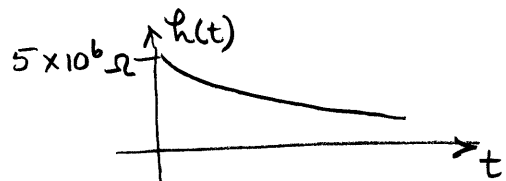
$$I_g(s) = \frac{V_o}{10^5} \left(1 + \frac{s}{50} \right) = \frac{V_o}{5 \times 10^6} (50 + s)$$

Solving for the transfer function

output \rightarrow $H(s) = \frac{V_o}{I_g} = \frac{5 \times 10^6}{s + 50} \Omega$.

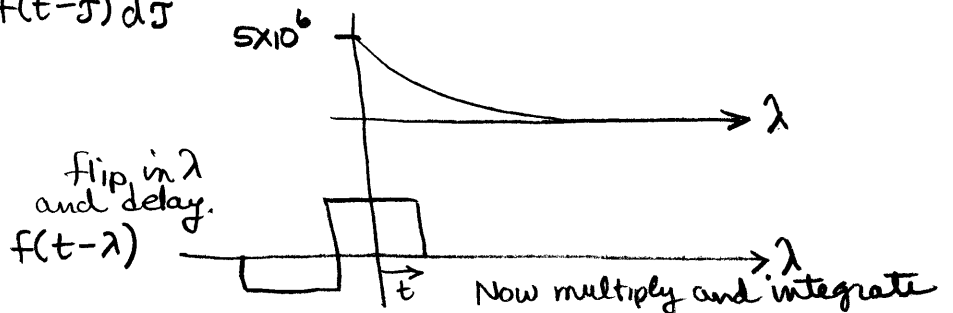
Inverse transforming

$$h(t) = 5 \times 10^6 e^{-50t} u(t)$$



Let's do solution graphically.

$$v_o = \int_0^t h(\sigma) f(t-\sigma) d\sigma$$



graphically you can see there are three regions of the answer.

$$0 \leq t \leq 0.1 \text{ s.}$$

$$0.1 \leq t \leq 0.2 \text{ s.}$$

$$0.2 \leq t \leq \infty$$

These answers are

$$0 \leq t \leq 0.1 \text{ s} \quad v_o = 5(1 - e^{-50t}) u(t)$$

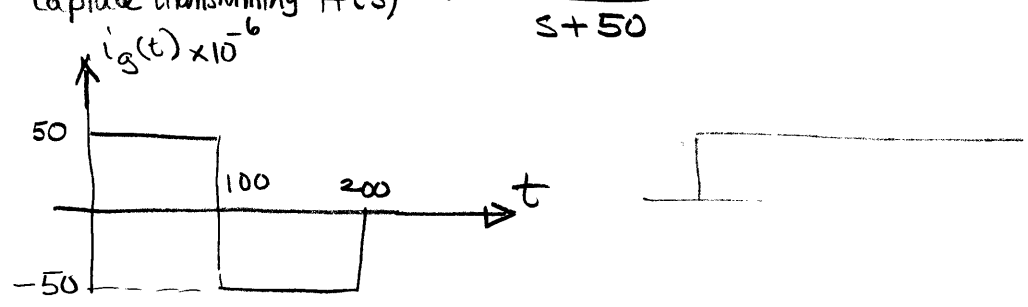
$$0.1 \leq t \leq 0.2 \text{ s} \quad v_o = [10e^{-50(t-0.1)} - 5e^{-50t} - 5] u(t)$$

$$0.2 \leq t \leq \infty \quad v_o = [10e^{-50(t-0.1)} - 5e^{-50(t-0.2)} - 5e^{-50t}] u(t)$$

Let's do this neatly using convolution in s-domain.

We already know $h(\lambda) = 5 \times 10^6 e^{-50\lambda} u(\lambda)$

Laplace transforming $H(s) = \frac{5 \times 10^6}{s+50}$



$$i_g(t) = [50 u(t) - 100 u(t-0.1) + 50 u(t-0.2)] \mu\text{A.}$$

the Laplace transform of $i_g(t)$ $I_g(s) = 50 \frac{1}{s} - 100 \frac{1}{s} e^{-0.1s} + 50 \frac{1}{s} e^{-0.2s}.$

the response of the circuit is $V(s) = H(s) I_g(s) = \left[\frac{250 \times 10^6}{s(s+50)} - \frac{500 \times 10^6 e^{-0.1s}}{s(s+50)} + \frac{250 \times 10^6 e^{-0.2s}}{s(s+50)} \right]_{10}$

inverse transforming

$$\frac{1}{s(s+50)} = \frac{a}{s} + \frac{b}{s+50} = \frac{as + 50a + bs}{s(s+50)}$$

$$\begin{aligned} \therefore 50a &= 1 & a &= \frac{1}{50} = .02 \\ a+b &= 0 & b &= -.02. \end{aligned}$$

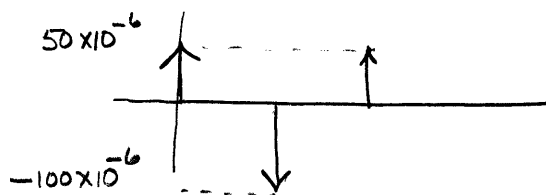
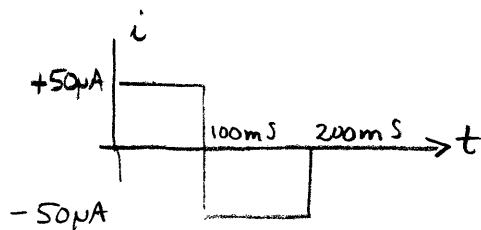
$$V(s) = \left\{ 250 \times 10^6 \frac{1}{50} \left[\frac{1}{s} - \frac{1}{s+50} \right] - 500 \times 10^6 \frac{e^{-0.1s}}{50} \left[\frac{1}{s} - \frac{1}{s+50} \right] + 250 \times 10^6 \frac{e^{-0.2s}}{50} \left[\frac{1}{s} - \frac{1}{s+50} \right] \right\} 10^{-6}$$

$$V(s) = 5 \left[\frac{1}{s} - \frac{1}{s+50} \right] - 10 \left[\frac{1}{s} - \frac{1}{s+50} \right] e^{-0.1s} + 5 \left[\frac{1}{s} - \frac{1}{s+50} \right] e^{-0.2s}$$

$$v(t) = \frac{5u(t) - 5e^{-50t}u(t) - 10u(t-0.1) + 10e^{-50(t-0.1)}u(t-0.1) + 5u(t-0.2) - 5e^{-50(t-0.2)}u(t-0.2)}{\quad}$$

Let's try it the other way.

What's the derivative of $i_g(t)$?



What is the system response to this function?

$$\text{if } h(\lambda) = 5 \times 10^6 e^{-50\lambda} u(\lambda).$$

$$\begin{aligned} \text{Then } o(t) &= (50 \times 10^{-6}) (5 \times 10^6 e^{-50t} u(t)) \\ &+ (-100 \times 10^{-6}) (5 \times 10^6 e^{-50(t-0.1)} u(t-0.1)) \\ &+ (50 \times 10^{-6}) (5 \times 10^6 e^{-50(t-0.2)} u(t-0.2)). \end{aligned}$$

$$o(t) = 250 e^{-50t} u(t) - 500 e^{-50(t-0.1)} u(t-0.1) + 250 e^{-50(t-0.2)} u(t-0.2).$$

The integral of this is the actual system response

$$\begin{aligned} \int_0^t 250 e^{-50\lambda} u(\lambda) d\lambda &= 250 \frac{e^{-50\lambda}}{-50} \Big|_0^t = -5e^{-50\lambda} \Big|_0^t \\ &= -5e^{-50t} + 5 \end{aligned}$$

$$-\int_0^t 500 e^{-50(\lambda-0.1)} u(\lambda-0.1) d\lambda = -\int_{-0.1}^{t-0.1} 500 e^{-50\gamma} u(\gamma) d\gamma.$$

$$\begin{aligned} &= -\int_0^{t-0.1} 500 e^{-50\gamma} u(\gamma) d\gamma = -500 \frac{e^{-50\gamma}}{-50} \Big|_0^{t-0.1} = 10 e^{-50\gamma} \Big|_0^{t-0.1} \\ &= 10 e^{-50(t-0.1)} - 10 \end{aligned}$$

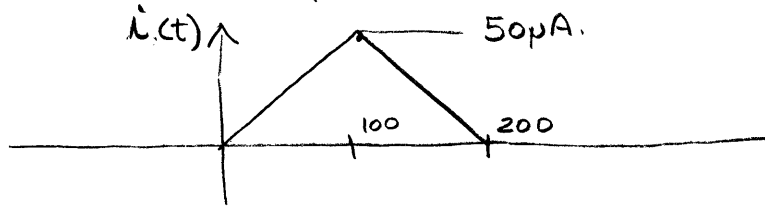
$$\int_0^t 250 e^{-50(\lambda-0.2)} u(\lambda-0.2) d\lambda = \int_{-0.2}^{t-0.2} 250 e^{-50\gamma} u(\gamma) d\gamma$$

$\gamma = \lambda - 0.2$

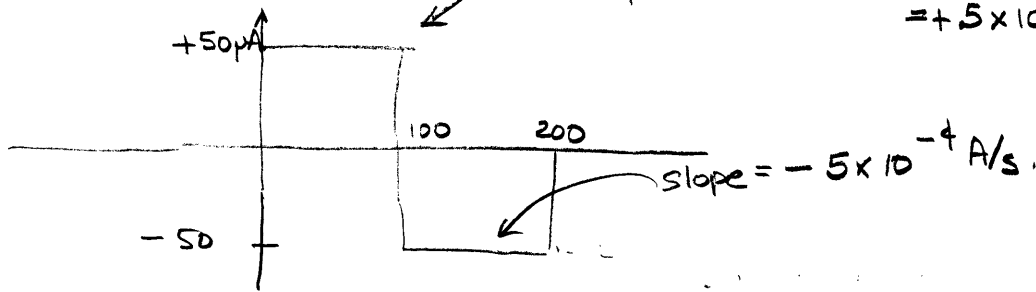
$$= 250 \frac{e^{-50\gamma}}{-50} \Big|_0^{t-0.2} = -5 e^{-(t-0.2)} + 5$$

$$\int v(t) dt = (5 - 5e^{-50t})u(t) + (10e^{-50(t-0.1)} - 10)u(t-0.1) \\ + (5 - 5e^{-(t-0.2)})u(t-0.2) \quad \blacksquare$$

How about the response to .



its derivative is $i'(t)$



The response to $\pm 50 \times 10^{-6}$ of the same time in a rectangular pulse is then

$$v(t) = 5 u(t) - 5 e^{-50t} u(t) - 10 u(t-0.1) + 10 e^{-50(t-0.1)} u(t-0.1) + 5 u(t-0.2) - 5 e^{-50(t-0.2)} u(t-0.2).$$

Since systems are linear

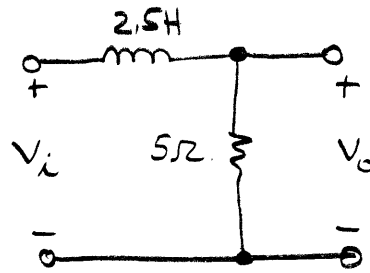
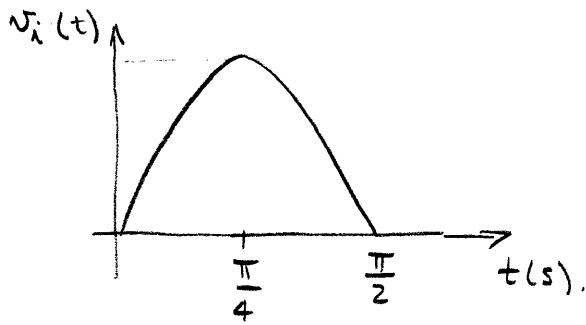
$$\text{if } i_r'(t) \rightarrow v(t)$$

$$i(t) = \int i_r'(\tau) d\tau \rightarrow \int v(t).$$

response to integral is integral of response.

$$\begin{aligned} & \int_0^t [5 - 5e^{-50\lambda}] u(\lambda) d\lambda \\ &= 5\lambda \Big|_0^t - \frac{5e^{-50\lambda}}{-50} \Big|_0^t = 5t + 0.1e^{-50\lambda} \Big|_0^t \\ &= [5t + 0.1e^{-50t} - 0.1] u(t). \end{aligned}$$

Problem 17.17.



the transfer function

$$H(s) = \frac{V_o}{V_i} = \frac{5}{5+2.5s} = \frac{2}{s+2}$$

inverse transforming

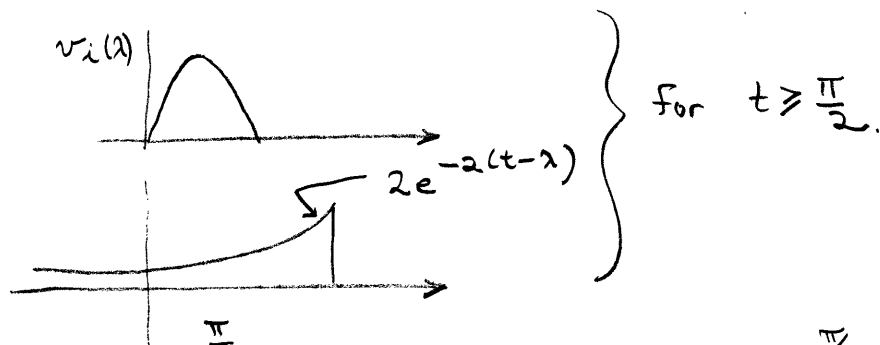
$$h(\lambda) = 2e^{-2\lambda}$$

period: $\frac{T}{2} = \frac{\pi}{2} \quad \therefore T = \pi \quad \text{or } f = \frac{1}{\pi}$

$$\omega = 2\pi f = 2\pi \frac{1}{\pi} = 2$$

$$v_i(\lambda) = 20 \sin 2\lambda \left[u(\lambda) - u\left(\lambda - \frac{\pi}{2}\right) \right]$$

This you just have to grind out:



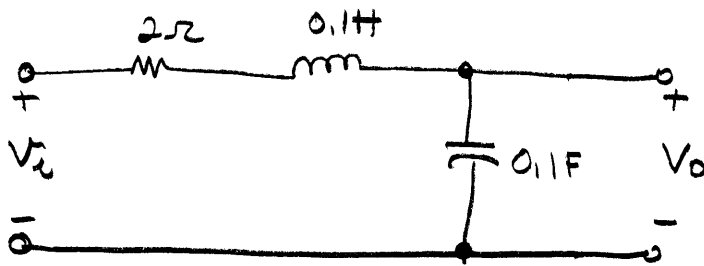
$$v_o = \int v_i(\lambda) h(t-\lambda) d\lambda = \int_0^{\pi/2} \underbrace{2e^{-2t+2\lambda}}_{h(t-\lambda)} \underbrace{20 \sin 2\lambda}_{v_i(\lambda)} d\lambda = 40e^{-2t} \int_0^{\pi/2} e^{2\lambda} \sin 2\lambda d\lambda$$

$$= 40e^{-2t} \left[\frac{e^{2\lambda}}{8} (2 \sin 2\lambda - 2 \cos 2\lambda) \right]_0^{\pi/2} = 10e^{-2t} \left[e^{\pi} (\overset{1}{\sin \pi} - \overset{-1}{\cos \pi}) - e^0 (\overset{1}{\sin 0} - \overset{1}{\cos 0}) \right]$$

