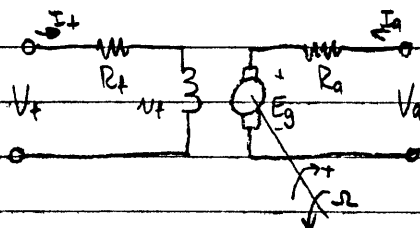


DC MACHINE BASICS

- KEEP UNITS STRAIGHT!
- BASIC D.C. MACHINE MODEL



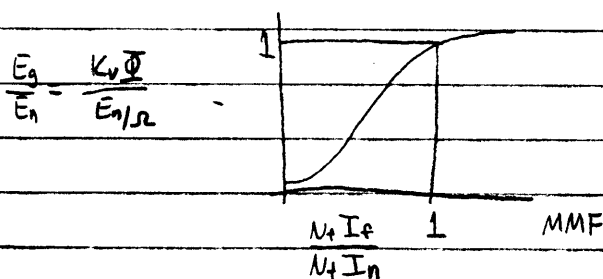
$$E_g = K_v \Phi \Omega \quad K_v = \text{VOLTAGE CONSTANT } (\approx \# \text{ SERIES TURNS/SECT.})$$

$$T = K_T \Phi I_a \quad K_T = \text{TORQUE CONSTANT} = K_v \text{ IN SI UNITS.}$$

$$P = T \Omega$$

- TO SOLVE PROBLEMS, WE MUST KNOW RELATIONSHIP BETWEEN Φ AND I_f .

USE SATURATION (MAGNETIZATION) CURVE, A NORMALIZED VERSION OF B-H CURVE.



THEY MUST TELL YOU THE NORMALIZATION VALUES TO GET NUMERICAL ANSWERS.

DC GENERATORS

SEPRATE EXCITATION

- FIELD CURRENT COMES FROM SOMEPLACE OTHER THAN GEN. ITSELF.
- USE SIMPLE RELATIONSHIPS & MODEL.

EX: S.E. DC GEN RATED 10KW, 240V, 2800 RPM
FOR 15HP WPT. NO LOAD $V_{out} = 260V$.

ARMATURE RESISTANCE:

$$I_{a,load} = \frac{10KW}{240V} = 41.6A$$

$$R_a = \frac{E_g - V_a}{I_{a,load}} = \frac{260 - 240}{41.6} = .48\Omega$$

MECHANICAL LOSSES:

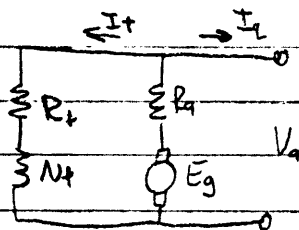
$$P_{in} = P_{out} + I_a^2 R_a + P_m$$

$$15HP \times \frac{746W}{HP} = 10,000 + 41.6^2 \cdot .48 + P_m$$

$$P_m = 359W.$$

SELF EXCITED GENERATORS.

- FIELD CURRENT COMES FROM ARMATURE VOLTAGE.



$$E_g = V_g + R_a(I_f + I_a)$$

PLUS SATURATION CURVE
CAN SOLVE PROBLEMS.

IT IS HELPFUL TO NORMALIZE THE EQUATION TO SATURATION CURVE REF. VALUES.

$$\frac{E_g}{E_n} = \frac{V_a + R_a I_L}{E_n} + R_a \frac{I_n}{E_n} \times \frac{I_f}{I_n}$$

$\frac{E_g}{E_n}$ VERT AXIS $\frac{V_a + R_a I_L}{E_n}$ VERT NORM. $\frac{I_n}{E_n}$ RATIO OF NORMALS $\frac{I_f}{I_n}$ HORIZ AXIS

EX: D.C. GEN, 10KW, 240V, 2800 RPM, 15 HP.

$$R_a = 1 \Omega$$

$V_{a, no\ load} = 260V$ (NO LOAD VOLTAGE) @ $I_f = 2.75 A$

USE FIG 7.2, NORM TO NO-LOAD VALUES.

FIND R_f TO S.E. @ RATED SPECS.

$$\text{KNOW THAT } I_L = \frac{10,000}{240} = 41.6A, E_n = 260, I_n = 2.75A.$$

$$\frac{E_g}{E_n} = \frac{240 + 1 \cdot 41.6}{260} + 1 \cdot \frac{2.75A}{260V} \times \frac{I_f}{I_n}$$

$$\frac{E_g}{E_n} = 1.083 + 0.0106 \frac{I_f}{I_n}, \text{ INTERSECT CURVE AT}$$

$$\frac{E_g}{E_n} = 1.1, \frac{I_f}{I_n} = 1.138, \text{ SO } R_f = \frac{V_a}{I_f} = \frac{240}{1.138 \cdot 2.75} = 76.7 \Omega.$$

REGULATION

$$\text{UNDER NO-LOAD, } E_g = I_f (R_f + R_a)$$

NORMALIZED,

$$\frac{E_g}{E_n} = (R_f + R_a) \frac{I_f}{I_n} \left(\frac{I_n}{E_n} \right) = (R_f + R_a) \left(\frac{I_n}{E_n} \right) \frac{I_f}{I_n}$$

SLOPE

INTERSECT WITH SAT CURVE FOR NO-LOAD VOLTAGE, $\frac{E_g}{E_n}$.

