

$$\therefore \frac{\partial^2 V^+}{\partial z^2} = \frac{1}{u^2} \frac{\partial^2 V}{\partial s^2}$$

$$\frac{\partial V^+}{\partial t^2} = \frac{\partial^2 V^+}{\partial s^2}$$

$$\text{or. } u^2 \frac{\partial^2 V^+}{\partial z^2} = \frac{\partial^2 V^+}{\partial t^2}$$

$$\text{or } \frac{\partial V^+}{\partial z^2} = \frac{1}{u^2} \frac{\partial^2 V^+}{\partial t^2}$$

Helmholtz equation

$$\nabla^2 \xi = \gamma^2 \frac{\partial^2 \xi}{\partial t^2}$$

$$\frac{\partial^2 \xi}{\partial z^2} = \gamma^2 \frac{\partial^2 \xi}{\partial t^2}$$

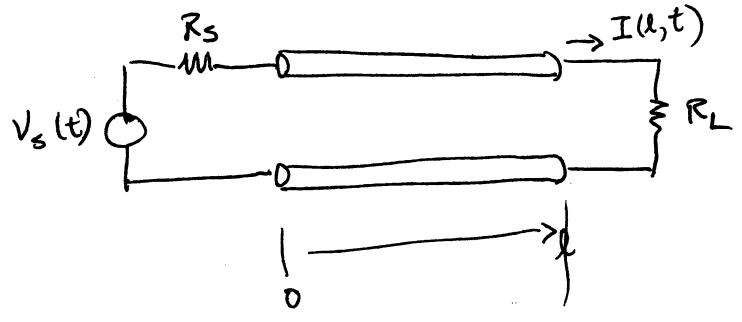
just as for traveling waves  $V$  and  $I$  must be related

$$I^+ \left( t - \frac{z}{u} \right) = \frac{V^+ \left( t - \frac{z}{u} \right)}{R_c}$$

$$I^- \left( t + \frac{z}{u} \right) = - \frac{V^- \left( t + \frac{z}{u} \right)}{R_c}$$

where  $R_c = \sqrt{\frac{L}{C}}$  } will not prove this.

consider the problem of a line connected to a load.



what is  $V(l,t)$

$$V(l,t) = R_L I(l,t)$$

in general this gives rise to forward & backward traveling waves, why.

$$\left. \begin{array}{l} \text{forward only} \quad V^+(t - \frac{l}{u}) = R_c I^+(t - \frac{l}{u}) \\ \text{backward only} \quad V^-(t + \frac{l}{u}) = -R_c I^-(t + \frac{l}{u}) \end{array} \right\} \text{transmission line}$$

$$V(l,t) = R_L I(l,t) \quad \left. \right\} \text{load}$$

Neither line equation describes the load unless  $R_L = R_c$

If  $R_L = R_c$  forward satisfies the load equation, but not the reverse.

just as for plane waves we could set this up and solve

$$\left. \begin{array}{l} \text{transmitted} \left\{ \begin{array}{l} V(l,t) = V^+(t - \frac{l}{u}) + V^-(t + \frac{l}{u}) \\ \quad = V^+(t - \frac{l}{u}) (1 + \Gamma_L) \quad \text{where} \quad \Gamma_L = \frac{V^-(t + \frac{l}{u})_{ref}}{V^+(t - \frac{l}{u})_{inc}} \\ I(l,t) = I^+(t - \frac{l}{u}) + I^-(t + \frac{l}{u}) \\ \quad = \frac{V^+(t - \frac{l}{u})}{R_c} - \frac{V^-(t + \frac{l}{u})}{R_c} \\ \quad = \frac{1}{R_c} V^+(t - \frac{l}{u}) [1 - \Gamma_L] \end{array} \right. \end{array} \right.$$

and we could even define a current reflection equation.

$$\text{if } v(l, t) = R_L I(l, t)$$

$$\text{where } v(l, t) = v^+ \left( t - \frac{l}{u} \right) (1 + \Gamma_L)$$

$$I(l, t) = \frac{1}{R_c} v^+ \left( t - \frac{l}{u} \right) (1 - \Gamma_L)$$

$$\text{then } \cancel{v^+ \left( t - \frac{l}{u} \right) (1 + \Gamma_L)} = R_L \frac{1}{R_c} \cancel{v^+ \left( t - \frac{l}{u} \right) (1 - \Gamma_L)}$$

$$(1 + \Gamma_L) = \frac{R_L}{R_c} (1 - \Gamma_L)$$

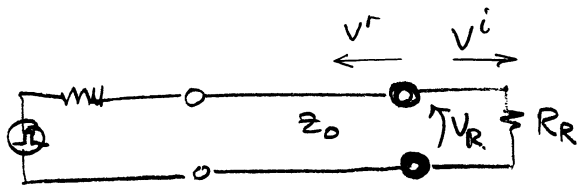
$$R_c + R_c \Gamma_L = R_L - R_L \Gamma_L$$

$$R_c \Gamma_L + R_L \Gamma_L = R_L - R_c$$

$$\Gamma_L = \frac{R_L - R_c}{R_L + R_c}$$

for current  $\Gamma$  is of the opposite sign

$$\text{since } \frac{I^-(t + \frac{l}{u})}{I^+(t - \frac{l}{u})} = \frac{\frac{1}{R_c} v^-(t + \frac{l}{u})}{-\frac{1}{R_c} v^+(t - \frac{l}{u})} = -\Gamma$$



resistor.  $V_R = V_i + V_r$   
 $I_R = I_i + I_r$   
 $= \frac{V_i - V_r}{Z_0}$  impedance for negative traveling waves

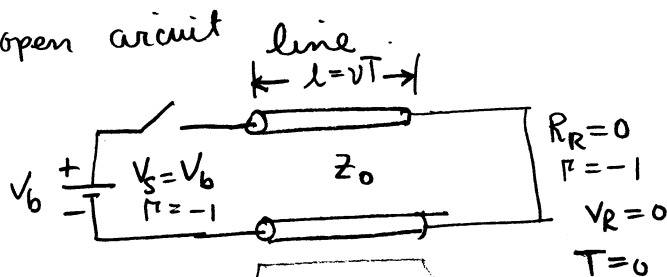
$i$  measured on line subtract.  
 $v$  measured to line.

$$\therefore R_R = \frac{V_R}{I_R} = \frac{V_i + V_r}{I_i + I_r} = \frac{V_i + V_r}{\frac{V_i - V_r}{Z_0}}$$

$$\Gamma_V = \frac{V_r}{V_i} = \frac{R_R - Z_0}{R_R + Z_0} \quad \Gamma_I = -\Gamma_V$$

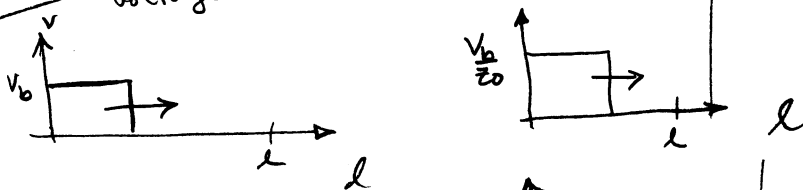
$$T = \frac{V_R}{V_i} = 1 + \Gamma = \frac{2R_R}{R_R + Z_0}$$

Example: open circuit

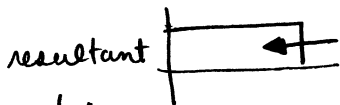
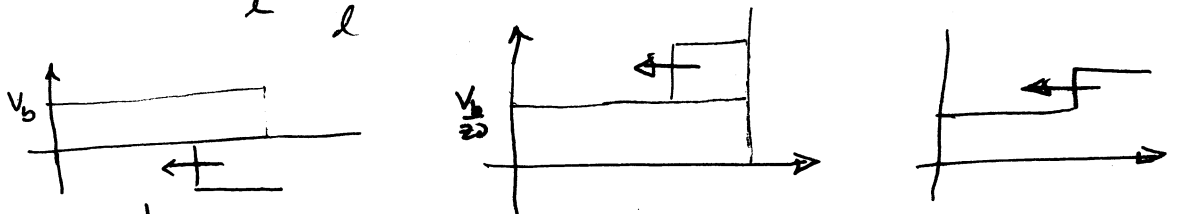


anywhere.  
 voltage and current on the line

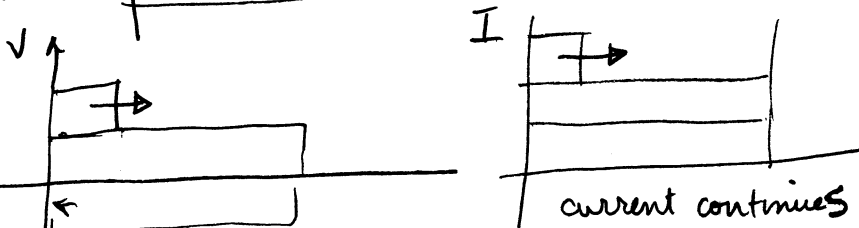
pulse moves out onto line.



as reflection  $\Gamma = -1$  so pulse reflects inverted



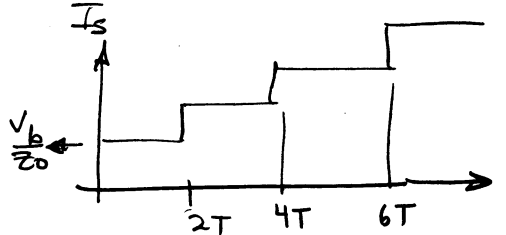
reflection at this end, battery is short  $\Gamma = -1$  cancels all pulses.



