

Chapter 1.

1.2 elements of digital image processing

picture elements - pixels.

typically in a rectangular sampling grid

use this rectangular grid to represent an image

image must be converted to digital form.

location is quantized

brightness is sampled and quantized - called a gray level.

1.2.1. Terminology of digital image processing

image contains descriptive information about object it represents.

visible images - our typical interest

optical images - formed with lenses, gratings & holograms

physical images - actual distributions of matter or energy

non visible physical images - temperature, pressure, elevation, etc. maps.

multi-spectral images - trispectral (R, G, B), etc.

picture - distribution of matter that is visible when properly illuminated

digital image processing - subjecting a numerical representation of an object to a series of operations in order to obtain a desired result.

digital image - a sampled, quantized functions of two dimensions that has been generated by optical means, sampled in an equally spaced rectangular grid pattern and quantized in equal intervals of amplitude.

some common exceptions

1. non-optical digital images
2. higher dimensional images; multi-spectral, color
3. non-standard sampling
4. non-standard quantization

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digital image processing - starts with one image and produces a modified version of the image.

image \rightarrow image transform

computer graphics - processing & display of images that exist conceptually, or as mathematical descriptions

emphasis on generation of an image given

1. model that describes object

2. illumination

3. geometry of an imaging camera

computer vision - development of systems that can interpret the content of natural scenes

digitizing - process of converting image from its original form into digital form. (reverse operation is display).

scanning - selective addressing of specific locations within the domain of an image.

in digitizing photographs this is the process of sequentially addressing small spots on the film.

rectangular grid scanning pattern is called a raster

operations on digital images

1. global - applied equally throughout entire digital image

2. point - value of output pixel depends only on value of the corresponding input pixel (usually contrast manipulation or contrast stretching)

3. local - gray level of output pixel is computed from gray levels of several pixels in a neighborhood of the corresponding input pixel.

sampling - measuring the gray level of an image at each pixel location

quantization - representation of the measured value by an integer

contrast - amplitude of gray-level differences within an image

gray scale resolution - # of bits/pixel gives number of levels in gray scale.

sampling density - # of sample points/unit length

pixel spacing = $\frac{1}{\text{sampling density}}$

magnification - size relationship between objects in image and objects in scene it represents.

Chapter 2 - Digitizing Images

2.2 Characteristics

pixel size

image size

local property measured - i.e. for film scanners optical density or transmittance

linearity - of the digitization, how accurate are the gray levels, i.e. proportional to actual brightness, etc.

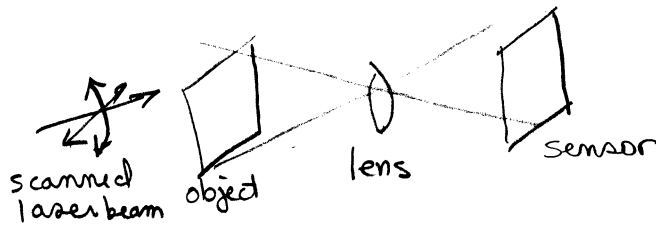
noise

2.3 Types of Image Digitizers

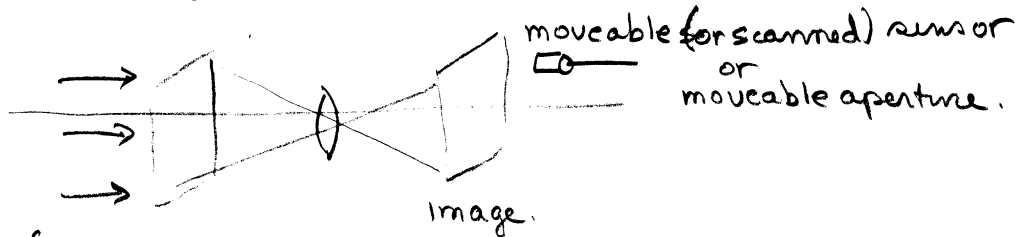
most common is digitizing camera, i.e. a television camera interfaced to a computer

film scanners have historically played a predominant role in image processing.

scan-in digitizing - illuminate small spot of object and collect all transmitted light.



scan out digitizer



uniform illumination

scan-in/scan-out digitizer - very complex.