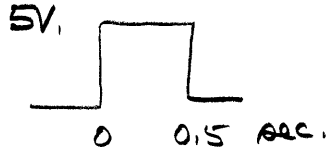
$$= 10e^{-2t} [-e^{\pi} + 1]$$

at $t = 2.2 \text{ sec}$. $v_o(2.2 \text{ sec}) = 10e^{-2(2.2)} [1 - e^{\pi}] \approx 2.96 \text{ V}$

17.15



$$v_i(t) = 5[u(t) - u(t-0.5)]$$



$$H(s) = \frac{\frac{1}{sC}}{R + sL + \frac{1}{sC}} = \frac{\frac{1}{C}}{sR + s^2L + \frac{1}{C}} = \frac{\frac{1}{C}}{s^2L + Rs + \frac{1}{C}} = \frac{\frac{1}{LC}}{s^2 + \frac{R}{L}s + \frac{1}{LC}}$$

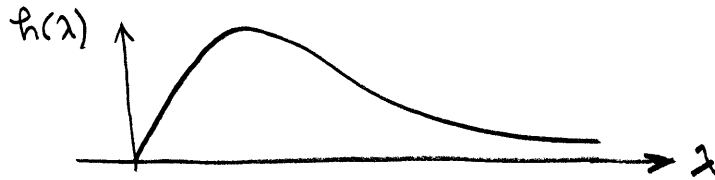
$$\frac{1}{LC} = \frac{1}{(0.1)(0.1)} = 100$$

$$\frac{R}{L} = \frac{2}{0.1} = 20$$

$$H(s) = \frac{100}{s^2 + 20s + 100} = \frac{100}{(s+10)^2}$$

$$te^{-at} \leftrightarrow \frac{1}{(s+a)^2}$$

$$h(\lambda) = 100\lambda e^{-10\lambda} u(\lambda)$$



② do graphically $v_i(t) \leftrightarrow \frac{5}{s} - \frac{5}{s} e^{-0.5s} = \frac{5}{s} (1 - e^{-0.5s})$

$$V_o(s) = H(s)V_i(s) = \frac{5}{s} (1 - e^{-0.5s}) \left(\frac{100}{(s+10)^2} \right) = 500 \frac{1}{s(s+10)^2} (1 - e^{-0.5s})$$

$$\frac{1}{s(s+10)^2} = \frac{a}{s} + \frac{b}{(s+10)^2} = \frac{a(s+10)^2 + bs}{s(s+10)^2}$$

$$a(s^2 + 20s + 100) + bs = 1$$

$$as^2 = 0$$

$$20as + bs = 0$$

$$100a = 1$$

$$\frac{1}{s(s+10)^2} = \frac{a}{s} + \frac{bs}{(s+10)^2} = \frac{a(s+10)^2 + bs^2}{s(s+10)^2}$$

$$a(s^2 + 20s + 100) + bs^2 = 1$$

$$as^2 + bs^2 = 0$$

$$20as = 0$$

$$\frac{1}{s(s+10)^2} = \frac{a}{s} + \frac{b}{s+10} + \frac{c}{(s+10)^2}$$

$$= \frac{a(s+10)^2 + bs(s+10) + cs}{s(s+10)^2}$$

$$a(s^2 + 20s + 100) + b(s^2 + 10s) + cs$$

$$s^2: a + b = 0$$

$$s^1: 20a + 10b + c = 0$$

$$s^0: 100a = 1$$

$$a = \frac{1}{100}$$

$$b = -\frac{1}{100}$$

$$20\left(\frac{1}{100}\right) + 10\left(-\frac{1}{100}\right) + c = 0$$

$$10\left(\frac{1}{5} - \frac{1}{10} + c = 0\right)$$

$$2 - 1 + 10c = 0$$

$$10c = -1$$

$$c = -\frac{1}{10}$$

$$V_o(s) = \frac{.01}{s} - \frac{.01}{s+10} - \frac{0.1}{(s+10)^2}$$

$$V_o(t) = .01 u(t) - .01 e^{-10t} u(t) - 0.1 t e^{-10t} u(t),$$

ANNOUNCEMENTS

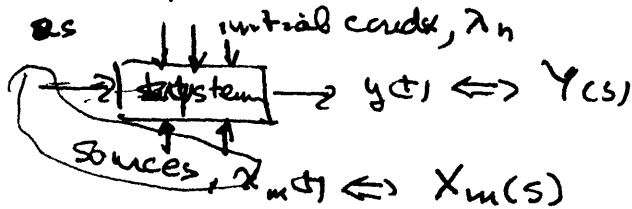
Quiz Average = 63 median = 65
 Quiz makeup draw poker - 2 problems to replace 2 pro
 must turn in old exo for this

When? Wed pm 9 pm
 one lab makeup permitted.

Correct in equation on bottom ps: Labs: $\Omega_{SS} = R_L (1 + \frac{R_2 B}{k^2})$

SYSTEM FUNCTIONS

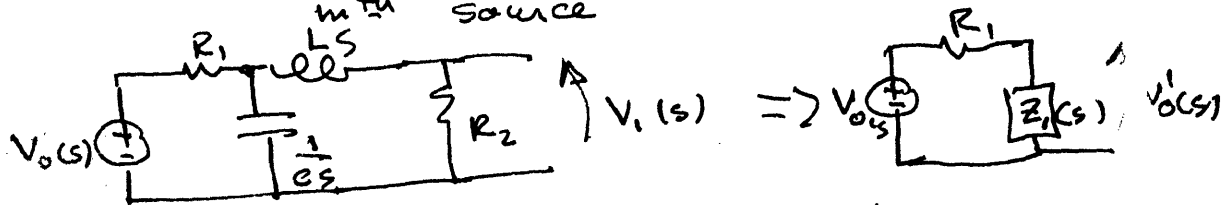
We saw that we are able to write the output of a system in terms of its Laplace transform as



$$Y(s) = \underbrace{\sum_{m=1}^M H_{em}(s) X_m(s)}_{\text{due to inputs called ZSR}} + \sum_{n=1}^N H_{en}(s) \frac{\lambda_n(0)}{s}$$

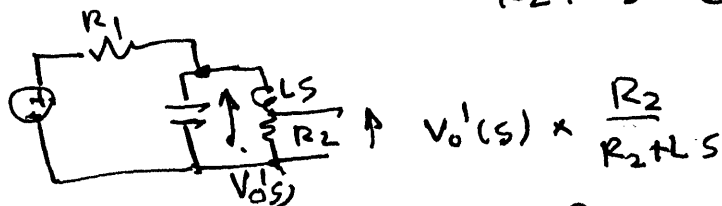
due to initial state of current in inductives or voltage on capacitors called ZIR

$H_{em}(s)$ is the system function for the m^{th} source



$$V_1(s) = V_0 \times \frac{(\frac{1}{cs})(Ls + R_2) / (R_2 + Ls + \frac{1}{cs})}{R_1 + \frac{1}{cs}}$$

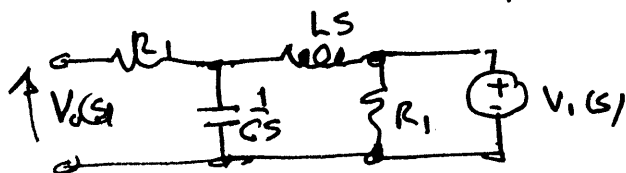
$$Z_1(s) = \frac{\frac{1}{cs} \parallel (R_2 + Ls)}{R_2 + Ls + \frac{1}{cs}}$$



$$H_1(s) = \frac{V_1(s)}{V_0(s)} = \frac{\frac{R_2}{R_1 LC}}{s^2 + s(\frac{1}{R_1 C} + \frac{R_2}{L}) + \frac{1}{LC}(1 + \frac{R_2}{R_1})}$$

dimensional checks

Now let's excite the system from the right

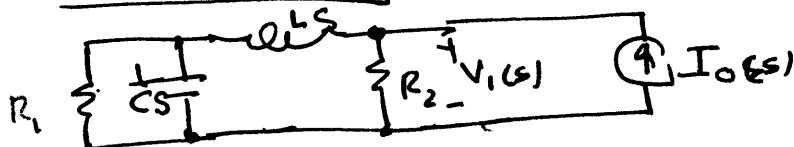


$$V_0(s) = \frac{(\frac{1}{Cs}) V_1(s)}{Ls + \frac{1}{Cs}} = \frac{\frac{1}{Lc}}{s^2 + \frac{1}{Lc}} V_1(s)$$

$$\frac{V_0(s)}{V_1(s)} = H_2(s) = \frac{\frac{1}{Lc}}{s^2 + \frac{1}{Lc}} \quad \text{which is not } H_1(s)$$

So identifying the output & input is absolutely important to obtain the correct system function.

Another example



we wish to find $\frac{V_1(s)}{I_0(s)}$ called the driving point impedance

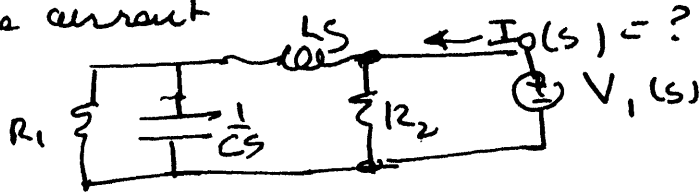
$$V_1(s) = R_2 \parallel \left(Ls + \frac{1}{Cs} \parallel R_1 \right) I_0(s)$$

$$Ls + \left(\frac{R_1/Cs}{R_1 + Cs} \right) = Ls + \frac{1}{s + \frac{1}{R_1}}$$

$$\frac{Ls(s + \frac{1}{R_1c}) + \frac{1}{c}}{s + \frac{1}{R_1c}} = \frac{s^2 + \frac{s}{R_1c} + \frac{1}{Lc}}{\frac{1}{L} (s + \frac{1}{R_1c})}$$

$$H_2(s) = \frac{V_1(s)}{I_0(s)} = \frac{R_2 (s^2 + \frac{s}{R_1c} + \frac{1}{Lc})}{s^2 + s(\frac{1}{R_1c} + \frac{R_2}{L}) + \frac{1}{Lc} (1 + \frac{R_2}{R_1})}$$

Now let's drive the circuit with a voltage & measure the current



$$I_0(s) = \frac{V_1(s)}{R_2} + \frac{V_1(s)}{LS + \frac{R_1/cS}{R_1 + \frac{1}{cS}}}$$

$$= V_1(s) \times \frac{s^2 + s\left(\frac{1}{R_1 c} + \frac{R_2}{L}\right) + \frac{1}{LC}\left(1 + \frac{R_2}{R_1}\right)}{R_2 \left(s^2 + \frac{s}{R_1 c} + \frac{1}{LC}\right)}$$

the driving-point admittance, $H_4(s) = \frac{I_0(s)}{V_1(s)}$

$H_4(s) = \frac{1}{H_3(s)}$ the reciprocal of the driving-point impedance.

You will recall that when we were dealing with the sinusoidal steady state the impedances were $j\omega L$, $\frac{1}{j\omega c}$. The Laplace transform domain has them as LS , $\frac{1}{cS}$ so the only mathematical difference is the replacement of s with $j\omega$.

If the input to an LTI network is a complex exponential $X e^{j\omega t}$ and the steady-state output is $Y e^{j\omega t}$ then

$$\frac{Y}{X} = H(s) \Big|_{s=j\omega} \quad \text{so we can}$$

use the system function to arrive at the response to the s-s-s input because the

assumption is that the ZIR due to starting transients have died out.

we have seen that the ~~transform~~ response to $X(s)$ is

$Y(s) = H(s)X(s)$ in general we found the time response by performing a partial fraction expansion of $Y(s)$ to get it into the form of a known transformed time function

$$Y(s) = \frac{a_n s^n + a_{n-1} s^{n-1} + \dots + a_1 s + a_0}{b_m s^m + b_{m-1} s^{m-1} + \dots + b_1 s + b_0} = \frac{N(s)}{D(s)}$$

a, b are real.

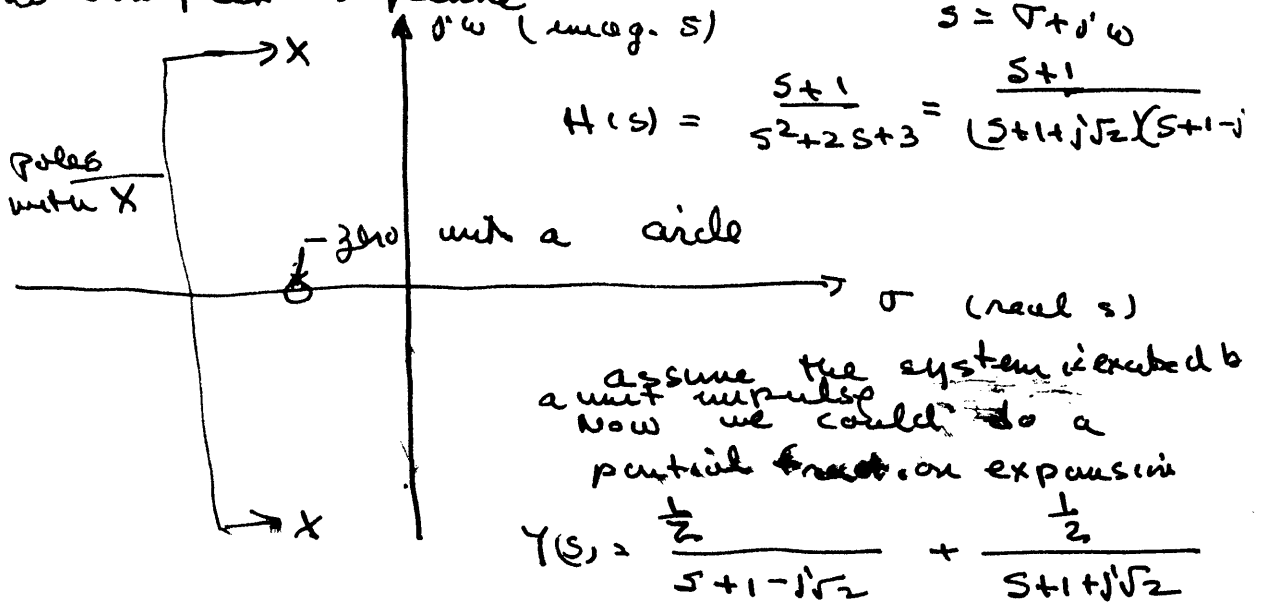
we can always write the $N(s)$ & $D(s)$ in terms of their roots, s_i

$$N(s) = a_n (s - s_{z1})(s - s_{z2})(s - s_{z3}) \dots (s - s_{zn})$$

$$D(s) = b_n (s - s_{p1})(s - s_{p2}) \dots (s - s_{pm})$$

if the root s_{pi} (or s_{zi}) is complex then these must ~~be~~ be a complex conjugate of it to

we can characterize the system function by the locations of its poles and zeroes in the complex s -plane



assume the system is excited by a unit impulse now we could do a partial fraction expansion

$$Y(s) = \frac{1}{2} \frac{1}{s+1-j\sqrt{2}} + \frac{1}{2} \frac{1}{s+1+j\sqrt{2}}$$

$$y(t) = \frac{1}{2} e^{-t} e^{j\sqrt{2}t} + \frac{1}{2} e^{-t} e^{-j\sqrt{2}t}$$

if the pole were in the rhp what happens

Yes, we would have had $e^{+t} \left[\frac{e^{j\sqrt{2}t} + e^{-j\sqrt{2}t}}{2} \right]$
 as a response -
called unstable.