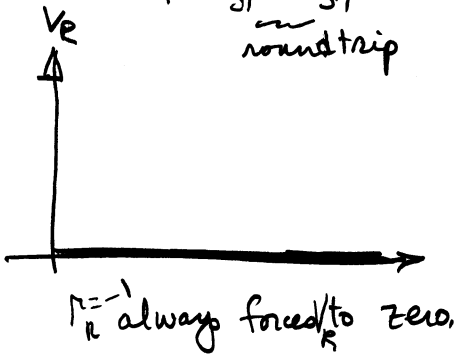
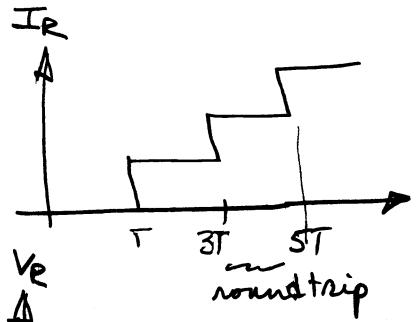
current continues to add up.

voltage goes between 0 and  $V_0$

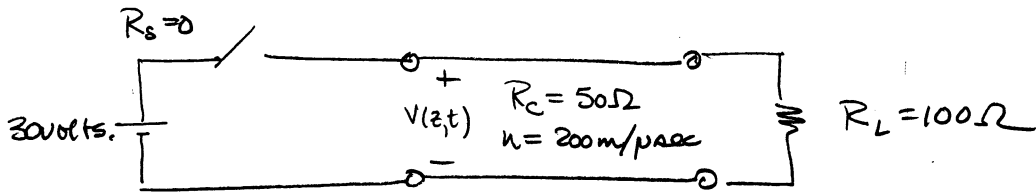
what happens at each end,



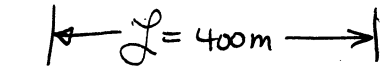
$\Gamma = -1$  also keeps voltages constant.



$\Gamma_R = -1$  always forced to zero.



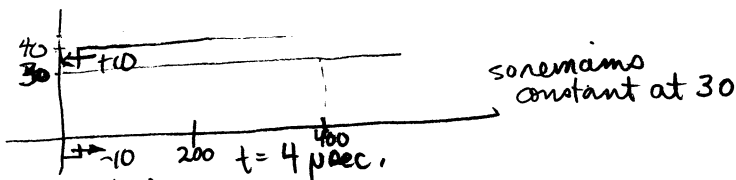
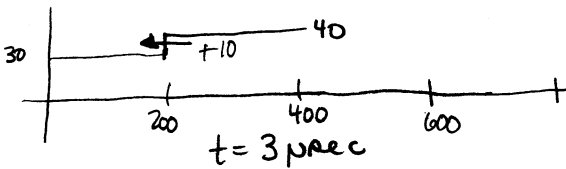
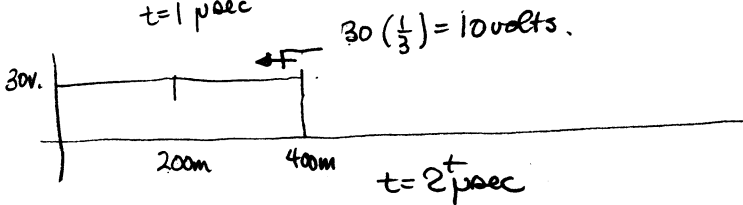
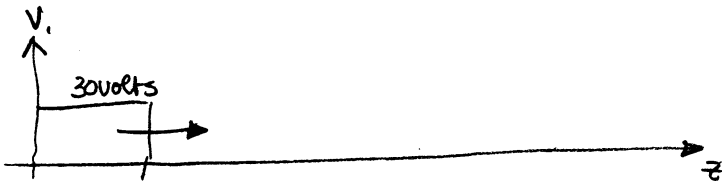
$$\Gamma_s = \frac{0 - 50}{0 + 50} = -1$$



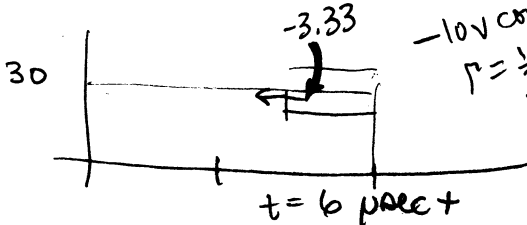
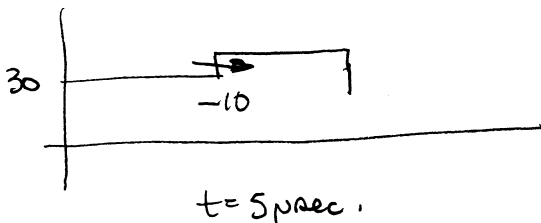
$$\Gamma_L = \frac{100 - 50}{100 + 50} = \frac{50}{150} = \frac{1}{3}$$

$$\Gamma_s = -1$$

$$\Gamma_L = \frac{1}{3}$$



$\Gamma = -1(10)$   
 what is incoming pulse  
 not total magnitude



Eventually This steadys down  
 to 30 volts.  
 $-10\text{V coming in}$   
 $\Gamma = \frac{1}{3} \therefore -3.33\text{ going back.}$

at each point in  
 time the total line  
 voltage is the sum  
 of the waves present on the  
 line.

transmission line equations

$$\frac{\partial V}{\partial z} = -L \frac{\partial I}{\partial t}$$

$$\frac{\partial I}{\partial z} = -C \frac{\partial V}{\partial t}$$

suppose  $V_s(t) = V_s \cos \omega t = \text{Re}(\hat{V}_s e^{j\omega t})$

if we assume  $V(z,t) = \hat{V}(z) e^{j\omega t}$  the transmission line eqns become:

$$\frac{d\hat{V}(z)}{dz} = -j\omega L \hat{I}(z)$$

$$\frac{d\hat{I}(z)}{dz} = -j\omega C \hat{V}(z)$$

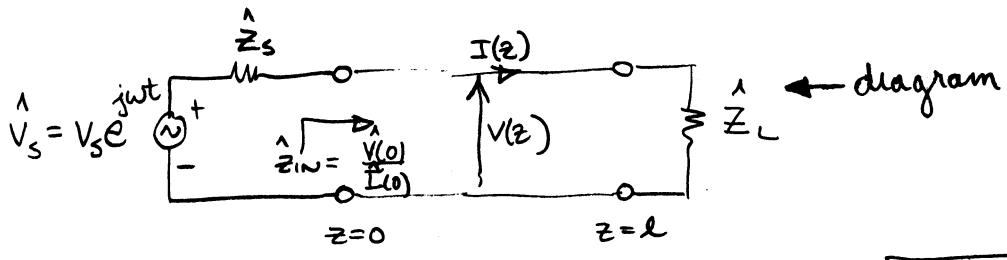
$$\therefore \frac{d^2 \hat{V}(z)}{dz^2} = -j\omega L \frac{d\hat{I}}{dz} = -j\omega L (-j\omega C \hat{V}(z))$$

$$\frac{d^2 \hat{V}(z)}{dz^2} = -\omega^2 LC \hat{V}(z) = -\frac{\omega^2}{u^2} \hat{V}(z) \quad \beta^2 \text{ lossless.}$$

$$\hat{V}(z) = \hat{V}^+ e^{-j\frac{\omega}{u}z} + \hat{V}^- e^{+j\frac{\omega}{u}z}$$

$$\hat{I}(z) = \hat{I}^+ e^{-j\frac{\omega}{u}z} + \hat{I}^- e^{+j\frac{\omega}{u}z}$$

$$= \frac{\hat{V}^+}{R_c} e^{-j\frac{\omega}{u}z} - \frac{\hat{V}^-}{R_c} e^{+j\frac{\omega}{u}z}$$



in general, at any point on the line

$$\hat{Z}(z) = \frac{\hat{V}(z)}{\hat{I}(z)}$$

in general, because of line-load-source discontinuities in impedance, we have forward and backward waves.