2.4 Image-digitizing components.

Light sources

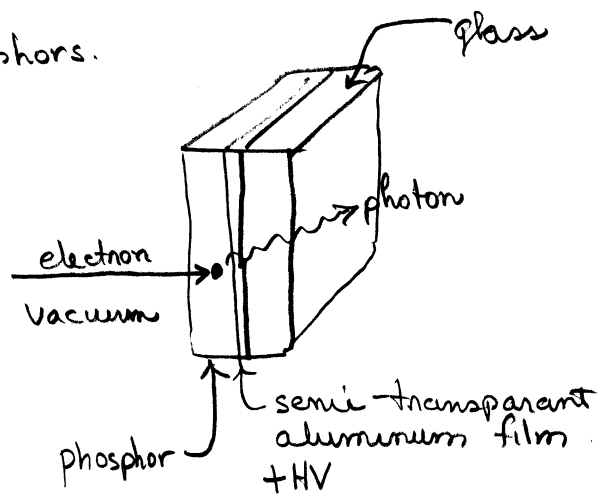
(1) - incandescent bulbs

} good for large area illumination

(2) Lasers

- excellent for scan-in digitizers

(3) Phosphors.

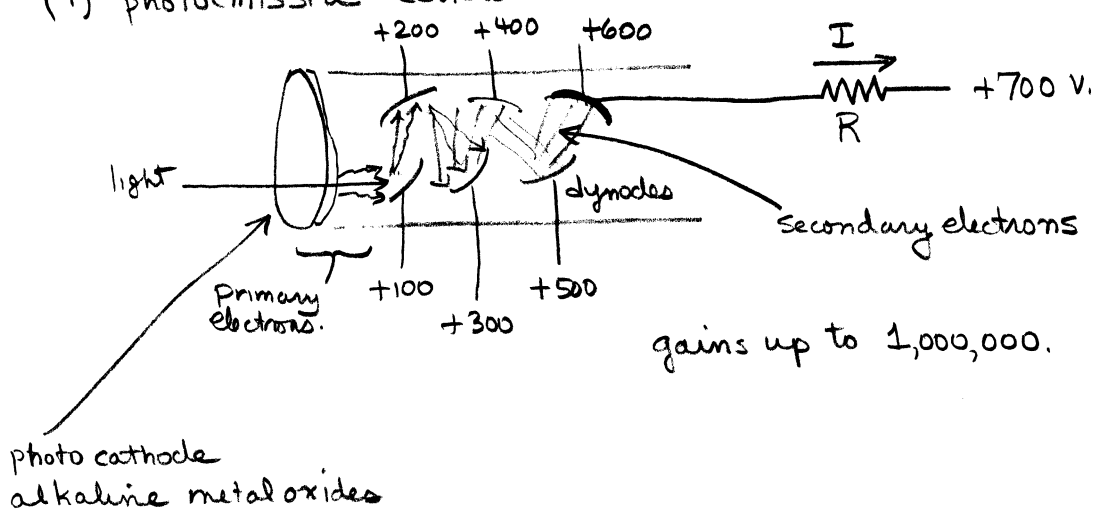


granularity of phosphor limits resolution to about 30-70 lp/mm.

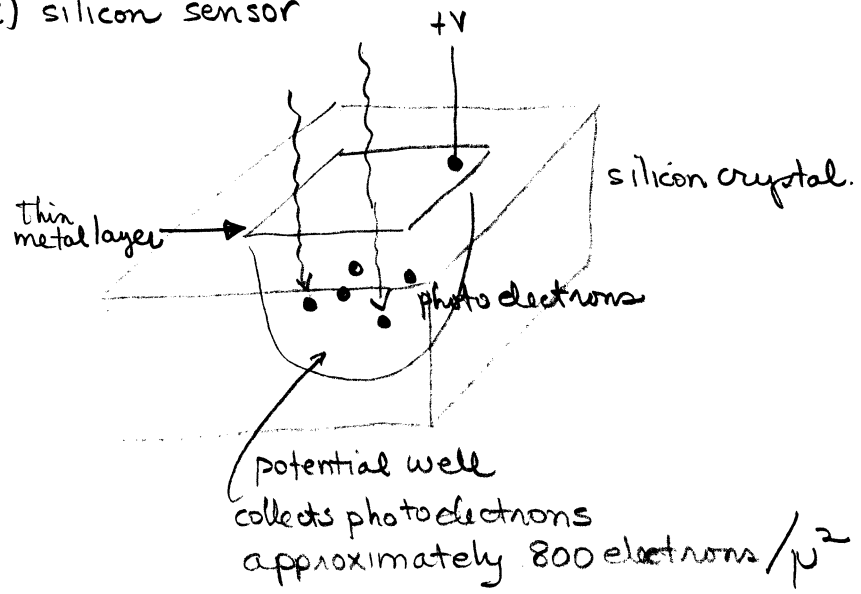
spectrum (color)
persistence (decay rate)
of light generated can be controlled by manufacture of the phosphor

Sensors

(1) photoemissive devices such as PMT's.