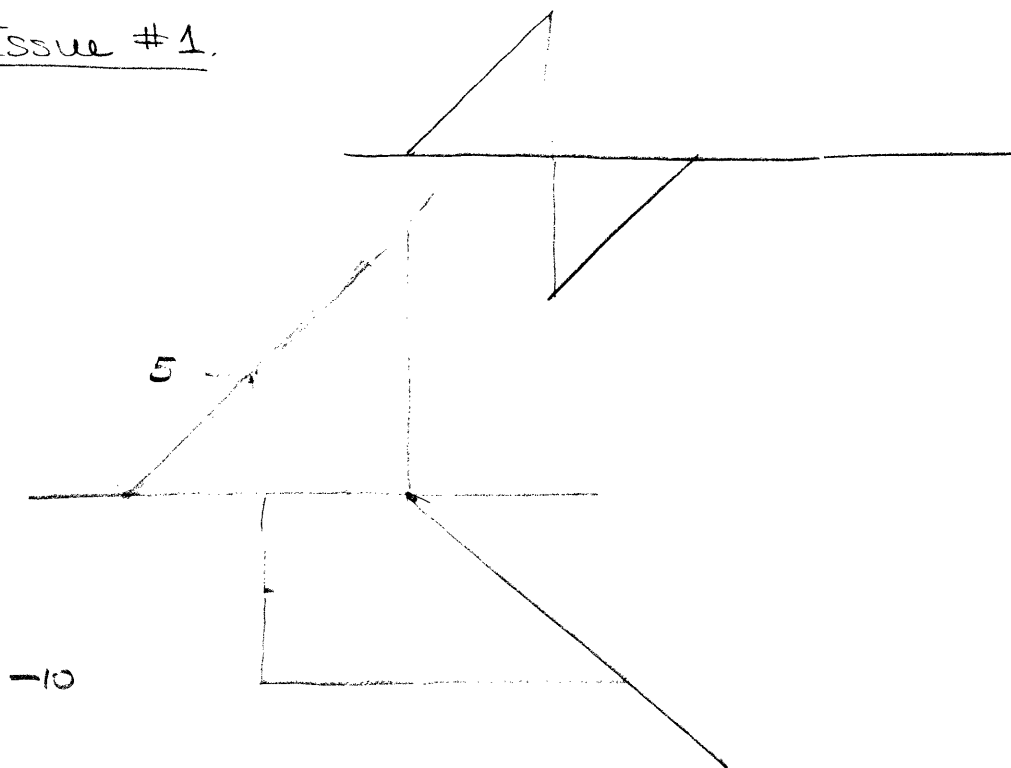
$$(s-1-j\sqrt{2})(s-1+j\sqrt{2})$$

$$D(s) = (s-1)^2 + 2 = s^2 - 2s + 1 + 2 = s^2 - 2s + 3$$

is unstable

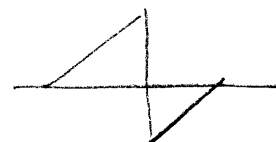
The poles must not lie in the right-half plane
 for the system to be stable!

Issue #1.



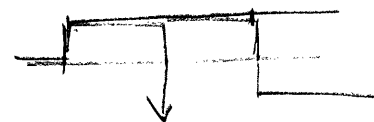
appropriate functional representation

$$5t u(t) - 10u(t-1) - 5t u(t-2)$$



Derivatives.

$$5u(t) - 10\delta(t-1) - 5u(t-2)$$



Integrals not really useful.

Laplace transform techniques

complex frequency s

special cases dc $s=0$

exponential $s=\sigma$

sinusoidal $s=j\omega$

exponential sinusoid $s=\sigma+j\omega$

we defined the one-sided Laplace transform

$$v(t) \leftrightarrow V(s) \quad V(s) = \int_0^{\infty} e^{-st} v(t) dt$$

$$v(t) = \frac{1}{2\pi j} \int_{\sigma_0 - j\infty}^{\sigma_0 + j\infty} e^{st} V(s) ds.$$

two-sided or bilateral Laplace transform

$$V(s) = \int_{-\infty}^{\infty} e^{-st} v(t) dt$$

sinusoidal steady state

R: R

C: $\frac{1}{j\omega C}$

L: $j\omega L$

laplace

R

$\frac{1}{sC}$

sL

Suppose the input to a LTI is $A \cos(\omega t + \phi)$

We know that $Y(s) = H(s) X(s)$.

If $x(t) = A \cos(\omega t + \phi) u(t)$

$$X(s) = \frac{A(s \cos \phi - \omega \sin \phi)}{s^2 + \omega^2}$$

$$Y(s) = H(s) \frac{A(s \cos \phi - \omega \sin \phi)}{s^2 + \omega^2} \cdot \frac{1}{s - j\omega}$$

$$Y(s) = \underbrace{\frac{K_1}{s - j\omega} + \frac{K_1^*}{s + j\omega}}_{\text{steady state response}} + \underbrace{\sum \text{terms generated by poles of } H(s)}_{\text{should all lie in left-half plane and will die out natural response}}$$

steady state response.

should all lie in left-half plane and will die out natural response.

So, what is K_1 ? $K_1 = \frac{H(s) A(s \cos \phi - \omega \sin \phi)}{s + j\omega} \Big|_{s = j\omega}$

$$K_1 = \frac{1}{2} H(j\omega) A e^{j\phi} \text{ --- complex } |H(j\omega)| e^{j\theta(\omega)}$$

This is an amazing result. It says that we can determine the transfer function and then evaluate it for $s = j\omega$.

→ inverse transform to get

$$y_{ss}(t) = A |H(j\omega)| \cos[\omega t + \phi + \theta(\omega)]$$

last time we were examining a way to exhibit the nature of a system function, $F(s) = \frac{N(s)}{D(s)}$

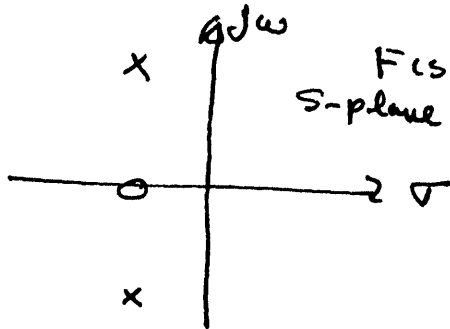
$N(s)$ and $D(s)$ may be written in terms of their roots.
 $N(s) = a_n(s-s_{z1})(s-s_{z2}) \dots (s-s_{zn})$

$D(s) = b_m(s-s_{p1})(s-s_{p2}) \dots (s-s_{pm})$

And when $s = s_{zj}$
 or when $s = s_{pk}$

$F(s) = 0$ - zero

$F(s) = \infty$ - pole



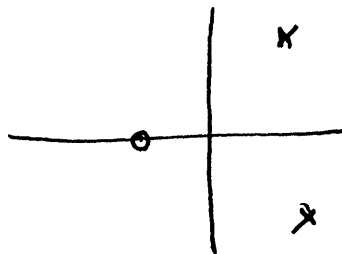
$F(s) = \frac{s+1}{s^2+2s+1}$
 S-plane

$\frac{s+1}{s^2+2s+1} = \frac{(s+1)}{(s+1-j\sqrt{2})(s+1+j\sqrt{2})}$

the system is stable

($f(t) \rightarrow 0$ as $t \rightarrow \infty$)

if poles are in l.h.p.



for $F(s) = \frac{s+1}{s^2-2s+1} = \frac{s+1}{(s-1+j\sqrt{2})(s-1-j\sqrt{2})}$
 impulse response is

$f(t) = e^{(1+\sqrt{2})t} \quad t \geq 0$

r.h.p. roots indicate an unstable system.

Note: roots are either real or appear as a complex-conjugate pair

Let's take a moment for a short review of the methods we've encountered in this course

① Kirchhoff's laws - KCL, KVL

- Applies to time varying systems - as well as s-s.

- terminal relations $I = f(V)$ or $V = g(I)$
 inductor $v = L \frac{di}{dt}$, $i = \int_0^t v d\lambda + i(0)$
 initial cond. + int \int

capacitor $i = C \frac{dv}{dt}$, $v = \frac{1}{C} \int_0^t i(\lambda) d\lambda + v(0)$

resistor $v = iR$, $i = \frac{1}{R} v = \textcircled{G} v$

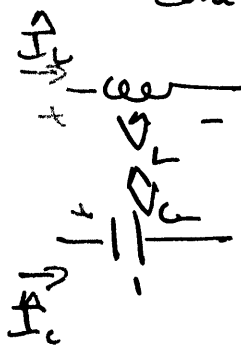
The sinusoidal steady state signals such as $\hat{I} e^{j\omega t}$ represent sinusoids i.e. $\text{Re} \hat{I} e^{j\omega t} = i(t)$, $v(t) = \text{Re} \hat{V} e^{j\omega t}$

The equations with $Z_L = j\omega L$

$$Z_C = \frac{1}{j\omega C}$$

$$R = R$$

represent the relationships between the complex magnitudes of voltages and currents



$$\hat{V}_L = j\omega L \hat{I}_L$$

$$\hat{V}_C = \frac{1}{j\omega C} \hat{I}_C$$

magnitudes which multiply $e^{j\omega t}$

the true (time voltage) is $v(t) = R \hat{I}_C e^{j\omega t}$

but do we NOT HAVE $v_L(0)$ or $v_C(0)$ (initial condx)

Transient problems - sources start at $t=0$

$$I(s) = \int_0^{\infty} i(t) e^{-st} dt \quad \leftarrow \text{Laplace transform}$$

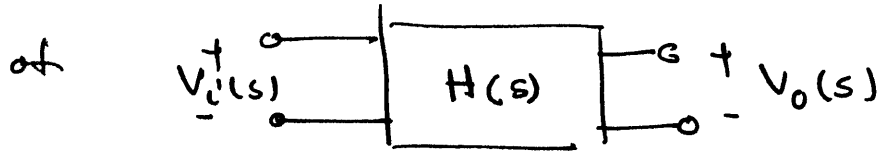
we have

$$V_L(s) = Ls I(s) \quad \begin{array}{c} \frac{V_L(s)}{I(s)} \\ \hline \end{array}$$

$$V_C(s) = \left(\frac{1}{Cs}\right) I_C(s) \quad \begin{array}{c} \frac{V_C(s)}{I_C(s)} \\ \hline \end{array}$$

The cute thing we see is that we can switch from a transient problem to a s-s-s-s problem by $s \rightarrow j\omega$. But these are two different problems with the same circuit.

So if we want to find the s-s-s-s. equivalent



we simply set \$s = j\omega\$, find \$V_o(j\omega) = V_i(j\omega) \times H(j\omega)\$

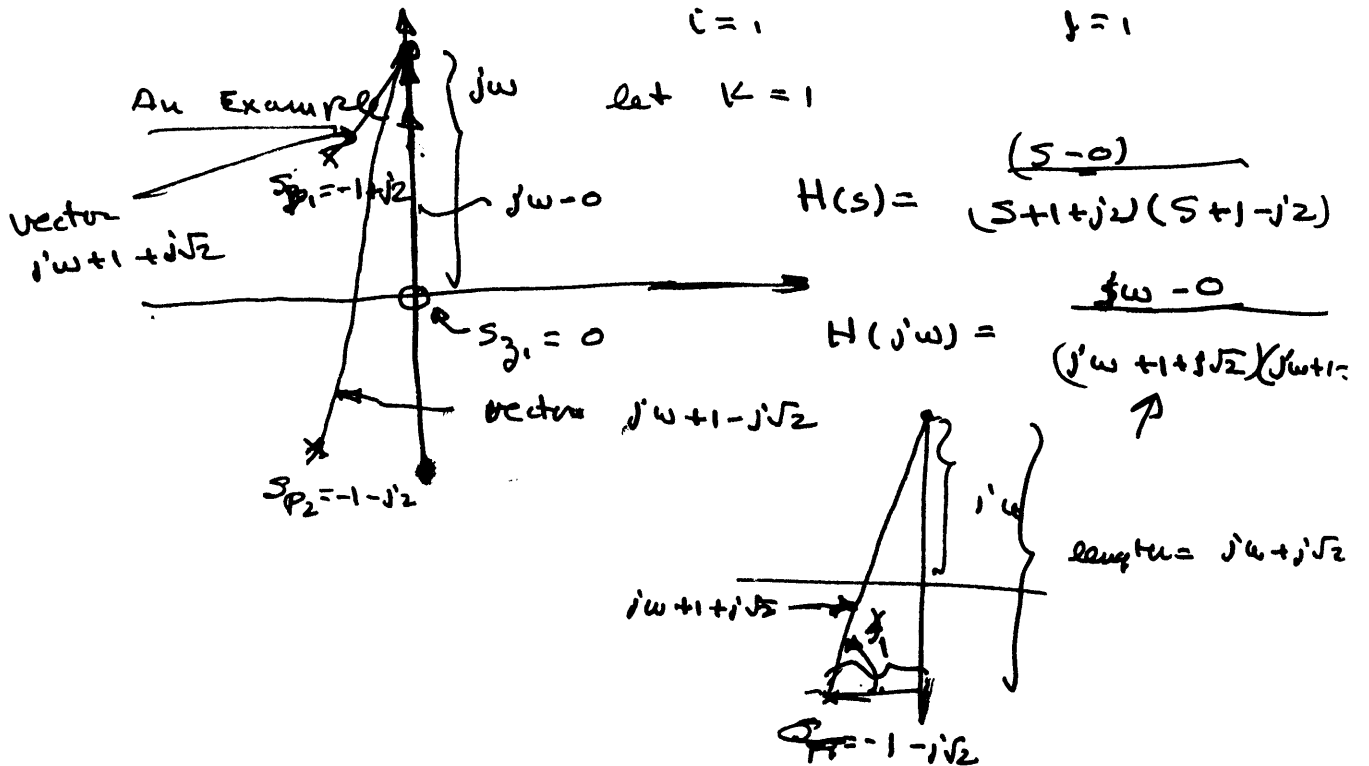
$$\text{then } v_o(t) = \text{Re} \{ V_o(j\omega) e^{j\omega t} \}$$

now let's look at \$H(j\omega)\$ knowing \$H(s)\$

$$H(s) = k \frac{(s-s_{z1})(s-s_{z2}) \dots (s-s_{zn})}{(s-s_{p1})(s-s_{p2}) \dots (s-s_{pm})} \Big|_{s=j\omega}$$

$$|H(j\omega)| = k \frac{\prod_{i=1}^n |j\omega - s_{zi}|}{\prod_{j=1}^m |j\omega - s_{pj}|}$$

$$\text{and } \angle H(j\omega) = \sum_{i=1}^n \angle (j\omega - s_{zi}) - \sum_{j=1}^m \angle (j\omega - s_{pj})$$

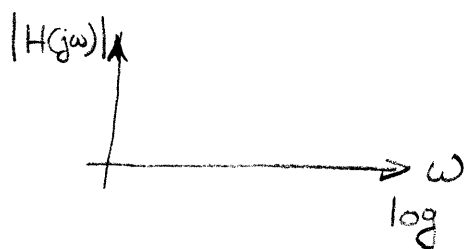


17.6. Bode diagrams

recall that the sinusoidal steady state response of a circuit is its transfer function evaluated at $s = j\omega$.