$$\hat{\Gamma}(z) = \frac{\hat{V}^-(z)}{\hat{V}^+(z)} \quad \begin{array}{l} \text{backward} \\ \text{forward} \end{array} \quad *$$

$$\hat{\Gamma}(z) = \frac{\hat{V}^- e^{+j\beta z}}{\hat{V}^+ e^{-j\beta z}} = \frac{\hat{V}^-}{\hat{V}^+} e^{j2\beta z}$$

using this definition we can write the waves (V & I) everywhere as.

$$\hat{V}(z,t) = \hat{V}^+ e^{-j\beta z} + \hat{V}^- e^{+j\beta z}$$

$$= \hat{V}^+ e^{-j\beta z} \left[ 1 + \frac{\hat{V}^- e^{+j\beta z}}{\hat{V}^+ e^{-j\beta z}} \right]$$

$$\hat{V}(z,t) = \hat{V}^+ e^{-j\beta z} [1 + \hat{\Gamma}(z)] \quad *$$

for current.

$$\hat{I}(z,t) = \frac{\hat{V}^+}{R_c} e^{-j\beta z} - \frac{\hat{V}^-}{R_c} e^{+j\beta z}$$

$$\hat{I}(z,t) = \frac{\hat{V}^+}{R_c} e^{-j\beta z} \left[ 1 - \frac{\hat{V}^-}{\hat{V}^+} \frac{e^{+j\beta z}}{e^{-j\beta z}} \right] \quad *$$

since we have  $\hat{V}$  and  $\hat{I}$

$$\hat{Z}_{in}(z) = \frac{\hat{V}(z)}{\hat{I}(z)} = \frac{V^+ e^{-j\beta z} [1 + \hat{\Gamma}(z)]}{\frac{V^+}{R_c} e^{-j\beta z} [1 - \hat{\Gamma}(z)]}$$

$$\hat{Z}_{in}(z) = R_c \frac{1 + \hat{\Gamma}(z)}{1 - \hat{\Gamma}(z)} \quad *$$

why is  $\hat{Z}_{in}$  not equal to just  $R_c$  because waves are distributed on the line. \*



$$\hat{\Gamma}(z) = \frac{\hat{V}^-}{\hat{V}^+} e^{j2\beta z}$$

and

$$Z_{IN}(z) = R_c \frac{1 + \hat{\Gamma}(z)}{1 - \hat{\Gamma}(z)}$$

are what we need to solve most problems as they relate the wave magnitudes, impedances and reflection coefficients. In fact they can be used to relate different points on the line.

suppose  $z=l$  (i.e. at the load)

$$Z_{IN}(z=l) = \hat{Z}_L = R_c \left[ \frac{1 + \hat{\Gamma}(z=l)}{1 - \hat{\Gamma}(z=l)} \right]$$

define  $Z_L$   
as impedance  
looking into load.

complex  
impedance of load

this allows us to solve for  $\hat{\Gamma}(z=l)$

define  $\hat{\Gamma}(z=l) \equiv \hat{\Gamma}_L$

then

$$\hat{\Gamma}_L = \frac{\hat{Z}_L - R_c}{\hat{Z}_L + R_c}$$

but

$$\hat{\Gamma}(z) = \frac{\hat{V}^-}{\hat{V}^+} e^{j2\beta z}$$

$$\hat{\Gamma}_L = \left[ \frac{\hat{V}^-}{\hat{V}^+} \right] e^{2j\beta l}$$

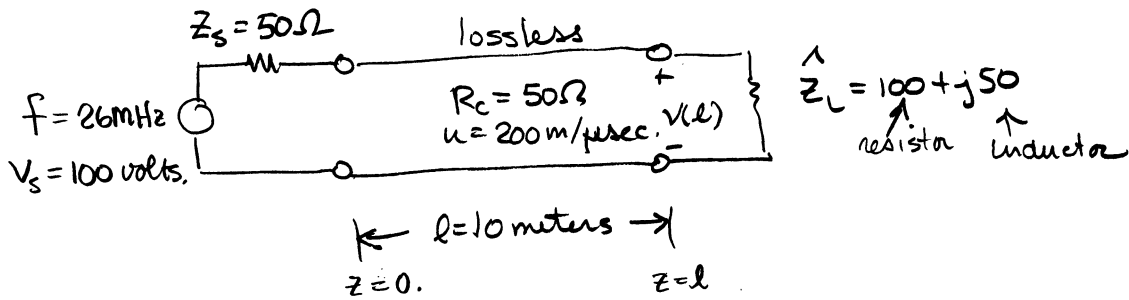
$$= \left[ \hat{\Gamma}(z) e^{-j2\beta z} \right] e^{j2\beta l}$$

$$\therefore \hat{\Gamma}(z) = \hat{\Gamma}_L e^{j2\beta(z-l)}$$

important result  $|\hat{\Gamma}(z)| = |\hat{\Gamma}_L|$

relates reflection coefficient at any point on line to that at load

Example:



Problem: determine the input impedance to the line and the phasor voltages at  $z=0$  and  $z=l$ .

① need for later

$$\beta = \frac{\omega}{u} = \frac{2\pi \times 26 \times 10^6 \text{ rad/sec}}{200 \text{ m/ps}} = 8.2 \times 10^{-1} \text{ rad/meter}$$

electrical length

$$2\beta l = (2) (8.2 \times 10^{-1} \frac{\text{rad}}{\text{m}}) (10 \text{ meters}) = 16.34 \text{ meters}$$

$$= 936^\circ = 936 - \left[ \frac{936}{360} \right] \times 360 = 216^\circ$$

② what is  $\hat{\Gamma}_L$  at load

$$\hat{\Gamma}_L = \frac{\hat{Z}_L - R_c}{\hat{Z}_L + R_c} = \frac{100 + j50 - 50}{100 + j50 + 50} = \frac{50 + j50}{150 + j50}$$

$$= 0.45 e^{j27^\circ}$$

③ this can be related to  $\hat{\Gamma}$  at  $z=0$

$$\hat{\Gamma}(z) = \hat{\Gamma}_L e^{+j2\beta(z-l)}$$

$$\hat{\Gamma}(z=0) = \hat{\Gamma}_L e^{-j2\beta l}$$

$$= 0.45 e^{j27^\circ} e^{-j216^\circ}$$

$$= 0.45 e^{-j189^\circ}$$

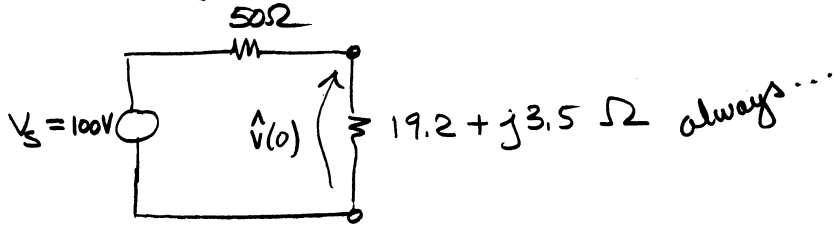
④ if we know  $\hat{\Gamma}$  at any point we know  $\hat{Z}_{IN}$

$$\hat{Z}_{IN}(z) = R_c \frac{1 + \hat{\Gamma}(z=l)}{1 - \hat{\Gamma}(z=l)}$$

$$\hat{Z}_{IN}(z=0) = R_c \frac{1 + \hat{\Gamma}(z=0)}{1 - \hat{\Gamma}(z=0)} = 50 \frac{1 + 0.45 e^{-j189^\circ}}{1 - 0.45 e^{-j189^\circ}}$$

$$= 19.53 e^{j10.4^\circ} = 19.2 + j3.5 \Omega$$

circuit generator sees is



$$\hat{V}(0) = \left[ \frac{19.2 + j3.5}{50 + 19.2 + j3.5} \right]_{100} = 28.2 e^{j7.5^\circ}$$

to get  $\hat{V}(z=l)$  we need to know either  $V^+$  or  $V^-$  at the load, as we know  $\hat{V}(z=0)$

$$\text{at } z=0 \quad \hat{V}(z) = \hat{V}^+ e^{-j\beta z} [1 + \hat{\Gamma}(z)]$$

$$28.2 e^{j7.5^\circ} = \hat{V}^+ (1) [1 + 0.45 e^{-j189^\circ}]$$

⑤ find  $V^+$  at  $z=0$   $V^+ = 50 e^{j0.033^\circ}$

$$\therefore \hat{V}(z=l) = \hat{V}^+ e^{-j\beta l} [1 + \hat{\Gamma}(z=l)]$$

$$= 50 e^{j0.033^\circ} e^{-j108^\circ} [1 + 0.45 e^{j27^\circ}]$$

⑥ then find  $\hat{V}(z=l) = 70.7 e^{-100^\circ}$

problem illustrated complexity of calculations.