(2) silicon sensor



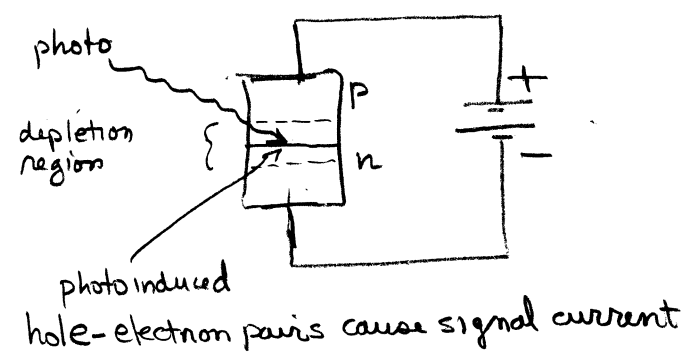
dynamic range - capacity in electrons / readout noise level in electrons.
 (can be as low as 5-10 electrons)

overexposure causes excess electrons that spread to other wells causing blooming

dark current is produced by thermal electrons (random bond breakage)
 can be reduced by cooling

(3) photodiodes - solid-state PN junction

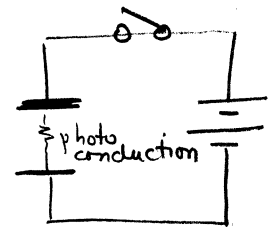
(a) depletion (reverse bias) mode



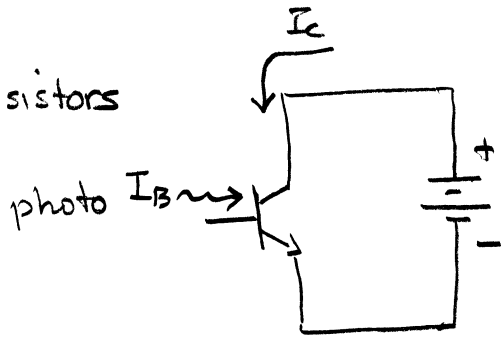
avalanche photodiode - very high reverse polarity gives electron multiplication similar to PMT
 gain up to 1000.

(b) integrating mode

p-n depletion region is a capacitor
 charge it up and remove potential
 photoconduction bleeds off charge.
 limits: small capacitance & dark current
 signal is required recharge.



(4.) photo-transistors

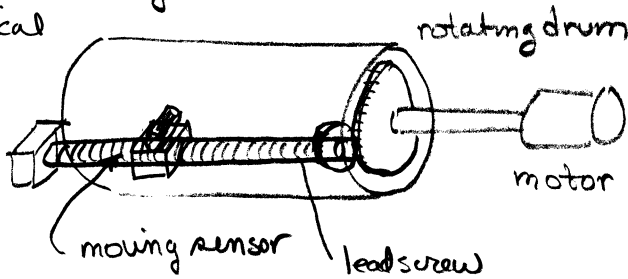


$$I_c = \beta L I_B$$

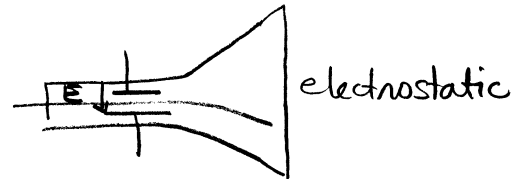
↑ light level.