Plots of $|H(j\omega)|$ and $\angle H(j\omega) = \theta(\omega)$ give a good idea of how the circuit will behave when the poles and zeros are reasonably separated.

Bode plot



① starting point

$$H(s) = \frac{K(s+z_1)}{s(s+p_1)}$$

② evaluate at $s = j\omega$

$$H(j\omega) = \frac{K(j\omega+z_1)}{j\omega(j\omega+p_1)}$$

③ Put into standard form

$$H(j\omega) = \frac{K z_1 (1 + j\frac{\omega}{z_1})}{j\omega p_1 (1 + j\frac{\omega}{p_1})} = \frac{K_0}{\frac{p_1}{z_1}} \frac{1 + j\omega/z_1}{j\omega (1 + j\omega/p_1)}$$

④

go to polar form.

$$H(j\omega) = K_0 \frac{|1 + j\frac{\omega}{z_1}| \angle \psi_1}{\omega \angle 90^\circ \{ |1 + j\frac{\omega}{p_1}| \angle \beta_1 \}}$$

where $\psi_1 = \tan^{-1}(\frac{\omega}{z_1})$
 $\beta_1 = \tan^{-1}(\frac{\omega}{p_1})$

$$\Rightarrow |H(j\omega)| = K_0 \frac{|1 + j\frac{\omega}{z_1}|}{\omega |1 + j\frac{\omega}{p_1}|} \quad \theta(\omega) = \psi_1 - 90^\circ - \beta_1$$

Plot $|H(j\omega)| = K_0 \frac{|1 + j\frac{\omega}{z_1}|}{\omega |1 + j\frac{\omega}{p_1}|}$

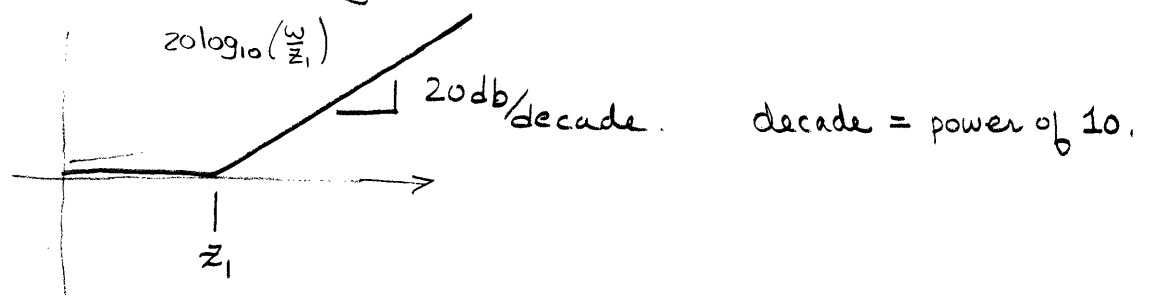
do in logs.

$$A_{db} = 20 \log_{10} |H(j\omega)|$$

$$A_{db} = 20 \log_{10} \frac{K_0 |1 + j\frac{\omega}{z_1}|}{\omega |1 + j\frac{\omega}{p_1}|}$$

$$= 20 \log_{10} K_0 + 20 \log_{10} |1 + j\frac{\omega}{z_1}| - 20 \log_{10} \omega - 20 \log_{10} |1 + j\frac{\omega}{p_1}|$$

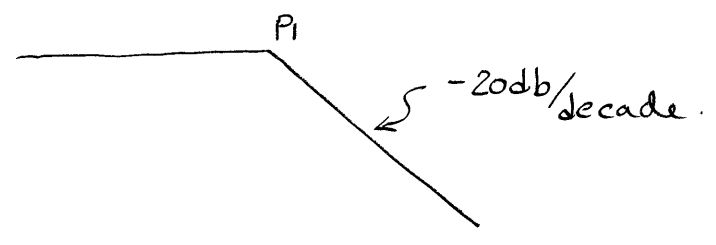
Plot each term separately and combine

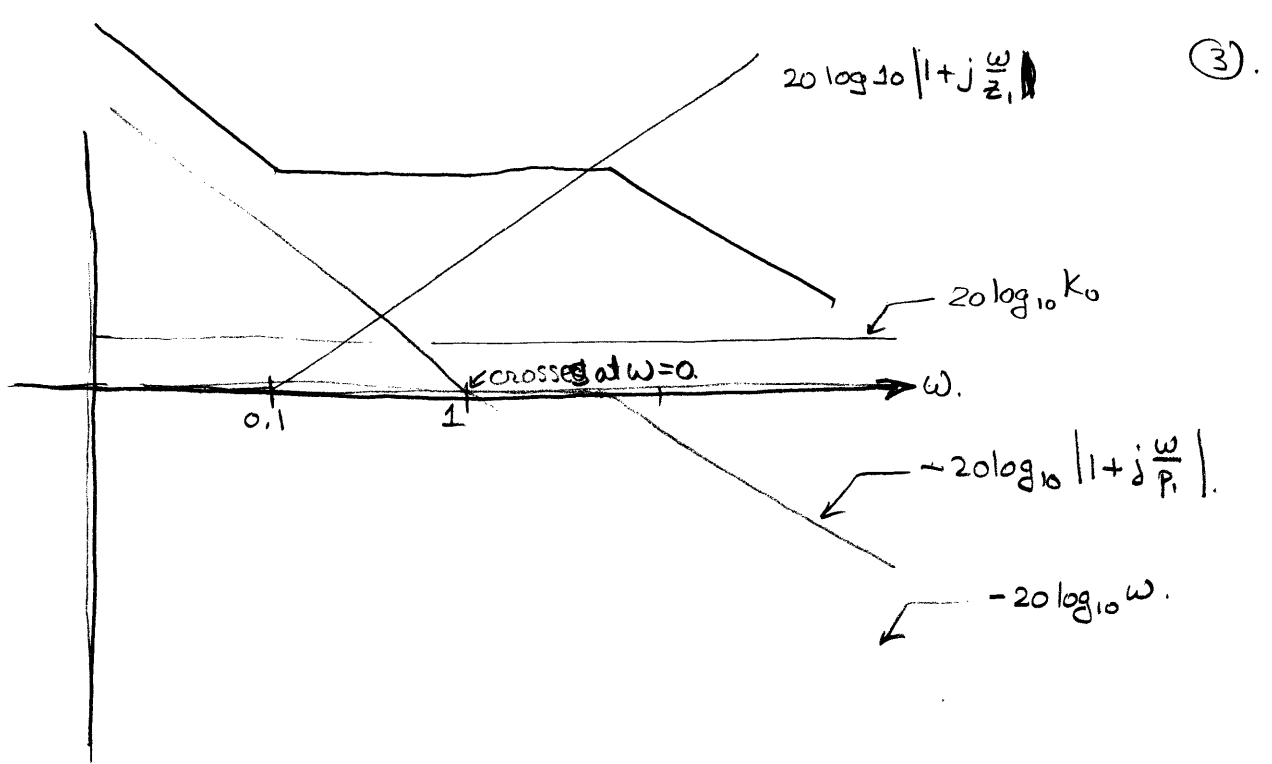


for $\frac{\omega}{z_1} \ll 1$ $1 + j\frac{\omega}{z_1} \approx 1$ and $\log(1) = 0$.

for $\frac{\omega}{z_1} \gg 1$ $1 + j\frac{\omega}{z_1} \approx j\frac{\omega}{z_1}$ and $\log |j\frac{\omega}{z_1}| = \log \frac{\omega}{z_1}$

$20 \log_{10} (1 + j\frac{\omega}{p_1})$ looks about the same.





$$A_{db} = 20 \log_{10} \frac{K_0 |1 + j \frac{\omega}{z_1}|}{\omega |1 + j \frac{\omega}{p_1}|}$$

$$= 20 \log_{10} K_0 + 20 \log_{10} |1 + j \frac{\omega}{z_1}| - 20 \log_{10} \omega - 20 \log_{10} |1 + j \frac{\omega}{p_1}|$$

Reading Assignment: 17.6, 17.7, (17.8)

Possible Problems:

17.27 (17.3)

17.28

17.29

17.30

17.31

17.34

17.32 Xtra Credit

16, 46 modified

PE review exam

- Bode diagrams provide information on the frequency response of a system. You normally plot magnitude in decibels and angle in degrees versus the logarithm of frequency. You use decibels because they are logarithmic and allow the product of terms to be represented as a sum.

$$A_{I|db} = 20 \log \left| \frac{I_2}{I_1} \right|$$

$$A_{v|db} = 20 \log \left| \frac{V_2}{V_1} \right|$$

In general,

$$A_{db} = 20 \log |A(j\omega)|$$

In general,

$$A(j\omega) = A \frac{(j\omega + z_1)(j\omega + z_2) \dots (j\omega + z_k)}{(j\omega)^n (j\omega + p_1)(j\omega + p_2) \dots (j\omega + p_m)}$$

Rewrite $j\omega + z_i = z_i \left(1 + j \frac{\omega}{z_i} \right)$
 $j\omega + p_j = p_j \left(1 + j \frac{\omega}{p_j} \right)$

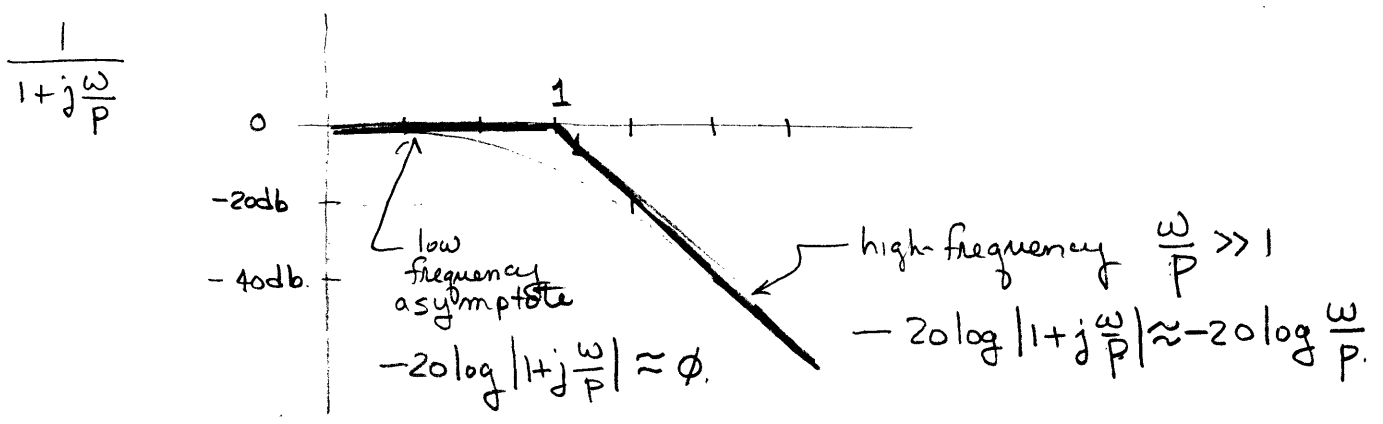
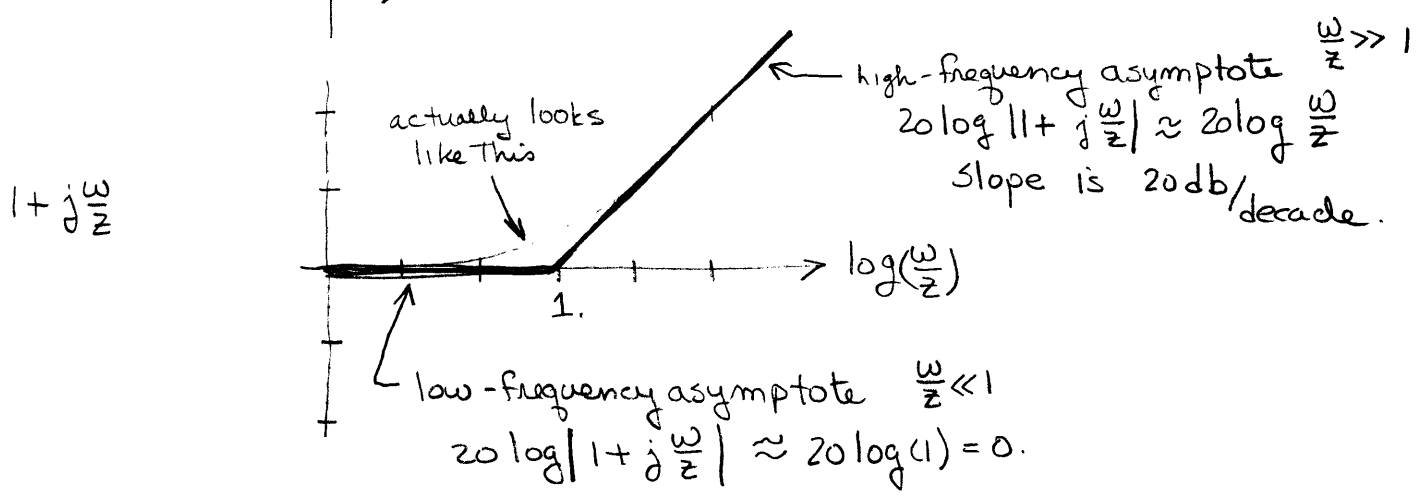
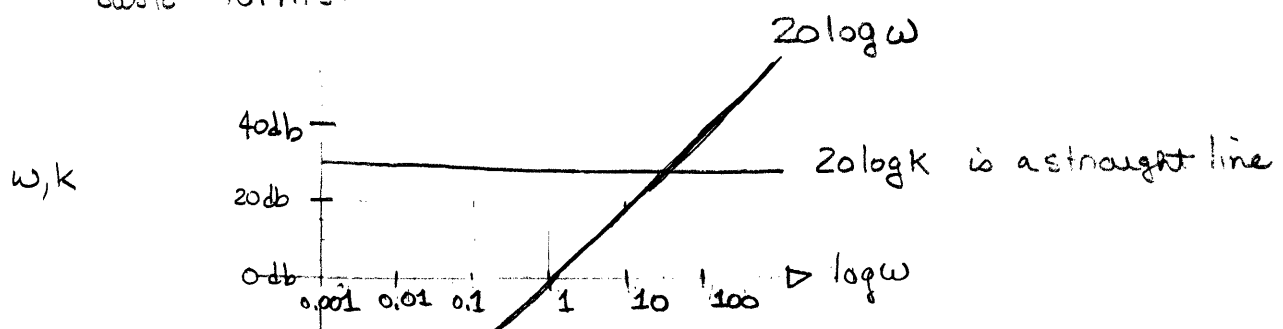
$$A(j\omega)_{db} = 20 \log k + \sum_{i=1}^k 20 \log \left| 1 + j \frac{\omega}{z_i} \right| - 20 n \log \omega - \sum_{j=1}^m 20 \log \left| 1 + j \frac{\omega}{p_j} \right|$$

$$k = A \frac{\prod_{i=1}^k (z_i)}{\prod_{j=1}^m (p_j)}$$

$$\angle A(j\omega) = -90n + \sum_{i=1}^k \tan^{-1} \left(\frac{\omega}{z_i} \right) - \sum_{j=1}^m \tan^{-1} \left(\frac{\omega}{p_j} \right)$$

from $\frac{1}{(j\omega)^n}$
 $\frac{z + j\omega}{\tan^{-1}(\frac{\omega}{z})}$
kikewise

basic forms.



$$G_1(j\omega) = K \frac{(1 + j\frac{\omega}{z})}{(1 + j\frac{\omega}{p})}$$

zero at $\omega = z$
pole at $\omega = p$.