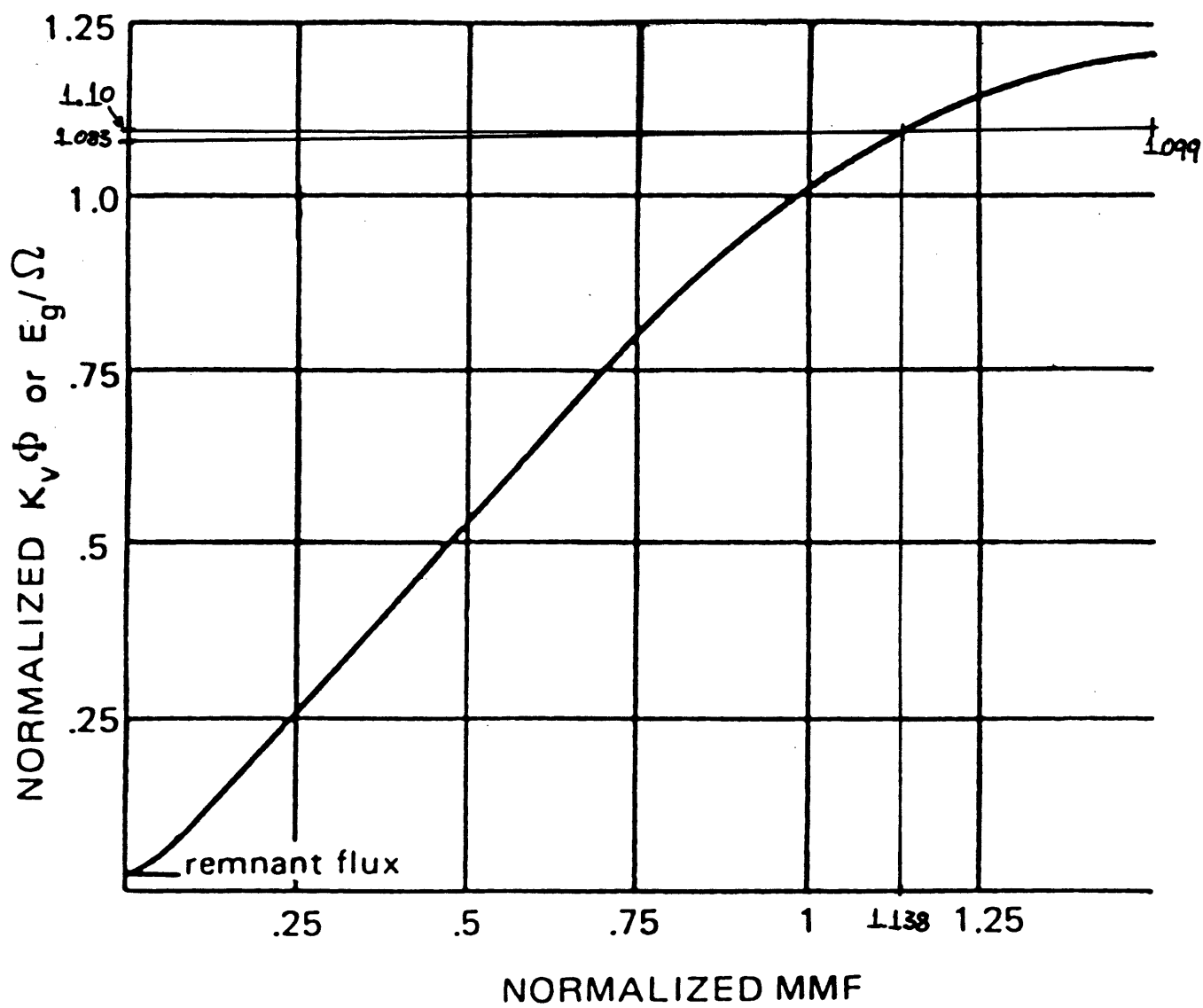
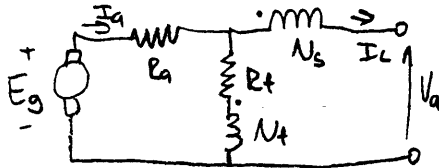


Figure 7.2 Saturation curve

COMPOUND GENERATORS

- USE I_L TO BOOST Φ



$$\text{NOW } \text{MMF} = N_f I_f + N_s I_L$$

AGAIN, NORMALIZE BY $N_f I_n$

$$\text{MMF}_n = \frac{I_f + \frac{N_s}{N_f} I_L}{I_n}$$

FOR FLAT COMPOUNDING: (FLAT COMPOUNDING WORKS FOR LIMITED RANGE OF OP. POINTS)
OPS = OPERATING POINT SLOPE, THEN

$$\textcircled{A} \quad \frac{N_s}{N_f} = \frac{R_a I_n}{\text{OPS} \cdot E_n}$$

$$\frac{E_g}{E_n} = \frac{V_a + R_a I_L \left(1 - \frac{N_s}{N_f}\right)}{E_n} + R_a \left(\frac{I_n}{E_n}\right) \text{MMF}_n$$

IF SAT CURVE WAS LINEAR FUNCTION, WE COULD SOLVE SIMULT. IT'S NOT, SO MUST ITERATE GO FROM SLOPE

IF THIS OP. POINT IS CLOSE TO CHOSEN OPS, USE IT IN $R_f = \frac{V_a}{I_f}$

IF NOT, CALL IT NEW OP. POINT AND START FROM $\textcircled{A}$

EX:

DC GEN RATINGS: 10KW 2800 RPM
240V 15 HP

HAS PARAMETERS: $R_a = 0.48 \Omega$

NO LOAD $V_g = 260V$ @ 2800 RPM, $I_f = 2.75A$, EXCITED SEPARATELY.

USE FIG 7.2, NORMALIZED TO NO-LOAD VALUES.

FIND $\frac{N_s}{N_f}$ & R_f FOR FLAT COMPOUNDING AT RATED SPECS.

NORMALIZATION VALUES $E_n = 260V$, $I_n = 2.75A$.

AT NORMALIZATION POINT, OPS = 0.71,

$$\text{SO } \frac{N_s}{N_f} = \frac{R_a I_n}{\text{OPS} \cdot E_n} = \frac{0.48 \cdot 2.75}{0.71 \cdot 260} = 0.00715$$

$$\frac{E_g}{E_n} = \frac{V_a + R_a I_L \left(1 - \frac{N_s}{N_f}\right)}{E_n} + R_a \left(\frac{I_n}{E_n}\right) \text{MMF}_n$$

$$= \frac{240 + (0.48) \left(\frac{10,000}{240}\right) (1 - 0.00715)}{260} + (0.48) \left(\frac{2.75}{260}\right) (1)$$