2.4.3 Scanning mechanisms

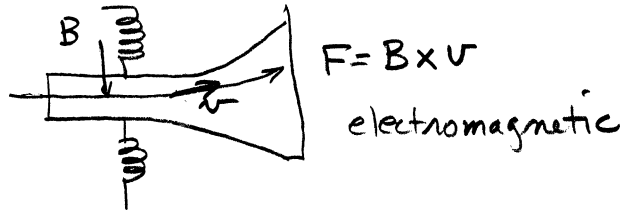
mechanical



electron beam



electrostatic

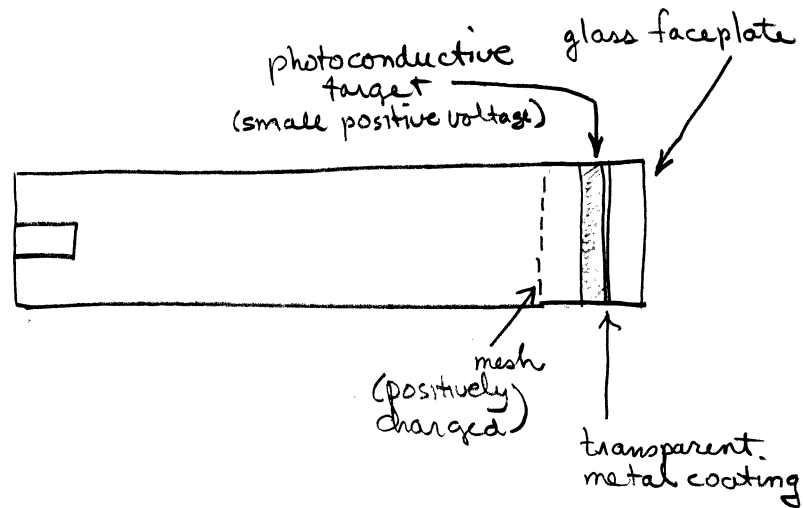


$$F = B \times v$$

electromagnetic

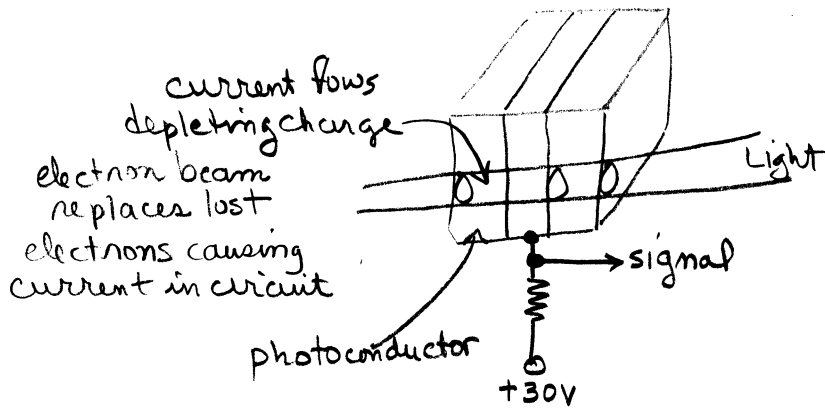
2.5 Electron Image Tube Cameras

Vidicon



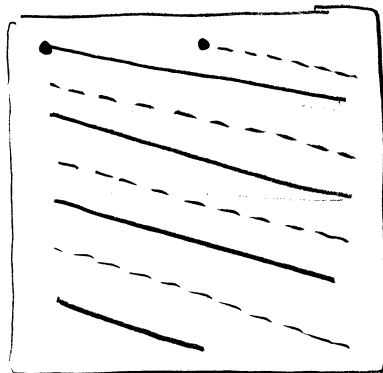
mesh decelerates incoming electrons

photoconductor is an insulator with no incident light
 electron beam negatively charges inside
 of photoconductor to balance + charge on metal coating



Scanning convention

RS-170



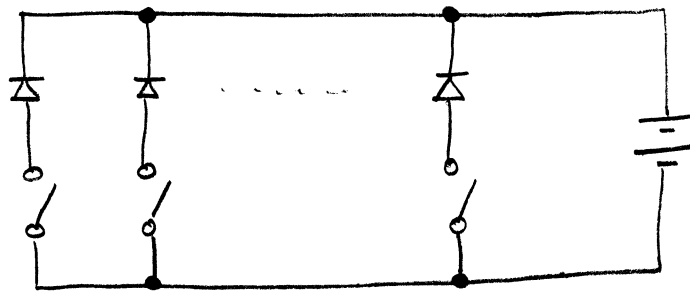
- 30 frames/sec.
- 525 lines/frame
- 15750 lines/sec.
- 63.5 psec/line
- 2 fields/frame.
- 262.5 lines/field
- 60 fields/sec.
- odd line.
- even line

60 Hz field rate minimizes perceived flicker

30 Hz frame rate reduces transmission bandwidth.

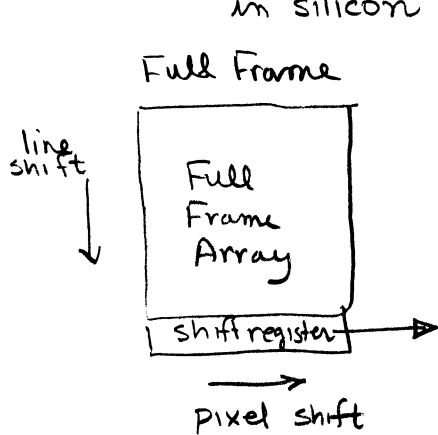
2.6 Solid State Cameras.