need a faster way of relating line impedances.

combine  $\hat{z}_{IN}(z=l) = \hat{z}_L = R_c \frac{1 + \hat{\Gamma}(z=l)}{1 - \hat{\Gamma}(z=l)}$

$$\hat{\Gamma}_L = R_c \frac{1 + R_L}{1 - R_L}$$

$$\hat{\Gamma}_L = \hat{\Gamma}_L(z) e^{j2\beta(l-z)}$$

to get  $\hat{z}_{IN}(z) = R_c \frac{\hat{z}_L + jR_c \tan \beta(l-z)}{R_c + j\hat{z}_L \tan \beta(l-z)}$

so that in one step we can get

$$\hat{z}_{IN}(z=0) = R_c \frac{\hat{z}_L + jR_c \tan \beta l}{R_c + j\hat{z}_L \tan \beta l}$$

this is very easy to use if  $l$  is in wavelengths.

if  $z_L = 0$  a short

$$z_{IN}(z=0) = R_c \frac{jR_c \tan \beta l}{R_c} = jR_c \tan \beta l$$

but  $\beta = \frac{2\pi}{\lambda}$

if  $l = \frac{\lambda}{4} \Rightarrow \beta l = \frac{2\pi}{\lambda} \frac{\lambda}{4} = \frac{\pi}{2}$

$$z_{IN}(z=0) = \frac{jR_c \tan \frac{\pi}{2}}{j\omega L} \rightarrow \infty \quad \underline{\text{an open!}} \quad (\text{ac only})$$

pick  $z_L = \infty$

$$z_{IN}(z=0) = R_c \frac{1}{j \tan \beta l} = \frac{-jR_c}{j\omega C} \rightarrow 0 \quad \text{a short!} \quad (\text{ac only})$$

$$\frac{1}{j\omega C} = -\frac{j}{\omega C}$$

a quarter-wavelength of line transforms everything

suppose  $Z_L = j\omega L$  inductive load.

lines can act as impedance transformers.

$$Z_{IN}(z=0) = R_c \frac{j\omega L + jR_c \tan \frac{\pi}{2} \leftarrow \frac{\lambda}{4}}{R_c + j(j\omega L) \tan \frac{\pi}{2}} \rightarrow R_c \frac{jR_c}{-\omega L}$$

$$= -j \frac{R_c^2}{\omega L} \text{ (a capacitor)}$$

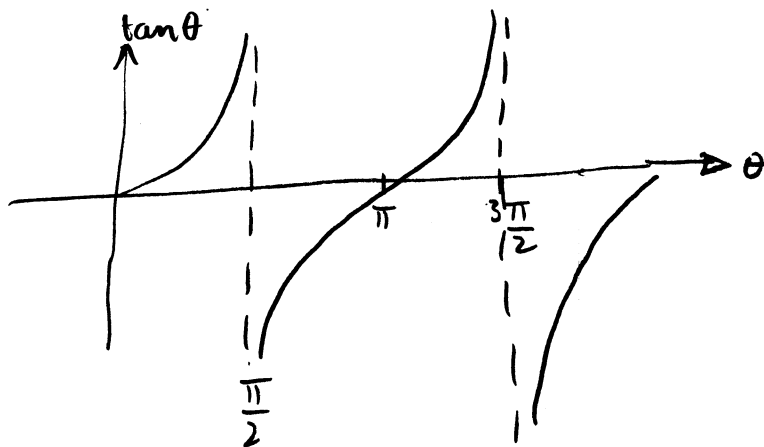
Not just a quarter wave line does this, any multiple of  $\frac{\lambda}{2} + \frac{\lambda}{4}$

$$\text{since } Z_{IN}(z=0) = R_c \frac{Z_L + jR_c \tan \beta l}{R_c + jZ_L \tan \beta l}$$

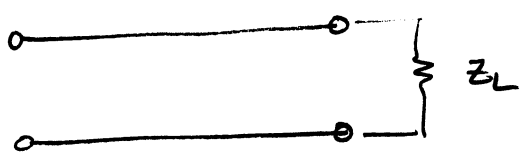
obviously,  $Z_{IN}$  repeats every  $\frac{\lambda}{2}$ .

$$\text{since } \beta l = \frac{2\pi}{\lambda} \cdot n \frac{\lambda}{2} = n\pi$$

because

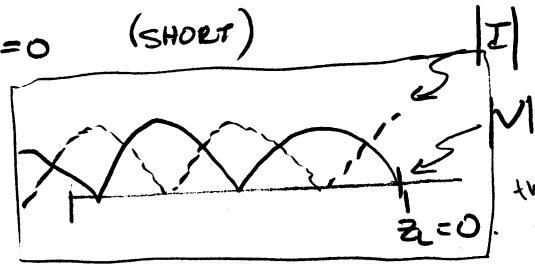


this can also be seen in the line voltages.



line voltages also repeat every  $\frac{\lambda}{2}$ . Will show this later.

if  $Z_L = 0$  (SHORT)



there are  $e^{-j\beta z}$  terms here...

are voltage and current  $90^\circ$  out of phase? YES

if  $Z_L = 0$

$$\Gamma_L = \frac{0 - R_c}{0 + R_c} = -1$$

$$\hat{V}(z,t) = \hat{V}^+ e^{-j\beta z} [1 + \Gamma(z)]$$

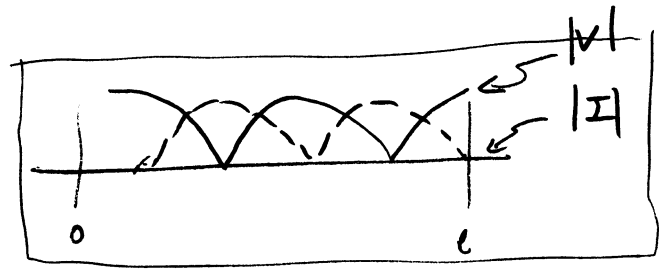
$$\hat{V}(l,t) = \hat{V}^+ e^{-j\beta z} [1 - 1]$$

on the other hand

$$\hat{I}(z,t) = \frac{\hat{V}^+}{R_c} e^{-j\beta z} [1 - \Gamma(z)]$$

$$\text{or } \hat{I}(l,t) = \frac{\hat{V}^+}{R_c} e^{-j\beta l} [1 + 1]$$

if  $Z_L = \infty$  (OPEN)



$$\beta \lambda = 2\pi$$

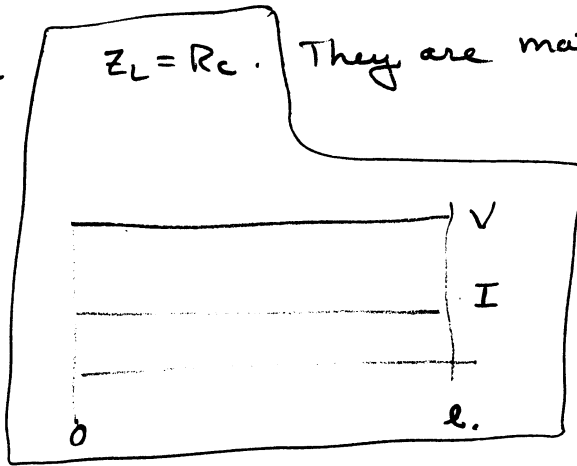
$$\lambda = \frac{c}{f}$$

$$= \frac{3 \times 10^8 \text{ cm/sec}}{2 \times 10^9 \text{ /sec}}$$

$$= 1.5 \times 10^{-1} \text{ cm}$$

$$\approx 1.5 \text{ cm}$$

suppose  $Z_L = R_c$ . They are matched.



how to prove this, easy.