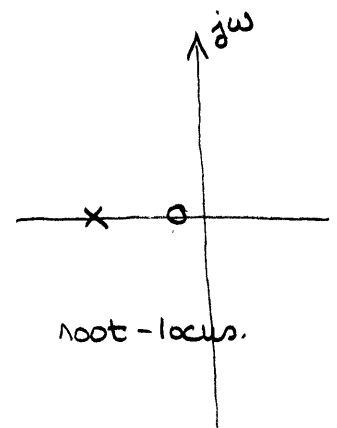
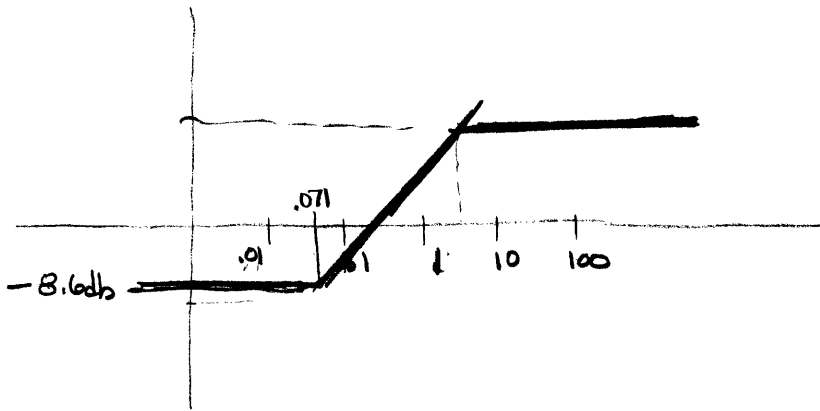
Called the gain K

use logs. $G_1(j\omega) |_{db} = 20 \log |K| + 20 \log |1 + j\frac{\omega}{z}| - 20 \log |1 + j\frac{\omega}{p}|$

I. suppose $z < p$.

$$K = 0.37 \quad z = .071$$

$$p = 4.6$$



$$20 \log |24| + 20 \log |1 + j\frac{\omega}{.071}| - 20 \log |1 + j\frac{\omega}{4.6}|$$

for ω small only $20 \log |0.37| \cong -8.6 \text{ dB}$.

since $\frac{1}{z} \gg \frac{1}{p}$ the zero comes in first. adding

$$20 \log |1 + j\frac{\omega}{z}| \quad \text{corner frequency at } \omega = z.$$

continues at $+20 \text{ dB/decade}$ until effects of pole come in.
one pole goes at -20 dB/decade canceling out zero.

upper frequency limit

$$K \frac{j\frac{3}{4}}{j\frac{3}{4}} = K \frac{p}{z} = (0.37) \frac{4.6}{(.071)} = 24$$

$$20 \log 24 = 27.6 \text{ dB}.$$

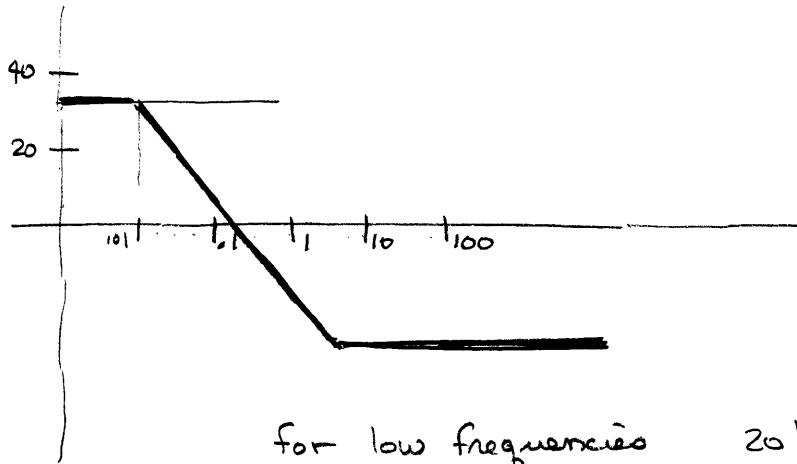
same transfer function

$$G_1(j\omega)|_{db} = 20 \log |k| + 20 \log \left| 1 + j \frac{\omega}{z} \right| - 20 \log \left| 1 + j \frac{\omega}{p} \right|$$

$$K = 40 \quad z = 5 \quad p = .02$$

case II. suppose $p < z$

$$G_1(j\omega)|_{db} = 20 \log |40| + 20 \log \left| 1 + j \frac{\omega}{5} \right| - 20 \log \left| 1 + j \frac{\omega}{.02} \right|$$



for low frequencies $20 \log |40| = 32$

as ω increases pole at $\omega = .02$ comes in.
 -20 dB/decade

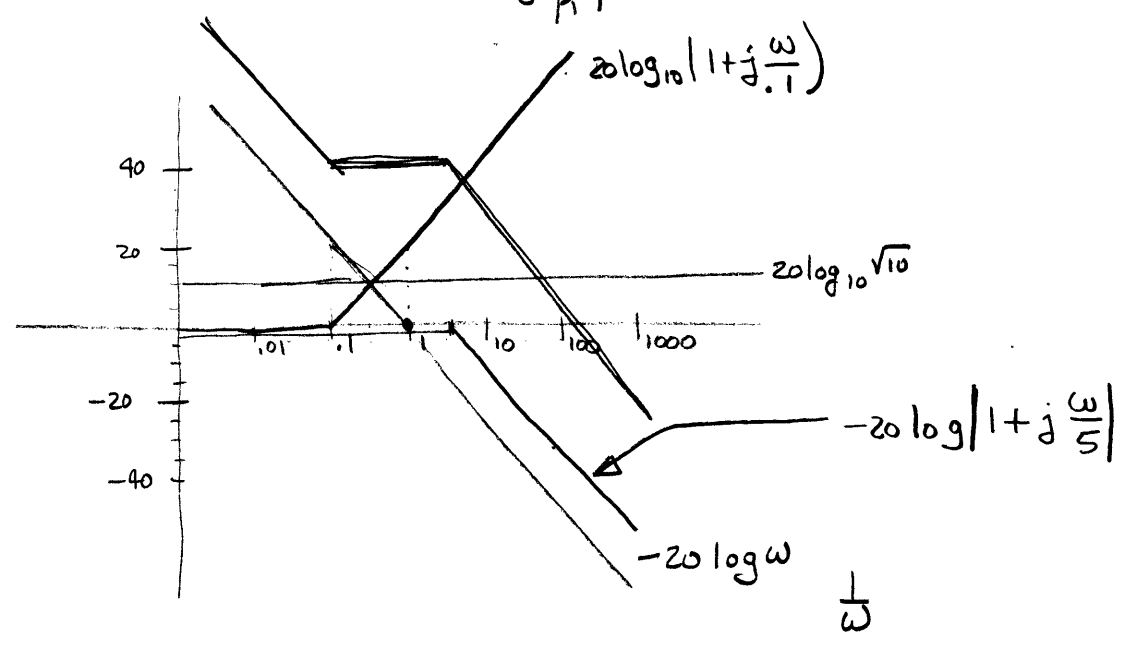
as ω continues to increase zero at
 $\omega = 5$ comes in
 $+20 \text{ dB/decade}$ which cancels
 out pole

more functions

$$A_{db} = 20 \log_{10} \frac{K_0 |1 + j \frac{\omega}{z_1}|}{\omega |1 + j \frac{\omega}{p_1}|}$$

$$K_0 = \sqrt{10} \quad z_1 = 0.1$$

$$p_1 = 5$$



what does sum look like?

17.7 complex poles & zeros.

$$H(s) = \frac{K}{(s + \alpha - j\beta)(s + \alpha + j\beta)}$$

re-write in standard form

$$s^2 + 2\zeta\omega_n s + \omega_n^2$$

$$s^2 + s\alpha + \cancel{sj\beta} + s\alpha + \alpha^2 + \cancel{j\alpha\beta} - \cancel{j\beta s} - \cancel{j\beta\alpha} + \beta^2$$

$$s^2 + 2s\alpha + \alpha^2 + \beta^2$$

by inspection $\omega_n^2 = \alpha^2 + \beta^2$

$$\zeta\omega_n = \alpha$$

ω_n corner frequency
 Zeta \rightarrow ζ damping factor
 if $\zeta < 1$ roots are complex
 $\zeta \geq 1$ $(s + p_1)(s + p_2)$
 this is what we have done.

for $\zeta < 1$. put into standard form

$$H(s) = \frac{K}{s^2 + 2\zeta\omega_n s + \omega_n^2} = \frac{K}{\omega_n^2} \frac{1}{1 + 2\zeta \frac{s}{\omega_n} + \frac{s^2}{\omega_n^2}}$$

$$H(j\omega) = \frac{K_0}{1 - (\frac{\omega}{\omega_n})^2 + j(\frac{2\zeta\omega}{\omega_n})} \quad \text{where } K_0 = \frac{K}{\omega_n^2}$$

do normalized variable $u = \frac{\omega}{\omega_n}$

$$H(j\omega) = \frac{K_0}{1 - u^2 + j2\zeta u}$$

put into polar view

$$H(j\omega) = \frac{K_0}{|(1 - u^2) + j2\zeta u|} < \beta_1 \quad \text{where } \beta_1 = \frac{2\zeta u}{1 - u^2}$$

amplitude plot

$$A_{db} = 20 \log_{10} K_0 - 20 \log_{10} |(1-u^2) + j2\zeta u|$$

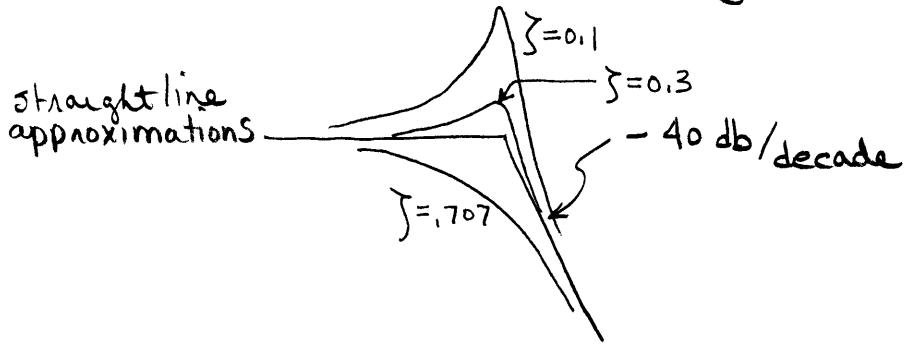
$$-20 \log_{10} |(1-u^2) + j2\zeta u| = -20 \log_{10} \sqrt{(1-u^2)^2 + 4\zeta^2 u^2}$$

$$= -20 \frac{1}{2} \log_{10} (u^4 - 2u^2 + 1 + 4\zeta^2 u^2)$$

$$A_{db} = -10 \log_{10} (u^4 + 2u^2(2\zeta^2 - 1) + 1)$$

as $u \rightarrow 0$ $A_{db} \rightarrow -10 \log_{10}(1) = 0$

as $u \rightarrow \infty$ $A_{db} \rightarrow -10 \log_{10} u^4 = -40 \log_{10} u$



ζ controls the behavior near the corner frequency.

non-trivial example. $H(s) = \frac{100(s+1)}{s^2 + 8s + 100}$

put into standard form

$$H(s) = \frac{s+1}{1 + (\frac{s}{10})^2 + 0.8(\frac{s}{10})} \leftarrow \text{after dividing by 100}$$

should be in form $\frac{s}{\omega_n} \Rightarrow \omega_n = 10$

$$H(j\omega) = \frac{1 + j\omega \angle \psi_1}{|1 - (\frac{\omega}{10})^2 + j0.8(\frac{\omega}{10})| \angle \beta_1}$$

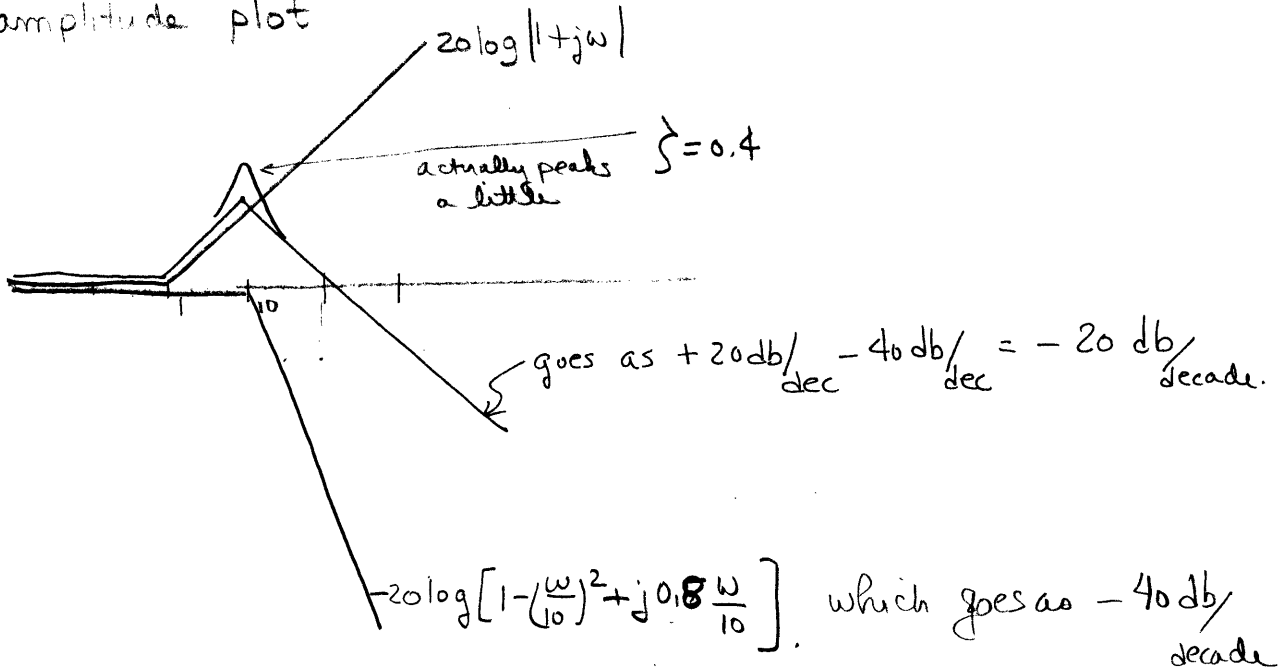
$$\psi_1 = \text{Tan}^{-1}(\omega)$$

$$\beta_1 = \text{Tan}^{-1} \left[\frac{0.8 \frac{\omega}{10}}{1 - (\frac{\omega}{10})^2} \right]$$

$$A_{db} = 20 \log_{10} |1 + j\omega| - 20 \log_{10} \left| 1 - (\frac{\omega}{10})^2 + j0.8(\frac{\omega}{10}) \right|$$