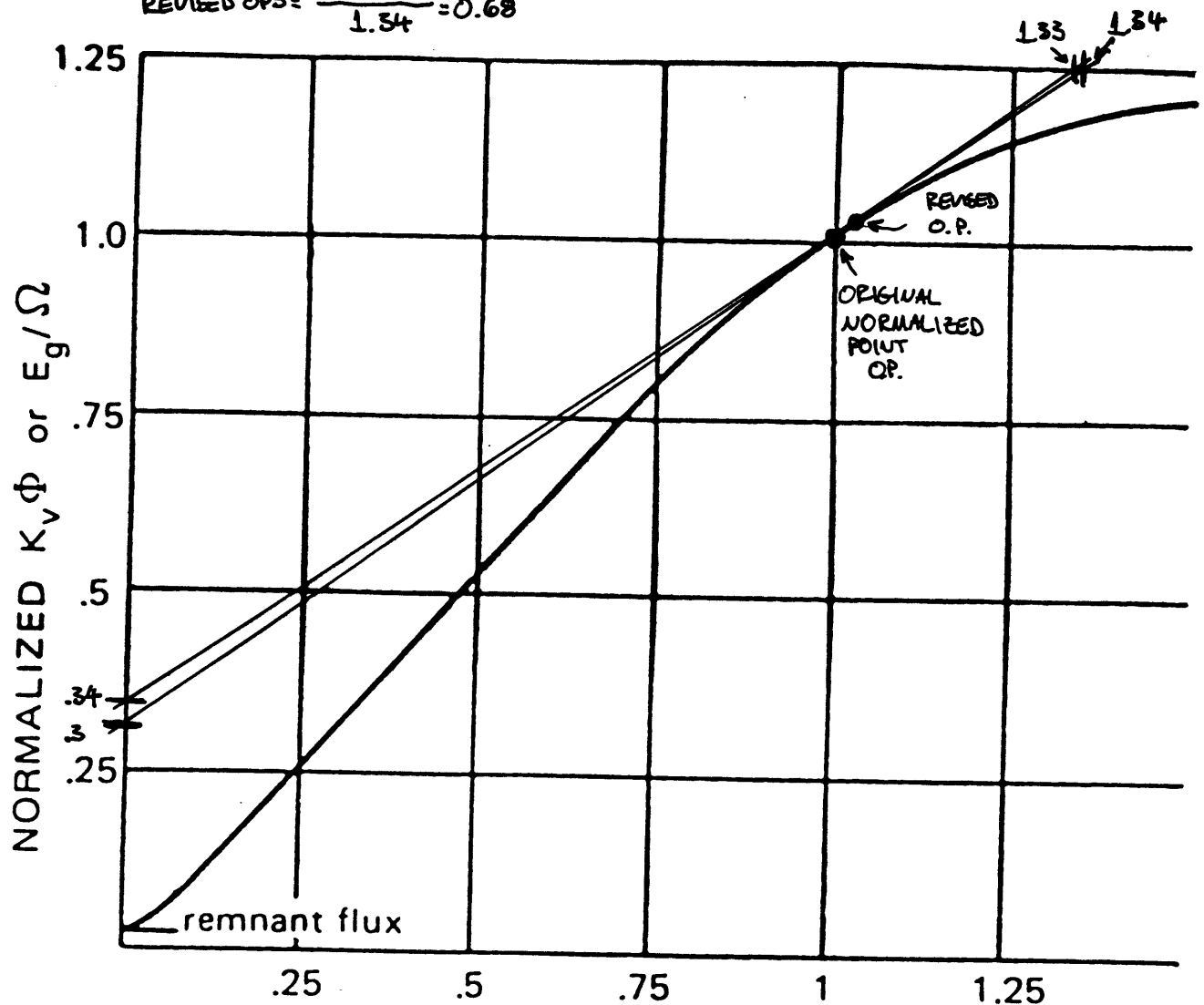
$$= 1.0045$$

DOUBLE WITH DERIVATION
GO TO EXAMPLE,

P2

$$\text{NORMAL OPS} = \frac{1.25 - 3}{1.33} = 0.71$$

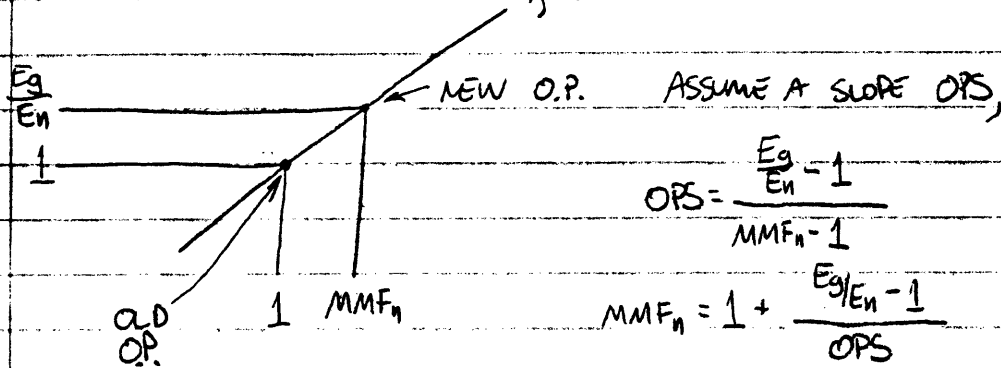
$$\text{REVISED OPS} = \frac{1.25 - .34}{1.34} = 0.68$$



NORMALIZED MMF

Figure 7.2 Saturation curve

MUST NOW FIND MMF_n , (YOU CAN GET FROM GRAPH, BUT USE LINEAR PROJECTION).



ERROR IN SOLUTION BOOK

$$MMF_n = 1.0063$$

(WE ARE CLOSE, BUT WILL DO ITERATION TO ILLUSTRATE)

$$NEW OPS = 0.68$$

$$NOW \frac{N_s}{N_f} = 0.00747, E_g = 261.2 \text{ AS IN PREVIOUS EQUATIONS.}$$

$$FROM BEFORE, MMF_n = \frac{I_f + \frac{N_s}{N_f} I_L}{I_n}$$

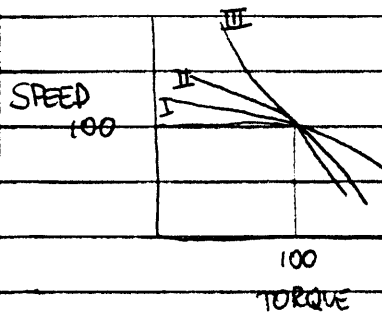
$$I_f = I_n MMF_n - \frac{N_s}{N_f} I_L$$

$$= 2.75 \cdot 1.0063 - 0.00747 \left(\frac{10,000}{240} \right)$$

$$I_f = 2.46A$$

$$SO \quad R_f = \frac{V_a}{I_f} = \frac{240}{2.46} = 97.6 \Omega$$

DC MOTORS



I = SEPARATE & SHUNT

II = COMPOUND

III = SERIES

SEPARATELY EXCITED DC

- ANALYSIS SIMILAR TO S.E. DC GENERATOR
- SYSTEM EQUATIONS IN BOOK

SHUNT MOTOR

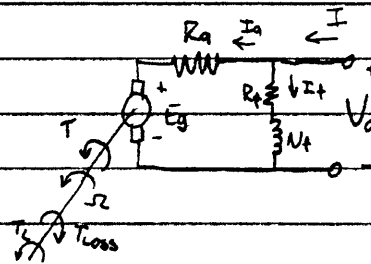
- POWER RELATIONSHIPS

$$P_{in} = P_a + P_f = V_a I_a + V_a I_f$$

$$P_a = P_s + I_a^2 R_a = E_g I_a + I_a^2 R_a$$

$$P_s = P_{loss} + P_{load}$$

$$P_s = P_{loss} + T_L \Omega$$



$$E_g I_a = T \Omega = P_{loss} + T_L \Omega$$

EX: DC SHUNT MOTOR, 200V, 25A, 1000 RPM, 5 HP.