$$\Gamma_L = \frac{R_c - R_c}{R_c + R_c} = 0.$$

$$\therefore \hat{V}(l, t) = \hat{V}^+ e^{-j\beta l}$$

$$\hat{I}(l, t) = \frac{\hat{V}^+}{R_c} e^{-j\beta l}.$$

$$\hat{V}(z) = \hat{V}^+ e^{-j\beta z}$$

$$\hat{I}(z) = \frac{\hat{V}^+}{R_c} e^{-j\beta z}.$$

$$\hat{V}(z) = \hat{V}(l, t) e^{+j\beta l} e^{-j\beta z}$$

$$\hat{I}(z) = \frac{\hat{V}(l, t) e^{j\beta l}}{R_c} e^{-j\beta z}$$

$$|\hat{V}(z)| = |\hat{V}(l, t)|$$

$$|\hat{I}(z)| = \frac{|\hat{V}(l, t)|}{R_c}$$

just as we expected. ■

crank diagram

recall  $\hat{V}(z) = \hat{V}^+ e^{-j\beta z} [1 + \hat{\Gamma}(z)]$

we were plotting  $|\hat{V}(z)|$

voltage on line

$\therefore |\hat{V}(z)| = |\hat{V}^+| |1 + \hat{\Gamma}(z)|$

this is independent of z.

want to look at z-dependence of this.

recall  $\hat{\Gamma}(z) \triangleq \frac{\hat{V}^-}{\hat{V}^+} e^{+j2\beta z}$

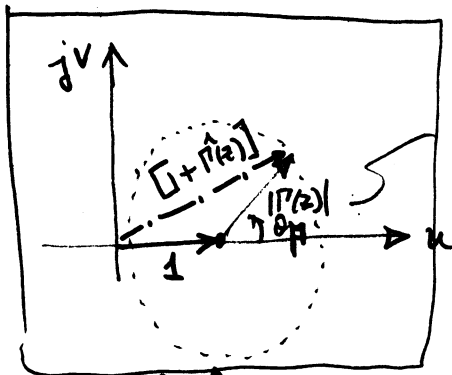
so write  $\hat{\Gamma}(z) = |\hat{\Gamma}(z)| e^{j\theta_{\Gamma}}$

$|\hat{\Gamma}(z)| = \left| \frac{V_m^- e^{+j\theta^-}}{V_m^+ e^{+j\theta^+}} \right| = \frac{V_m^-}{V_m^+}$

how about  $\theta_{\Gamma} = e^{j\theta^-} e^{-j\theta^+} e^{j2\beta z} = e^{j\theta_{\Gamma}}$

$\therefore \theta_{\Gamma} = 2\beta z + (\theta^- - \theta^+)$

plot  $(1 + \hat{\Gamma}(z))$  in  $u + jv$  plane



From definition  $\Gamma(z)$  is periodic in  $z$ , i.e. every time  $2\beta z = n2\pi$   
 $\alpha\beta z = n\pi$ .

$\frac{2\pi}{\lambda} z = n\pi$   
 $z = n \frac{\lambda}{2}$

$\therefore$  irregardless of  $z_L$

voltage is periodic at  $\frac{\lambda}{2}$

same for current.

exact location is dependent on  $z_L$

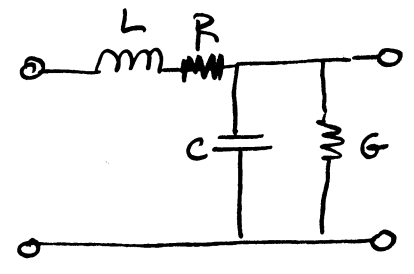
show voltage is periodic.



A systems look at a transmission line.

$$\frac{\partial V}{\partial z} = -RI - L \frac{\partial I}{\partial t}$$

$$\frac{\partial I}{\partial z} = -GV - C \frac{\partial V}{\partial t}$$



suppose  $V(0,t) = \begin{cases} V_0 & 0 < t < T \\ 0 & t > T \end{cases}$

Pick  $R = G = 0.$

$$\frac{\partial V}{\partial z} = -L \frac{\partial I}{\partial t} \quad \frac{\partial I}{\partial z} = -C \frac{\partial V}{\partial t}$$

boundary conditions

$$V(x,0) = I(x,0) = 0 \quad V(0,t) = \begin{cases} V_0 & 0 < t < T \\ 0 & t > T \end{cases}$$

let  $\tilde{V}(x,s) = \mathcal{L}\{V(x,t)\}$   $\tilde{I}(x,s) = \mathcal{L}\{I(x,t)\}$

$$\frac{d\tilde{V}}{dz} = -L \left\{ s\tilde{I} - \overset{0}{I(x,0)} \right\} \quad \frac{d\tilde{I}}{dz} = -C \left\{ s\tilde{V} - \overset{0}{V(x,0)} \right\}$$

initial value theorem.

$$\therefore \frac{d\tilde{V}}{dz} = -Ls\tilde{I} \quad \frac{d\tilde{I}}{dz} = -Cs\tilde{V}$$

$$\frac{d^2\tilde{V}}{dz^2} = -Ls \frac{d\tilde{I}}{dz} = -Ls(-Cs\tilde{V}) = +LCs^2\tilde{V}$$

what is the general solution of this equation...?

$$\frac{d^2\tilde{V}}{dz^2} = \gamma^2\tilde{V} \quad \text{where } \gamma^2 = LCs^2.$$

general solution is  $\tilde{V}(x,s) = Ae^{-\gamma x} + Be^{+\gamma x}$

and A and B can be found from the boundary conditions.

suppose boundedness picks  $B=0$ , i.e. limit magnitude

write  $v(0,t) = p(t)$ .

Then  $\mathcal{L}[v(0,t)] = \tilde{V}(0,s) = p(s)$ .

$$\tilde{V}(x,s) = A e^{-\sqrt{LCs^2} x}$$

$$\tilde{V}(0,s) = A = p(s)$$

$$\therefore \tilde{V}(x,s) = p(s) e^{-\sqrt{LCs^2} x}$$

$$\begin{aligned} & \mathcal{L}^{-1} \left[ e^{-\sqrt{LCs^2} x} \right] \\ &= \mathcal{L}^{-1} \left[ e^{-\frac{s x}{u}} \right] \end{aligned}$$

but this is simply a delay.  
of  $\frac{x}{u}$ .

$$\text{so } v(x,t) = p\left(t - \frac{x}{u}\right)$$

not necessarily a delay  
if  $R$  or  $G \neq 0$ .

degree of mismatch

voltage standing wave ratio

why is this useful. for a perfect line (matched)

$$|\hat{V}|_{\max} = |\hat{V}|_{\min}$$

for any other situation

$$|\hat{V}|_{\max} \neq |\hat{V}|_{\min}$$

∴ use this as a convenient indicator of mismatch...

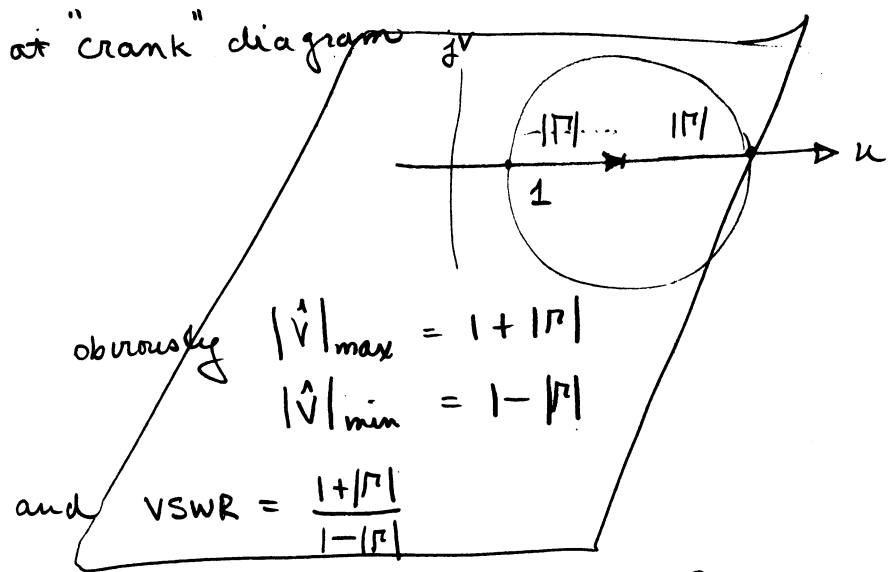
$$\boxed{VSWR = \frac{|\hat{V}|_{\max}}{|\hat{V}|_{\min}}}$$

and VSWR between 1 and ∞.