(1) Photodiode arrays

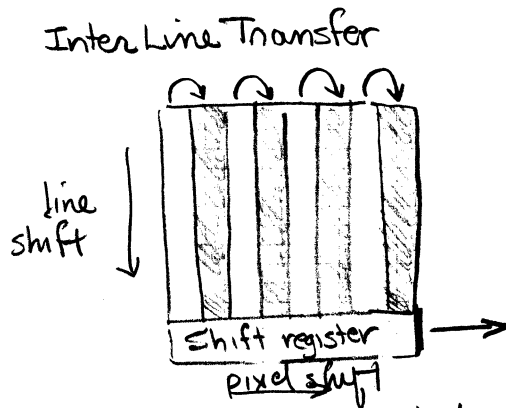


operates diodes in light integrating mode
 diodes are charged up one at a time, charge current is signal
 usually 1-D arrays FAX scanners, spectroscopy

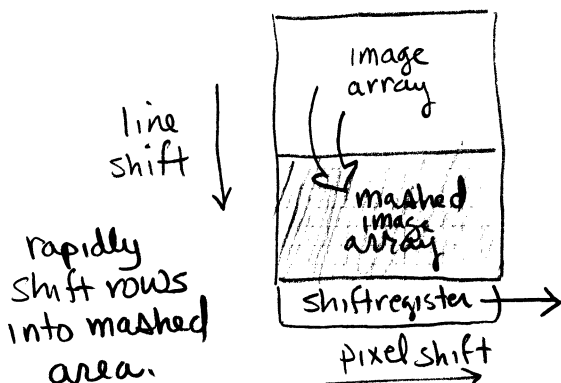
(2) CCD's - 2-D arrays of potential wells (photodetector wells) in silicon



keep CCD shuttered during readout
 shifts out one row at a time



shift charge packets to masked wells after exposure
 All shifted at once.
 Read out while accumulating next image.
 50% of chip masked

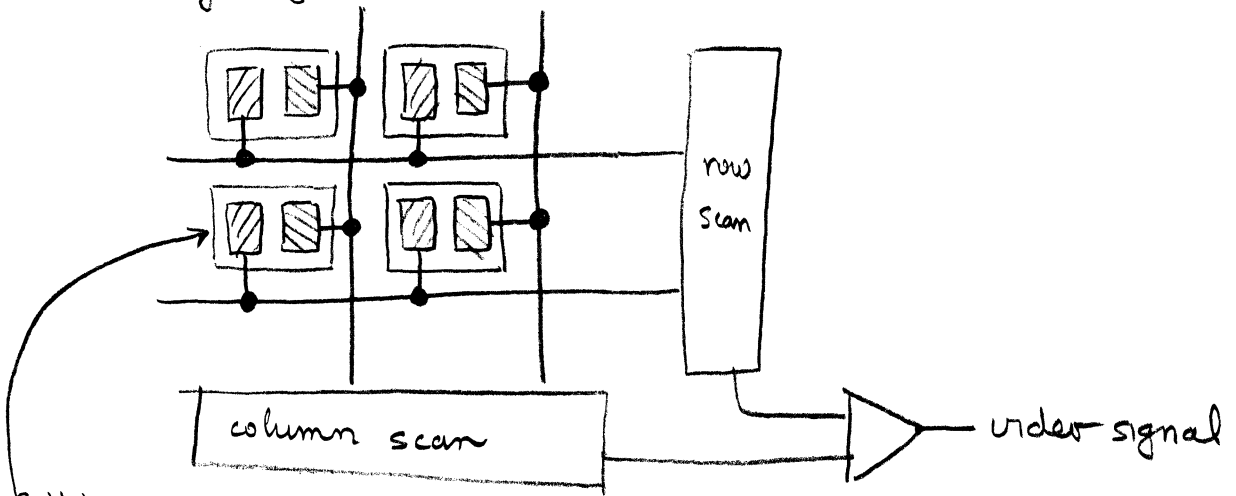


readout noise - random noise generated by electronics

photon noise - quantum nature of light
 $= \sqrt{\# \text{ of electrons in well}}$