$$R_a = .5 \Omega, R_f = 100$$

ROTATIONAL LOSSES:

NO-LOAD SPEED:

$$P_{in} = V_a I = 5000 \text{ W}$$

NEXT PAGE

$$5000 \text{ W} = P_a + \frac{V_a^2}{R_f}$$

$$P_a = 4600 \text{ W}$$

$$P_s = P_a - I_a^2 R_a$$

$$= P_a - \left(I - \frac{V_a}{R_f}\right)^2 R_a$$

$$P_s = 4336 \text{ W}$$

$$P_{loss} = P_s - 746(5)$$

$$P_{loss} = 606 \text{ W}$$

FIND

NO LOAD SPEED:

$$\text{FROM BEFORE, } P_s = 4336 \text{ W} = T \Omega$$

$$T = \frac{4336}{1000 \cdot \frac{\pi}{30}} = 41.4 \text{ Nm} = K \Phi I_a$$

$$K \Phi = \frac{41.4}{23} = 1.8 \text{ Wb}$$

$$\left(I_a = I - \frac{V_a}{R_f} \right) \\ = 25 - \frac{200}{100} = 23$$

UNDER NO LOAD COND,

$$P_s = 606 \text{ W} = T \Omega$$

$$= K \Phi I_a \Omega$$

$$\text{SO } I_a = \frac{337}{\Omega}$$

$$\text{NOW } V_a = I_a R_a + K \Phi \Omega \quad (\text{FROM LAST AGO})$$

$$200 = (.5) \left(\frac{337}{\Omega} \right) + 1.8 \Omega$$

- SOLVE QUADRATIC -

$$\Omega = 110, .9$$

$$\text{OR } 1051, 8.6 \text{ RPM}$$



COMPOUND DC MOTORS

- CUMULATIVE COMPOUNDING

FIELDS ADD IN

Φ

- PRODUCES HIGH
STARTING TORQUE

- DIFFERENTIAL COMPOUNDING

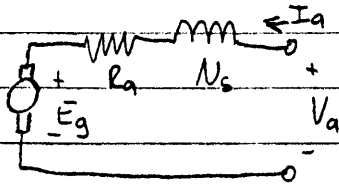
FIELDS SUBTRACT IN Φ

- PRODUCES BETTER
SPEED REGULATION

ALL ANALYSIS WEDID ON COMPOUND GENERATORS STILL
VALID, EXCEPT FOR DIFFERENTIAL COMPOUNDING,

$$\underline{\underline{\text{MMF} = I_f N_f - I_a N_s}}$$

SERIES DC MOTORS - HIGH STARTING TORQUE



SAME BASIC EQUATIONS
AS BEFORE

EX: DC SERIES MOTOR, RUNS @ RATED SPEED, $V_a, I_a, R_a = .001$
LOAD ^{DEMAND} INCREASES BY 25%. WHAT % DOES R CHANGE?

$$T = K \Phi I_a \text{ AND } \Phi \propto I_a$$

LET $\Phi = p I_a$, SO

$$T = K_p I_a^2$$

$$\text{IF } 1.25T = K_p (\sqrt{1.25} I_a)^2$$

SO I_a INCREASES BY $\sqrt{1.25} = 1.12$.

$V_a \approx E_g$ (SINCE R_a IS SO SMALL),

$$E_g = K \Phi \Omega$$

$$= K_p I_a \Omega$$

$$\Omega K_p (1.12 I_a) = (.894 \Omega) K_p I_a$$

SO Ω CHANGES BY FACTOR OF .894.

INDUCTION MOTORS

- JUST LIKE SPINNING TRANSFORMERS.

Ω_s : ANGULAR VELOCITY OF MMF WAVE IN STATOR

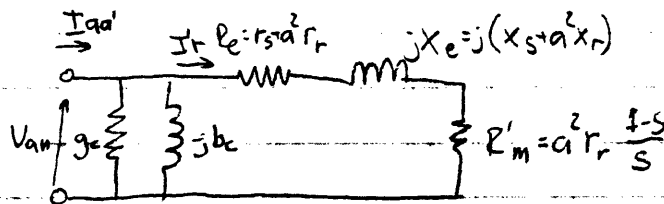
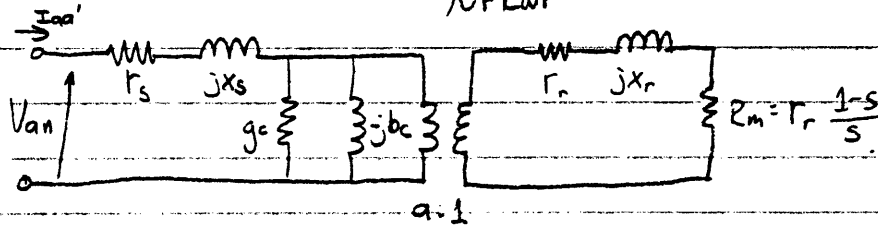
$$\Omega_s = \frac{2\omega}{p} \quad \begin{array}{l} p = \# \text{ POLES.} \\ \omega = \text{INPUT ANGULAR VELOCITY OF POWER} \end{array}$$

Ω_r : A.V. OF ROTOR.

$$\text{SLIP } s = \frac{\Omega_s - \Omega_r}{\Omega_s} \quad \left[\text{MANY OTHER GOOD FORMULAS IN BOOK} \right]$$

FREQUENCY SEEN BY ROTOR $\omega_r = s\omega$.

PER PHASE TRANSFORMER TURNS RATIO $a = \frac{N_s K_{ws}}{N_r K_{wr}} \quad K_w = \text{WINDING FACTOR.}$



EX 440V MOTOR HAS PER PHASE PARAMS $X_e = .712 \Omega$, $R_e = .283 \Omega$,
1200 RPM (6 POLE) $r_s = .126$ IN DELTA.

FIND STARTING TORQUE, T .