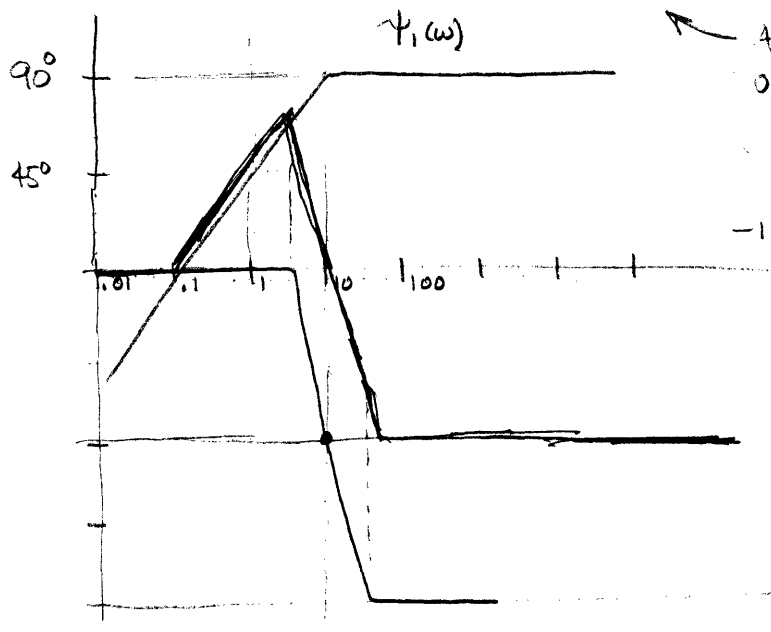
$$\theta(\omega) = \psi_1 - \beta_1 = \text{tan}^{-1} \omega - \text{tan}^{-1} \left(\frac{0.8 \frac{\omega}{10}}{1 - (\frac{\omega}{10})^2} \right)$$

basic amplitude plot



phase plot.

$$\phi_1 = \tan^{-1}(\omega) - \tan^{-1} \left[\frac{0.8 \left(\frac{\omega}{10} \right)}{1 - \left(\frac{\omega}{10} \right)^2} \right]$$



this we just have to learn

slope depends on }
 larger }
 larger slope

ω (rad/sec).

for denominator position

Here is a tough one

$$H(s) = \frac{5(1+0.1s)}{s(1+0.5s)\left[1+0.6\left(\frac{s}{50}\right)+\left(\frac{s}{50}\right)^2\right]}$$

$$\frac{5(1+j\frac{10}{\omega})}{(j\omega)(1+j\frac{\omega}{2})\left[1+0.6\left(\frac{j\omega}{50}\right)+\left(\frac{j\omega}{50}\right)^2\right]}$$

- ① constant gain $K=5$
- ② pole at origin
- ③ pole at $s=-2$
- ④ zero at $s=-10$
- ⑤ complex poles $s=-15 \pm$

put into standard form

$$\left[1 - \left(\frac{\omega}{50}\right)^2 + j0.6\left(\frac{\omega}{50}\right)\right]$$

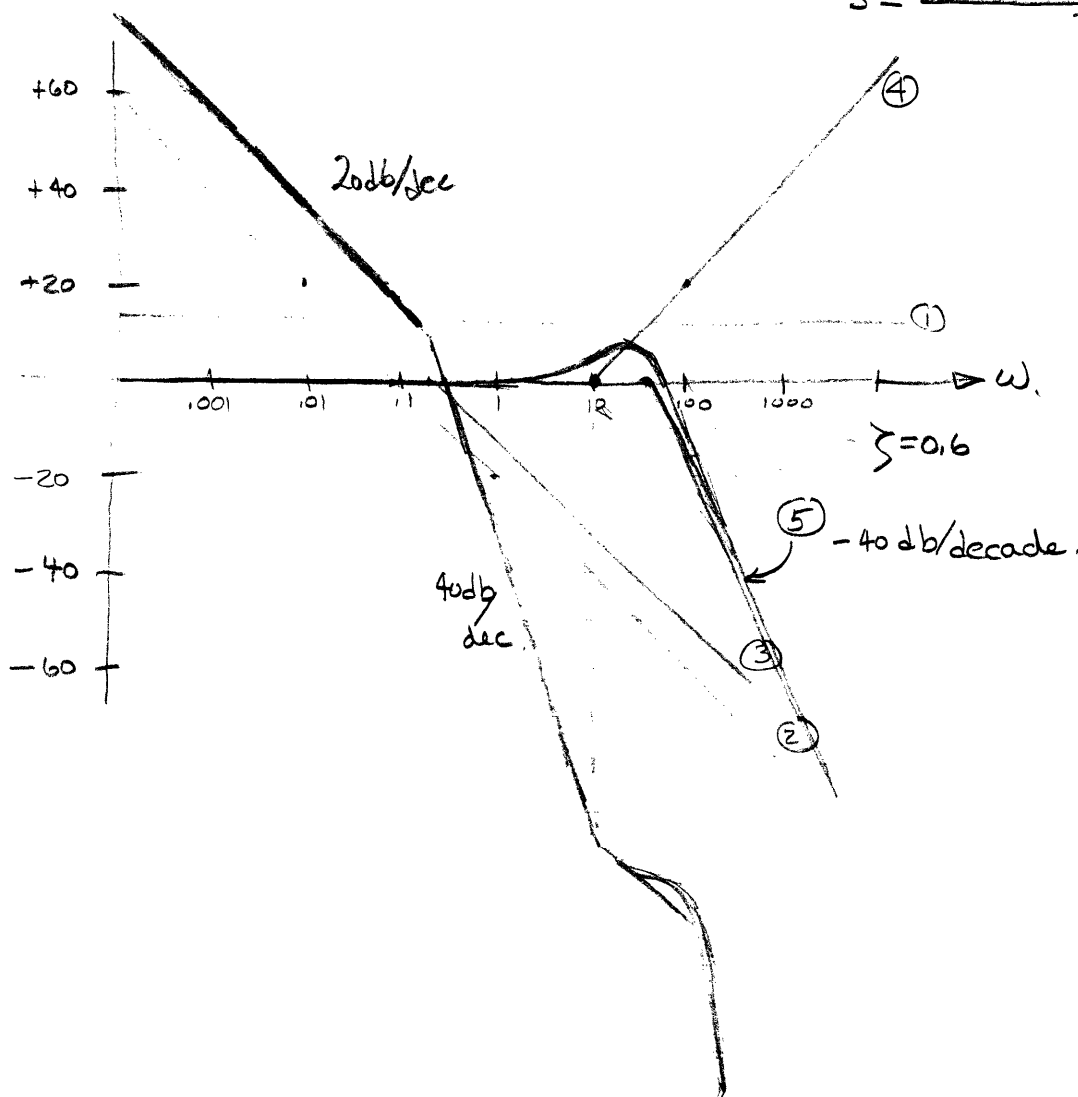
$$\omega_n = 50 \quad \left| \begin{array}{l} 2\zeta\omega_n \\ 2(1.3) \end{array} \right.$$

$$\left(\frac{s}{50}\right)^2 \left[\left(\frac{s}{50}\right)^2 + 0.6\left(\frac{s}{50}\right) + 1 \right]$$

$$s^2 + 30s + 2500$$

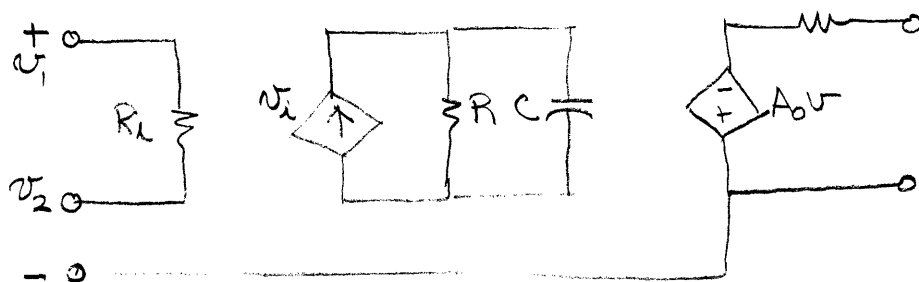
$$s = \frac{-30 \pm \sqrt{900 - 4(2500)}}{2}$$

$$s = \frac{-30 \pm \sqrt{9100}j}{2}$$



Frequency response of op-amp circuits

Gain of an op-amp varies with frequency.



$$A(j\omega) = \frac{A_0}{1 + j\frac{\omega}{\omega_1}}$$

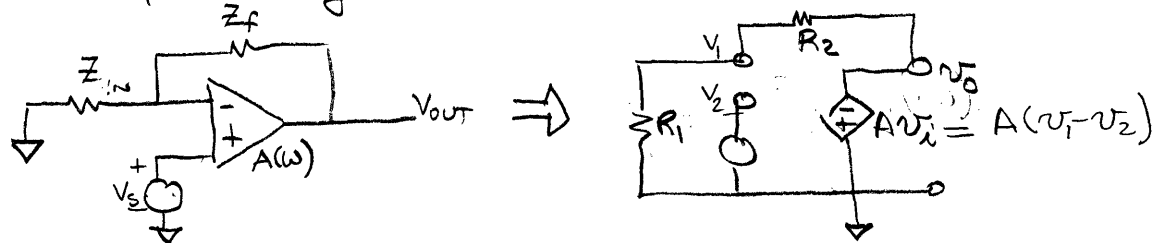
$$\omega_1 = \frac{1}{RC}$$

ω_1 break frequency, usually less than 100

A_0 dc gain $> 10^4$

How about a non-inverting op-amp?

We have previously derived the dc gain as,



$$v_o = -A v_i$$

$$v_i = v_1 - v_2 = v_1 - v_3$$

use divider

$$v_1 = \frac{R_1}{R_1 + R_2} v_o \equiv k v_o$$

$$v_i = k v_o - v_3$$

$$-\frac{v_o}{A} = k v_o - v_3$$

$$v_o = -A (k v_o - v_3)$$

$$v_o = \frac{+A v_3}{1 + AR}$$

$$\text{or } \frac{v_o}{v_3} = \frac{A}{1 + AR}$$

$$\therefore \frac{V_o}{V_s} = \frac{A}{1+AR}$$

normally this would become $\frac{A}{AR} = \frac{1}{R}$

$$\text{if } A(j\omega) = \frac{A_0}{1+j\omega/\omega_1}$$

where $\omega_1 = 10 \text{ rad/sec.}$

$$A_0 = 10^5$$

$$R_2 = 100k$$

$$R_1 = 10k$$

$$R = 0.1$$

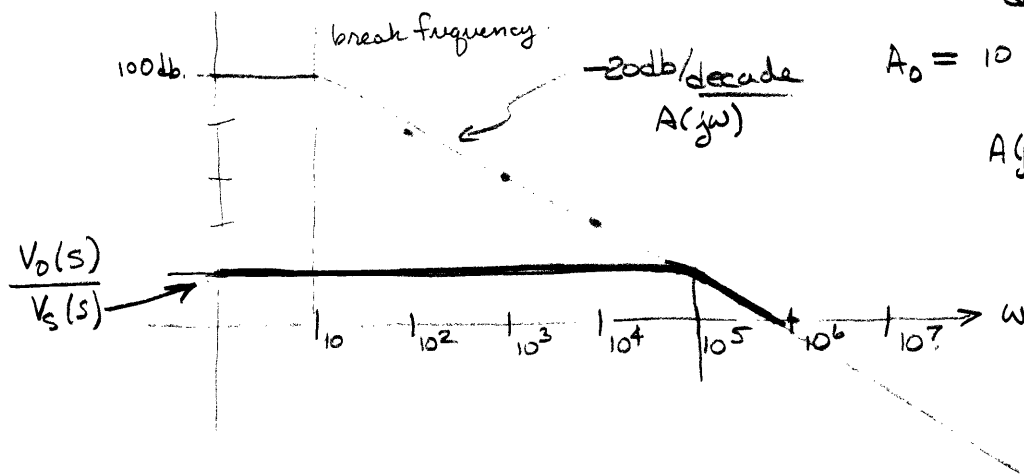
$$\frac{V_o(s)}{V_s(s)} = \frac{\frac{A_0}{1+j(\frac{\omega}{\omega_1})}}{1+k \frac{A_0}{1+j\frac{\omega}{\omega_1}}} = \frac{A_0}{1+j(\frac{\omega}{\omega_1}) + kA_0}$$

$$= \frac{A_0}{1+kA_0 + j\frac{\omega}{\omega_1}} \cdot \frac{\frac{1}{1+kA_0}}{\frac{1}{1+kA_0}} = \frac{\left(\frac{A_0}{1+kA_0}\right) \Rightarrow A_c \text{ total gain at dc.}}{1+j\frac{\omega}{\omega_1} \left(\frac{1}{1+kA_0}\right) \Rightarrow A_2}$$

$$= \frac{A_c}{1+j\frac{\omega}{\omega_2} \frac{1}{A}}$$

single pole

-20 db/dec.



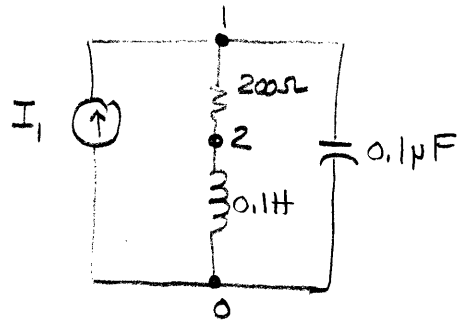
$$\frac{V_o(s)}{V_s(s)} = \frac{10}{1+j\frac{\omega}{10} (10^{-4})} = \frac{10}{1+j\frac{\omega}{10^5}}$$

$$A_c = \frac{A_0}{1+0.1A_0} \approx 10$$

$$\frac{20 \log \frac{1}{1+0.1 \cdot 10^5}}{\omega} \approx 10^{-4}$$

of points

• AC <sweep type> <n> <start f> <end freq>



Resonant circuit

I1 0 1 AC 0.1

R 1 2 200

L 2 0 0.1

C 1 0 0.1U

• AC LIN 100 1E2 1E4.