charge transfer efficiency

2.6.3. Charge Injection Devices



2 thin metal electrodes on each well

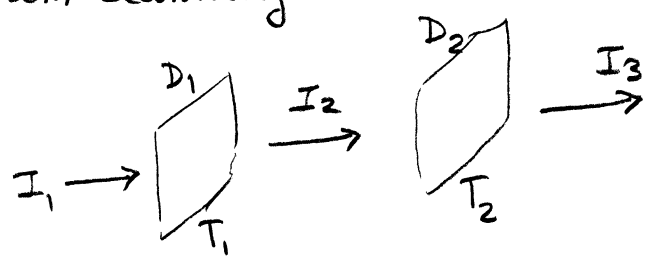
- ① when row & column electrode +, photoelectrons will accumulate (integration mode). All rows & columns + to acquire an image.
- ② when one electrode driven to 0 or -, photoelectrons shift to under other electrode creating a signal current pulse. Can shift back & forth as needed. (non-destructive readout mode)
- ③ if both electrodes $\leq 0^V$ then charge flushed into substrate. This gives substrate current but empties well. (destructive readout mode)

Advantages of CID

- good in severe environmental & lighting conditions
- very little blooming since no pathway connecting cells.
- no worry about charge transfer efficiency

Considerably less sensitive than CCD's.

2.7 Film Scanning



$$T_1 = \frac{I_2}{I_1} \begin{array}{l} \text{transmitted flux density} \\ \text{incident flux density} \end{array}$$

optical density $D_1 = \log \frac{I_1}{I_2} = \log \frac{1}{T_1} = -\log T_1$ $0 \leq D_1 \leq \infty$
 since $T < 1$

$$D_2 = \log \frac{I_2}{I_3} = \log \frac{1}{T_2} = -\log T_2$$

For two filters in series,

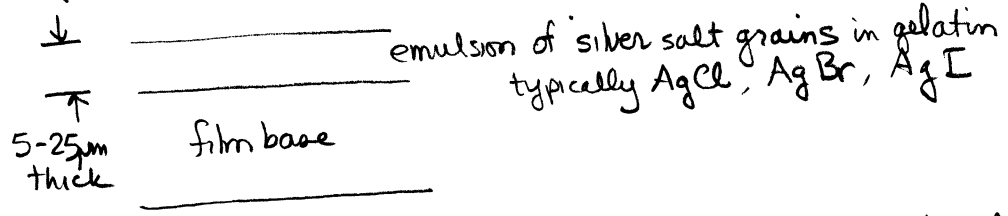
$$T_3 = \frac{I_3}{I_1} = \frac{I_3}{I_2} \frac{I_2}{I_1} = T_2 T_1$$

$$T_2 = \frac{I_3}{I_2}$$

but $D_3 = \log \frac{I_1}{I_3} = \log \left(\frac{I_1}{I_2} \times \frac{I_2}{I_3} \right) = \log \left(\frac{1}{T_1} \times \frac{1}{T_2} \right) = -\log T_1 - \log T_2 = D_1 + D_2$

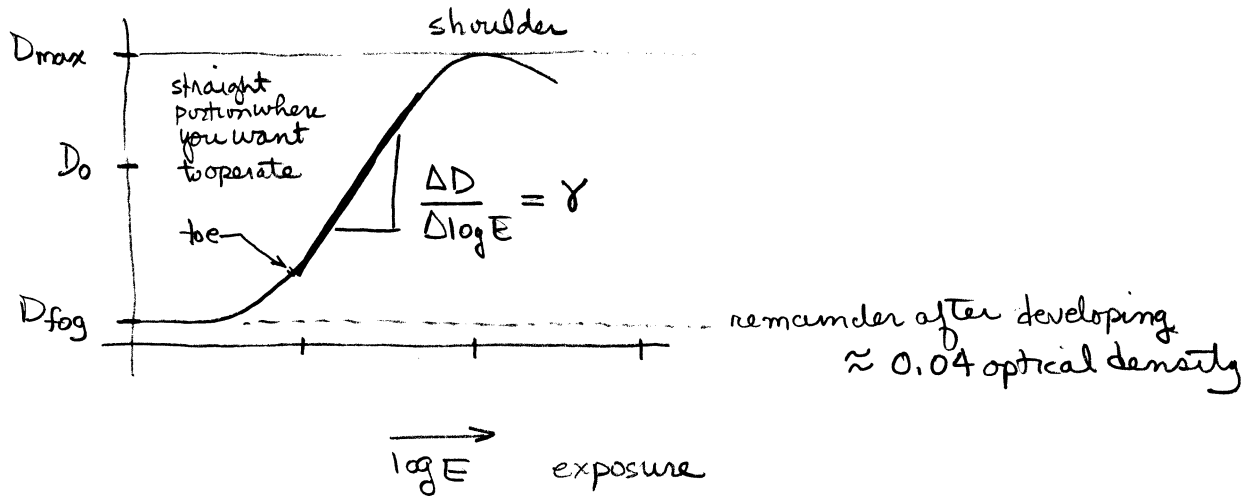
transmittances multiply
 densities add.
 $T = 10^{-D(x,y)}$