STATOR IN Δ : ($q = \# \text{ PHASES}$)

$$R_e = r_s + a^2 r_r \rightarrow a^2 r_r = 0.157$$

$$T_{\text{START}} = \frac{q |V_m|^2}{\Omega_s} \left[\frac{a^2 r_r}{R_e^2 + X_e^2} \right] = \frac{3 \left| \frac{440}{\sqrt{3}} \right|^2}{1200 \times \frac{2\pi}{60}} \left[\frac{.157}{.283^2 + .712^2} \right] = 412 \text{ Nm (EQ 7.78)}$$

SHUNT ELEMENTS CAN BE NEGLECTED, $s=1$,

$$I_{\text{START}} = \frac{440/\sqrt{3}}{\sqrt{R_e^2 + X_e^2}} = 332 \text{ A.}$$

STATOR IN Y:

SINCE $Z_{ln} = \frac{Z_{ll}}{3}$, ALL IMPEDANCES MULTIPLIED BY 3.

$$T_{START} = 412 \times \frac{3}{3^2} = 137 \text{ Nm}$$

$$I_{START} = \frac{332}{3} = 111 \text{ A.}$$

INDUCTION MOTOR TESTS

NO-LOAD TEST - JUST LIKE OPEN CT X-MFR TEST. ($S \approx 0$)

LOCKED ROTOR TEST - JUST LIKE SHORT CT X-MFR TEST ($S=1$).

NO LOAD

LOCKED ROTOR

$$g_c = \frac{P_{NL}}{|V_{an}|^2 q}$$

$$R_e = \frac{P_{LR}}{I^2 \tan \phi}$$

$$b_c = \frac{Q_{NL}}{|V_{an}|^2 q}$$

$$X_e = \frac{Q_{LR}}{I^2 \tan \phi}$$

EX NO LOAD TEST

3 ϕ 440V, 1200W, 2500VA ($V_{an} = \frac{440}{\sqrt{3}} = 254 \text{ V}$)

$$g_c = \frac{1200}{3 \cdot 254^2} = 6.2 \text{ mS}$$

$$b_c = \frac{\sqrt{2500^2 - 1200^2}}{3 \cdot 254^2} = 11.3 \text{ mS}$$

LOCKED ROTOR TEST

$I = 21 \text{ A}$, $P_{in} = 375 \text{ W}$ P.F. = .37

$$R_e = \frac{375}{3 \cdot 21^2} = .283 \Omega$$

$$X_e = \frac{P \cdot \tan \cos^{-1} .37}{3 \cdot 21^2} = .712 \Omega$$

USUALLY LUMP
ROTATIONAL LOSSES
IN WITH g_c .

YOU CAN DETERMINE
 T_s AND $a^2 T_r$ FROM
POWER IN, POWER OUT & SLIP.
VERY STRAIGHT FWD.
SEE EQ 7.83, P 7-14.

STARTING INDUCTION MOTORS (3 ϕ)

COVERED IN BOOK

- 1) START IN Y, SWITCH TO Δ , IMPEDANCES $\times 3$.
- 2) USE AUTOTRANSFORMER TO ADJUST LINE-NEUTRAL VOLTAGE
- 3) ADD RESISTANCE TO ROTOR.

DO NOT CONFUSE WITH SINGLE ϕ INDUCTION MOTOR STARTING. THAT IS ANOTHER LECTURE.

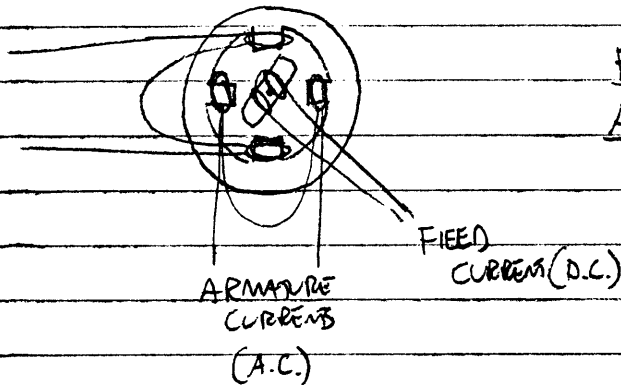
SYNCHRONOUS MACHINES

- MOST COMPLEX ROTATING MACHINES.

- AS IN INDUCTION MACHINE,

$$\Omega_s = \frac{2\omega}{p}$$

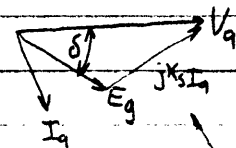
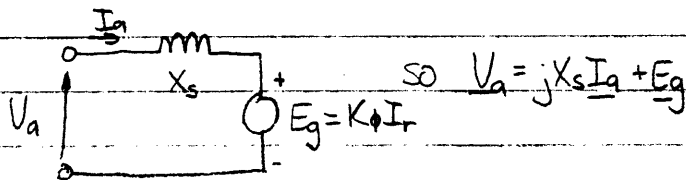
BUT $\Omega_r = \Omega_s$, SO $S = 0$.



FIELD WINDINGS ON ROTOR
ARMATURE WINDINGS ON STATOR

(UNDERLINE PHASORS)

MOTOR PER PHASE CKT:



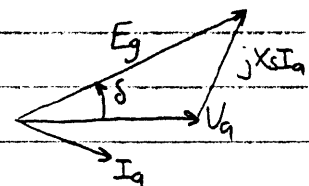
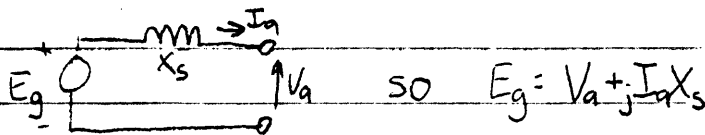
DECOMPOSE $\underline{E_g} = |E_g| \cos \delta - j |E_g| \sin \delta$.