• PLOT AC VM(1,0)

• PROBE

• END.

linear frequency.

VDB(1,0)

plot $|V|$ in dB.

VP(1,0)

plot phase V

Interesting PROBE FEATURES.

Plot_control
 Add_plot
 Exit

} adds a second plot.

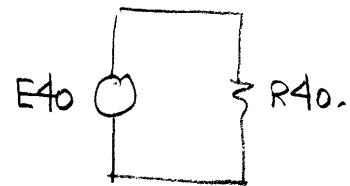
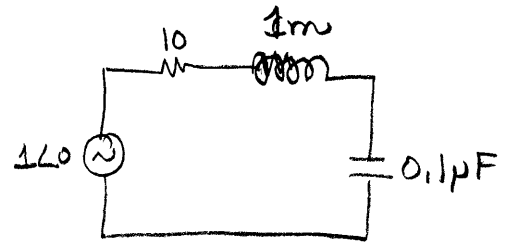
Importing data

E name +node -node FREQ {expression} = {freq, magdB, phase}

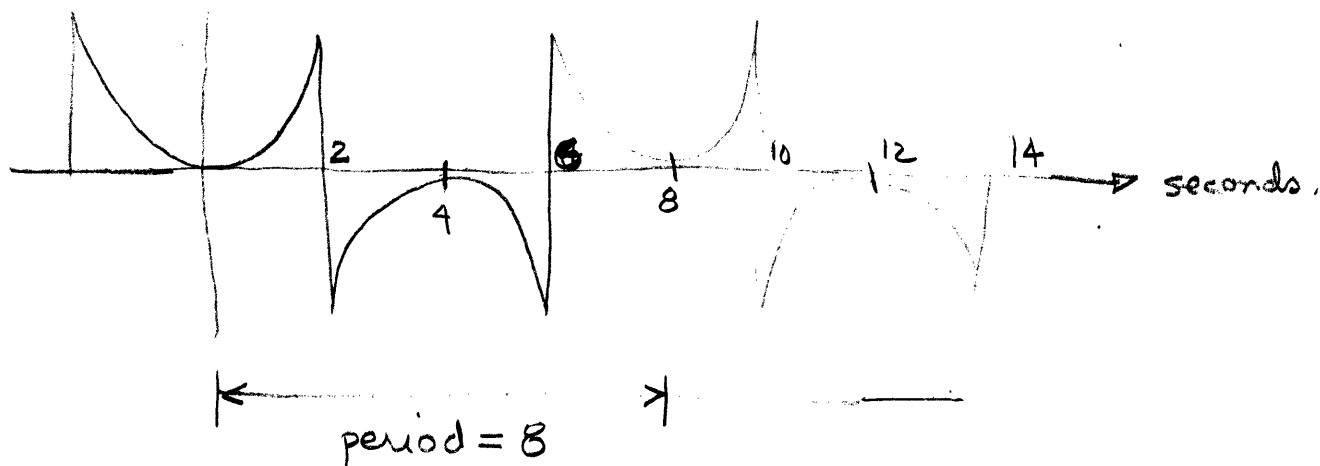
Comparison

```

VS 1 0 AC 1
R12 1 2 10
L23 2 3 1m
C30 3 0 0.1p
E40 4 0 FREQ {V(1)} = (
+ 10085 2.384 -7.31
+ 10511 4.601 -0.74
  ⋮
+ 24637 -2.360 -178.67
+ 25824 -2.610 -174.36 }
R40 4 0 1.
• AC DEC 20 10k 25k.
• PROBE
• END.
  
```



Problem 18.12.



by inspection even symmetry. $f(t) = f(-t)$
 \Rightarrow all sine terms are zero

quarter wave symmetry.
 half wave { shift by $\frac{1}{2}$ cycle (4.)
 and invert

+ symmetry around midpoint of positive half cycles & negative.

if function is even $a_n = 0$

dc term $a_k = 0$ for k even

$$a_k = \frac{8}{T} \int_0^{T/4} f(t) \cos k\omega t dt, k \text{ odd}$$

$b_k = 0$ since even function

basically always do dc and odd/even terms.

$$\text{dc. } a_n = \frac{1}{T} \int_{t_0}^{t_0+T} f(t) dt = \frac{1}{T} \int_0^8 f(t) dt$$

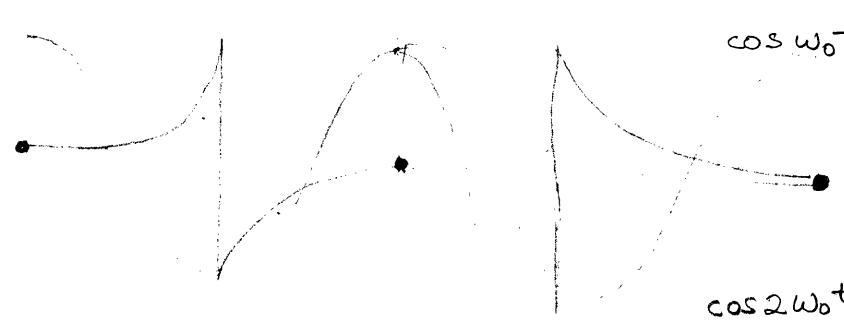
by inspection this integral is zero.

sine terms by inspection are zero.

how about cosine terms

$$a_k = \frac{2}{T} \int_{t_0}^{t_0+T} f(t) \cos k \omega_0 t dt.$$

$$= \frac{2}{8} \int_0^8 f(t) \cos k \omega_0 t dt.$$



$$\omega_0 = \frac{2\pi}{T} = \frac{2\pi}{8} = \frac{\pi}{4}$$

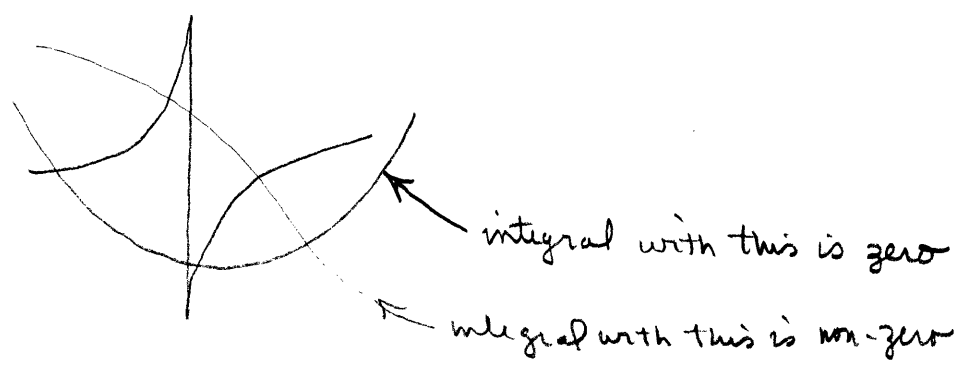
cos 2\omega_0 t

$$\cos \omega_0 t = \cos \frac{\pi}{4} t$$

$$\cos 2\omega_0 t = \cos \frac{2\pi}{4} t = \cos \frac{\pi}{2} t$$

quarter wave
 symmetry about midpoint
 if even k even = 0,

examining



18.29

$$v_g = 50 \sum_{n=1,3,5,\dots}^{\infty} \frac{\pi^2 n^2 - 8}{n^3} (-1)^{n+1} \cos n\omega_0 t \text{ V.}$$

/I

period = 0.2π seconds.

response at $\omega = 250 \text{ rad/sec.}$

$$\omega_0 = \frac{2\pi}{T} = \frac{2\pi}{.2\pi} = \frac{20}{2} = 10.$$

look at 25th harmonic.

$$V_{g,25} = 50 \frac{\pi^2(625) - 8}{(25)^3} (-1)^{26} \cos 250t \text{ volts.}$$

$$= 19.71 \cos 250t$$

put this into circuit.

$$a_k = \frac{1}{4} \int_0^8 f(t) \cos(k \frac{\pi}{4} t) dt$$

$$= \frac{1}{4} \left[\int_0^2 t^2 \cos(k \frac{\pi}{4} t) dt + \int_2^4 (t-4)^2 \cos(k \frac{\pi}{4} t) dt \right.$$

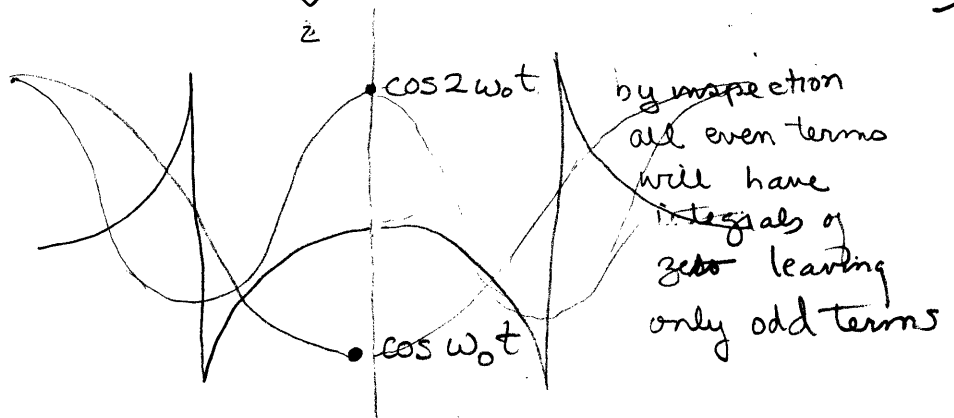
$$\left. + \int_4^6 (t-4)^2 \cos(k \frac{\pi}{4} t) dt + \int_6^8 (t-8)^2 \cos(k \frac{\pi}{4} t) dt \right]$$

$$= \frac{1}{4} \left[\int_0^2 t^2 \cos(k \frac{\pi}{4} t) dt + \int_2^6 (t-4)^2 \cos k \frac{\pi}{4} t dt + \int_6^8 (t-8) \cos \frac{k \pi}{4} t dt \right]$$

symmetric
function ~~about~~
~~line~~
cosine is also

but according to previous picture its not this integral but each half. i.e.

$$a_k = \frac{1}{4} \left[\int_0^2 t^2 \cos(k \frac{\pi}{4} t) dt + \int_2^4 (t-4)^2 \cos(k \frac{\pi}{4} t) dt + \text{other terms} \right]$$



by inspection
all even terms
will have
integrals of
zero leaving
only odd terms

by inspection all even terms go to zero.
and the integrals for the odd terms are
all the same.

$$a_k = 4 \times \frac{1}{4} \int_0^2 t^2 \cos\left(k \frac{\pi}{4} t\right) dt$$

$$= \int_0^2 t^2 \cos\left(k \frac{\pi}{4} t\right) dt.$$

look integrals up.

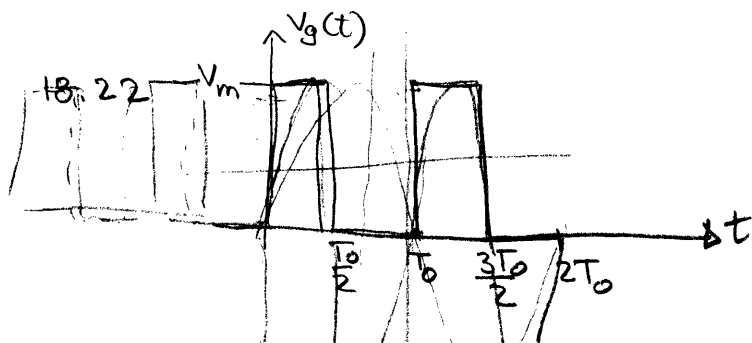
$$= 4 \left\{ \frac{2t}{k^2 \left(\frac{\pi}{4}\right)^2} \cos k \frac{\pi}{4} t + \frac{k^2 \left(\frac{\pi}{4}\right)^2 - 2}{k^3 \left(\frac{\pi}{4}\right)^3} \sin k \frac{\pi}{4} t \right\} \Big|_0^2$$

$$= 4 \left\{ \frac{2 \cdot 2}{k^2 \left(\frac{\pi}{4}\right)^2} \left[\cos k \frac{\pi}{2} - \cos 0 \right] + \frac{k^2 \left(\frac{\pi}{4}\right)^2 - 2}{k^3 \left(\frac{\pi}{4}\right)^3} \left[\sin k \frac{\pi}{2} - 0 \right] \right\}$$

for all k.

$$= 4 \left[\frac{k^2 \left(\frac{\pi}{4}\right)^2 - 2}{k^3 \left(\frac{\pi}{4}\right)^3} \right] \sin\left(k \frac{\pi}{2}\right) = 4 \left[\frac{\frac{k^2 \pi^2}{4} - 2}{k^3 \frac{\pi^3}{64}} \sin\left(k \frac{\pi}{2}\right) \right]$$

$$= \frac{k^2 \pi^2 - 8}{k^3 \pi^3} \cdot 64 \sin\left(k \frac{\pi}{2}\right)$$



half-wave
 half-wave
 $f(t) = -f(t - \frac{T}{2})$
 I don't think this is half-wave symmetric

what is the Fourier series for $V_g(t)$

function is odd \rightarrow sine terms
 no cosine terms
 expect dc term

$$\omega_0 = \frac{2\pi}{T} = \frac{2\pi}{2T_0} = \frac{\pi}{T_0}$$

$$a_v = \frac{1}{T} \int_{t_0}^{t_0+T} f(t) dt$$

$$= \frac{1}{2T_0} \int_0^{2T_0} f(t) dt = \frac{1}{2T_0} \times 2 \times V_m \frac{T_0}{2} = \frac{V_m}{2}$$

how about other terms sine only

$$a_k = 0$$

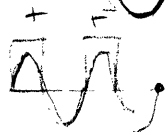
$$b_k = \frac{2}{T} \int_{t_0}^{t_0+T} f(t) \sin(k\omega_0 t) dt = \frac{2}{2T_0} \int_0^{2T_0} f(t) \sin(k \frac{\pi}{T_0} t) dt$$

first term will add

second term will cancel $b_2 = 0$
 only even terms



$$\sin(\frac{\pi t}{T_0})$$



$$\sin(2 \frac{\pi t}{T_0})$$

$$2 \times \frac{1}{T_0} \int_0^{2T_0} \sin(k \frac{\pi t}{T_0}) dt = \frac{2}{T_0} \left[\frac{-\cos(k \frac{\pi t}{T_0})}{(\frac{k\pi}{T_0})} \right]_0^{2T_0}$$

$$= -\frac{2V_m}{k\pi} \cos(k \frac{\pi t}{T_0}) \Big|_0^{2T_0} = -\frac{2V_m}{k\pi} [\cos k\pi 2 - 1]$$