for a matched line VSWR = 1.

for  $R_L = 0$  or  $R_L = \infty$  the minimum is zero and  $VSWR \rightarrow \infty$

look at "crank" diagram



but this becomes very easy to measure if we recall

$$\hat{\Gamma}(z) = \hat{\Gamma}_L e^{j2\beta(z-l)}$$

$$\text{then } |\hat{\Gamma}(z)| = |\hat{\Gamma}_L|$$

$$\therefore VSWR = \frac{1 + |\hat{\Gamma}_L|}{1 - |\hat{\Gamma}_L|}$$

VSWR is often easily measured as an indicator of  $\Gamma_L$

power on a transmission line.

in the +z direction time averaged power

$$P_{avg+z} = \frac{1}{2} \text{Re} [\hat{V}(z) \hat{I}^*(z)]$$

this is in both directions.

$$\left\{ \begin{array}{l} \hat{V}(z) = \hat{V}_+ e^{-j\beta z} [1 + \hat{\Gamma}(z)] \\ \hat{I}(z) = \frac{\hat{V}_+}{R_c} e^{-j\beta z} [1 - \hat{\Gamma}(z)] \end{array} \right. \quad \hat{V}^*(z) = \frac{\hat{V}_+^*}{R_c} e^{+j\beta z} [1 - \hat{\Gamma}^*(z)]$$

$$P_{avg+z} = \frac{1}{2} \text{Re} \left[ \cancel{(\hat{V}_+ e^{-j\beta z})} (1 + \hat{\Gamma}(z)) \frac{\hat{V}_+^*}{R_c} e^{+j\beta z} (1 - \hat{\Gamma}^*(z)) \right]$$

$$= \frac{1}{2} \text{Re} \left[ \frac{|\hat{V}_+|^2}{R_c} [1 + \hat{\Gamma}(z)] [1 - \hat{\Gamma}^*(z)] \right]$$

$$= \frac{1}{2} \frac{|\hat{V}_+|^2}{R_c} \text{Re} \left[ 1 + \underbrace{\hat{\Gamma}(z) - \hat{\Gamma}^*(z)}_{\text{imaginary only}} - \hat{\Gamma}(z) \hat{\Gamma}^*(z) \right]$$

consider, if  $\Gamma = a + jb$   
 $\Gamma^* = a - jb$

and  $\Gamma - \Gamma^* = j2b$

$$\therefore P_{avg+z} = \frac{1}{2} \frac{|\hat{V}_+|^2}{R_c} (1 - |\hat{\Gamma}|^2)$$

but  $|\hat{\Gamma}|^2 = |\hat{\Gamma}_L|^2$

$$P_{avg+z} = \frac{1}{2} \frac{|\hat{V}_+|^2}{R_c} (1 - |\hat{\Gamma}_L|^2)$$

depending on the magnitude of  $\Gamma_L$

there are imaginary terms which were ignored since  $P_{avg} = \frac{1}{2} \text{Re} [E \times H^*]$

we can have no power delivered to the load.

$$\begin{aligned} \text{if } R_L = 0 & \quad \Gamma_L = -1 \\ R_L = \infty & \quad \Gamma_L = +1 \end{aligned}$$

$$\text{then } P_{\text{AVG}+z} = 0$$

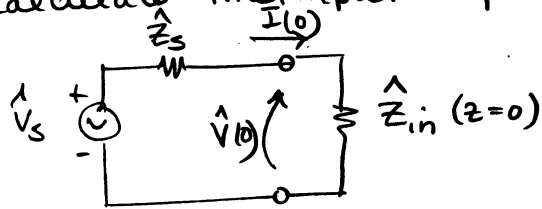
max power transfer ONLY if  $\Gamma_L = 0$ .

Suppose we want the power delivered to the load. (if matched).  
if matched  
Ohm's Law.

$$P_{\text{AVG}+z} = \frac{1}{2} \frac{|V_m^+|^2}{R_c} \quad \text{if } R_L = R_c.$$

how do we find power delivered to load for general case.

① calculate line input impedance  $Z_{in}$



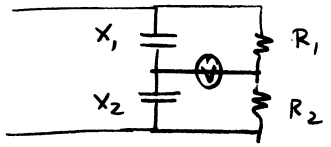
$$\begin{aligned} P_{in} &= \frac{1}{2} \text{Re} \left[ \hat{V}(z=0) \hat{I}^*(z=0) \right] \\ &= \frac{1}{2} \text{Re} \left[ \hat{V}(z=0) \frac{\hat{V}^*(z=0)}{\hat{Z}_{in}^*(z=0)} \right] \\ P_{in} &= \frac{1}{2} \frac{|\hat{V}(z=0)|^2}{\text{Re} \left[ \frac{1}{\hat{Z}_{in}^*(z=0)} \right]} \end{aligned}$$

$$\textcircled{2} \quad \hat{V}(z=0) = \frac{\hat{Z}_{in}(z=0)}{\hat{Z}_{in}(z=0) + \hat{Z}_s} \hat{V}_s$$

③ if the line is lossless  
 $P_{in} = P_{\text{LOAD}}$ .

# How do you measure VSWR

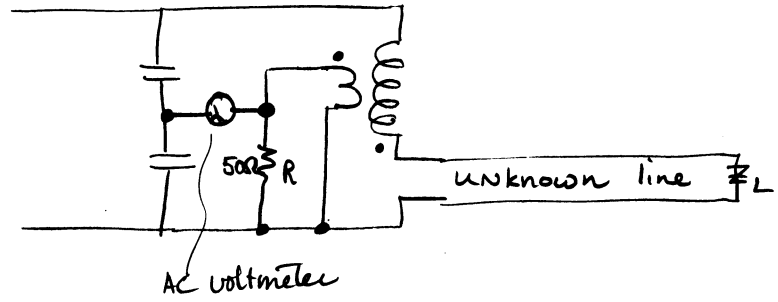
A.C. bridge technique



if 
$$\frac{X_2}{X_1 + X_2} = \frac{R_2}{R_1 + R_2}$$

Then  $V = 0$ .

a.c. bridge ...

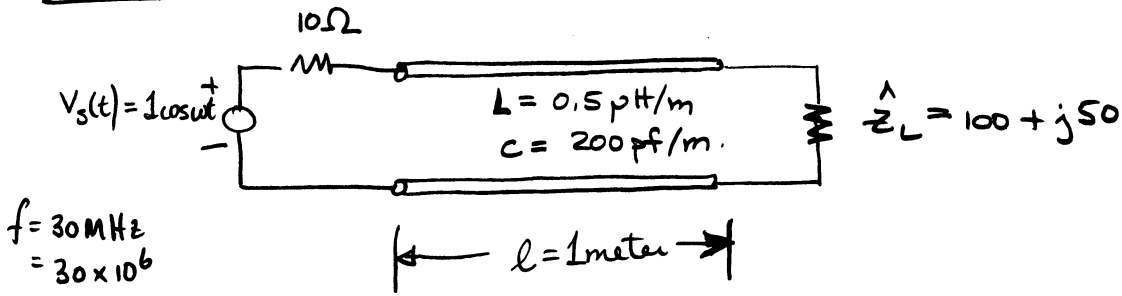


note  $R$  is real only.

if  $Z_L$  is real voltage across  $R$  will be  $180^\circ$  out of phase with voltage across bridge and  $V = 0$  indicating match.

if  $Z_L$  is complex then  $V \neq 0$

Example:



① what is  $R_c$  and  $u$ ?

$$R_c = \sqrt{\frac{L}{C}} = \sqrt{\frac{0.5 \times 10^{-6}}{200 \times 10^{-12}}} = 50 \Omega.$$

$$u = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{\frac{1}{2} \times 10^{-6} \times 200 \times 10^{-12}}} = \frac{1}{\sqrt{10^2 \times 10^{-18}}} = \frac{1}{10^{-10}}$$

$$= 10^8 \text{ m/sec or } 100 \text{ meters}/\mu\text{sec}.$$

② what is the electrical length of the line?