Photographic film



exposing emulsion to light, molecules are reduced to silver and grain becomes exposed

development reduces silver halide grains to silver
 exposed grains reduce MUCH more rapidly than unexposed ones
 after developing wash unreduced grains away



Film resolution

expose emulsion with sinusoidal pattern of light intensity

$$\log E = \log E_0 + \sin(2\pi f x)$$

where E_0 puts us in the central part of the H-D curve.

just using H-D curve

$$D(x) = D_0 + \gamma \sin(2\pi f x)$$

however, if f is large grain size and light scattering reduce contrast

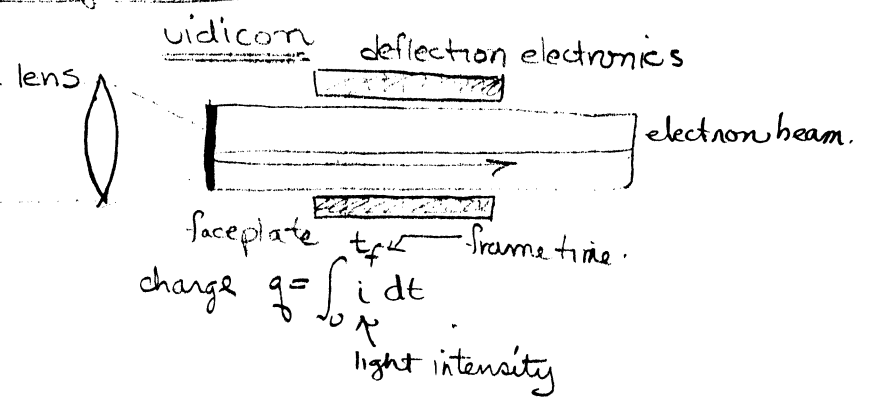
$$D(x) = D_0 + \gamma M(f) \sin(2\pi f x)$$

$M(f)$ is called the modulation transfer function (MTF)