SOLVING, $I_a = \frac{|E_g| \sin \delta}{X_s} - j \frac{V_a - |E_g| \cos \delta}{X_s}$

SIGN OF δ
DISTINGUISHES

$$S = q [V_a I_a^*] = q \left[\frac{V_a |E_g| \sin \delta}{X_s} + j \frac{V_a^2 - V_a |E_g| \cos \delta}{X_s} \right]$$

FOR GENERATOR:

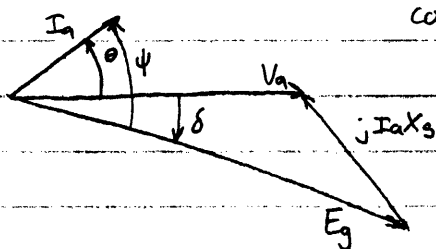


BY SAME ANALYSIS,

$$S = q \left[\frac{|E_g| V_a \sin \delta}{X_s} + j \frac{|E_g|^2 - |E_g| V_a \cos \delta}{X_s} \right]$$

SYNCHRONOUS MOTORS

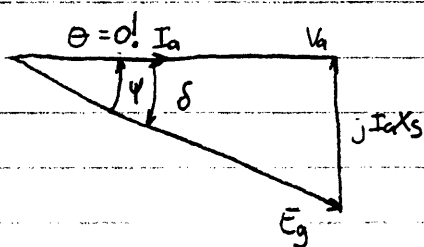
$\cos \theta = \text{POWER FACTOR}$



INTO FORMULAS 7.111-7.114, P 7-20

FORMULAS GIVE EQUIPMENT FOR
S.M. PROBLEMS

NOTE THAT SINCE $|E_g| = K_\phi I_f$, WE CAN CORRECT POWER
FACTOR ANGLE θ JUST BY VARYING I_f ,



JUST BY REDUCING I_f ,
WE MADE $\theta = 0$!

EX: 3 ϕ , 440V, 60Hz, 3600 RPM SYNC MOTOR HAS

PER PHASE $X_s = 20\Omega$, $R_a = 5\Omega$,

$I_a = \text{MINIMUM @ } I_f = 5A$, $P_{in} = 900W$. $I_{a, \text{rated}} = 12A$

WANT TO FIND

LOAD PWR

EFFICIENCY

UNDER NO LOAD, $\delta \rightarrow 0$, $E_g \approx V_a$ SO I_a IN PHASE WITH $V_a = 254V$.

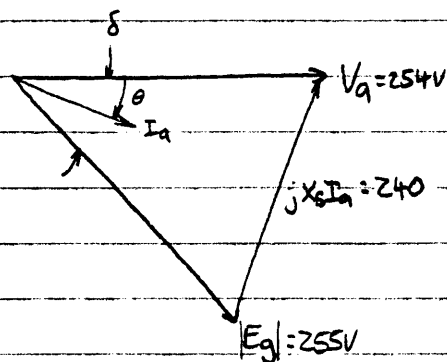
$P_{NL} = V_a I_a = 900W$, SO $I_a = \frac{900/3}{440/3} = 1.18A$

$$|E_g| = (V_a^2 + (I_a X_s)^2)^{1/2} = 255V$$

UNDER RATED LOAD, $I_a = 12A$, $X_s I_a = 240$.

DRAW DIAGRAM

$$(a^2 = b^2 + c^2 - 2ab \cos \alpha)$$



IMMEDIATELY, FROM LAW OF COSINES,

$$\delta = -56.3^\circ$$

FROM LAW OF SINES,

$$\theta = -27.9^\circ$$

LOAD POWER:

$$\begin{aligned} P_{\text{LOAD}} &= 3(P_{\text{IN}} - P_{\text{LOSS}}) - P_{\text{ROTATION}} \\ &= 3(V_a I_a \cos \theta - I_a^2 R_a) - 900 \\ &= 6970 \text{ W} \end{aligned}$$

$$\text{EFFICIENCY: } \eta = \frac{P_L}{P_{\text{IN}}} \times 100 = 86.3\%$$

 I_R FOR 5KVAR OF P.F. CORRECTION UNDER LOAD:

$$\text{SINCE } |E_g| = K_\phi I_R, \text{ AT } I_R = 5\text{A}, |E_g| = 255, \text{ SO } K_\phi = 51.$$

$$\text{NEED APPARENT POWER } S = P_{\text{IN}} - j5000$$

$$S = 8081 - j5000 = 3V_a I_a^*$$

$$I_a^* = \frac{8081 - j5000}{3 \cdot 254} = 10.6 - j6.56 \text{ A}$$

$$jX_s I_a = j20 I_a = -131 + j212 \text{ V}$$

$$\text{SINCE } E_g = -jX_s I_a + V_a = 385 - j212 \text{ V}, |E_g| = 440 \text{ V}$$

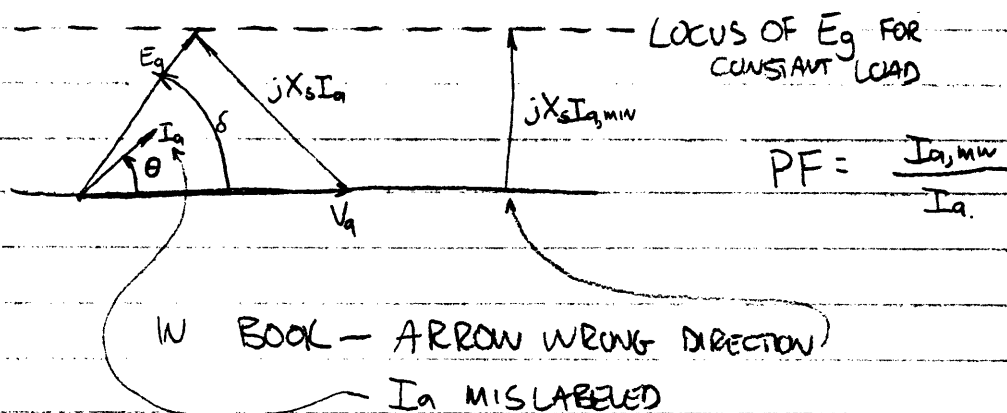
$$I_R = \frac{|E_g|}{K_\phi} = \frac{440}{51} = 8.6 \text{ A}$$

SYNCHRONOUS GENERATORS

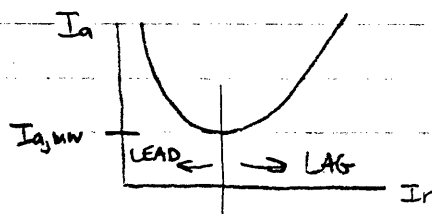
- MUST HAVE $\delta > 0$ FOR GENERATOR.
- SEE EQUATIONS 7.121-7.125, P 7-22 FOR PROBLEM SOLVING EQUIPMENT.

- UNDER CONSTANT LOAD:

$$T_{\text{SHAFT}} = 3V_a |E_g| \sin \delta X_s \Omega_s$$



PLOT I_a vs. $I_r \propto E_g$,



EX: I_r (A)	2	3	5.5	8	12	15	20	23	27
I_a (A)	60	45	30	21	15	18	32	45	60

SYNC GEN, 60 Hz, 480V, 50 KVA, $I_r = 20A$, 30HP, CONST LOAD.