First, what is  $\lambda$ .

$$\beta = \frac{2\pi}{\lambda} = \frac{\omega}{u} \quad \therefore \lambda = \frac{2\pi u}{\omega} = \frac{2\pi u}{2\pi f} = \frac{u}{f}$$

$$= \frac{10^8 \text{ m/sec}}{30 \times 10^6 / \text{sec}} = \frac{100}{30} \text{ meters}$$

$$= 3.333 \text{ meters}.$$

$$\therefore l = \frac{1 \text{ meter}}{3.3333 \text{ etc.}} = 0.3 \lambda$$

③ what is  $\hat{\Gamma}_L$ ?

$$\hat{\Gamma}_L = \frac{Z_L - R_c}{Z_L + R_c} = \frac{100 + j50 - 50}{100 + j50 + 50} = \frac{50 + j50}{150 + j50} = 0.45 e^{j27^\circ}$$

$$\beta l = \frac{2\pi}{\lambda} \cdot 0.3 \lambda = 0.6 \pi$$

to get the power to the load... we need the input impedance.

We can get the input impedance by relating  $\Gamma_L$  to the input reflection coefficient.

$$\hat{\Gamma}(z) = \hat{\Gamma}_L e^{j2\beta(z-l)}$$

$$\begin{aligned} \therefore \hat{\Gamma}(0) &= 0.45 e^{j27^\circ} e^{-j2\beta l} \\ &= 0.45 e^{j27^\circ} e^{-j2\beta l} \end{aligned}$$

$$2\beta l = 2 \cdot \frac{2\pi}{\lambda} \cdot 0.3\lambda = 4\pi(0.3) = 1.2\pi = 216^\circ$$

$$\hat{\Gamma}(0) = 0.45 e^{j27^\circ} e^{-j216^\circ} = 0.45 e^{-189^\circ}$$

$$\hat{Z}_{in}(z=0) = R_C \frac{1 + \Gamma(z=0)}{1 - \Gamma(z=0)}$$



to get the input impedance.

$$\hat{Z}_{in}(z) = R_c \frac{Z_L + j R_c \tan \beta(l-z)}{R_c + j Z_L \tan \beta(l-z)}$$

$$\text{at } z=0 \quad \hat{Z}_{in}(0) = R_c \frac{Z_L + j R_c \tan \beta l}{R_c + j Z_L \tan \beta l}$$

$$= (50 \Omega) \frac{100 + j 50 + j 50 \tan(216^\circ)}{50 + j (100 + j 50) \tan(216^\circ)}$$

$$= 19.5 e^{j 10^\circ}$$

what is the input voltage?

$$\hat{V}(0) = \frac{\hat{Z}_{in}(0)}{\hat{Z}_s + \hat{Z}_{in}(0)} \hat{V}_s = \frac{19.5 e^{j 10^\circ}}{10 + 19.5 e^{j 10^\circ}} 1 \text{ volt.} = 0.66 e^{j 3.5^\circ}$$

$$\hat{I}(0) = \frac{\hat{V}(0)}{\hat{Z}_{in}(0)} = \frac{0.66 e^{j 3.5^\circ}}{19.5 e^{j 10^\circ}} = 0.034 e^{-j 6.5^\circ}$$

what is our input power.

$$P_{AV+Z} = \frac{1}{2} \text{Re} [\hat{V}(0) \hat{I}^*(0)] = \frac{1}{2} \text{Re} [(0.66)(0.034) e^{-j 3.0^\circ}]$$

$$= 0.011 \text{ watts.}$$

and as long as the line is lossless

$$P_{LOAD} = 0.011 \text{ watts.}$$

Back in electrostatics we learned that  $\nabla^2\phi = -\frac{\rho}{\epsilon_0}$

For most problems,  $\rho = 0$  simplifying the problem.

There is a special class of problems for which  $\nabla^2\phi = 0$  and either  $\phi$  or  $\frac{\partial\phi}{\partial n}$  is specified on the boundaries. This is called a

boundary value problem with Dirichlet ( $\phi$ ), Neumann ( $\frac{\partial\phi}{\partial n}$ ) or mixed boundary conditions. There is a very powerful

method called separation of variables to solve such problems,

consider  $\nabla^2\phi$  in rectangular coordinates.

$$\nabla^2\phi = \frac{\partial^2\phi}{\partial x^2} + \frac{\partial^2\phi}{\partial y^2} + \frac{\partial^2\phi}{\partial z^2} \quad (1)$$

To solve this problem we assume that  $\phi$  can be written as

$$\phi = f(x)g(y)h(z). \quad (2)$$

This can be applied in any problem where the boundaries coincide with constant coordinate surfaces. Substituting (2) into (1)

$$gh \frac{\partial^2 f}{\partial x^2} + fh \frac{\partial^2 g}{\partial y^2} + fg \frac{\partial^2 h}{\partial z^2} = 0.$$

Dividing through by  $fgh$ .

$$\frac{1}{f} \frac{d^2 f}{dx^2} + \frac{1}{g} \frac{d^2 g}{dy^2} + \frac{1}{h} \frac{d^2 h}{dz^2} = 0$$

Each term is a function of only one variable so it is reasonable that each is a constant, a different constant, all of which must sum to zero.

$\downarrow$   
 $k_x^2$

$\downarrow$   
 $k_y^2$

$\downarrow$   
 $k_z^2$

$k_x^2, k_y^2$  and  $k_z^2$  are called separation constants because they result in three separate equations.

$$\frac{d^2 f}{dx^2} + k_x^2 f = 0$$

$$\frac{d^2 g}{dy^2} + k_y^2 g = 0$$

$$\frac{d^2 h}{dz^2} + k_z^2 h = 0$$

} we will pick  $k_x, k_y$  and  $k_z$  to reflect the boundary condition after we determine the solutions of these equations.

use  $p$  as an example

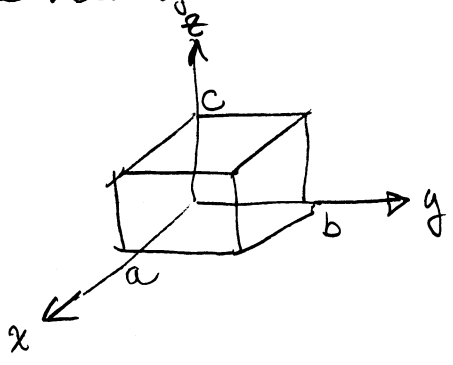
① if  $k^2 = 0$        $\frac{d^2 p}{dx^2} = 0$        $\frac{dp}{dx} = c_1$        $p(x) = c_1 x + c_2$       where  $c_1, c_2$  are constants

② if  $k^2 > 0$        $\frac{d^2 p}{dx^2} + k^2 p = 0$        $p(x) = c_1 \sin kx + c_2 \cos kx$

③ if  $k^2 < 0$        $\frac{d^2 p}{dx^2} + k^2 p = 0$        $p(x) = c_1 e^{-kx} + c_2 e^{+kx}$

picking say  $k_x = 0$  will result in  $k_y^2 + k_z^2 = 0$  and the equations for  $g(y)$  and  $h(z)$  will result in functions looking like the above. where we can pick either  $g$  to be exponential, or  $h$  to be exponential by choosing the sign of  $k_y^2$  or  $k_z^2$ .

Consider the rectangular Dirichlet Boundary-value problem.



boundary conditions

Let  $\phi$  be 0 volt on all sides except the top which is set to some  $V(x,y)$

at  $x=0, x=a \quad \phi \equiv 0 \quad \forall y, z \quad \therefore f(x) = \text{constant on these surfaces.}$

if  $k_x = 0$  easy to meet this criteria if  $C_1, C_2 = 0$ .

$k_x > 0$  ← this is the proper choice

$k_x < 0$  only if  $C_1, C_2 = 0$

$\therefore$  pick  $k_x > 0$  and see what happens.

$$\therefore f(x) = C_1 \sin k_x x + C_2 \cos k_x x$$

$$\text{as } f(0) = 0 \quad \therefore C_2 = 0.$$

$$\text{but } f(a) = 0 = C_1 \sin k_x a$$

$$\text{but } \sin k_x a = 0 \quad \text{for } k_x a = n\pi \quad \text{where } n = 1, 2, 3, \dots$$

$$\therefore k_x = \frac{n\pi}{a}$$

This type of problem has the general solution

$$f(x) = \sum_{n=1}^{\infty} C_n \sin \frac{n\pi}{a} x$$

We could also pick  $k_y > 0$  giving

$$g(y) = \sum_{m=1}^{\infty} C_m \sin \frac{m\pi}{b} y$$

if I pick  $k_x^2$  and  $k_y^2$ ,  $k_z^2$  is determined

$$k_x^2 + k_y^2 + k_z^2 = 0$$

$$k_z^2 = -(k_x^2 + k_y^2) = -\left(\frac{n^2\pi^2}{a^2} + \frac{m^2\pi^2}{b^2}\right)$$

equation becomes  $\frac{d^2p}{dz^2} - k^2 p = 0$   
 solutions  $e^{kz} + e^{-kz}$

$$\therefore k_z = \pm j \left[ \left(\frac{n\pi}{a}\right)^2 + \left(\frac{m\pi}{b}\right)^2 \right]$$

What solution is this?

$$h(z) = c_1 e^{-k_z z} + c_2 e^{k_z z}$$

since we often need  $h(z)=0$  for some  $z$  we instead pick the forms.

$$h(z) = c_1 \cosh k_z z + c_2 \sinh k_z z$$

↖ never goes to zero
↖ goes to zero

where  $\cosh x = \frac{1}{2}(e^x + e^{-x})$   
 $\sinh x = \frac{1}{2}(e^x - e^{-x})$

In our problem  $h(0)=0$  so  $\therefore c_1=0$ .