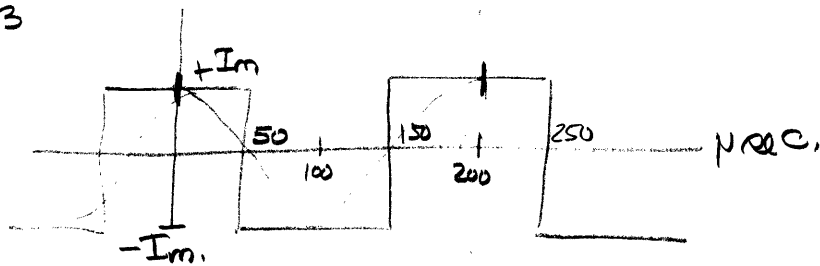
$$= +\frac{2V_m}{k\pi}$$

$$\therefore V_g(t) = \frac{V_m}{2} + \frac{2V_m}{\pi} \sum_{k=1}^{\infty} \frac{1}{k} \sin k\omega_0 t$$

18.23

$I_m = 105\pi \text{ mA}$

(F)



$\omega_0 = \frac{2\pi}{T}$

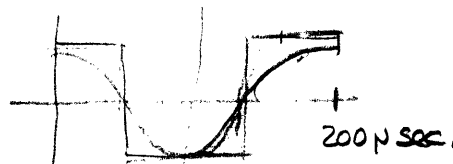
no dc term $v_g = 0$

has even symmetry; cosines only, $a_k \neq 0$, $b_k = 0$.

$$a_k = \frac{2}{T} \int_{t_0}^{t_0+T} f(t) \cos k\omega_0 t dt$$

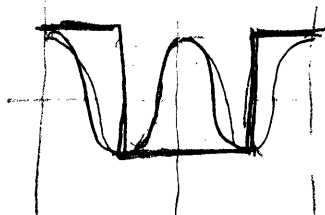
$$= \frac{2}{200 \times 10^{-6}} \int_0^{200 \times 10^{-6}} f(t) \cos k\omega_0 t dt$$

$k=1$, $\cos \omega_0 t$

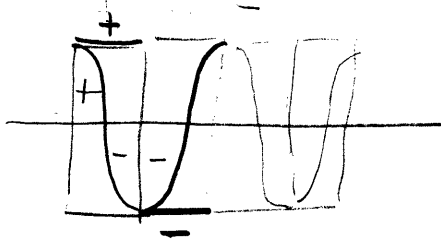


all add

$k=2$, $\cos 2\omega_0 t$



all cancel



overall each sub-integral is positive

So all odd.

$$a_k = 4 \times \frac{2}{200\mu} \int_0^{50\mu} I_m \cos\left(\frac{k \cdot 2\pi t}{200\mu}\right) dt = \frac{8}{200\mu} I_m \left. \frac{\sin\left(\frac{k \cdot 2\pi t}{200\mu}\right)}{\frac{k \cdot 2\pi}{200\mu}} \right|_0^{50\mu}$$

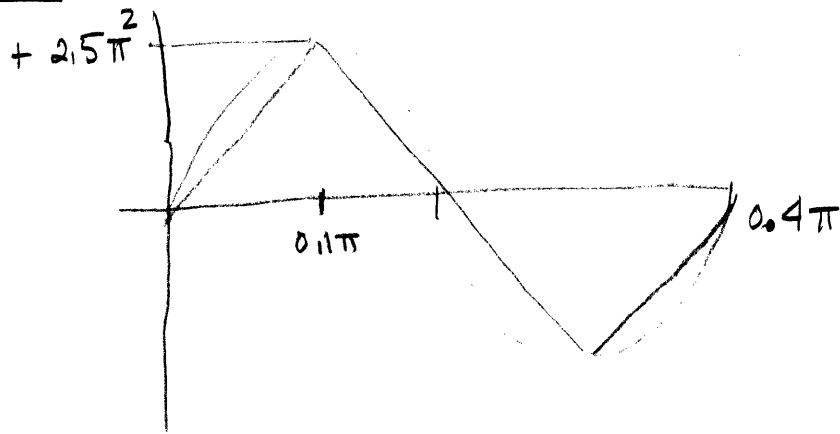
$$= \frac{8 I_m}{200\mu} \frac{\sin\left(\frac{k \cdot 2\pi \cdot 50\mu}{4 \cdot 200\mu}\right)}{\frac{k \cdot 2\pi}{200\mu}} = \frac{8 I_m}{k \cdot 2\pi} \sin\left(\frac{k\pi}{2}\right)$$

if k is odd good!

$$a_k = \frac{4 I_m (-1)^{\frac{k+1}{2}}}{k\pi}$$

18.28

/G



find $i_g(t)$ by inspection odd function \Rightarrow no cosines
 no dc.
 sines only.

$$a_n = 0$$

$$a_k = 0$$

$$b_k = \frac{2}{T} \int_{t_0}^{t_0+T} f(t) \sin k\omega_0 t \, dt$$

$$\omega_0 = \frac{2\pi}{0.4\pi}$$

$$= \frac{2}{T} \int_0^{0.4\pi} f(t) \sin\left(k \frac{2\pi}{T} t\right) dt$$

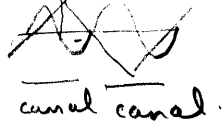
$k=1$

perfect match

4x

odd's only.

$k=2$


 canal canal.

0

no even

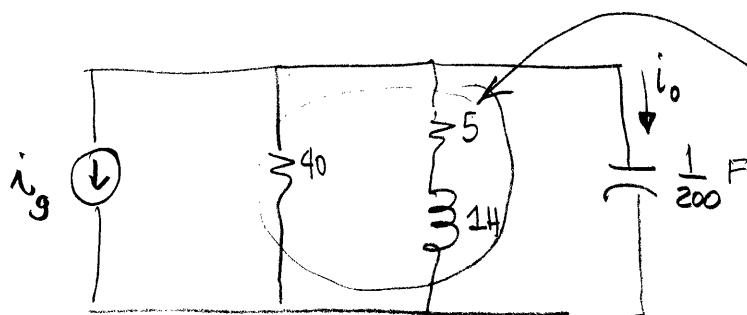
$$\begin{aligned}
 b_k &= 4 \times \frac{2}{T} \int_0^{T/4} \frac{2.5\pi^2}{T/4} t \sin\left(k \frac{2\pi t}{T}\right) dt \\
 &= \frac{80\pi^2}{T^2} \int_0^{T/4} t \sin\left(\frac{k2\pi t}{T}\right) dt = \frac{80\pi^2}{T^2} \int_0^{T/4} t d\left[\frac{-\cos\left(\frac{k2\pi t}{T}\right)}{\frac{k2\pi}{T}}\right] \\
 &= \frac{80\pi^2}{T^2} \left[\frac{-t \cos\left(\frac{k2\pi t}{T}\right)}{\frac{k2\pi}{T}} \Big|_0^{T/4} + \int_0^{T/4} \cos\left(\frac{k2\pi t}{T}\right) dt \right] \frac{1}{k2\pi/4} \\
 &= \frac{80\pi^2}{T^2} \left[\left[\frac{-\frac{T}{4} \cos\left(\frac{k2\pi}{4}\right) - 0 \cos(0)}{\frac{k2\pi}{T}} \right] + \frac{\sin\left(\frac{k2\pi t}{T}\right) \Big|_0^{T/4}}{\frac{k2\pi}{T}} \right] \frac{1}{\frac{2\pi k}{T}} \\
 &= \frac{80\pi^2}{T^2} \left[\frac{-\frac{T}{4} \cos\left(\frac{k\pi}{2}\right) - 0}{\frac{k2\pi}{T}} + \frac{\sin\left(\frac{k2\pi}{4}\right)}{\frac{k2\pi}{T}} \right] \\
 &= \frac{80\pi^2}{T^2} \left[\frac{-\frac{T}{4} \cos\left(\frac{k\pi}{2}\right)}{\frac{k2\pi}{T}} + \frac{\sin\left(\frac{k\pi}{2}\right)}{\frac{k2\pi}{T}} \right] \\
 &= \frac{80\pi^2}{T^2} \cdot \frac{T^2}{k^2 \frac{4}{\pi^2}} \sin\left(\frac{k\pi}{2}\right) = \frac{20}{k^2} (-1)^{k+1}
 \end{aligned}$$

$$i_g(t) = \sum_{k=1,3,5}^{\infty} \frac{20}{k^2} \sin\left(\frac{k2\pi t}{T}\right) \quad \frac{10}{.4} = \frac{100}{4} = 25$$

fifth harmonic

$$i_5(t) = \frac{20}{25} \sin\left(\frac{5 \cdot 2\pi t}{0.4\pi}\right) = \frac{4}{5} \sin 25t$$

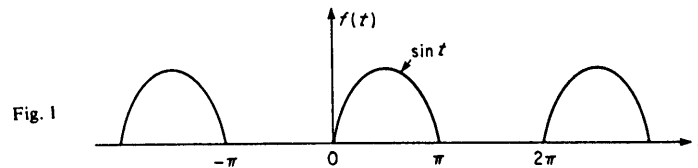
$$i_5(t) = 0.8 \sin 25t$$



$$5\omega_0 = 5 \frac{2\pi}{0.4\pi} = \frac{10}{.4} = 25$$

$$\begin{aligned}
 Z &= \frac{40(5 + j25)}{40 + 5 + j25} \\
 &= \frac{40}{200} \frac{(1 + j5)}{(9 + j5)} = \frac{40(1 + j5)}{9 + j5}
 \end{aligned}$$

Find the Fourier series of the half-wave rectified sinusoid as shown in Fig. 1.



Solution: The function $f(t)$ can be represented over one period as

$$f(t) = \begin{cases} \sin t & 0 \leq t < \pi \\ 0 & \pi \leq t < 2\pi \end{cases}$$

Since there is no half-wave symmetry we can expect a d.c. value. Hence,

$$a_0 = \frac{1}{T} \int_0^T f(t) dt = \frac{1}{2\pi} \int_0^{\pi} \sin t dt + \frac{1}{2\pi} \int_{\pi}^{2\pi} 0 dt$$

$$a_0 = \frac{1}{2\pi} [-\cos t]_0^{\pi} = \frac{1}{2\pi} [1 + 1] = \frac{1}{\pi}.$$

However we cannot say that the function has odd or even symmetry. Therefore, we must determine a_n and b_n .

The Fourier representation of a periodic function is

$$a_0 + \sum_{n=1}^{\infty} (a_n \cos n\omega_0 t + b_n \sin n\omega_0 t)$$

where

$$a_n = \frac{2}{T} \int_0^T f(t) \cos n\omega_0 t dt$$

and

$$b_n = \frac{2}{T} \int_0^T f(t) \sin n\omega_0 t dt.$$

First we find

$$b_n = \frac{2}{2\pi} \int_0^{\pi} \sin(t) \sin(nt) dt; \quad \omega_0 = 1$$

by the trigonometric function-product relationship

$$\sin t \sin nt = \frac{1}{2} \cos(t-nt) - \frac{1}{2} \cos(t+nt).$$

We obtain

$$b_n = \frac{1}{\pi} \int_0^{\pi} \left[\frac{1}{2} \cos t(1-n) - \frac{1}{2} \cos t(1+n) \right] dt$$

$$b_n = \frac{1}{\pi} \left[\frac{1}{2(1-n)} \sin t(1-n) - \frac{1}{2(1+n)} \sin t(1+n) \right]_0^{\pi}$$

$$b_n = \frac{1}{\pi} \left[\frac{1}{2(1-n)} \sin(\pi-n\pi) - \frac{1}{2(1+n)} \sin(\pi+n\pi) - 0 + 0 \right]$$

$$b_n = \frac{1}{2\pi} \left(\frac{1}{1-n} \sin(\pi-n\pi) - \frac{1}{1+n} \sin(\pi+n\pi) \right).$$

When we substitute any positive value for n into the above expression we obtain $b_n = 0$; for $n = 1$ we obtain the undetermined form $\frac{0}{0}$ for the first term. Using L'Hospital's rule we can evaluate $\frac{1}{1-n} \sin(\pi-n\pi)$ for $n = 1$ as follows:

$$\text{Let } g(n) = \frac{g_1(n)}{g_2(n)} = \frac{\sin(\pi-n\pi)}{1-n}$$

$$\text{where } g_1(n) = \sin(\pi-n\pi) \quad \text{and} \quad g_2(n) = 1-n.$$

By L'Hospital's rule we can evaluate

$$G(n) = \frac{g_1'(n)}{g_2'(n)} = \frac{-\pi \cos(\pi-n\pi)}{-1}.$$

If $G(1)$ exists then $g(1) = G(1)$. Hence.

$$g(1) = \pi \cos(\pi-\pi) = \pi \quad \text{and}$$

$$b_1 = \frac{1}{2\pi} (\pi) = \frac{1}{2}.$$

The only sine component in the Fourier series is $\frac{1}{2} \sin t$. We proceed to find a_n :

$$a_n = \frac{1}{\pi} \int_0^{\pi} \sin(t) \cos(nt) dt$$

$$a_n = \frac{1}{\pi} \int_0^{\pi} \left[\frac{1}{2} \sin t(1+n) + \frac{1}{2} \sin t(1-n) \right] dt$$

$$a_n = -\frac{1}{2\pi} \left[\frac{1}{1+n} \cos t(1+n) + \frac{1}{1-n} \cos t(1-n) \right]_0^{\pi}$$

$$a_n = -\frac{1}{2\pi} \left[\frac{1}{1+n} \cos(\pi+n\pi) + \frac{1}{1-n} \cos(\pi-n\pi) \right. \\ \left. - \left(\frac{1}{1+n} + \frac{1}{1-n} \right) \right].$$

When $n = 1$ we obtain

$$a_1 = -\frac{1}{2\pi} \left[\frac{1}{2} + \frac{1}{0} - \left(\frac{1}{2} + \frac{1}{0} \right) \right]$$

where the two indeterminate terms are both equal to zero by L'Hospital's rule, giving $a_1 = 0$.

When $n = 2$ we obtain

$$a_2 = -\frac{1}{2\pi} \left[-\frac{1}{3} + 1 - \frac{1}{3} + 1\right] = -\frac{2}{3\pi}.$$

When $n = 3$ we again find

$$a_3 = -\frac{1}{2\pi} \left[\frac{1}{4} - \frac{1}{3} - \frac{1}{4} + \frac{1}{3}\right] = 0.$$

Continuing in this way we find that for all odd harmonics ($n = 1, 3, 5, \dots$) a_n is zero and all even harmonics ($n = 2, 4, 6, \dots$)

$$a_n = -\frac{1}{2\pi} \left[-\frac{1}{1+n} - \frac{1}{1-n} - \frac{1}{1+n} - \frac{1}{1-n}\right]$$

$$a_n = -\frac{1}{2\pi} \left[-\frac{2}{1+n} - \frac{2}{1-n}\right] = \frac{1}{2\pi} \left[\frac{2}{1+n} + \frac{2}{1-n}\right]$$

$$a_n = \frac{1}{2\pi} \left[\frac{2(1-n)+2(1+n)}{n^2-1}\right] = \frac{2}{\pi} \frac{1}{1-n^2}.$$

Hence, we can express the half-wave rectified sine wave as

$$f(t) = \frac{1}{\pi} + \frac{1}{2} \sin t + \frac{2}{\pi} \sum_{n=2,4,6,\dots} \frac{1}{1-n^2} \cos nt.$$