→ ROTOR I FOR .8 LAG PF: $.8 = \frac{I_{a, \text{mw}}}{I_a}$, $I_a = \frac{15}{.8} = 18.75A$

- INTERPOLATE: $\frac{I_r - 15}{18.75 - 18} = \frac{20 - 15}{32 - 18} \rightarrow I_r = 15.34A$

→ I_r FOR $I_a = 40A$, LEADING, $\frac{40 - 45}{I_r - 3} = \frac{30 - 45}{5.5 - 3}$, $I_r = 3.83A$

→ RESULTING PF = $\frac{15}{40} = 0.375$, LEADING.

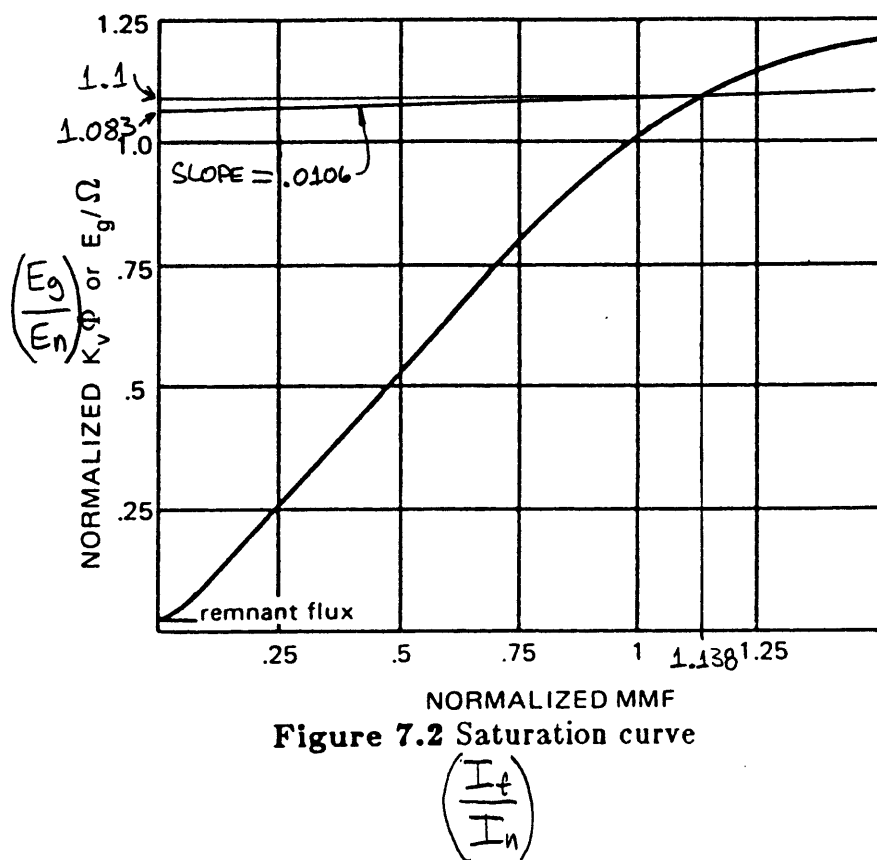
SELF EXCITED DC GENERATOR EXAMPLE

S.E. GENERATOR, RATED 10KW, 240V, 2800 RPM.

$R_a = 1 \Omega$, $V_a, \text{NO LOAD} = 260V @ I_f = 2.75A$.

USE FIG 7.2, NORMALIZED TO NO-LOAD VALUES.

FIND R_f TO SELF EXCITE @ RATED SPECS.



① CURVE IS NORMALIZED TO NO-LOAD VALUES, SO
 $E_n = 260V$, $I_n = 2.75A$.

② $I_L = \frac{P}{V} = \frac{10,000}{240} = 41.6A$.

③ PLUG NUMBERS INTO NORMALIZED LOOP EQUATION:

$$\frac{E_g}{E_n} = \frac{V_a + R_a I_L}{E_n} + R_a \frac{I_n I_f}{E_n I_n}$$

$$\frac{E_g}{E_n} = \frac{240 + 1 \cdot 41.6}{260} + 1 \cdot \frac{2.75}{260} \frac{I_f}{I_n}$$

$$\frac{E_g}{E_n} = 1.083 + 0.0106 \frac{I_f}{I_n}$$

PLOT THIS LINE ON CURVE.

④ LINE INTERSECTS CURVE AT

$$\frac{E_g}{E_n} = 1.1, \quad \frac{I_f}{I_n} = 1.138$$

$$R_f = \frac{V_a}{I_f} = \frac{240}{1.138 \cdot 2.75} = 76.7 \Omega$$

COMPOUND GENERATOR EXAMPLE

DC GENERATOR HAS RATINGS: 10 KW
240V

$$2800 \text{ RPM. } I_L = \frac{10,000}{240} = 41.7 \text{ A.}$$

AND PARAMETERS: $R_a = .48 \Omega$

$$V_{g, \text{no load}} = 260 \text{ V @ } I_f = 2.75 \text{ A}$$

USE FIG 7.2, NORMALIZED TO NO-LOAD VALUES.

FIND $\frac{N_s}{N_f}$ AND R_f FOR FLAT COMPOUNDING AT RATED SPECS.