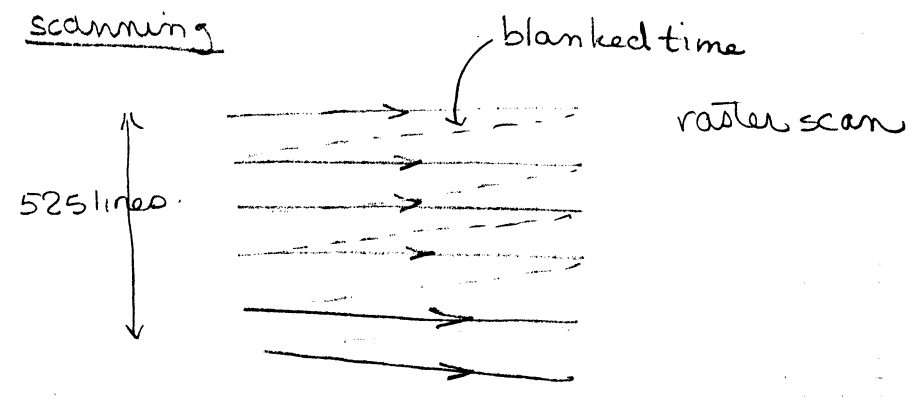
f_L frequency at which M drops to 0.1

HW
1
5
7
9
10
11

Image sensors



to make this process correspond to reading intensity is to keep t_f a constant

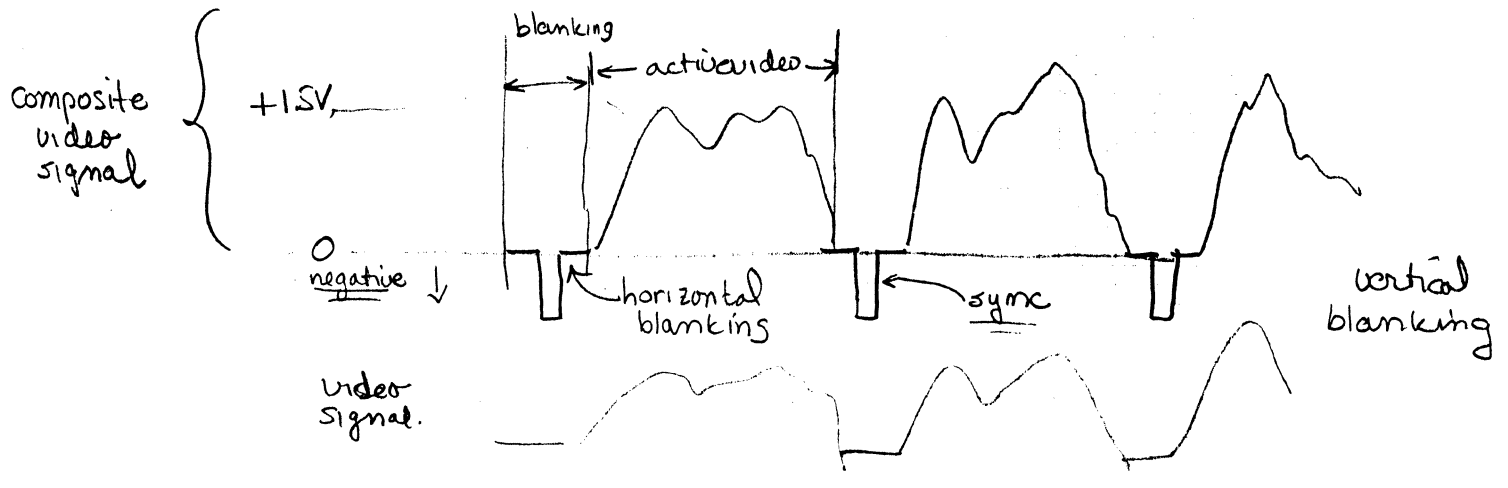


30 frames/second

$$\text{scan velocity} = \frac{1 \text{ sec}}{30 \text{ frames}} \cdot \frac{1 \text{ frame}}{525 \text{ lines}} = \frac{63.5 \mu\text{sec}}{\text{line}}$$

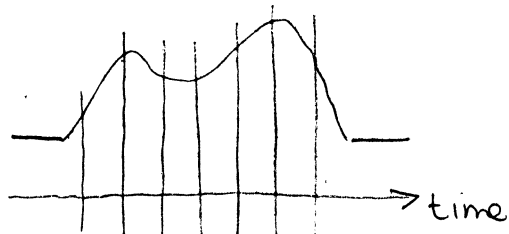
U.S. standard.

52 μsec active + 18 μsec blanking

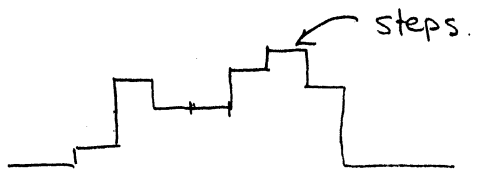


Sampling process

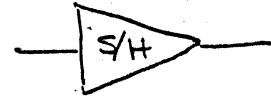
video signal



sample at regular intervals



sample/hold

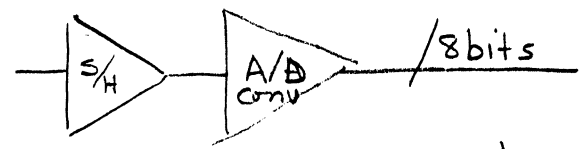


of samples/line = horizontal resolution

of lines = vertical resolution

often 10 nsec/pixel giving ≈ 512 pixels/line good!

Dynamic Range

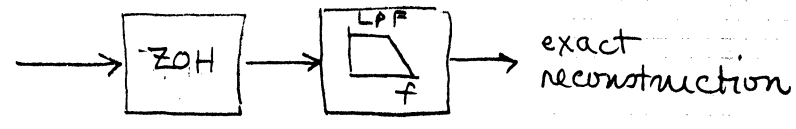
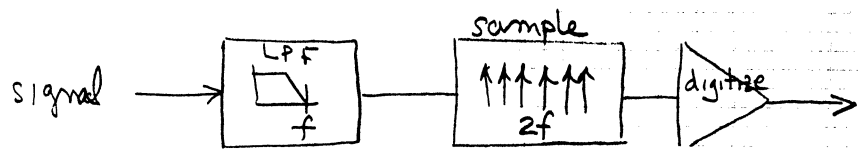


of bits/sample = dynamic range.

mention iris on camera.

Sampling Theorem

1948



mention effects of spatial resolution