$\therefore$  our general solution is

$$\phi(x, y, z) = f(x)g(y)h(z) = \sum_{n=1}^{\infty} \sum_{m=1}^{\infty} A_n B_m \sin \frac{n\pi x}{a} \sin \frac{m\pi y}{b} \sinh k_z z$$

and the  $c_2$  for  $h(z)$  was incorporated into  $A_n B_m$ .

Now, how do we finish the problem.

WE CHEAT and use the result

$$\int_0^a \sin \frac{n\pi x}{a} \sin \frac{s\pi x}{a} dx = 0 \quad n \neq s \quad = \frac{a}{2} \quad \text{if } n=s$$

$$\int_0^b \sin \frac{m\pi y}{b} \sin \frac{s\pi y}{b} dy = 0 \quad m \neq s \quad = \frac{b}{2} \quad \text{if } m=s$$

What is our final B.C.'s

at  $z=c$  
$$V(x,y) = \sum_{n=1}^{\infty} \sum_{m=1}^{\infty} A_n B_m \sin \frac{n\pi x}{a} \sin \frac{m\pi y}{b} \underbrace{\sinh \Gamma_{mn} c}$$

$$\Gamma_{mn} = \sqrt{\left(\frac{n\pi}{a}\right)^2 + \left(\frac{m\pi}{b}\right)^2}$$

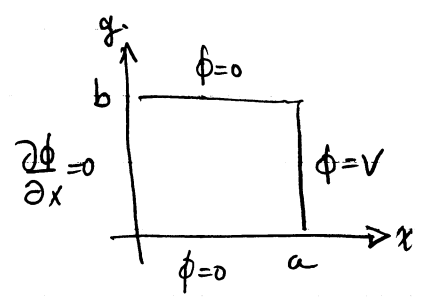
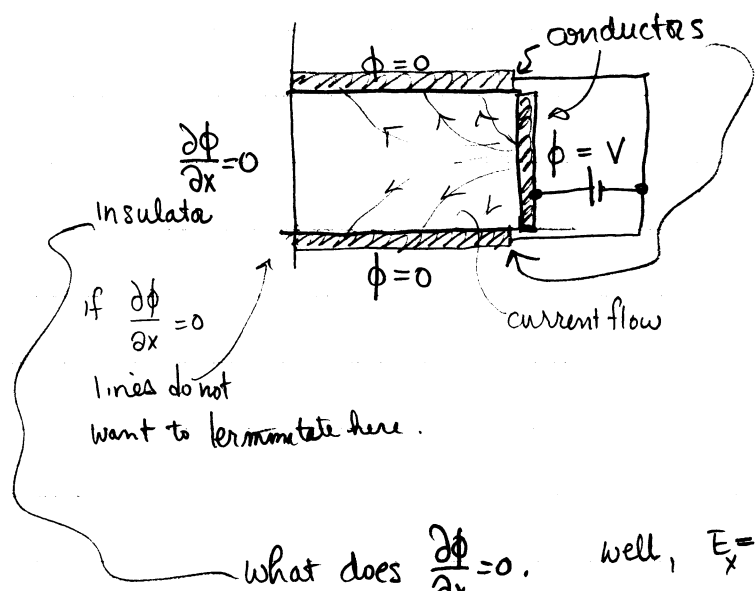
what we do is a 2-D Fourier transform of the left & right.

$$\int_0^a \int_0^b V(x,y) \sin \frac{s\pi x}{a} \sin \frac{t\pi y}{b} dx dy = \sum_{n=1}^{\infty} \sum_{m=1}^{\infty} A_n B_m \left[ \int_0^a \sin \frac{n\pi x}{a} \sin \frac{s\pi x}{a} dx \right] \left[ \int_0^b \sin \frac{m\pi y}{b} \sin \frac{t\pi y}{b} dy \right] \sinh \Gamma_{mn} c.$$

$$= A_s B_t \frac{a}{2} \frac{b}{2} \sinh \Gamma_{st} c.$$

this is the 2-D Fourier transform and if  $V(x,y)$  is known we just plug away varying  $s$  and  $t$  to get the constant  $A_s B_t \sinh \Gamma_{st} c$

Let's do a funny problem in two-dimensions!



what does  $\frac{\partial \phi}{\partial x} = 0$ . well,  $E_x = -\frac{\partial \phi}{\partial x}$  and  $J = \sigma E$   
 $\therefore J_x = -\sigma \frac{\partial \phi}{\partial x} \rightarrow 0$  along  $x=0$

What is the solution

want  $\phi=0$  at both  $y=0$  and  $y=b$  so pick  $\sin$  &  $\cos$ , i.e.  $k_y^2 > 0$  solution.

$$\nabla^2 \phi = 0$$

$$\nabla^2 f g = 0$$

$$g \frac{d^2 f}{dx^2} + f \frac{d^2 g}{dy^2} = 0$$

$$\frac{1}{f} \frac{d^2 f}{dx^2} + \frac{1}{g} \frac{d^2 g}{dy^2} = 0 \Rightarrow$$

$$\frac{d^2 f}{dx^2} - k_x^2 f = 0.$$

$$\frac{d^2 g}{dy^2} + k_y^2 g = 0.$$

since  $\phi=0$  in  $y$  direction I want  $g$  to be sinusoids

$$g = A \sin k_y y + B \cos k_y y.$$

$$g(0) = 0 \therefore B = 0$$

$$g(b) = 0 \therefore k_y b = n\pi \quad \text{or} \quad k_y = \frac{n\pi}{b}.$$

$$g(y) = \sum_{n=1}^{\infty} A_n \sin \frac{n\pi}{b} y$$

what is  $f$ ?

$$f = A \sinh k_x x + B \cosh k_x x$$

$$\frac{\partial f}{\partial x} = A k_x \cosh k_x x + B k_x \sinh k_x x$$

$\frac{\partial f}{\partial x} = 0$  at  $x=0$  since  $\cosh$  never goes to zero then  $A=0$ .

$$\text{and } f(x) = B \cosh k_x x$$

and it remains to satisfy the B.C. at  $x=a$ .

$$\therefore V(x,y) = \sum_{n=1}^{\infty} A_n \sin \frac{n\pi}{b} y \cosh \frac{n\pi}{b} x$$

$$v(a,y) = V_0 = \sum_{n=1}^{\infty} A_n \sin \frac{n\pi}{b} y \cosh \frac{n\pi a}{b}$$

multiply through by  $\sin \frac{m\pi}{b} y$  and integrate  $\int_0^b$

$$\int_0^b V_0 \sin \frac{m\pi}{b} y \, dy = \sum_{n=1}^{\infty} A_n \cosh \frac{n\pi a}{b} \underbrace{\int_0^b \sin \frac{n\pi}{b} y \sin \frac{m\pi}{b} y \, dy}_{\frac{b}{2} \delta_{mn}}$$

$$V_0 \left[ \frac{\cos \frac{m\pi}{b} y}{\frac{m\pi}{b}} \right]_0^b = V_0 \left[ -\cos \frac{m\pi b}{b} + 1 \right]$$

$$= V_0 [1 - \cos m\pi].$$

$$\therefore V_0 \left[ \frac{1 - \cos m\pi}{\frac{m\pi}{b}} \right] = A_m \cosh \left( \frac{m\pi a}{b} \right) \frac{b}{2}$$

$$A_m = \frac{2V_0 [1 - \cos m\pi]}{b \left[ \cosh \frac{m\pi a}{b} \right] \frac{m\pi}{b}} = \frac{2V_0}{m\pi} \left[ \frac{1 - \cos m\pi}{\cosh \frac{m\pi a}{b}} \right]$$