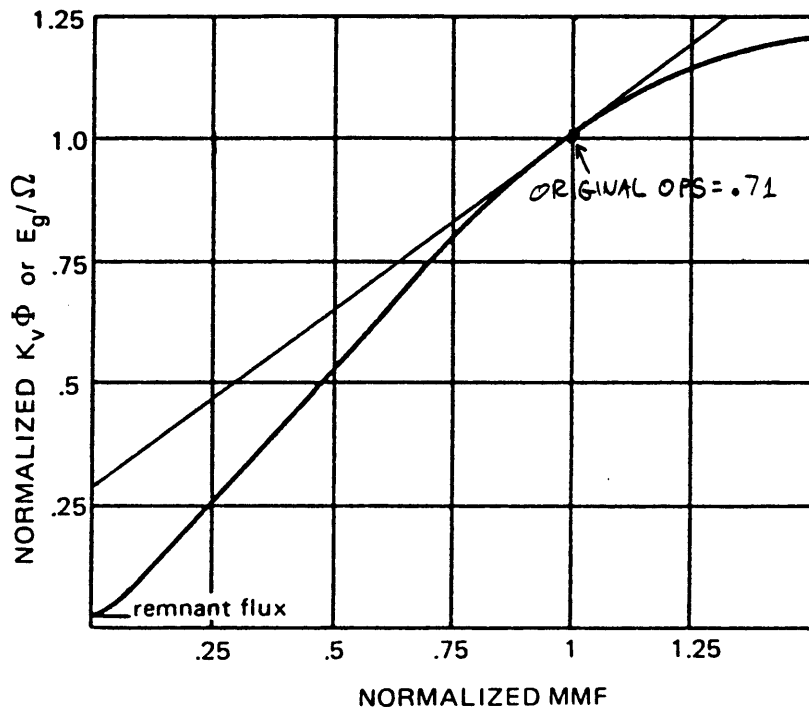


Figure 7.2 Saturation curve

- ① OBSERVE NORMALIZATION VALUES

$$E_n = 260 \text{ V } I_n = 2.75 \text{ A.}$$

USE NORMALIZATION POINT AS FIRST GUESS AT PROPER OPERATING POINT, AND MEASURE SLOPE THERE.

$$\text{OPS} = .71.$$

- ② CALCULATE TURNS RATIO

$$\frac{N_s}{N_f} = \frac{R_a I_n}{\text{OPS} \cdot E_n} = \frac{.48 \cdot 2.75}{.71 \cdot 260}$$

$$\frac{N_s}{N_f} = 0.00715.$$

- ③ CALCULATE FIELD CURRENT

$$I_f = I_n \cdot \text{MMF}_n - \left(\frac{N_s}{N_f} \right) I_L$$

$$I_f = 2.75 \cdot 1 - 0.00715 \cdot 41.7$$

$$I_f = 2.45 \text{ A.}$$

- ④ CALCULATE NEW OPERATING PT.

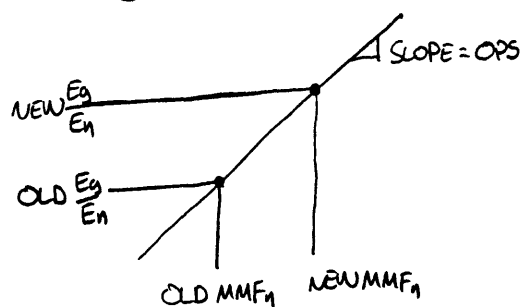
$$E_g = V_a + R_a (I_f + I_L)$$

$$E_g = 240 + .48(2.45 + 41.7)$$

$$E_g = 261 \text{ V.}$$

$$\frac{E_g}{E_n} = 1.0046.$$

⑤ FIND NEW MMF_f VIA LINEAR APPROXIMATION.



$$OPS = \frac{NEW \frac{E_g}{E_n} - OLD \frac{E_g}{E_n}}{NEW MMF_f - OLD MMF_f}$$

$$NEW MMF_f = \frac{NEW \frac{E_g}{E_n} - OLD \frac{E_g}{E_n}}{OPS} + OLD MMF_f$$

IN THIS CASE,

$$NEW MMF_f = \frac{1.0046 - 1}{.71} + 1$$

$$NEW MMF_f = 1.00646$$

⑥ MEASURE SLOPE AT NEW OP. POINT.

$$OPS = .68$$

⑦ TURNS RATIO

$$\frac{N_s}{N_f} = \frac{R_a I_n}{OPS \cdot E_n} = \frac{.48 \cdot 2.75}{.68 \cdot 260}$$

$$\frac{N_s}{N_f} = 0.00747$$

⑧ FIELD CURRENT

$$I_f = I_n \cdot MMF_f - \left(\frac{N_s}{N_f} \right) I_L$$

$$I_f = 2.75 \cdot 1.00646 - 0.00747 \cdot 41.7$$

$$I_f = 2.46 A$$

⑨ OP. POINT

$$E_g = V_a + R_a (I_f + I_L)$$

$$E_g = 240 + .48 (2.46 + 41.7)$$

$$E_g = 261 V$$

⑩ NOTE THAT THE NEW E_g IS VERY CLOSE TO THE PREVIOUSLY CALCULATED E_g , SO WE MAY PROCEED TO STEP #11. IF THE NEW E_g IS NOT CLOSE, GO BACK TO STEP #5, AND ITERATE UNTIL IT CONVERGES.

⑪ $\frac{N_s}{N_f} = 0.00747$, FROM ABOVE.

$$R_f = \frac{V_a}{I_f} = \frac{240}{2.46} = 97.6 \Omega$$

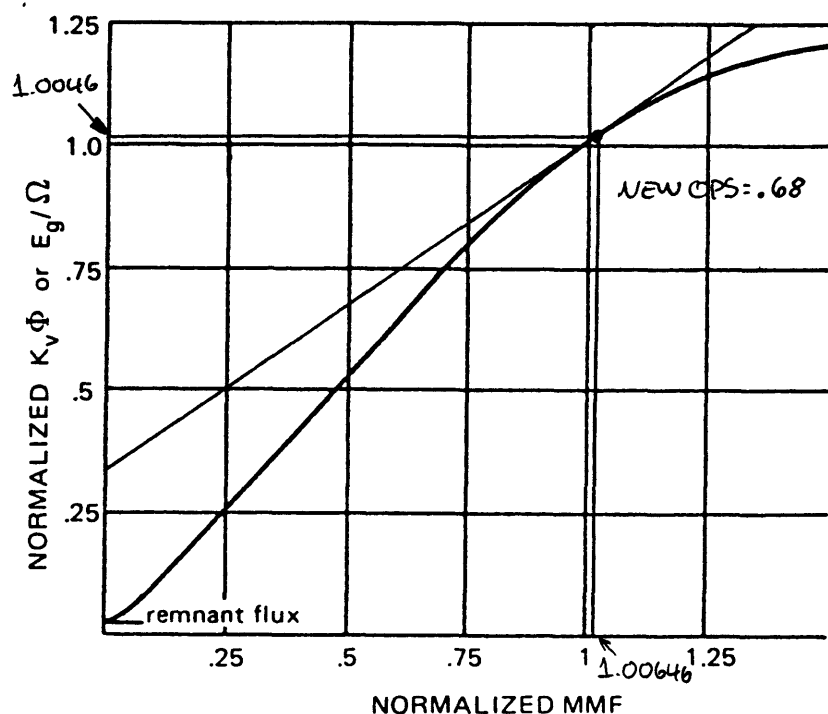


Figure 7.2 Saturation curve